

CENG 384 - Signals and Systems for Computer Engineers  
Spring 2023  
Homework 1

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March 31, 2023

1. (a)

$$z = x + yj \implies \bar{z} = x - yj$$

$$2z + 5 = j - \bar{z}$$

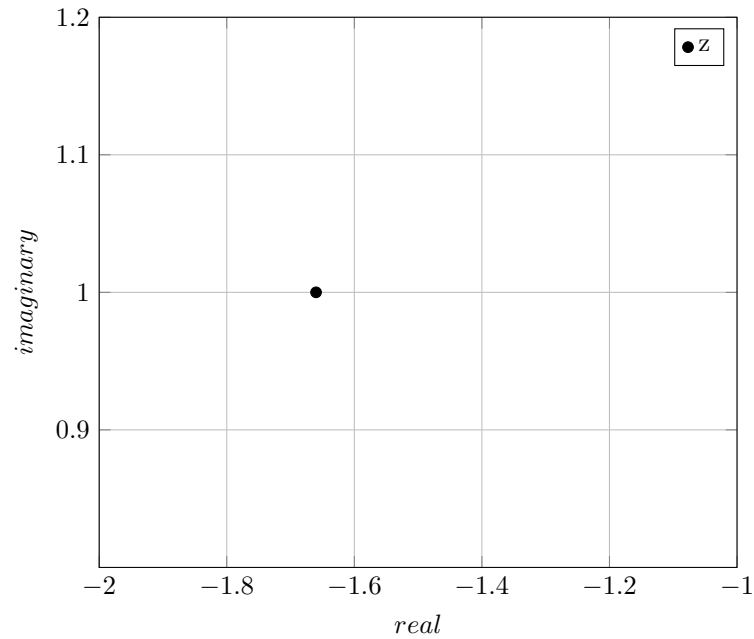
$$2(x + yj) + 5 = j - (x - yj)$$

$$2x + 5 + 2yj = (1 + y)j - x$$

$$y = 1, x = \frac{-5}{3}$$

$$z = \frac{-5}{3} + j$$

$$|z|^2 = \frac{25}{9} + 1 = \frac{34}{9}$$



(b)

$$z = re^{j\theta} \implies z^5 = r^5 e^{j5\theta}$$

$$32j = 32e^{j\pi/2}$$

$$32e^{j\pi/2} = r^5 e^{j5\theta} \implies r = 2, \theta = \pi/10$$

$$z = 2e^{j\pi/10}$$

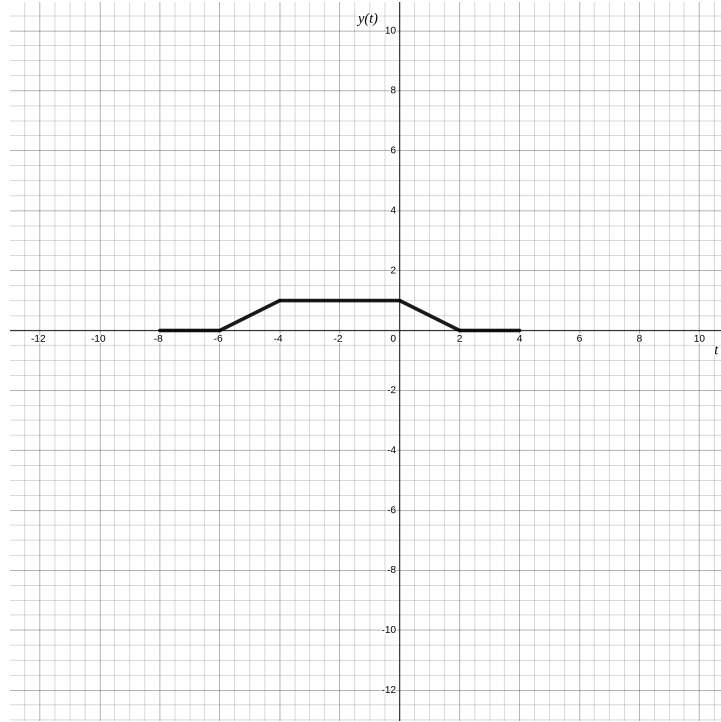
(c)

$$\begin{aligned}z &= \frac{(1+j)(\frac{1}{2} + \frac{\sqrt{3}}{2})j}{j-1} \\&= \frac{(j+1)(1+j)(\frac{1}{2} + \frac{\sqrt{3}}{2})j}{(j+1)(j-1)} \\&= \frac{(j+1)^2(\frac{1}{2} + \frac{\sqrt{3}}{2})}{-2} \\&= \frac{(j^2 + 2j + 1)(\frac{1}{2} + \frac{\sqrt{3}}{2})}{-2} \\&= \frac{(-1 + 2j + 1)(\frac{1}{2} + \frac{\sqrt{3}}{2})}{-2} \\&= \frac{2j(\frac{1}{2} + \frac{\sqrt{3}}{2})}{-2} \\&= -j(\frac{1}{2} + \frac{\sqrt{3}}{2}) \\z &= r \cos \theta + r \sin \theta j \\j(-\frac{1}{2} - \frac{\sqrt{3}}{2}) &= r \cos \theta + r \sin \theta j \\r \cos \theta &= 0 \\r \sin \theta &= -\frac{1}{2} - \frac{\sqrt{3}}{2} \\\cos \theta &= 0 \\\sin \theta &= -1 \\r &= \frac{1}{2} + \frac{\sqrt{3}}{2} \\\theta &= -\pi/2\end{aligned}$$

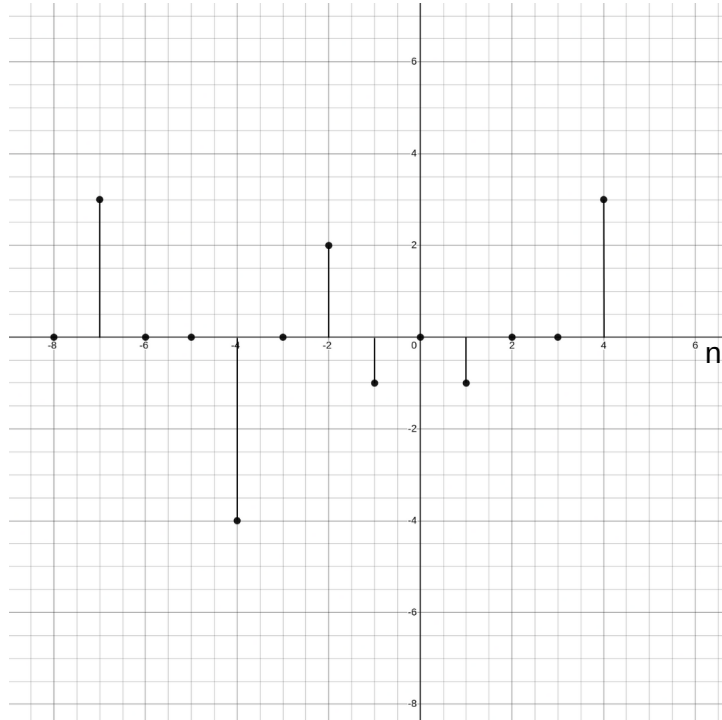
(d)

$$\begin{aligned}z &= je^{-j\pi/2} \\&= e^{j\pi/2}e^{-j\pi/2} \\&= e^0 = 1\end{aligned}$$

2. The graph of the function is given below.



3. (a) The graph of the function  $x[-n] + x[2n - 1]$  is given below.



(b)

$$\begin{aligned}
 x[n] &= -\delta[n-1] + 2\delta[n-2] - 4\delta[n-4] + 3\delta[n-7] \\
 x[-n] &= -\delta[-n-1] + 2\delta[-n-2] - 4\delta[-n-4] + 3\delta[-n-7] \\
 &= -\delta[n+1] + 2\delta[n+2] - 4\delta[n+4] + 3\delta[n+7] \\
 x[2n-1] &= -\delta[2n-2] + 2\delta[2n-3] - 4\delta[2n-5] + 3\delta[2n-8] \\
 &= -\delta[n-1] + 3\delta[n-4] \\
 x[-n] + x[2n-1] &= -\delta[n+1] + 2\delta[n+2] - 4\delta[n+4] + 3\delta[n+7] - \delta[n-1] + 3\delta[n-4]
 \end{aligned}$$

4. (a)

$$\begin{aligned}
x(t) &= x(t + t_0) \\
5 \sin(3t - \frac{\pi}{4}) &= 5 \sin(3(t + t_0) - \frac{\pi}{4}) \\
\sin(3t - \frac{\pi}{4}) &= \sin(3t + 3t_0 - \frac{\pi}{4}) \\
\sin(3t - \frac{\pi}{4}) &= \sin(3t) \cos(3t_0 - \frac{\pi}{4}) + \cos(3t) \sin(3t_0 - \frac{\pi}{4}) \\
\sin(3t) \cos(-\frac{\pi}{4}) + \cos(3t) \sin(-\frac{\pi}{4}) &= \sin(3t) \cos(3t_0 - \frac{\pi}{4}) + \cos(3t) \sin(3t_0 - \frac{\pi}{4}) \\
\sin(3t) \frac{\sqrt{2}}{2} - \cos(3t) \frac{\sqrt{2}}{2} &= \sin(3t) \cos(3t_0 - \frac{\pi}{4}) + \cos(3t) \sin(3t_0 - \frac{\pi}{4}) \\
\sin(3t) \frac{\sqrt{2}}{2} - \sin(3t) \cos(3t_0 - \frac{\pi}{4}) &= \cos(3t) \frac{\sqrt{2}}{2} + \cos(3t) \sin(3t_0 - \frac{\pi}{4}) \\
\sin(3t) \left( \frac{\sqrt{2}}{2} - \cos(3t_0 - \frac{\pi}{4}) \right) &= \cos(3t) \left( \frac{\sqrt{2}}{2} + \sin(3t_0 - \frac{\pi}{4}) \right) \\
\frac{\sqrt{2}}{2} - \cos(3t_0 - \frac{\pi}{4}) &= 0 \\
\frac{\sqrt{2}}{2} + \sin(3t_0 - \frac{\pi}{4}) &= 0 \\
t_0 &= \frac{2\pi}{3}
\end{aligned}$$

(b)

$$\begin{aligned}
x[n] &= x[n + t_0] \\
\cos[\frac{13\pi}{10}n] + \sin[\frac{7\pi}{10}n] &= \cos[\frac{13\pi}{10}(n + t_0)] + \sin[\frac{7\pi}{10}(n + t_0)] \\
\sin[\frac{\pi}{2} - \frac{13\pi}{10}n] + \sin[\frac{7\pi}{10}n] &= \sin[\frac{\pi}{2} - \frac{13\pi}{10}(n + t_0)] + \sin[\frac{7\pi}{10}(n + t_0)] \\
\sin[\frac{5\pi}{10} - \frac{13\pi}{10}n] + \sin[\frac{7\pi}{10}n] &= \sin[\frac{5\pi}{10} - \frac{13\pi}{10}(n + t_0)] + \sin[\frac{7\pi}{10}(n + t_0)] \\
\sin[\frac{\pi}{10}(13n - 5)] + \sin[\frac{7\pi}{10}n] &= \sin[\frac{\pi}{10}(13n + 13t_0 - 5)] + \sin[\frac{7\pi}{10}(n + t_0)] \\
2 \sin(\frac{\frac{\pi}{10}(13n - 5) + \frac{7\pi}{10}n}{2}) \cos(\frac{\frac{\pi}{10}(13n - 5) - \frac{7\pi}{10}n}{2}) &= 2 \sin(\frac{\frac{\pi}{10}(13n + 13t_0 - 5) + \frac{7\pi}{10}(n + t_0)}{2}) \cos(\frac{\frac{\pi}{10}(13n + 13t_0 - 5) - \frac{7\pi}{10}(n + t_0)}{2}) \\
\sin(\frac{\pi}{20}(20n - 5)) \cos(\frac{\pi}{20}(6n - 5)) &= \sin(\frac{\pi}{20}(20n + 20t_0 - 5)) \cos(\frac{\pi}{20}(6n + 6t_0 - 5)) \\
\sin(n\pi - \frac{\pi}{4}) \cos(\frac{3n\pi}{10} - \frac{\pi}{4}) &= \sin(n\pi + t_0\pi - \frac{\pi}{4}) \cos(\frac{3n\pi + 3t_0\pi}{10} - \frac{\pi}{4})
\end{aligned}$$

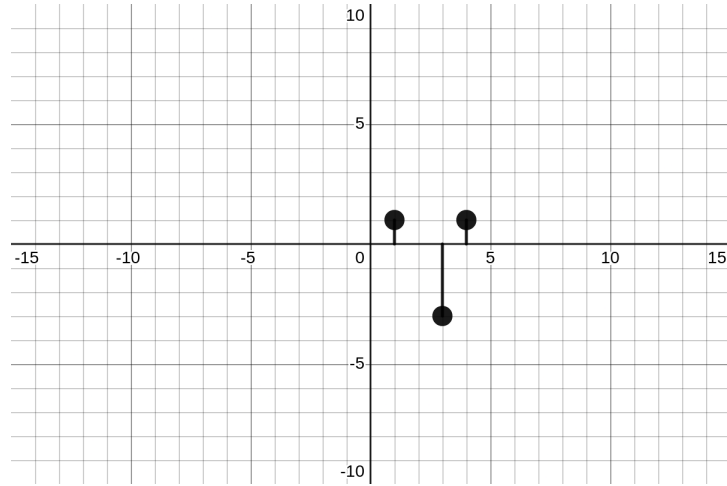
The smallest integer  $t_0$  that satisfies the equation above is  $t_0 = 20$ .

(c) The signal is not periodic as there is no integer that satisfies the equation below.

$$\frac{1}{2} \cos(7n - 5) = \frac{1}{2} \cos(7(n + t_0) - 5)$$

5. (a)  $x(t) = u[t - 1] - 3u[t - 3] + u[t - 4]$

(b)  $\frac{dx(t)}{dt} = \delta(t-1) - 3\delta(t-3) + \delta(t-4)$  The graph of  $\frac{dx(t)}{dt}$  is given below.



6. (a)

$$y(x) = tx(2x + 3)$$

*Memory:* The system has memory, as the output depends on the future values of the input. For example, for  $t = 3$ , the output value depends on the future value of the input,  $y(3) = 3x(9)$ .

*Stability:* The system is **not** stable, as there is no finite number  $b'$  such that  $|y(t)| \leq b'$  for all  $t$ .

*Causality:* The system is **not** causal, as the output depends on the future values of the input.

*Linearity:* The system is linear, because the superposition principle holds.

$$x_1 \implies y_1(t) = tx_1(2t + 3)$$

$$x_2 \implies y_2(t) = tx_2(2t + 3)$$

$$x_3 = a_1x_1 + a_2x_2$$

*assumption*

$$y_3 = t(a_1x_1 + a_2x_2) = a_1y_1 + a_2y_2$$

*Invertibility:* The system is invertible for  $t \neq 0$ .

$$y(t) = tx(2t + 3)$$

$$\frac{1}{t}y(t) = x(2t + 3)$$

$$\frac{1}{t}y\left(\frac{t-3}{2}\right) = x(t)$$

*Time invariance:* The system is **not** time invariant.

$$y(t) = tx(2t + 3)$$

$$y(t - t_0) = (t - t_0)x(2(t - t_0) + 3) \neq tx(2(t - t_0) + 3)$$

(b)

$$y[n] = \sum_{k=1}^{\infty} x[n-k]$$

*Memory:* The system has memory, as the output depends on the past values of the input. For example, for  $n = 6$ , the output value depends on the past values of the input,  $y[6] = x[5] + x[4] + x[3] + \dots$ .

*Stability:* The system is **not** stable, as there is no finite number  $b'$  such that  $|y(t)| \leq b'$  for all  $t$ . For example, if

we take  $x(n)$  as the unit step function, the signal  $\sum_{k=1}^{\infty} u[n-k]$  is unbounded for  $n \Rightarrow \infty$ .

*Causality:* The system is causal, as the output depends on the past values of the input.

*Linearity:* The system is linear, because the superposition principle holds.

$$\begin{aligned} x_1 &\Rightarrow y_1(n) = \sum_{k=1}^{\infty} x_1[n-k] \\ x_2 &\Rightarrow y_2(n) = \sum_{k=1}^{\infty} x_2[n-k] \\ a_1 y_1 + a_2 y_2 &= \sum_{k=1}^{\infty} (a_1 x_1[n-k] + a_2 x_2[n-k]) \\ \sum_{k=1}^{\infty} x_3[n-k] &= a_1 \sum_{k=1}^{\infty} x_1[n-k] + a_2 \sum_{k=1}^{\infty} x_2[n-k] \end{aligned}$$

*Invertibility:* The system is not invertible, because the output depends on all the past values of the input.

*Time invariance:* The system is time invariant, because a delay in the input signal  $x[n]$  by  $x$ , causes a corresponding delay for the output signal  $y[n]$  by  $x$  as well.

$$y[n] = \sum_{k=1}^{\infty} x[n-k]$$

$$y[n-n_0] = \sum_{k=1}^{\infty} x[(n-n_0)-k]$$

7. (a)

```
def decompose(signal_name):
    """Read the CSV file with the signal name, decompose the signal into even and odd components,
    and save the results as PNG files."""

    with open(signal_name + ".csv", "r", encoding="ascii") as file:
        data = [float(item) for item in file.read().split(",")]
        start = int(data[0])
        signal = data[1:]
        end = start + len(signal) - 1

    pyplot.title("Original Signal")
    pyplot.plot(range(start, end + 1), signal)
    pyplot.savefig(IMAGES_PATH + signal_name + "_original.png")
    pyplot.clf()

    if abs(start) > end:
        signal = signal + [0] * (abs(start) - end)
        end = -start
    else:
        signal = [0] * (end - abs(start)) + signal
        start = -end

    even = [(x + y) / 2 for x, y in zip(signal, signal[::-1])]
    odd = [(x - y) / 2 for x, y in zip(signal, signal[::-1])]

    pyplot.title("Even Component")
    pyplot.plot(range(start, end + 1), even)
    pyplot.savefig(IMAGES_PATH + signal_name + "_even.png")
    pyplot.clf()
```

```

pyplot.title("Odd Component")
pyplot.plot(range(start, end + 1), odd)
pyplot.savefig(IMGES_PATH + signal_name + "_odd.png")
pyplot.clf()

```

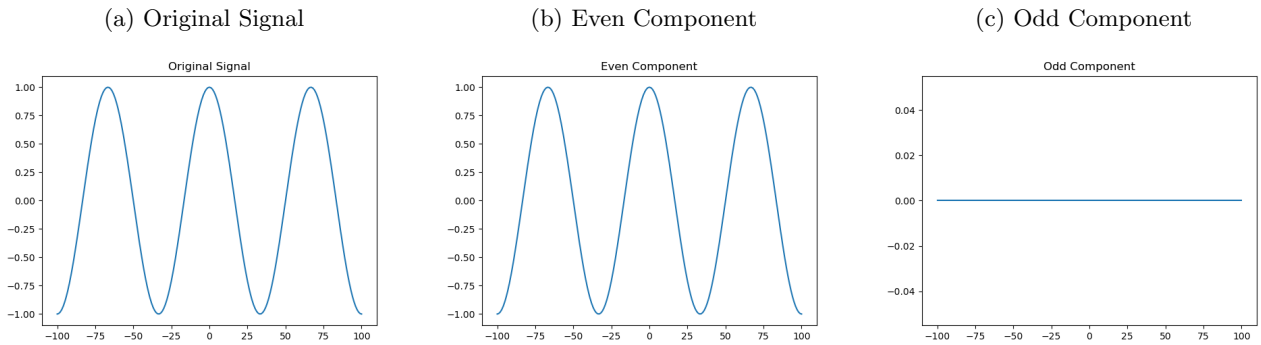


Figure 1: Sinusoidal Signal Decomposition

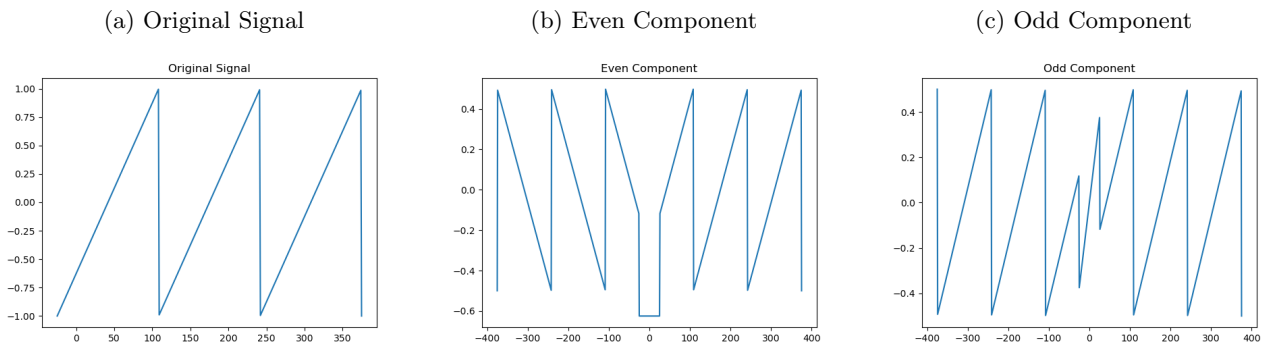


Figure 2: Shifted Sawtooth Signal Decomposition

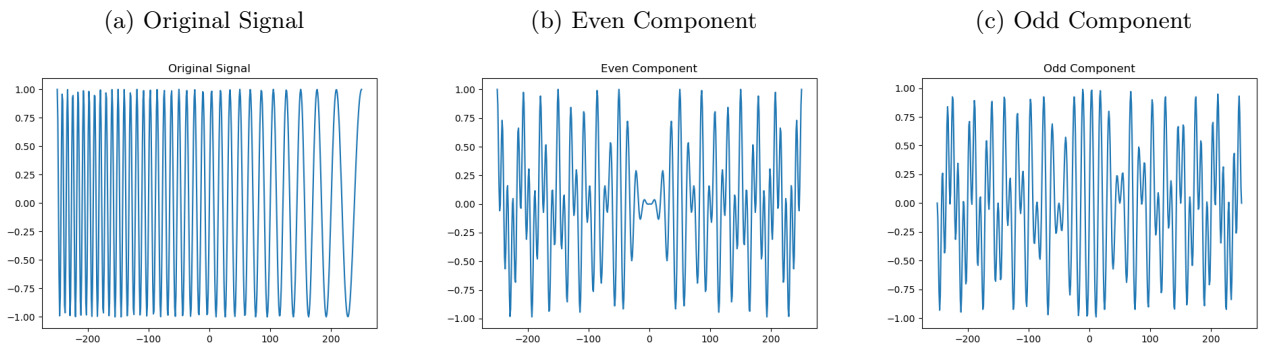


Figure 3: Chirp Signal Decomposition

(b)

```

class Signal:
    def __init__(self, signal, start, a, b):
        self.signal = signal
        self.start = start
        self.a = a
        self.b = b

    def __getitem__(self, index):
        return self.signal[self.a * index + self.b - self.start]

```

```

def shift_n_scale(signal_name):
    """
    Read the CSV file with the signal name, shift and scale the signal,
    and save the results as PNG files.

    This functions reads a signal  $x[n]$ , and produces  $x[a*n + b]$  for  $a$  and  $b$ 
    """

    with open(signal_name + ".csv", "r", encoding="ascii") as file:
        data = [float(item) for item in file.read().split(",")]
    start = int(data[0])
    a = int(data[1])
    b = int(data[2])
    signal = Signal(data[3:], start, a, b)
    end = start + len(signal.signal) - 1

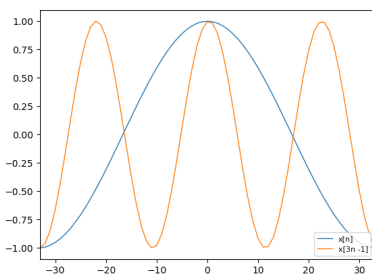
    new_start = (start - b) // a
    new_end = (end - b) // a
    pyplot.xlim(new_start, new_end)

    pyplot.plot(range(start, end + 1), signal.signal, linewidth=1)

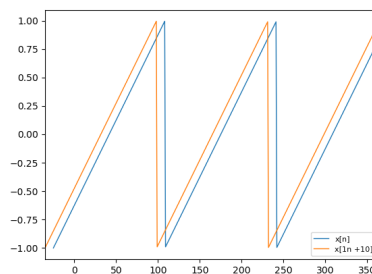
    if new_start > new_end:
        domain = range(new_start, new_end, -1)
    else:
        domain = range(new_start, new_end + 1)
    pyplot.plot(
        domain,
        [signal[i] for i in domain],
        linewidth=1,
    )
    pyplot.legend(
        ["x[n]", "x[" + str(a) + "n " + ("+" if b >= 0 else "") + str(b) + "]",
        loc="lower right",
        fontsize=8,
    )
    pyplot.savefig(IMAGES_PATH + signal_name)
    pyplot.clf()

```

(a) Sinusoidal Signal



(b) Shifted Sawtooth Signal



(c) Chirp Signal

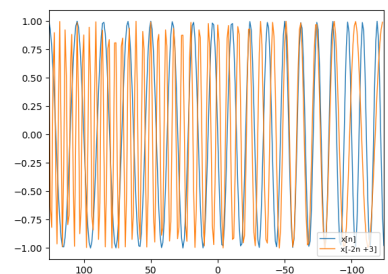


Figure 4: Shift and Scale