

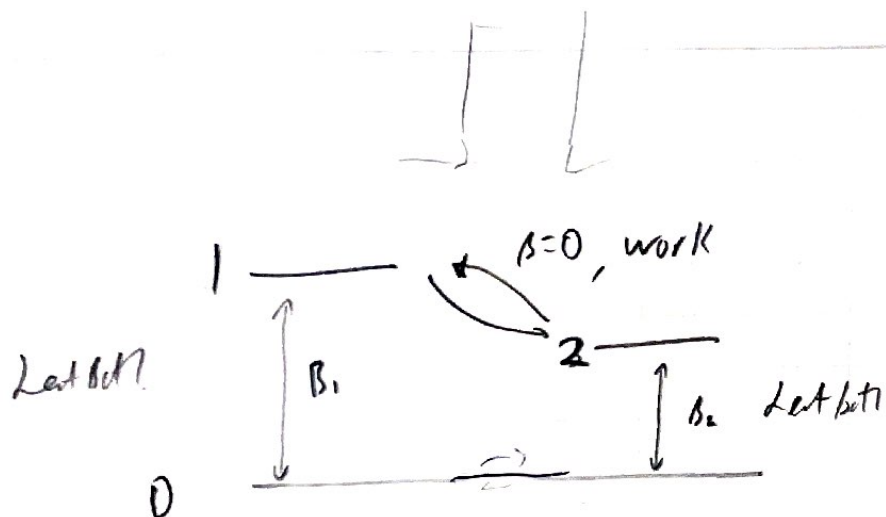
#12

12.0

$$\frac{\lambda_{01}}{\lambda_{10}} = e^{+\beta_1 \Delta E}$$

$$T_1 = 2T_2 \quad \textcircled{c}$$

$$\beta_1 = \frac{1}{2}\beta_2$$



$$\frac{P[x|x_0]}{P[\tilde{x}|\tilde{x}_0]} = e^{\tilde{z}^{env}} = e^{-\beta Q} \quad (\text{one bath})$$

$$= e^{-\beta_1 Q_1 - \beta_2 Q_2}$$

$P^{ss} \neq \text{converged}$

$$S = -\sum p \ln p$$

$$s(x) = -\ln p$$

$$S = \langle s \rangle$$

← ensemble average

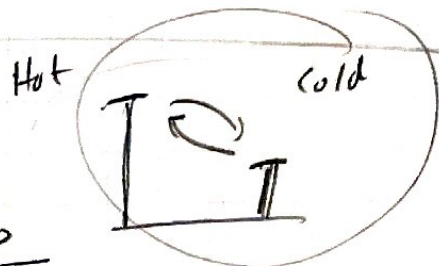
$$\frac{P[x]}{P[\tilde{x}]} = e^{-\beta_1 Q_1 - \beta_2 Q_2 + \Delta S}$$

$$\Delta S^{(x)} = (-\ln p(x;t)) - (-\ln p(x;0))$$

Heat engine

Heat Pump

Useless machine



$$Q = \begin{pmatrix} 0 & 1 & 2 \\ \lambda_{10} & \lambda_{01} & \lambda_{02} \\ \lambda_{20} & 1 & \end{pmatrix}$$

12 B

12.1

1

Classical Mechanics

Hamiltonian

$$H(\overset{\text{momenta}}{p}, \overset{\text{positions}}{q}, t)$$

general coordinates

[~~is~~ more than just external world]

Hamilton's equations

$$\frac{\partial p}{\partial t} = - \frac{\partial H}{\partial q}$$

$$\frac{\partial q}{\partial t} = \frac{\partial H}{\partial p}$$

Cartesian coordinates

$$H(v, r)$$

$$p = mv$$

$$H = K + U$$

$$= \frac{1}{2}mv^2 + U$$

Newton

$$F = ma$$

$$F = m \frac{dv}{dt}$$

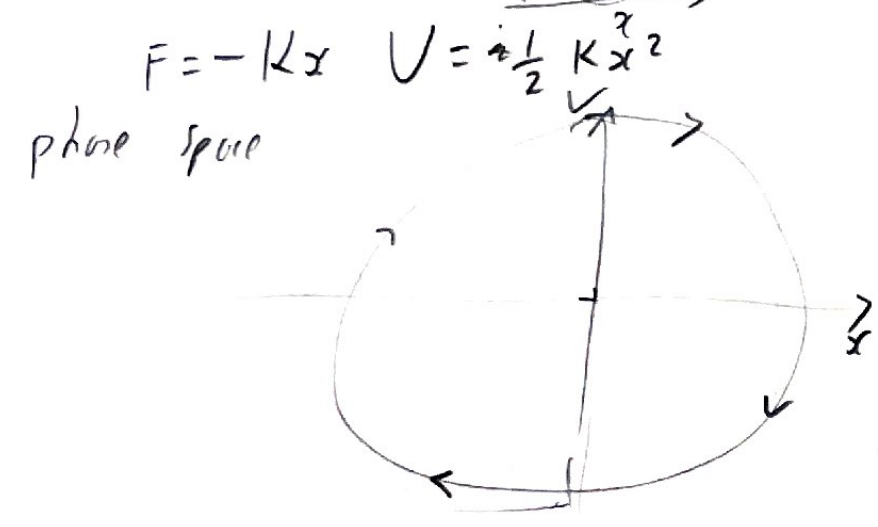
$$\frac{\partial v}{\partial t} = - \frac{1}{m} \frac{\partial U}{\partial r}$$

$$= \frac{1}{m} F$$

$$\frac{\partial r}{\partial t} = v$$

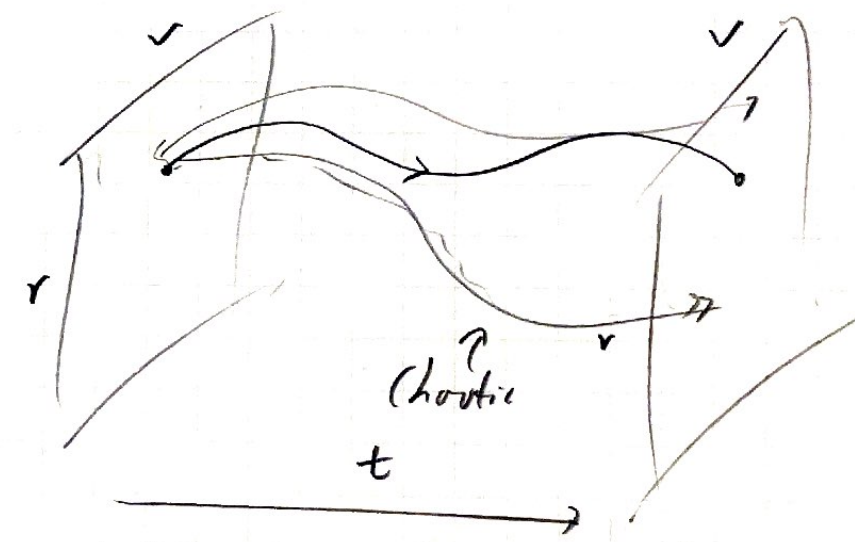
1/2 mv^2

Integrable system  
(1) Harmonic Oscillator  $\Rightarrow$



$\omega = \sqrt{\frac{K}{m}}$   $x(t) = A \cos(\omega t + c)$

Chaotic system



deterministic & invertable  
Chaotic

Liouville's eq

Liouvillian

$$\frac{\partial \rho(p, q; t)}{\partial t} = - \mathcal{L} \rho$$

$$\rho(p, q; t + \Delta t) = e^{-\Delta t \mathcal{L}} \rho(p, q; t)$$

$$\mathcal{L} \rho = \frac{\partial H}{\partial p} \frac{\partial \rho}{\partial q} - \frac{\partial H}{\partial q} \frac{\partial \rho}{\partial p}$$

[This is with  $e^{+tQ}$  convention]

(or ties in)

$$\mathcal{L}(v, r) = \underbrace{\mathcal{L}_r}_{v \frac{\partial}{\partial r}} + \mathcal{L}_v \quad \frac{1}{m} \frac{\partial}{\partial v}$$



12.8

Discussion: Jarzynski Eq for Deterministic ex.

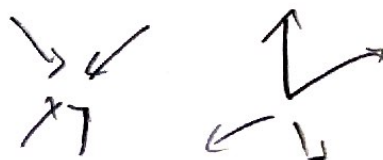
④

2nd Law Problem of, 3 meanings  
(Wolfram)

$(\dot{p}, \dot{q})$   
vector field



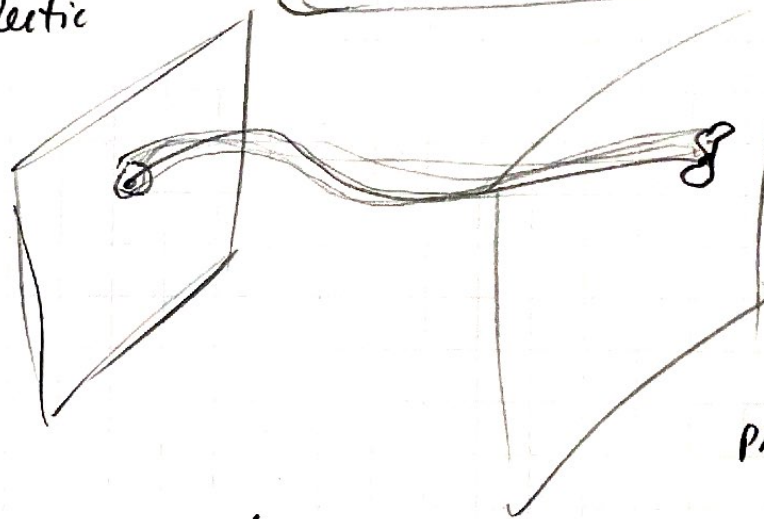
Divergence free



[Incompressible flow  
e.g. water]

Hamiltonian flow  
"symplectic"

$$P_\lambda[x] = P_{\tilde{\lambda}}[\tilde{x}] \quad H(t)$$



conservation of phase space!

Entropy does not change  
THERMODYNAMICALLY REVERSIBLE!

# Deterministic Thermostats

1984, 1985

NOSÉ 1984 HOOVER 1985  
"Nose - Hoover Thermostat"

$$m \frac{\partial v}{\partial t} = F - \lambda \frac{\partial g}{\partial v}$$

constraint

$$g(r, v, t) = 0$$

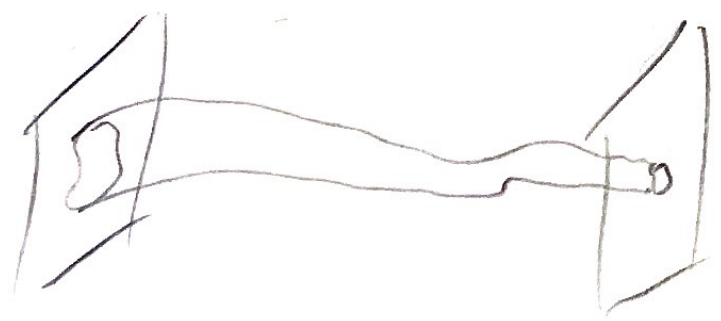
constant kinetic energy

isokinetic

$$g = \left( \sum \frac{1}{2} m v^2 \right) - K = 0$$

$[\lambda]$  is Lagrange multiplier to make constraint true

$$\frac{P_{\lambda}[\bar{x}]}{P_{\bar{\lambda}}[\bar{x}]} = e^{+\bar{Z}}$$



phase space contraction  $\rightarrow$   
Entropy production  
[see early FTs]

⑥

Molecular Dynamics

Discrete time

$$\rho(r, v; t + \Delta t) = e^{-\Delta t \mathcal{L}} \rho(r, v; t)$$

$$\mathcal{L} = \mathcal{L}_V + \mathcal{L}_R$$

$$e^{(A+B)\epsilon} \approx e^{A \frac{\epsilon}{2}} e^{B\epsilon} e^{A \frac{\epsilon}{2}} + O(\epsilon^3)$$

(using the Taylor series expansion)

$$e^{-\Delta t \mathcal{L}} \approx \underbrace{e^{-\frac{\Delta t}{2} \mathcal{L}_V}}_V \underbrace{e^{-\frac{\Delta t}{2} \mathcal{L}_R}}_R e^{-\frac{\Delta t}{2} \mathcal{L}_R} e^{-\frac{\Delta t}{2} \mathcal{L}_V}$$

Strang, (symmetric Trotter)  
operator splitting

$$AB \neq BA$$



[BARK] 42

$$V \quad v(t + \frac{\Delta t}{2}) = v(t) + \frac{\Delta t}{2} \frac{f}{m}$$

Velocity Verlet

$$R \quad r(t + \frac{\Delta t}{2}) = r(t) + \frac{\Delta t}{2} v(t + \frac{\Delta t}{2})$$

"Leap frog"

$$R \quad r(t + \Delta t) = r(t + \frac{\Delta t}{2}) + \frac{\Delta t}{2} v(t + \frac{\Delta t}{2})$$

← Evolve Force!

$$V \quad v(t + \Delta t) = v(t + \frac{\Delta t}{2}) + \frac{\Delta t}{2} \frac{f}{m}$$

position verlet

time.

V R R V V R R V V R R

velocity verlet

• Time Symmetric

• Symplectic (conserves phase space!) Hamiltonian dynamics



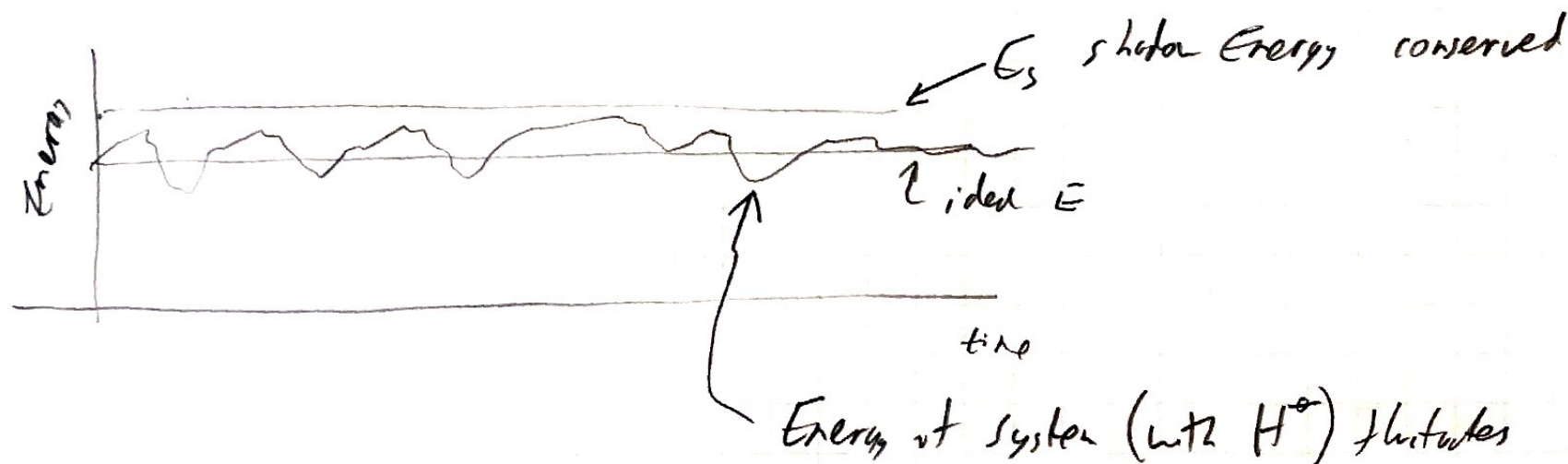
[Discussion  $\rightarrow$  Anomalies]

12. (8)

## Shooting Work

Shooting Hamiltonian  $H_{\#}^s \approx H^0 + O(\Delta t^3) (?)$

MD



$$W_s^{\text{shooting}} = H[v(t), r(t)] - H[v(0), r(0)]$$

(David Sivak)

Metropolisize