MINUTES

Check antenna

- Check if it's a signal issue
- Or check if hardware issue
- Check if Q can report upon in terms of link
    - Drop packets etc
    - What parameters can change on the situation

Seems like collision detection inbuilt on the drones

Made manual control easier

- Move throttle up to take control

Write docs in same way as report

Found new GPS

- Around $50
- On digikey
- Should be plug and play
- May need to check the data received
- Check if its standard or company specific nmea package

GUI:

- Flask server on drones
- Made own folder that has important files
- Once ros is done, can add in the folder
    - Can call one of the methods can send ros file over to the drones
- Flask server can send information on GUI

- Think this as a user story

    - Starting in the lab how do I know they are ready
    - When in the field, how do I know everything is good
- Need to talk about what has been achieved
- Little bit of time to close some gaps
- Can you connect on an isolated network? Make sure that comes across
- Technical is good – but need to hammer home user story
    - Can actually take this out
    - Is better than the CLI

Write docs, can add appendix to get some credit maybe

Alright to keep old stuff in a DEPRICATED folder