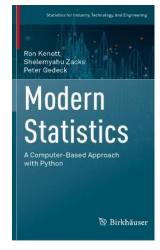
A Biomed Data Analyst Training Program

Supervised learning

Professor Ron S. Kenett





Preview This chapter is a door opener to computer age statistics. It covers a range of supervised and unsupervised learning methods and demonstrates their use in various applications.

7.1 Introduction to Computer Age Statistics

Big data and data science applications have been facilitated by hardware developments in computer science. As data storage began to increase, more advanced software was required to process it. This led to the development of cloud computing and distributed computing. Parallel machine processing was enhanced by the development of Hadoop, based on off-the-shelf Google File System (GFS) and Google MapReduce, for performing distributed computing.

Chapter 7

Modern Statistics: A Computer Based Approach with Python by Ron Kenett, Shelemyahu Zacks, Peter Gedeck

Publisher: Springer International Publishing; 1st edition (September 15, 2022) ISBN-13: 978-3031075650

(c) 2022 Ron Kenett, Shelemyahu Zacks, Peter Gedeck

The code needs to be executed in sequence.

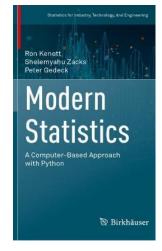
```
In [1]: import warnings
    import os
    os.environ['OUTDATED_IGNORE'] = '1'
    from outdated import OutdatedPackageWarning
    warnings.filterwarnings('ignore', category=FutureWarning)
    warnings.filterwarnings('ignore', category=OutdatedPackageWarning)
```

Modern Analytic Methods: Part I

Ron Kenett, Shelemyahu Zacks, Peter Gedeck Pages 361-393

Modern analytic methods: Part I

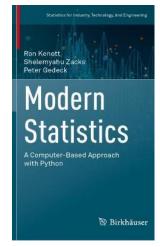
```
In [2]: import warnings
   import random
   import pandas as pd
   import numpy as np
   from sklearn.ensemble import RandomForestClassifier
   from sklearn.naive_bayes import MultinomialNB
   from sklearn.metrics import accuracy_score
   from sklearn.impute import SimpleImputer
   from sklearn.neural_network import MLPClassifier
   from sklearn.preprocessing import MinMaxScaler
   from sklearn.metrics import confusion_matrix, ConfusionMatrixDisplay
```





7.5 Decision Trees

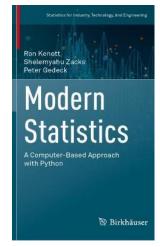
Partition models, also called decision trees, are non-parametric tools used in supervised learning in the context of classification and regression. In supervised learning you observe multiple covariate and one or more target variables. The goal is to predict or classify the target using the values of covariates. Decision trees are based on splits in covariates or predictors that create separate but homogeneous groups. Splits are not sensitive to outliers but are based on a "greedy" one -step look ahead, without accounting for overall performance. Breiman et al. (1984) implement a decision tree procedure called CART (Classification And Regression Trees). Other procedures are C4.5 and CHAID (Chi-square Automatic Interaction





Example 7.2 Data set **SENSORS.csv** consists of 174 measurements from 63 sensors tracking performance of a system under test. Each test generates values for these 63 sensors and a status determined by the automatic test equipment. The distribution of the test results is presented in Fig. 7.5. Our goal is to predict the outcome recorded by the testing equipment, using sensor data. The test results are coded as Pass (corresponding to "Good," 47% of the observations) and Fail (all other categories, marked in grey). The column **Status** is therefore a dichotomized version of the column **Test result**.

```
sensors = mistat.load_data('SENSORS.csv')
dist = sensors['testResult'].value_counts()
dist = dist.sort_index()
ax = dist.plot.bar(color='lightgrey')
ax.patches[dist.index.get_loc('Good')].set_facecolor('black')
plt.show()
```





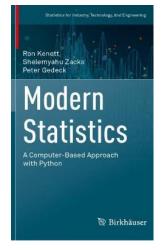
The goal is to predict the outcome recorded by the testing equipment, using sensor data. We can use scikit-learn for this. It has decision tree implementations for classification and regression. Here, we create a classification model for Pass-Fail using the 67 sensors.

```
from sklearn.tree import DecisionTreeClassifier, plot_tree, export_text

predictors = [c for c in sensors.columns if c.startswith('sensor')]
outcome = 'status'
X = sensors[predictors]
y = sensors[outcome]

# Train the model
clf = DecisionTreeClassifier(ccp_alpha=0.012, random_state=0)
clf.fit(X, y)

# Visualization of tree
plot_tree(clf, feature_names=list(X.columns))
plt.show()
```



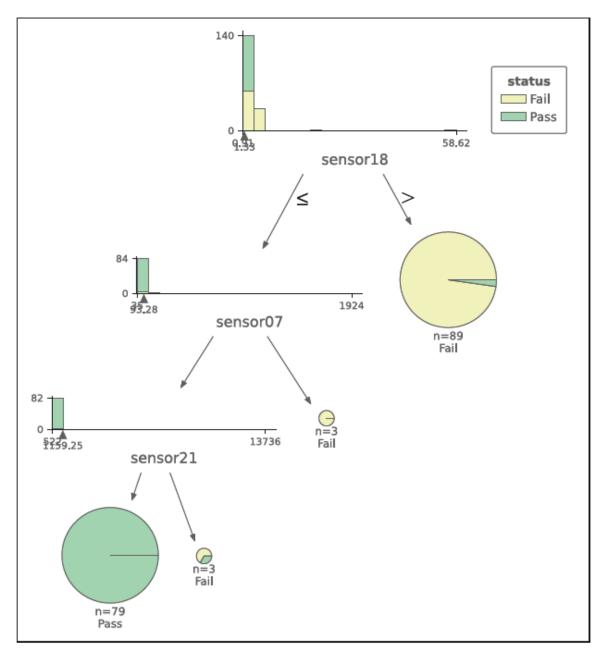
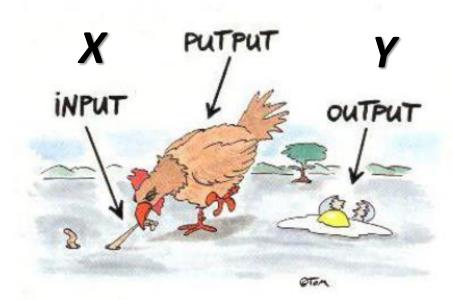
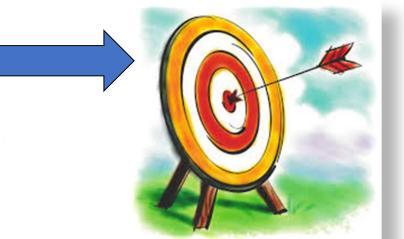


Fig. 7.7 Decision tree visualization of classification tree

	←		- <i>X</i> –		—	Y
1	Α	В	С	D	E	F
1	Country 💌	Salesperson 💌	Order Date 💌	OrderID 💌	Units 💌	Order Amoun
2	USA	Fuller	1/01/2011	10392	13	1,440.00
3	UK	Gloucester	2/01/2011	10397	17	716.72
4	UK	Bromley	2/01/2011	10771	18	344.00
5	USA	Finchley	3/01/2011	10393	16	2,556.95
6	USA	Finchley	3/01/2011	10394	10	442.00
7	UK	Gillingham	3/01/2011	10395	9	2,122.92
8	USA	Finchley	6/01/2011	10396	7	1,903.80
9	USA	Callahan	8/01/2011	10399	17	1,765.60
10	USA	Fuller	8/01/2011	10404	7	1,591.25
11	USA	Fuller	9/01/2011	10398	11	2,505.60
12	USA	Coghill	9/01/2011	10403	18	855.01
13	USA	Finchley	10/01/2011	10401	7	3,868.60
14	USA	Callahan	10/01/2011	10402	11	2,713.50
15	UK	Rayleigh	13/01/2011	10406	15	1,830.78
16	USA	Callahan	14/01/2011	10408	10	1,622.40
17	USA	Farnham	14/01/2011	10409	19	319.20
18	USA	Farnham	15/01/2011	10410	16	802.00

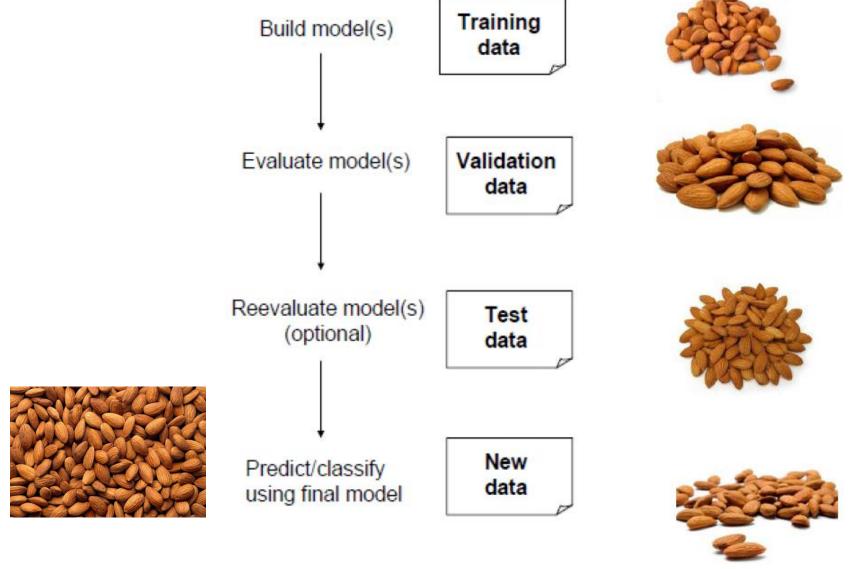


Supervised Learning





Data Stratification





Decision Trees







	Income	Lot_Size	Ownership
1	60	18.4	owner
2	85.5	16.8	owner
3	64.8	21.6	owner
4	61.5	20.8	owner
5	87	23.6	owner
6	110.1	19.2	owner
7	108	17.6	owner
8	82.8	22.4	owner
9	69	20	owner
10	93	20.8	owner
11	51	22	owner
12	81	20	owner
13	75	19.6	non-owner
14	52.8	20.8	non-owner
15	64.8	17.2	non-owner
16	43.2	20.4	non-owner
17	84	17.6	non-owner
18	49.2	17.6	non-owner
19	59.4	16	non-owner
20	66	18.4	non-owner
21	47.4	16.4	non-owner
22	33	18.8	non-owner
23	51	14	non-owner
24	63	14.8	non-owner

Splitting on Continuous Variables

- Order records according to one variable, say lot size
- Split at the first value
- Measure the dissimilarity between the two subsets
- Split at the next value, and continue
- Repeat for the other variable(s)
- For all variables, the split value that drives the greatest dissimilarity in propensities (or probabilities) is selected as the split point

Splitting on Categorical Variables

- Examine all possible ways in which the categories can be split.
- E.g., nominal categories A, B, C can be split 3 ways

```
{A} and {B, C}{B} and {A, C}{C} and {A, B}
```

With many categories, # of potential splits becomes huge

Splitting on Categorical Variables

- For ordinal data (ordered categories) there is an option for the splits to respect ordering
- Example: An ordinal predictor takes on the values 1, 2, 3, or 4
- The data can be split 3 ways:

```
{1} and {2, 3, 4}
{1, 2} and {3, 4}
{1, 2, 3} and {4}
```

Gini Index

Gini Index for rectangle A containing m records

$$I(A) = 1 - \sum_{k=1}^{m} p_k^2$$

p = proportion of cases in rectangle A that belong to class k

- I(A) = 0 when all cases belong to same class
- Max value when all classes are equally represented (= 0.50 in binary case)

Entropy

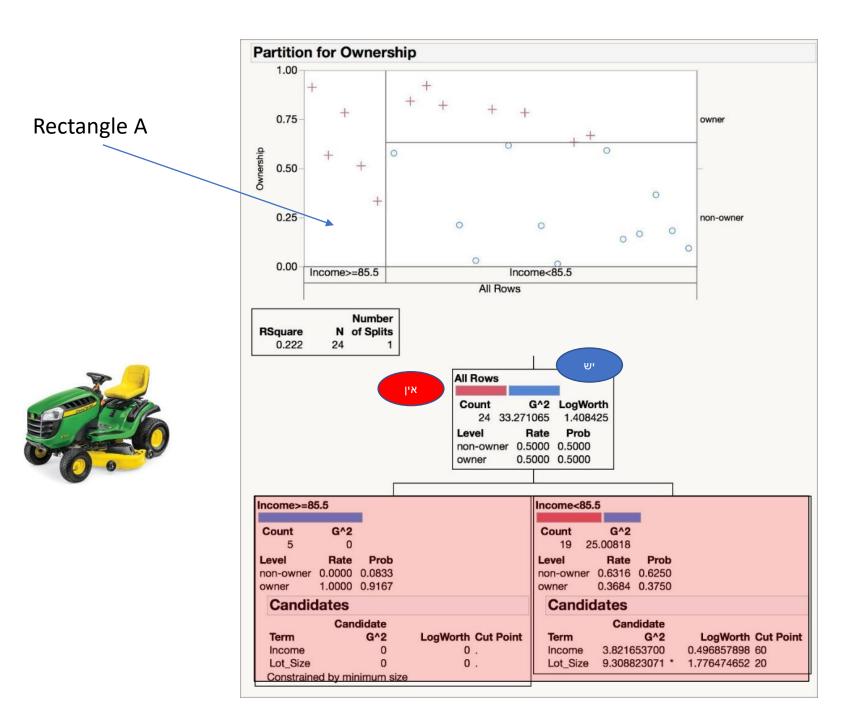
p = proportion of cases (out of m) in rectangle A that belong to class k

entropy
$$(A) = -\sum_{k=1}^{m} p_k \log_2(p_k)$$

• Entropy ranges between 0 (most pure) and $log_2(m)$ (equal representation of classes)

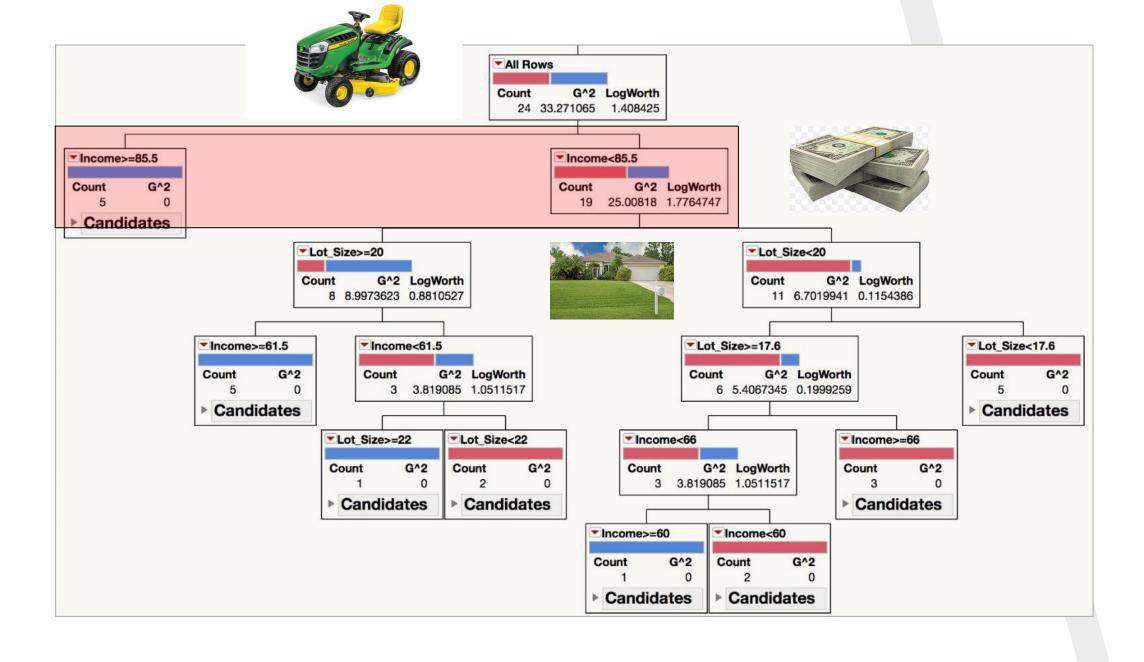
Impurity and Recursive Partitioning

- Obtain overall impurity measure (weighted avg. of individual rectangles)
- At each successive stage, compare this measure across all possible splits in all variables
- Choose the split that reduces impurity the most
- Chosen split points become nodes on the tree



Gini and Entropy measures are not available in JMP. JMP uses measures of dissimilarity (G² and Sum of Squares) rather than measures of impurity





▼ Leaf Report

Response Prob

Leaf Label	non-owner .2 .4 .6 .8	owner
Income>=85.5	0.0833	0.9167
Income<85.5&Lot_Size>=20&Income>=61.5	0.0815	0.9185
Income<85.5&Lot_Size>=20&Income<61.5&Lot_Size>=22	0.2512	0.7488
Income<85.5&Lot_Size>=20&Income<61.5&Lot_Size<22	0.8342	0.1658
Income<85.5&Lot_Size<20&Lot_Size>=17.6&Income<66&Income>=60	0.2901	0.7099
Income<85.5&Lot_Size<20&Lot_Size>=17.6&Income<66&Income<60	0.8601	0.1399
Income<85.5&Lot_Size<20&Lot_Size>=17.6&Income>=66	0.8933	0.1067
Income<85.5&Lot_Size<20&Lot_Size<17.6	0.9248	0.0752



Tree Structure

- Split points become nodes on the tree
- Leaves are the terminal nodes (there are no further splits)
- Read down tree to derive the decision rule

E.g., Income < 85.5, Lot Size is >= 20, and Income >=61.5, the probability that a household is an owner is 0.9185.

- Records within each node are from the training data (validation data are not used in building the tree)
- Default cutoff = 0.5 is used for classification

In the previous example, the record would be classified as an owner.

The Riding Mowers

The leaf report provides a summary the splits

It displays the rules for classifying outcomes

For example, If Income < 85.5, Lot Size is < 17.6, the probability that a household is an owner is 0.0752. This record will be classified as a non-owner.

Leaf Report		
Response Prob		
Leaf Label	non-owner .2 .4 .6 .8	owner
Income>=85.5	0.0833	0.9167
Income<85.5&Lot_Size>=20&Income>=61.5	0.0815	0.9185
Income<85.5&Lot_Size>=20&Income<61.5&Lot_Size>=22	0.2512	0.7488
Income<85.5&Lot_Size>=20&Income<61.5&Lot_Size<22	0.8342	0.1658
Income<85.5&Lot_Size<20&Lot_Size>=17.6&Income<66&Income>=60	0.2901	0.7099
Income<85.5&Lot_Size<20&Lot_Size>=17.6&Income<66&Income<60	0.8601	0.1399
Income<85.5&Lot_Size<20&Lot_Size>=17.6&Income>=66	0.8933	0.1067
Income<85.5&Lot_Size<20&Lot_Size<17.6	0.9248	0.0752

$$Prob_{i} = \frac{n_{i} + prior_{i}}{\sum (n_{i} + prior_{i})}$$

where the summation is across all response levels; n_i is the number of observations at the node for the i^{th} response level; and prior_i is the prior probability for the i^{th} response level, calculated as follows:

$$prior_i = \lambda p_i + (1-\lambda)P_i$$

where p_i is the prior_i from the parent node, P_i is the Prob_i from the parent node, and λ is a weighting factor currently set at 0.9.

Leaf Report		
Response Prob		
Leaf Label	non-owner .2 .4 .6 .8	owner
Income>=85.5	0.0833	0.9167
Income<85.5&Lot_Size>=20&Income>=61.5	0.0815	0.9185
Income<85.5&Lot_Size>=20&Income<61.5&Lot_Size>=22	0.2512	0.7488
Income<85.5&Lot_Size>=20&Income<61.5&Lot_Size<22	0.8342	0.1658
Income<85.5&Lot_Size<20&Lot_Size>=17.6&Income<66&Income>=60	0.2901	0.7099
Income<85.5&Lot_Size<20&Lot_Size>=17.6&Income<66&Income<60	0.8601	0.1399
Income<85.5&Lot_Size<20&Lot_Size>=17.6&Income>=66	0.8933	0.1067
Income<85.5&Lot_Size<20&Lot_Size<17.6	0.9248	0.0752

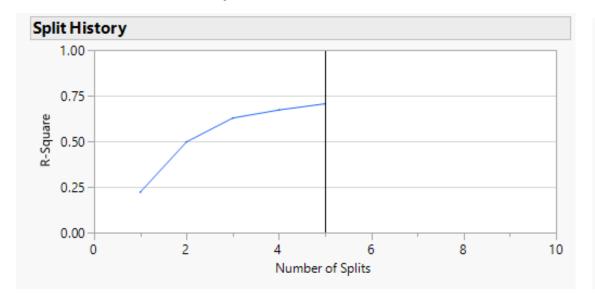
Stopping Tree Growth

Natural end of process is 100% purity in each leaf

This overfits the data, which end up fitting noise in the data

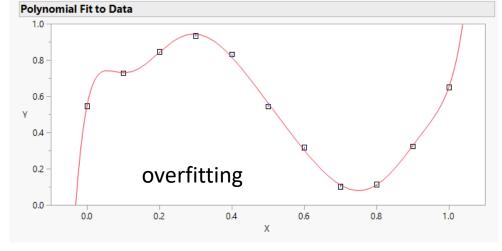
Overfitting leads to low predictive accuracy of new data

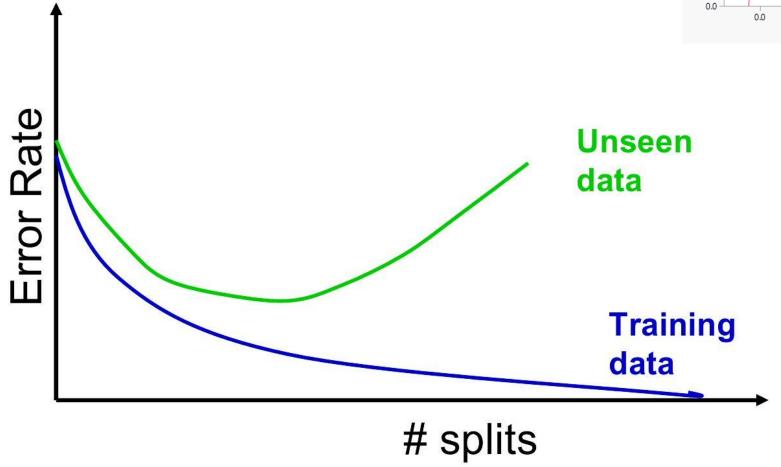
Past a certain point, the error rate for the validation data starts to increase



Measure	Trainir	g Defini	Definition		
Entropy RSquare	0.70	50 1-Logl	1-Loglike(model)/Loglike(0)		
Generalized RSqu	are 0.832	23 (1-(L(0	(1-(L(0)/L(model))^(2/n))/(1-L(0)^(2/n))		
Mean -Log p	0.20	38 ∑-Log	Σ -Log(ρ[j])/n		
RASE	0.23	33 √ ∑(y[j]	$\sqrt{\sum(y[i]-\rho[i])^2/n}$		
Mean Abs Dev	0.16	20 ∑ [y[j]-	Σ[y[j]-ρ[j]]/n		
Misclassification	Rate 0.08	33 ∑(ρ[j];	έρMax)/n		
N	24	n			
Confusion N	latrix				
	Training		_		
Actual	Predicted	Count			
Ownership	non-owner	owner			
non-owner	12	0			
owner	2	10			

Full Tree Error Rate





CART - Classification and regression trees

- CART lets tree grow to full extent, then prunes it back
- Idea is to find that point at which the validation error begins to rise
- Generate successively smaller trees by pruning leaves
- At each pruning stage, multiple trees are possible
- Use cost complexity to choose the best tree at that stage

Cost Complexity

$$CC(T) = Err(T) + \alpha L(T)$$

CC(T) = cost complexity of a tree Err(T) = proportion of misclassified records L(T) – size of tree α = penalty factor attached to tree size (set by user)

Among trees of given size, choose the one with lowest CC Do this for each size of tree

CART - Classification and regression trees

- Nonparametric (no probabilistic assumptions)
- Automatically performs variable selection
- Uses any combination of continuous/discrete variables
 - Very nice feature: ability to automatically bin massively categorical variables into a few categories (zip code, business class, make/model...)
- Invariant to monotonic transformations of predictive variable
- Unlike regression, not sensitive to outliers in predictive variables

CART Overview

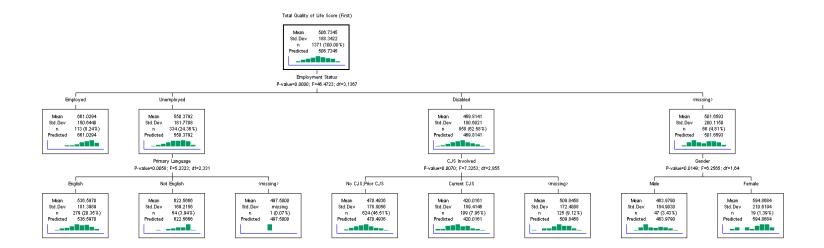
- Classification and Regression Trees are an easily understandable and transparent method for predicting or classifying new records
- A tree is a graphical representation of a set of rules
- Trees must be pruned to avoid over-fitting of the training data
- As trees do not make any assumptions about the data structure, they usually require large samples

CHAID - Chi-squared automatic interaction detector

- CHAID, older than CART, uses chi-square statistical test to limit tree growth
- Splitting stops when purity improvement is not statistically significant

CHAID - Chi-squared automatic interaction detector

- CHAID is a non-binary decision tree.
- The decision or split made at each node is still based on a single variable, but can result in multiple branches.
- The split search algorithm is designed for categorical variables.



Classification Trees: CART versus CHAID

- At each split, the CHAID algorithm looks for the predictor variable that if split, most "explains" the category response variable. In order to decide whether to create a particular split based on this variable, the CHAID algorithm tests a hypothesis regarding dependence between the split variable and the categorical response (using the chi-squared test for independence). Using a prespecified significance level, if the test shows that the split variable and the response are independent, the algorithm stops the tree growth. Otherwise, the split is created, and the next best split is searched. In contrast, the CART algorithm decides on a split based on the amount of homogeneity within class that is achieved by the split. The split is reconsidered based on considerations of over-fitting.
- CHAID is most useful for analysis, whereas CART is more suitable for prediction. In other words, CHAID should be used when the goal is to describe or understand the relationship between a response variable and a set of explanatory variables, whereas CART is better suited for creating a model that has high prediction accuracy of new cases.

Limiting Tree Size

JMP uses a combination of limiting tree growth and pruning the tree after it has grown

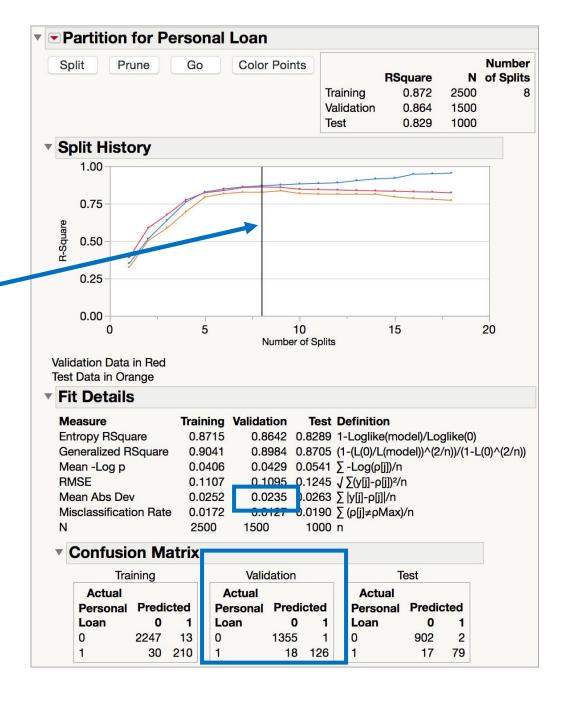
- Minimum Split Size: Controls the minimum number of records in terminal nodes
- Validation: The tree is grown, and pruned back to maximize the RSquare on the validation data

When validation is used, the "Go" option automates tree growth and pruning

The tree with the maximum Validation Rsquare has 8 splits

The tree is grown to 18 splits, and is pruned back to 8 splits

Validation error rate and confusion matrix for the final tree (cutoff for classification = 0.50)



Validation

Generalized RSquare A measure that can be applied to general regression models. It is based on the likelihood function L and is scaled to have a maximum value of 1. The value is 1 for a perfect model, and 0 for a model no better than a constant model. The Generalized RSquare measure simplifies to the traditional RSquare for continuous normal responses in the standard least squares setting. Generalized RSquare is also known as the Nagelkerke or Craig and Uhler R^2 , which is a normalized version of Cox and Snell's pseudo R^2 . See Nagelkerke (1991).

Entropy RSquare (Appears only when the response is nominal or ordinal.) A measure of fit that compares the log-likelihoods from the fitted model and the constant probability model. Entropy RSquare ranges from 0 to 1, where values closer to 1 indicate a better fit. See "Entropy RSquare" on page 501 in the "Statistical Details" chapter.

RSquare Gives the RSquare for the model.

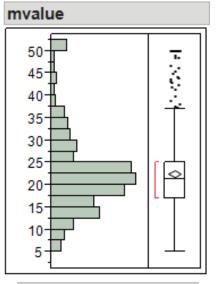
Validation

- **RMSE** Gives the root mean square error. When the response is nominal or ordinal, the differences are between 1 and p (the fitted probability for the response level that actually occurred).
- **Mean Abs Dev** The average of the absolute values of the differences between the response and the predicted response. When the response is nominal or ordinal, the differences are between 1 and p (the fitted probability for the response level that actually occurred).
- **Misclassification Rate** The rate for which the response category with the highest fitted probability is not the observed category. Appears only when the response is nominal or ordinal.
- **-LogLikelihood** Gives the negative of the log-likelihood. See Fitting Linear Models.
- **SSE** Gives the error sums of squares. Available only when the response is continuous.
- **Sum Freq** Gives the number of observations that are used. If you specified a Freq variable in the Neural launch window, Sum Freq gives the sum of the frequency column.
- If there are multiple responses, fit statistics are given for each response, and an overall Generalized RSquare and negative Log-Likelihood is given.

Regression Trees for Prediction

- Used with continuous outcome variable
- Procedure like classification tree
- Many splits attempted, choose the one that maximizes the difference between subgroup means
- Difference measured as the sum of squared deviations
- Prediction is the average of the numerical target variable (rather than a probability)

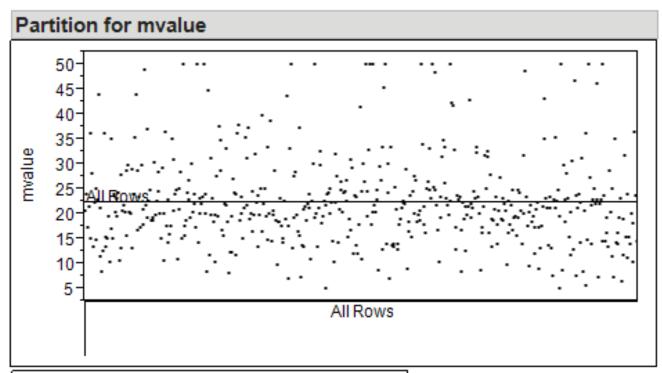
Regression Trees



Quantiles						
100.0%	maximum	50				
99.5%		50				
97.5%		50				
90.0%		34.9				
75.0%	quartile	25				
50.0%	median	21.2				
25.0%	quartile	16.95				
10.0%		12.7				
2.5%		8.235				
0.5%		5.321				
0.0%	minimum	5				

Summary Statistics

Mean 22.532806 Std Dev 9.1971041 Std Err Mean 0.4088611 Upper 95% Mean 23.336085 Lower 95% Mean 21.729528 N 506

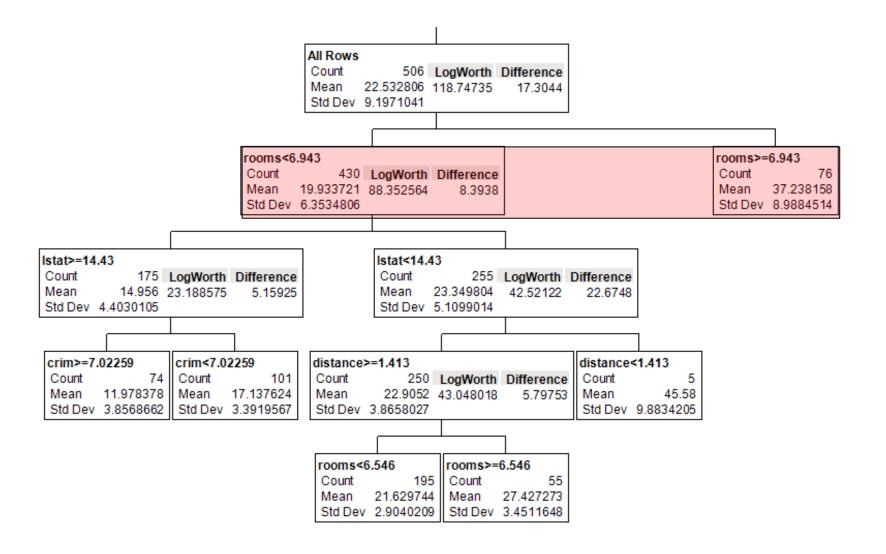


			Number	
RSquare	RMSE	N	of Splits	AICc
0.000		506	0	0

All Rows
Count 506
Mean 22.532806
Std Dev 9.1971041



Regression Trees



Boston Housing Data

All Rows

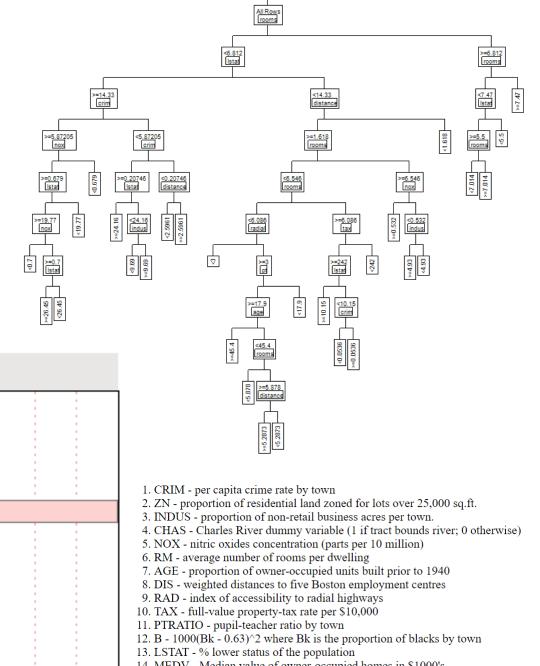
Count 506 Mean 22.532806 Std Dev 9.1971041

Candid	Candidates							
Term	Candidate SS	LogWorth						
crim	8266.17273	32.6638216						
zn	6669.06251	24.9773486						
indus	11083.22547	48.7519537						
chas	1312.07927	4.1110954						
nox	9536.22405	39.5670978						
rooms	19339.55503 *	118.7473483						
age	5573.64765	19.6751451						
distance	4994.54054	17.1453361						
radial	6708.64333	24.6205659						
tax	8618.08428	34.5266980						
pt	10438.69478	44.8775094						
b	5259.31980	18.2910466						
Istat	18896.19401	113.7427626						

	All Itoms					
	Count			Difference		
	Mean 22.53	2806 118.	74735	17.3044		
	Std Dev 9.197	1041				
rooms<6.943		ro	oms>=6.9	943		
Count 430		C	ount	76		
Mean 19.933721		M	ean 3	7.238158		
Std Dev 6.3534806		St	d Dev 8	.9884514		
Candidates			Candid	lates		
Term Candidat	e SS LogV	Vorth	Term	Candidate	SS	LogWorth
crim 4300.96	7311 38.575	28016	crim	1296.353	462	4.24150833
zn 1961.91	2781 13.9394	18488	zn	154.894	267	0.16015922
indus 3552.75	6728 29.655	39469	indus	650.180	018	1.45829879
chas 533.16	5511 3.568	06955	chas	97.802	924	0.53155728
nox 4806.34	4267 45.2293	39006	nox	510.976	6998	0.97911866
rooms 2498.67	6569 18.6895	59899	rooms	3060.957	7502 *	19.65116632
age 3618.34	1104 30.3939	95326	age	106.820	174	0.05293436
distance 3526.24	8005 29.354	82815	distance	210.835	5800	0.20608146
radial 2778.26	4622 21.2984	49865	radial	1296.353	462	4.68218182
tax 3487.17	4824 28.925	48472	tax	1296.353	462	4.30278667
pt 3808.64	7013 32.662	54455	pt	1514.119	195	5.52903675
b 2454.65	5577 18.2683	37433	b	750.759	9998	1.79989185
Istat 7311.85	2356 * 88.352	56425	Istat	2011.069	9265	8.73682304
Ч						
	•					

-log₁₀(*p*-value)

All Rows



Term	of Splits	SS	
crim	3	924.046	
zn	0	0.000	
indus	2	86.329	
chas	0	0.000	
nox	3	265.824	
rooms	6	12285.998	
age	1	50.482	
distance	3	642.560	
radial	1	39.724	
tax	1	68.077	
pt	1	40.686	
b	0	0.000	
Istat	6	4131.903	

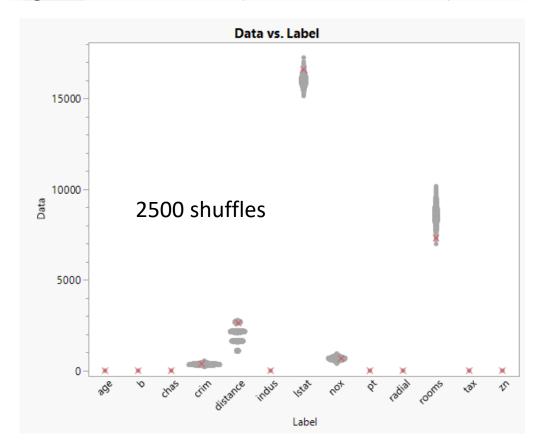
Number

14. MEDV - Median value of owner-occupied homes in \$1000's

Actual by Predicted Plot Training Set 50 **Leaf Report** Leaf Label Mean Count 40 lstat>=9.97&lstat>=16.14&nox>=0.609&crim>=9.91655 9.68666667 30 40 Istat>=9.97&Istat>=16.14&nox>=0.609&crim<9.91655 14.41 |stat>=9.97&|stat>=16.14&nox<0.609 17.5947368 38 lstat>=9.97&lstat<16.14 20.2123894 113 63 lstat<9.97&rooms<7.454&distance>=1.6132&rooms<6.8&rooms<6.546 23.1253968 Actual 30 27 42 5 lstat<9.97&rooms<7.454&distance>=1.6132&rooms<6.8&rooms>=6.546 26.7185185 lstat<9.97&rooms<7.454&distance>=1.6132&rooms>=6.8 32.002381 Istat<9.97&rooms<7.454&distance<1.6132 50 22 44.2954545 Istat<9.97&rooms>=7.454 20 10 20 30 50 Predicted Validation Set 50 Validation Frequencies 40 Prob Level Count 380 0.75099 Training Validation 126 0.24901 Total 506 1.00000 N Missing Actual 2 Levels Validation Training 20 Adjusted Rates Row Counts Training Set 0.75 0.75099 380 Validation Set 0.24901 126 10 Test Set Excluded Rows **Total Rows** 506 20 30 40 50 **△** Options Predicted New Column Name Validation Validation Column Type Formula

■ Column Contributions

Term	Number of Splits	SS	Portion
Istat	2	16598.194	0.6019
rooms	3	7310.3095	0.2651
distance	1	2618.78505	0.0950
nox	1	668.298301	0.0242
crim	1	382.455048	0.0139
zn	0	0	0.0000
indus	0	0	0.0000
chas	0	0	0.0000
age	0	0	0.0000



Advantages of Trees

- Easy to use, understand
- Produce rules that are easy to interpret & implement
- Variable selection & reduction is automatic
- Do not require the assumptions of statistical models
- Can work without extensive handling of missing data (this is an option in the Partition dialog in JMP)

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Disadvantages of Trees

- May not perform well where there is structure in the data that is not well captured by horizontal or vertical splits
- Since the process deals with one variable at a time, no way to capture interactions between variables

Improving Trees

- Single trees may not have good predictive ability.
- Results from multiple trees can be combined to improve performance
- The resulting model is an "ensemble" model
- Two multi-tree approaches in JMP Pro:
 - Bootstrap Forests (a variant of Random Forests)
 - Boosted Trees

Ensemble Tree Methods

Bootstrap Forests (Random Forrest)

Grow many trees to bootstrapped versions of the training data and average them

Boosted Trees (Boosting)

Repeatedly grow shallow trees to the residuals and build up an additive model consisting of a sum of trees

Ensemble Tree Methods

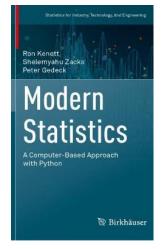
Bootstrap Forests

- A random sample is drawn with replacement from the data set (bootstrapping)
- 2. Predictors are randomly drawn from the candidate list of predictors
- 3. A small tree is fit (a "weak learner")
- 4. The process is repeated
- 5. The final model is the average of all of the trees, producing a "Bootstrap aggregated" (or "bagged) model

Ensemble Tree Methods

Boosted Trees

- 1. A simple (small) tree is fit to the data with a random sample of the predictors
- The scaled residuals from this tree are calculated
- A new simple tree is fit to these scaled residuals with another random sample of predictors
- 4. This process continues
- 5. The final boosted model is the sum of the models for the individual trees



Chapter 7 Modern Analytic Methods: Part I



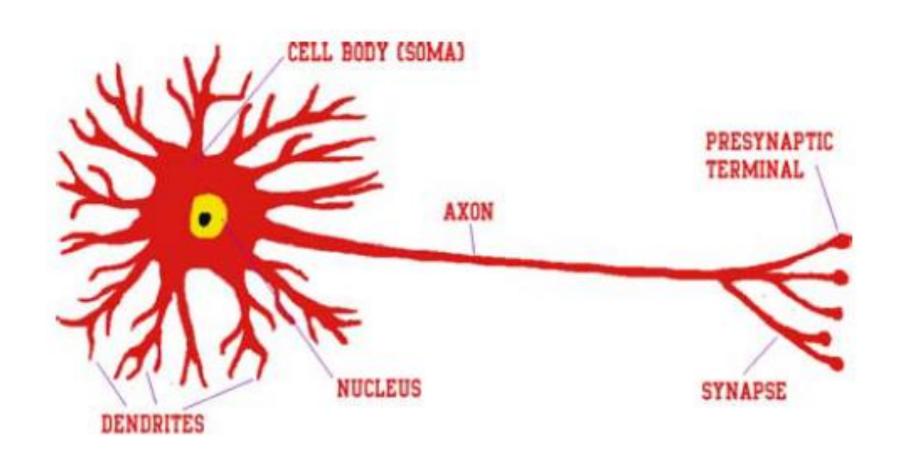
7.8 Neural Networks

A neural network is composed of a set of computational units, called neurons, connected together through weighted connections. Neurons are organized in layers so that every neuron in a layer is exclusively connected to the neurons of the preceding layer and the subsequent layer. Every neuron, also called a node, represents an autonomous computational unit and receives inputs as a series of signals that dictate its activation. Following activation, every neuron produces an output signal. All the input signals reach the neuron simultaneously, so the neuron receives more than one input signal, but it produces only one output signal. Every input signal is associated with a connection weight. The weight determines the relative importance the input signal can have in producing the final impulse transmitted by

Neural networks: Basic Idea

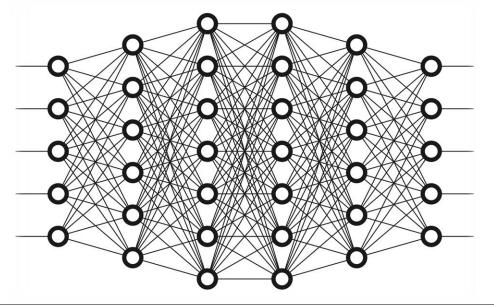
- Combine input information in a complex and flexible neural net "model"
- Model "coefficients" are continually tweaked in an iterative process
- The network's interim performance in classification and prediction informs successive tweaks

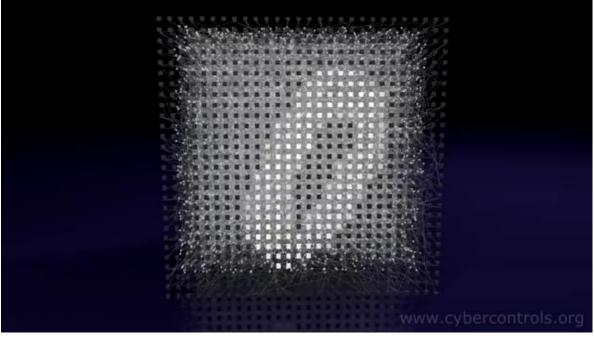
Neural Networks

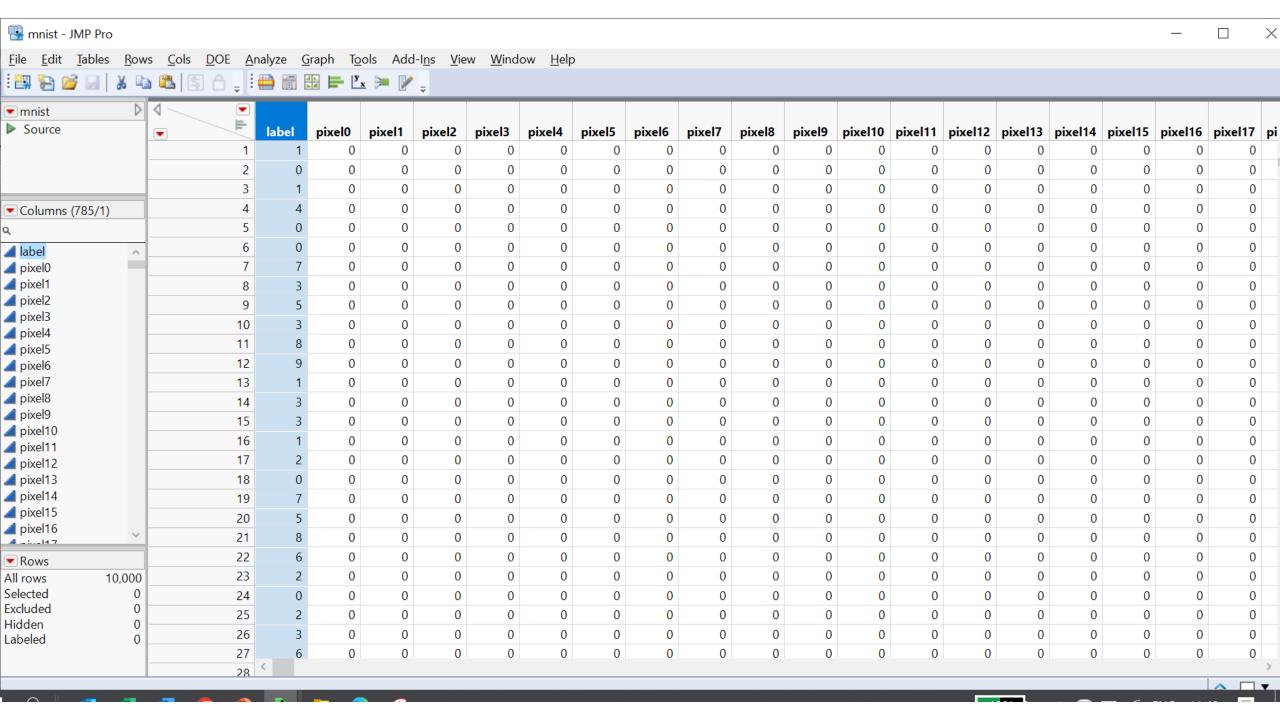


MNIST

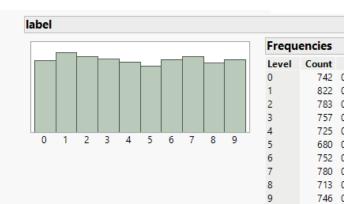
Modified National Institute of Standards and Technology







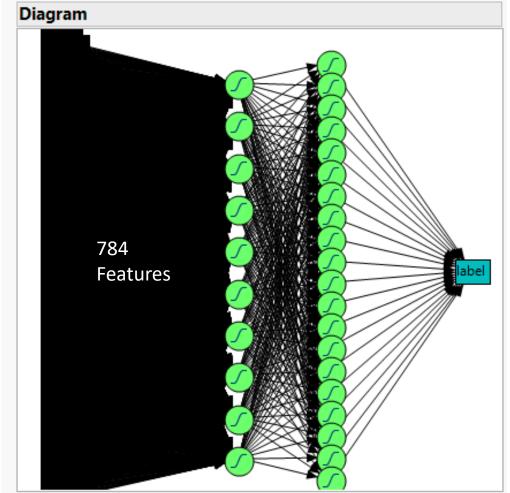
Measures	Value
Generalized RSquare	0.9800862
Entropy RSquare	0.7637519
RASE	0.3642818
Mean Abs Dev	0.1918127
Misclassification Rate	0.146
-LogLikelihood	1359.2096
Sum Freq	2500



Frequ	Frequencies							
Level	Count	Prob						
0	742	0.09893						
1	822	0.10960						
2	783	0.10440						
3	757	0.10093						
4	725	0.09667						
5	680	0.09067						
6	752	0.10027						
7	780	0.10400						
8	713	0.09507						
9	746	0.09947						
Total	7500	1.00000						
N Missi	ng	0						
10	Levels							

Confusion Ma.....

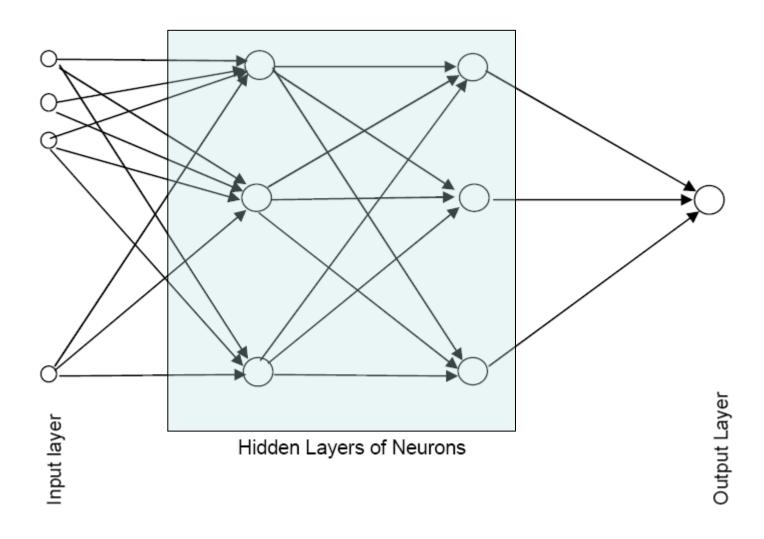
Actual		Predicted Count								
label	0	1	2	3	4	5	6	7	8	9
0	222	0	1	6	1	7	4	1	7	0
1	0	259	2	3	0	1	4	0	3	1
2	5	5	227	5	4	0	1	5	9	1
3	2	1	7	213	0	10	0	4	11	4
4	3	0	6	1	197	1	3	5	0	26
5	6	2	5	18	2	172	3	4	13	1
6	5	0	8	0	2	5	230	0	1	0
7	0	3	6	6	4	2	0	227	1	10
8	2	6	9	12	1	10	3	3	188	3
9	2	1	1	4	17	4	0	17	3	200



Network Structure

- Multiple layers
 - Input layer (raw observations)
 - Hidden layers
 - Output layer
- Nodes
- Weights (like coefficients, subject to iterative adjustment)
- Bias values (also like coefficients, but not subject to iterative adjustment)

Schematic Diagram





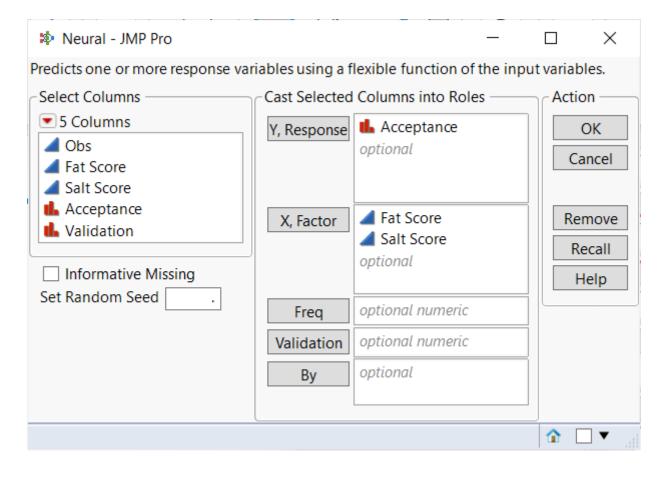


Using fat and salt content to predict consumer acceptance of cheese

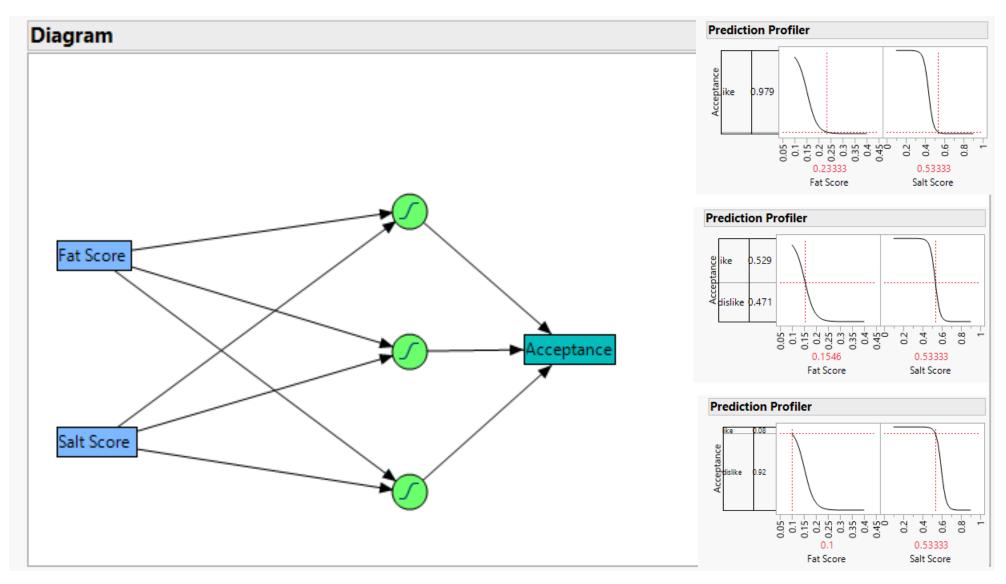
	Obs	Fat Score	Salt Score	Acceptance
1	1	0.2	0.9	like
2	2	0.1	0.1	dislike
3	3	0.2	0.4	dislike
4	4	0.2	0.5	like
5	5	0.4	0.5	like
6	6	0.3	0.8	like

Shmueli, G., Bruce, P., Stephens, M. and Patel, N. (2016) Data Mining for Business Analytics: Concepts, Techniques, and Applications with JMP Pro, Wiley, USA https://www.wiley.com/en-

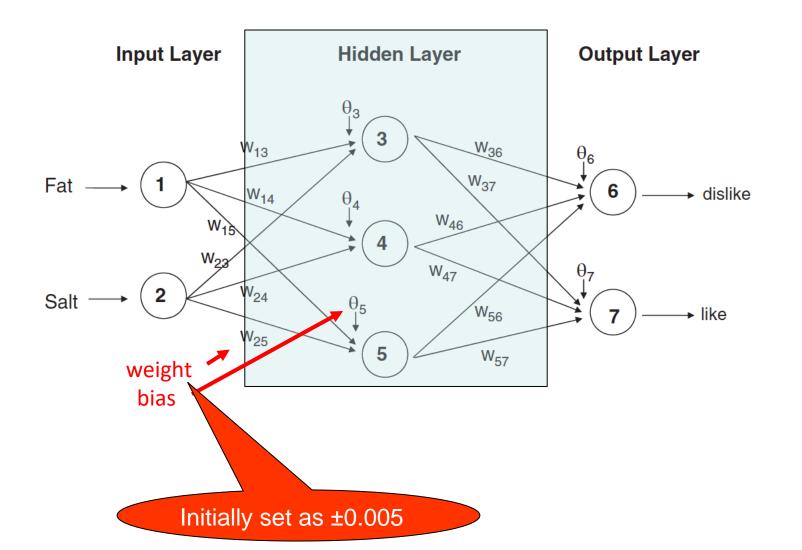
Tiny Example Neural Network



Tiny Example Neural Network



Tiny Example Neural Network



The Input Layer

For input layer, input = output

E.g., for record #1:

Fat input = output = 0.2

Salt input = output = 0.9

Output of input layer = input into hidden layer

The Hidden Layer

In this example, hidden layer has 3 nodes

Each node receives as input the output of all input nodes

Output of each hidden node is a function of the weighted sum of inputs

$$output_{j} = g(\Theta_{j} + \sum_{i=1}^{p} w_{ij} x_{i})$$

(The hidden layer function is also called an "activation function".)

The Hidden Layer

TanH The hyperbolic tangent function is a sigmoid function. TanH transforms values to be between -1 and 1, and is the centered and scaled version of the logistic function. The hyperbolic tangent function is:

$$\frac{e^{2x}-1}{e^{2x}+1}$$

where x is a linear combination of the X variables.

Linear The identity function. The linear combination of the X variables is not transformed.

The Linear activation function is most often used in conjunction with one of the non-linear activation functions. In this case, the Linear activation function is placed in the second layer, and the non-linear activation functions are placed in the first layer. This is useful if you want to first reduce the dimensionality of the X variables, and then have a nonlinear model for the Y variables.

For a continuous Y variable, if only Linear activation functions are used, the model for the Y variable reduces to a linear combination of the X variables. For a nominal or ordinal Y variable, the model reduces to a logistic regression.

The Hidden Layer

Gaussian The Gaussian function. Use this option for radial basis function behavior, or when the response surface is Gaussian (normal) in shape. The Gaussian function is:

$$e^{-\chi^2}$$

where x is a linear combination of the X variables.

Use the Boosting panel in the Model Launch control panel to specify the number of component models and the learning rate. Use the Hidden Layer Structure panel in the Model Launch control panel to specify the structure of the base model.

The learning rate must be $0 < r \le 1$. Learning rates close to 1 result in faster convergence on a final model, but also have a higher tendency to overfit data. Use learning rates close to 1 when a small Number of Models is specified.

Options

Method	Penalty Function	Description
Squared	$\sum \beta_i^2$	Use this method if you think that most of your X variables are contributing to the predictive ability of the model.
Absolute	$\sum \left eta_i \right $	Use either of these methods if you have a large number of X variables, and you think that a few of them contribute more than others to the predictive
Weight Decay	$\sum \frac{\beta_i^2}{1+\beta_i^2}$	ability of the model.
NoPenalty	none	Does not use a penalty. You can use this option if you have a large amount of data and you want the fitting process to go quickly. However, this option can lead to models with lower predictive performance than models that use a penalty.

The Weights

The weights θ (theta) and w are typically initialized to random values in the range -0.05 to +0.05

>JMP uses random normal starting weights

Equivalent to a model with random prediction (in other words, no predictive value)

These initial weights are used in the first round of training

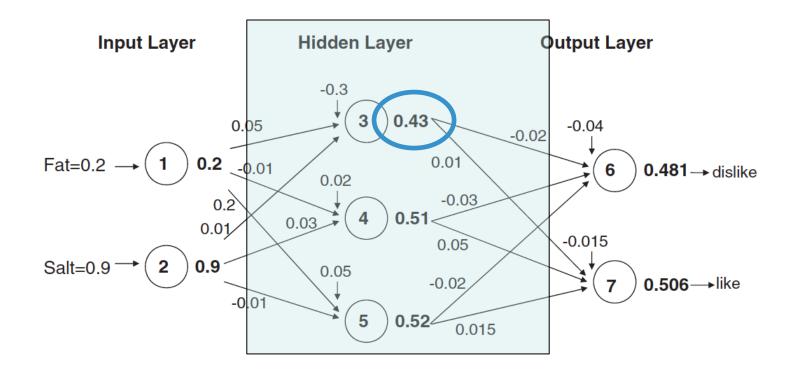
Output of Node 3, if g is a Logistic Function

$$output_{j} = g(\Theta_{j} + \sum_{i=1}^{r} w_{ij} x_{i})$$

Output_j =
$$g\left(\theta_j + \sum_{i=1}^p w_{ij} x_i\right) = \frac{1}{1 + e^{-(\theta_j + \sum_{i=1}^p w_{ij} x_i)}}.$$

$$output_3 = \frac{1}{1 + e^{-[-0.3 + (0.05)(0.2) + (0.01)(0.9)]}} = 0.43$$

Tiny Example Neural Weights



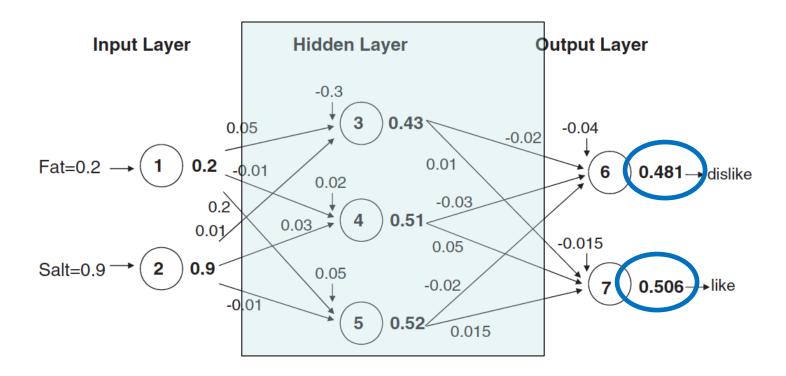
Shmueli, G., Bruce, P., Stephens, M. and Patel, N. (2016) Data Mining for Business Analytics: Concepts, Techniques, and Applications with JMP Pro, Wiley, USA https://www.wiley.com/en-

Output Layer

The output of the last hidden layer becomes input for the output layer Uses same function as above, i.e. a function g of the weighted average

$$\begin{aligned} \text{Output}_6 &= \frac{1}{1 + e^{-[-0.04 + (-0.02)(0.43) + (-0.03)(0.51) + (0.015)(0.52)]}} = 0.481 \\ \text{Output}_7 &= \frac{1}{1 + e^{-[-0.015 + (0.01)(0.430) + (0.05)(0.507) + (0.015)(0.511)]}} = 0.506 \end{aligned}$$

Tiny Example Output Layer



Mapping the output to a classification

These values are normalized so they are propensities (which add up to 1.0).

$$P(Y = Dislike) = Output_6/(Output_6 + Output_7)$$

= 0.481/(0.481 + 0.506) = 0.49
 $P(Y = Like) = 1 - P(Y = Dislike)$
= 0.506/(0.481 + 0.506) = 0.51

The default cutoff for classification is 0.5.

This first record would be classified as a Like.

Relation to Linear Regression

A net with a single output node and no hidden layers, where g is the identity function, takes the same form as a linear regression model

$$\hat{y} = \Theta + \sum_{i=1}^{p} w_i x_i$$

Initial Pass-Through Network

Goal: Find weights that yield best predictions

- The process we described above is repeated for all records
- At each record, compare prediction to actual
- Difference is the error for the output node
- Error is propagated back and distributed to all the hidden nodes and used to update their weights

Training the Model

Back Propagation of Error

- Output from output node k: \hat{y}_k
- Error associated with that node:

$$err_k = \hat{y}_k (1 - \hat{y}_k)(y_{k-}\hat{y}_k)$$

Note: this is like ordinary error, multiplied by a correction factor

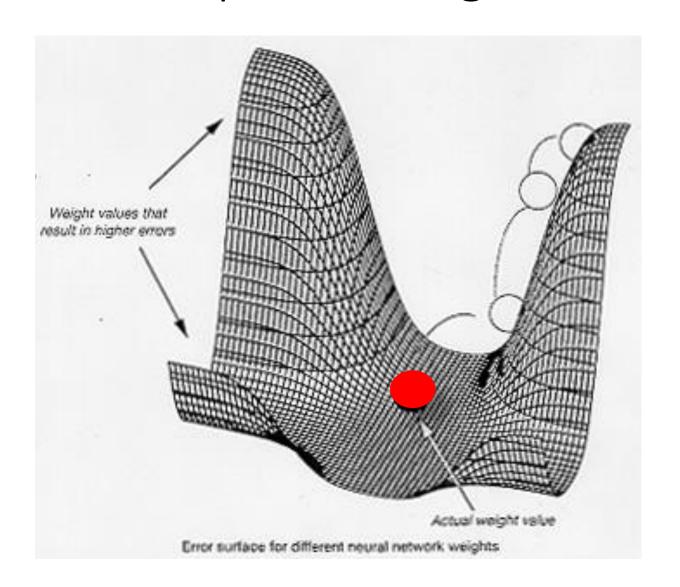
Error is Used to Update Weights

$$\theta_j^{new} = \theta_j^{old} + l(err_j)$$

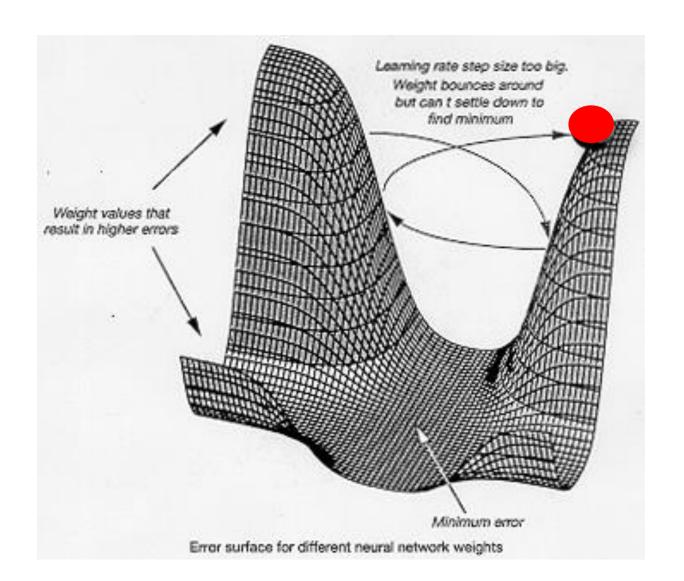
$$\mathbf{w}_{j}^{new} = \mathbf{w}_{j}^{old} + l(err_{j})$$

/ = constant between 0 and 1, reflects the "learning rate" or "weight decay parameter"

Error is Used to Update Weights



Error is Used to Update Weights



Case Updating

Weights are updated after each record is run through the network

• Completion of all records through the network is one *epoch* (also called *sweep* or *iteration*)

 After one epoch is completed, return to first record and repeat the process

Case Updating

In case updating, the weights are updated after each record is run through the network (called a *trial*). For example, if we used case updating in the tiny example, the weights would first be updated after running record 1 as follows: Using a learning rate of 0.5, the weights θ_7 , $w_{3,7}$, $w_{4,7}$, and $w_{5,7}$ are updated to

$$\theta_7 = -0.015 + (0.5)(0.123) = 0.047$$
 $w_{3,7} = 0.01 + (0.5)(0.123) = 0.072$
 $w_{4,7} = 0.05 + (0.5)(0.123) = 0.112$
 $w_{5,7} = 0.015 + (0.5)(0.123) = 0.077$

Similarly, we obtain updated weights $\theta_6 = 0.025$, $w_{3,6} = 0.045$, $w_{4,6} = 0.035$, and $w_{5,6} = 0.045$. These new weights are next updated after the second record is run through the network, the third, and so on, until all records are used. This is called one *epoch*, *sweep*, or *iteration* through the data. Typically, there are many iterations.

Batch Updating

 All records in the training set are fed to the network before updating takes place

 In this case, the error used for updating is the sum of all errors from all records

Batch Updating

In batch updating, the entire training set is run through the network before each updating of weights takes place. In that case, the errors err_k in the updating equation is the sum of the errors from all records. In practice, case updating tends to yield more accurate results than batch updating, but requires a longer run time. This is a serious consideration, since even in batch updating, hundreds or even thousands of sweeps through the training data are executed.

When does the updating stop? The most common conditions are one of the following:

- 1. When the new weights are only incrementally different from those of the preceding iteration
- 2. When the misclassification rate reaches a required threshold
- 3. When the limit on the number of runs is reached

Why It Works

Big errors lead to big changes in weights

Small errors leave weights relatively unchanged

 Over thousands of updates, a given weight keeps changing until the error associated with that weight is negligible, at which point weights change little

Common Criteria to Stop the Updating

When weights change very little from one iteration to the next

When the misclassification rate reaches a required threshold

When a limit on runs is reached

Neural Model fitting in JMP

- JMP uses an algorithm that finds optimal values of weights and bias values that minimize a function of the combined errors (maximum likelihood)
- This approach produces similar results to back propagation, but
 - ➤ Its generally much faster
 - It can be used for both continuous and categorical responses

Neural Model fitting in JMP

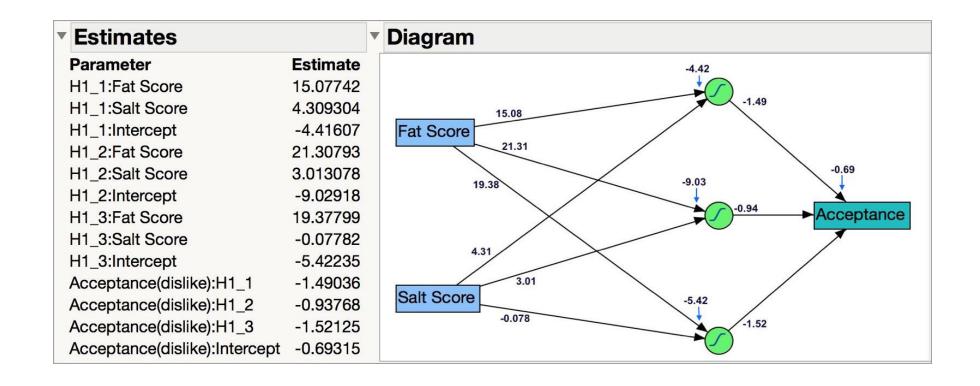
Neural models tend to overfit the data.

To avoid overfitting, JMP uses a **penalty parameter** and requires **crossvalidation**

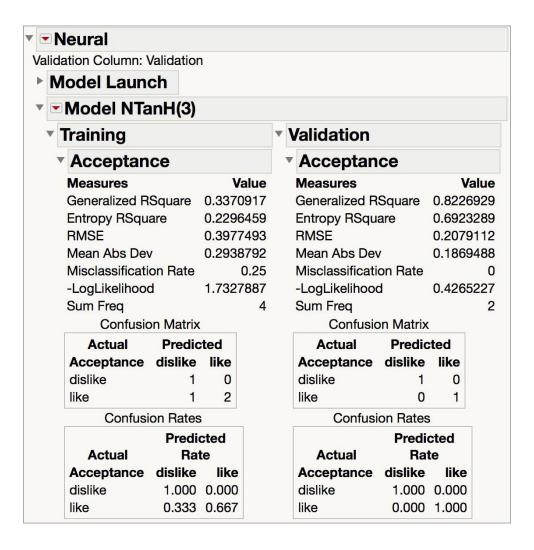
The JMP Neural fitting process:

- 1. Set the penalty to 0
- 2. Use random normal weights for the starting values
- 3. Vary the penalty parameter
- 4. For each value of the penalty parameter, search for weights that minimize error
- 5. Select the model with the lowest crossvalidation error

Tiny Example: Final Weights



Tiny Example: Fit Statistics



Tiny Example: Classifications

Estimated propensities and classifications

- One record in the training set was misclassified
- Both records in the validation set were correctly classified

	Obs	Fat Score	Salt Score	Acceptance	Validation	Probability (Acceptance =dislike)	Probability (Acceptance =like)	H1_1	H1_2	H1_3	Most Likely Acceptance
1	1	0.2	0.9	like	Training	0.447556	0.552444	0.84514	-0.77307	-0.66871	like
2	2	0.1	0.1	dislike	Training	0.949447	0.050553	-0.84508	-0.99728	-0.94094	dislike
3	3	0.2	0.4	dislike	Validation	0.722072	0.277928	0.160176	-0.94482	-0.65781	dislike
4	4	0.2	0.5	like	Training	0.655339	0.344661	0.360128	-0.92614	-0.66001	dislike
5	5	0.4	0.5	like	Training	0.022069	0.977931	0.954915	0.462325	0.816079	like
6	6	0.3	0.8	like	Validation	0.09597	0.90403	0.944404	-0.11269	0.162926	like

Specify Network Architecture in JMP

Number of hidden layers

Most popular – one hidden layer

Number of nodes in hidden layer(s)

More nodes capture complexity, but increase chances of overfit

Hidden Layer Activation Functions

 Combinations of three functions (TanH, Linear and Gaussian) can be applied in the hidden layers to add model complexity

User Inputs

JMP Network Architecture, cont.

Number of tours

How many times JMP restarts the model-fitting algorithm

"Learning Rate"

- Low values "downweight" the new information from errors at each iteration
- This slows learning, but reduces tendency to overfit to local structure

Advantages

Good predictive ability

Can capture complex relationships

No need to specify a model

Disadvantages

- Considered a "black box" prediction machine, with no insight into relationships between predictors and outcome
- No variable-selection mechanism, so you have to exercise care in selecting variables
- Heavy computational requirements if there are many variables

Addressing Disadvantages in JMP

- Considered a "black box" prediction machine, with no insight into relationships between predictors and outcome
 - >JMP Prediction Profiler allows you to explore the model
- No variable-selection mechanism, so you have to exercise care in selecting variables
 - >JMP Variable Importance can help identify most important variables
- Heavy computational requirements if there are many variables
 - ➤ The JMP Neural algorithm is more efficient than back propagation

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A journey in random forests and penalized regression in an industrial classification problem: How to use models to sharpen your questions

Ron S. Kenett¹, Chris Gotwalt² and Jean Michel Poggi³

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- 2 JMP Division, SAS, Research Triangle, NC, USA
- 3 Laboratoire de Mathématiques, Université Paris-Saclay, Orsay, and Université Paris Cité, France

Abstract

The mathematician and population geneticist Sam Karlin considered that "The purpose of models is not to fit the data but to sharpen the question". Motivated by this, we describe here a journey through questions, models and data analysis, to reach specific goals. Specifically, we consider random forests, ridge regression, lasso and elastic nets in a case study of 63 sensors collected in functional testing of an electronic system. The paper lists a sequence of questions and how they were tackled by statistical analysis, sometimes unsuccessfully. Eventually we were able to provide a robust, parsimonious and effective model for predicting the system condition, using a small subset of the 63 sensors. In handling this problem, we combine several innovative methods and insights that can prove useful also in other contexts. The underlying objective is enhancing the awareness to the journey representing the modeling process. We conclude with an assessment of the information quality provided by the analysis.