## CENG 384 - Signals and Systems for Computer Engineers Spring 2023 Homework 2

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1. (a)

$$y(t) = x(t) - 5\dot{y}(t)$$

(b)

$$y(t) = (e^{-t} + e^{-3t})u(t) - 5\dot{y}(t)$$

$$y(t) + 5\dot{y}(t) = (e^{-t} + e^{-3t})u(t)$$

$$y(t) = y_p(t) + y_h(t)$$

$$y_p(t) = Ke^{-t}u(t) + Le^{-3t}u(t)$$

$$Ke^{-t}u(t) + Le^{-3t}u(t) + 5(-Ke^{-t}u(t) - 3Le^{-3t}u(t)) = (e^{-t} + e^{-3t})u(t)$$

$$Ke^{-t}u(t) + Le^{-3t}u(t) - 5Ke^{-t}u(t) - 15Le^{-3t}u(t) = (e^{-t} + e^{-3t})u(t)$$

$$e^{-t}u(t)(K - 5K) + e^{-3t}u(t)(L - 15L) = (e^{-t} + e^{-3t})u(t)$$

$$K - 5K = 1$$

$$K = -1/4$$

$$L - 15L = 1$$

$$L = -1/14$$

$$y_p(t) = \frac{-1}{4}e^{-t}u(t) + \frac{-1}{14}e^{-3t}u(t)$$

$$y_h(t) = c_1e^{at}$$

$$c_1e^{at} + 5ac_1e^{at} = 0$$

$$c_1 + 5ac_1 = 0$$

$$\alpha = \frac{-1}{5}$$

$$y_h(t) = c_1e^{-\frac{1}{5}t}$$

$$y(t) = y_p(t) + y_h(t)$$

$$= \frac{-1}{4}e^{-t}u(t) + \frac{-1}{14}e^{-3t}u(t) + c_1e^{-\frac{1}{5}t}$$

$$y(0) = 0$$

$$0 = \frac{-1}{4} + \frac{-1}{14} + c_1$$

$$c_1 = \frac{9}{28}$$

$$y(t) = \frac{-1}{4}e^{-t}u(t) + \frac{-1}{14}e^{-3t}u(t) + \frac{9}{28}e^{-\frac{1}{5}t}$$

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2. (a)

$$\begin{split} y[n] &= x[n] * h[n] \\ &= \sum_{k=0}^n x[k]h[n-k] \\ &= \sum_{k=0}^n \left(2\delta[k] + \delta[k+1]\right) \left(\delta[n-(1+k)] + 2\delta[n+1-k]\right) \\ &= 2\sum_{k=0}^n \delta[k]\delta[n-(1+k)] + 4\sum_{k=0}^n \delta[k]\delta[n+1-k] + \sum_{k=0}^n \delta[k+1]\delta[n-(1+k)] + 2\sum_{k=0}^n \delta[k+1]\delta[n+1-k] \\ &= 2\delta\left[\frac{n-1}{2}\right] + 4\delta\left[\frac{n+1}{2}\right] + \delta\left[\frac{n-2}{2}\right] + 2\delta\left[\frac{n}{2}\right] \end{split}$$

(b)

$$\begin{split} y(t) &= \frac{dx(t)}{dt} * h(t) \\ &= \frac{d}{dt} \left( u(t-1) + u(t+1) \right) * e^{-t} \sin(t) u(t) \\ &= \left( \delta(t-1) + \delta(t+1) \right) * e^{-t} \sin(t) u(t) \\ &= \int_{-\infty}^{\infty} \left( \delta(\tau-1) + \delta(\tau+1) \right) e^{-t-\tau} \sin(t-\tau) d\tau \\ &= \int_{-\infty}^{\infty} \delta(\tau-1) e^{-t-\tau} \sin(t-\tau) d\tau + \int_{-\infty}^{\infty} \delta(\tau+1) e^{-t-\tau} \sin(t-\tau) d\tau \\ &= e^{-t-1} \sin(t-1) u(t) + e^{-t+1} \sin(t+1) u(t) \end{split}$$

3. (a)

$$\begin{split} y(t) &= x(t) * h(t) \\ &= \int_{-\infty}^{\infty} x(\tau)h(t-\tau)d\tau \\ &= \int_{-\infty}^{\infty} x(t-\tau)h(\tau)d\tau \\ &= \int_{-\infty}^{\infty} e^{-(t-\tau)}e^{-2\tau}d\tau \\ &= \int_{0}^{t} e^{-(t-\tau)}e^{-2\tau}d\tau \\ &= e^{-t} \int_{0}^{t} e^{\tau}d\tau \\ &= e^{-t} \left(1 - e^{-t}\right)u(t) \end{split}$$

(b)

$$\begin{split} y(t) &= x(t) * h(t) \\ &= \int_{-\infty}^{\infty} x(\tau)h(t-\tau)d\tau \\ &= \int_{-\infty}^{\infty} x(t-\tau)h(\tau)d\tau \\ &= \int_{-\infty}^{\infty} \left(u(t-\tau) - u(t-(\tau+1))\right)e^{3\tau}d\tau \\ &= \int_{-\infty}^{\infty} u(t-\tau)e^{3\tau}d\tau - \int_{-\infty}^{\infty} u(t-(\tau+1))e^{3\tau}d\tau \\ &= \int_{-\infty}^{t} e^{3\tau}d\tau - \int_{-\infty}^{t-1} e^{3\tau}d\tau \\ &= \frac{e^{3t}}{3} - \frac{e^{3t-3}}{3} \end{split}$$

4. (a)

$$\begin{split} y[n] - y[n-1] - y[n-2] &= 0 \\ y[n] &= y[n-1] + y[n-2] \\ y[2] &= y[1] - y[0] &= 2 \\ y[3] &= y[2] - y[1] &= 3 \\ y[4] &= y[3] - y[2] &= 5 \\ y[5] &= y[4] - y[3] &= 8 \end{split}$$

It is the Fibonacci sequence.

$$y[n] = \frac{(1+\sqrt{5})^n - (1-\sqrt{5})^n}{2^n\sqrt{5}}$$

$$y^{(3)}(t) - 6y''(t) + 13y'(t) - 10y(t) = 0$$

$$K^3 - 6K^2 + 13K - 10 = 0$$

$$K(K - 5)(K - 2) + (K + 5)(K - 2) = 0$$

$$(K - 2)(K^2 - 4K + 5) = 0$$

$$K = 2, 2 - j, 2 + j$$

$$\begin{aligned} y_h(t) &= c_1 e^{2t} + c_2 e^{(2+j)t} + c_3 e^{(2-j)t} \\ y_h(t) &= c_1 e^{2t} + c_2 \left( e^{2t} \cos(t) + j e^{2t} \sin(t) \right) + c_3 \left( e^{2t} \cos(t) - j e^{2t} \sin(t) \right) \\ y_h(t) &= c_1 e^{2t} + c_2 e^{2t} \cos(t) + c_3 e^{2t} \cos(t) + c_2 j e^{2t} \sin(t) - c_3 j e^{2t} \sin(t) \\ y_h(t) &= c_1 e^{2t} + (c_2 + c_3) e^{2t} \cos(t) + j (c_2 - c_3) e^{2t} \sin(t) \\ y_h(t) &= C_1 e^{2t} + C_2 e^{2t} \cos(t) + C_3 e^{2t} \sin(t) \end{aligned}$$

$$y''(0) = 3$$

$$= 4C_1 + 3C_2 + 4C_3$$

$$y'(0) = 1.5$$

$$= 2C_1 + 2C_2 + C_3$$

$$y(0) = 1$$

$$= C_1 + C_2$$

$$C_1 = 2$$

$$C_2 = -1$$

$$C_3 = -0.5$$

$$y_h(t) = 2e^{2t} - e^{2t}\cos(t) - \frac{1}{2}e^{2t}\sin(t)$$

$$y''(t) + 5y'(t) + 6y(t) = \cos(5t)$$

$$= \frac{e^{j5t} - e^{-j5t}}{2}$$

$$= \frac{e^{j5t}}{2} - \frac{e^{-j5t}}{2}$$

$$y_p(t) = c_1 e^{j5t} + c_2 e^{-j5t}$$

$$-25c_1e^{j5t} - 25c_2e^{-j5t} + 25jc_1e^{j5t} - 25jc_2e^{-j5t} + 6c_1e^{j5t} + 6c_2e^{-j5t} = \frac{e^{j5t}}{2} - \frac{e^{-j5t}}{2}$$
$$e^{j5t} \left(-19c_1 + 25jc_1\right) + e^{-j5t} \left(-19c_2 - 25jc_2\right) = \frac{e^{j5t}}{2} - \frac{e^{-j5t}}{2}$$

$$(-19c_1 + 25jc_1) = (-19c_2 - 25jc_2) = \frac{1}{2}$$

$$c_1 = \frac{1}{50j - 38}$$

$$c_2 = \frac{-1}{50j + 38}$$

$$y_p(t) = \frac{1}{50j - 38}e^{j5t} - \frac{1}{50j + 38}e^{-j5t}$$

(b)

$$y''(t) + 5y'(t) + 6y(t) = 0$$
$$K^{2} + 5K + 6 = 0$$
$$K = -3, -2$$

$$y_h(t) = c_1 e^{-3t} + c_2 e^{-2t}$$

(c)

$$y(t) = y_p(t) + y_h(t)$$

$$= \frac{1}{50j - 38}e^{j5t} - \frac{1}{50j + 38}e^{-j5t} + c_1e^{-3t} + c_2e^{-2t}$$

$$y(0) = y'(0) = 0$$

$$\frac{1}{50j - 38} - \frac{1}{50j + 38} + c_1 + c_2 = 0$$

$$\frac{5j}{50j - 38} + \frac{5j}{50j + 38} - 3c_1 - 2c_2 = 0$$

$$c_1 = \frac{3}{34}$$
$$c_2 = \frac{-2}{29}$$

$$y(t) = \frac{1}{50j - 38}e^{j5t} - \frac{1}{50j + 38}e^{-j5t} + \frac{3}{34}e^{-3t} - \frac{2}{29}e^{-2t}$$

6. (a)

$$w[n] - \frac{1}{2}w[n-1] = x[n]$$

$$w[n] = 0, \forall n < 0$$

$$w[0] - \frac{1}{2}w[-1] = x[0]$$

$$w[0] = x[0]$$

$$w[1] - \frac{1}{2}w[0] = x[1]$$

$$w[1] = x[1] + \frac{1}{2}x[0]$$

$$w[2] - \frac{1}{2}w[1] = x[2]$$

$$w[2] = x[2] + \frac{1}{2}x[1] + \frac{1}{4}x[0]$$
...
$$w[n] = \sum_{k=0}^{n} 2^{-k}x[n-k]$$

$$h_0[n] = \sum_{k=0}^{n} 2^{-k}\delta[n-k]$$

$$= 2^{-n}$$

$$(\delta[n-k] = 0 \text{ for } k! = n)$$

(b) If we feed the first system with the unit impulse, we get  $h_0[n]$ . If we feed the second system with  $h_0[n]$ , we get

$$h[n] = \sum_{k=0}^{n} 2^{-k} 2^{-n+k}$$
$$= \sum_{k=0}^{n} 2^{-n}$$
$$= (n+1) * 2^{-n}$$

(c)

$$y[n] = x[n] * h[n]$$

$$= \sum_{k=-\infty}^{\infty} x[n-k]h[k]$$

$$= \sum_{k=0}^{\infty} x[n-k]h[k] \qquad (h[k] = 0 \text{ for } k < 0)$$

$$= \sum_{k=0}^{\infty} x[k] * (n+1) * 2^{k-n}$$

- 7. (a)
  - (b)