

# **Deep Learning**

19 Variational Autoencoder

Dr. Konda Reddy Mopuri Dept. of Al, IIT Hyderabad Jan-May 2025

#### **Autoencdoers**



 Designed to reproduce input, especially reproduce the input from a learned encoding

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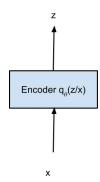
- Designed to reproduce input, especially reproduce the input from a learned encoding
- We attempted to project the data into the latent space and model it via a probability distribution
- This wasn't satisfying



(a) 'Regularized' autoencoder to enforce latent space 'organization'

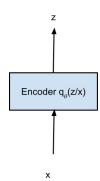


- Wey idea is to make both Encoder and Decoder stochastic
  - instead of encoding an i/p as a single point, we encode it as a distribution over the latent space



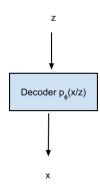


- Wey idea is to make both Encoder and Decoder stochastic
  - instead of encoding an i/p as a single point, we encode it as a distribution over the latent space
- ${\color{red} 2}$  Latent variable z is drawn from a probability distribution for the given input  ${\color{red} x}$





1 Then, the reconstruction is chosen probabilistically from the sampled z





Takes i/p and returns the parameters of a probability density (e.g. Gaussian, mean and covariance matrix)

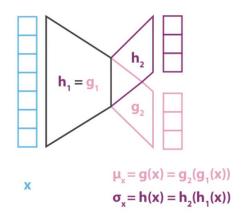


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- Takes i/p and returns the parameters of a probability density (e.g. Gaussian, mean and covariance matrix)
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- 3 NN implementation of the encoder gives (for every input x) a vector mean and a diagonal covariance







Decoder takes the latent vector z and returns the parameters for a distribution

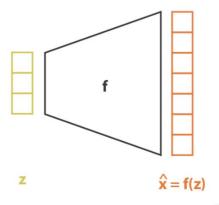


- Decoder takes the latent vector z and returns the parameters for a distribution
- 2  $p_{\phi}(x/z)$  gives mean and variance for each pixel in the output



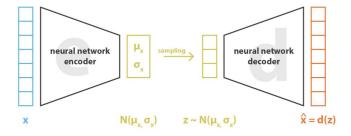
- Decoder takes the latent vector z and returns the parameters for a distribution
- ②  $p_{\phi}(x/z)$  gives mean and variance for each pixel in the output
- Reconstruction of x is via sampling





# **VAE** Forward pass







 ${\color{blue} \blacksquare}$  Loss for AE:  $l_2$  distance between the input and its reconstruction



- f Q Loss for AE:  $l_2$  distance between the input and its reconstruction
- ② In case of VAE: we need to learn parameters of two probability distributions



- ① Loss for AE:  $l_2$  distance between the input and its reconstruction
- In case of VAE: we need to learn parameters of two probability distributions
- 3 For each input  $x_i$  we maximize expected value of returning  $x_i$  (or, minimize the NLL)

$$-\mathbb{E}_{z \sim q_{\theta}(z/x_i)}[\log p_{\phi}(x_i/z)]$$



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Problem: Input images may be memorized in the latent space



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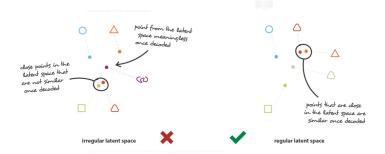
- Problem: Input images may be memorized in the latent space
  - $\, \bullet \, \to \mathsf{similar}$  inputs may get different representations in z space



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- Problem: Input images may be memorized in the latent space
  - $\,\bullet\,\,\to\,$  similar inputs may get different representations in z space
  - $\, \bullet \,$  close points in the latent space should not give two completely different contents once decoded







$$-\mathbb{E}_{z \sim q_{\theta}(z/x_i)}[\log p_{\phi}(x_i/z)]$$

① Continuity and Completeness: We prefer continuous latent representations to give meaningful parameterization (e.g. smooth transition between i/ps)



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- ① Continuity and Completeness: We prefer continuous latent representations to give meaningful parameterization (e.g. smooth transition between i/ps)
- ② Solution: Force  $q_{\theta}(z/x_i)$  to be close to a standard distribution (e.g. Gaussian)



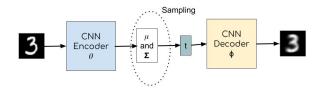
$$l_i(\theta, \phi) = -\mathbb{E}_{z \sim q_{\theta}(z/x_i)}[log \ p_{\phi}(x_i/z)] + \mathbb{KL}(q_{\theta}(z/x_i)||p(z))$$

First term promotes recovery, sencond term keeps encoding continuous (beats memorization)



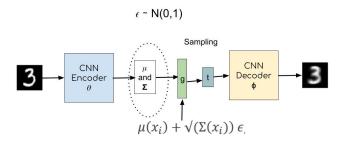
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$$l_i(\theta, \phi) = -\mathbb{E}_{z \sim q_{\theta}(z/x_i)}[\log p_{\phi}(x_i/z)] + \mathbb{KL}(q_{\theta}(z/x_i)||p(z))$$





• Sample z from the prior p(z)



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- ullet Run z through the decoder  $(\phi) o$  distribution over data
- ullet Sample from that distribution to generate the sample  ${\sf x}$
- For simplicity, in practice, only the means of the pixels are inferred (deterministic)



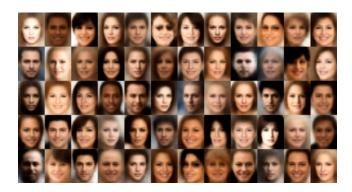


Figure credits: Wojceich



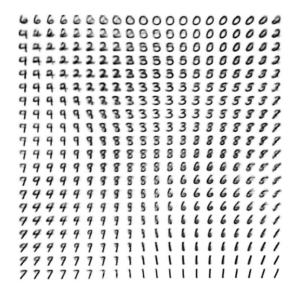
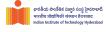


Figure credits: Kingma et al.

# Edit/Manipulate samples with VAE







### The Evidence Lower Bound (ELBO)



1 Latent variable  $\rightarrow$  variable which is not directly observable and is assumed to affect the response variables



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- 2 Aim



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  - representing the effect of unobservable covariates/factors
  - account for measurement errors
  - controlled/customized generation of the samples



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- ② Because the latent variables explain the data in a simpler way



f 1 Data samples x follow a distribution p(x)



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- $\ \, \ \, \ \, \ \, \ \, \ \,$  They are mapped on to latent variable z that follow a distribution p(z)



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- ② They are mapped on to latent variable z that follow a distribution p(z)
- $\ \mathfrak{g}(z)$  prior distribution that models the behavior of latent variables





- $\ \, \textbf{2} \ \, p(x,z) = p(x/z)p(z) \text{, describes the model} \\$



- ② p(x,z) = p(x/z)p(z), describes the model



- 2 p(x,z) = p(x/z)p(z), describes the model
- 3 Marginal distribution p(x) (goal of the model) describes how likely a sample is





- $\ \ \, \ \, \ \, \ \,$  Generation process of computing the data point x from the latent variable z
- 2 We move from the latent space to the actual data distribution





- ① Generation process of computing the data point  $\boldsymbol{x}$  from the latent variable  $\boldsymbol{z}$
- We move from the latent space to the actual data distribution
- 3 Represented by the likelihood p(x/z)



 $\begin{tabular}{ll} \textbf{Inference - process of finding the latent variable $z$ from the data point } $x$ \\ \hline $x$ \\ \hline $x$ \\ \hline$ 

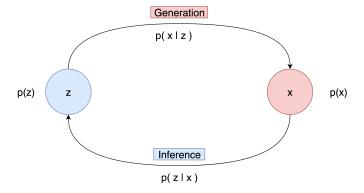


- $\begin{tabular}{ll} \textbf{ Inference process of finding the latent variable } z \end{tabular} \begin{tabular}{ll} r \end{tabular} \begin{$
- ② Formulated by the posterior distribution p(z/x)

### **Generation-Inference**



• If we assume that we (somehow) know the likelihood p(x/z), the posterior p(z/x), the marginal p(x), and the prior p(z)





① How to find these distributions?







- 3 But?



- 2 posterior =  $\frac{\text{likelihood} \cdot \text{prior}}{\text{Evidence}}$
- 3 But?
- 4 Evidence computation  $\int p_{\theta}(x/z) \cdot p_{\theta}(z) dz$  (over all the latent space) is intractable  $\to$  can't compute the LHS



- 2 posterior =  $\frac{\text{likelihood} \cdot \text{prior}}{\text{Evidence}}$
- 3 But?
- **4** Evidence computation  $\int p_{\theta}(x/z) \cdot p_{\theta}(z) dz$  (over all the latent space) is intractable  $\to$  can't compute the LHS
- $\$  Variational inference suggests to use another (known) distribution  $q_\phi(z/x)$  to approximate the posterior  $\to$  (allows to compute the evidence and sample)



$$p_{\theta}(z/x) \approx q_{\phi}(z/x)$$



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- ② We have to learn the parameters of  $q_{\phi}(z/x)$
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- 4 KL Divergence



$$D_{KL} = \mathbb{E}_{q_{\phi}} \left[ log \frac{q_{\phi}(z/x)}{p_{\theta}(z/x)} \right]$$



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- $D_{KL}(q_{\phi}||p_{\theta}) = \mathbb{E}_{q_{\phi}}[\log q_{\phi}(z/x)] \mathbb{E}_{q_{\phi}}[\log p_{\theta}(z/x)]$



- Note that we don't know the denominator (the GT)







- 3 It is the marginal log likelihood or the log evidence



- $D_{KL}(q_{\phi}||p_{\theta}) = \mathbb{E}_{q_{\phi}}[\log q_{\phi}(z/x)] \mathbb{E}_{q_{\phi}}[\log p_{\theta}(z,x)] + \log p_{\theta}(x)$
- It is the marginal log likelihood or the log evidence
- 4 We can't compute because we don't have its analytical form







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- $\mathbb{D} D_{KL}(q_{\phi}||p_{\theta}) = \mathbb{E}_{q_{\phi}}[\log q_{\phi}(z/x)] \mathbb{E}_{q_{\phi}}[\log p_{\theta}(z,x)] + \frac{\log p_{\theta}(x)}{\log p_{\theta}(x)}$
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- This is the lower bound on the evidence



- 3 Here, we know that  $D_{KL} \geq 0$
- 5 This is the lower bound on the evidence
- $\bullet$  Now, in order to reduce the  $D_{KL}$ , we can maximize the ELBO





- $\textbf{2} \ \ \mathsf{ELBO} = -\mathbb{E}_{q_\phi}[\log q_\phi(z/x)] + \mathbb{E}_{q_\phi}[\log p_\theta(x/z)] + \mathbb{E}_{q_\phi}[\log p_\theta(z)]$



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- **6** VAEs model  $p_{\theta}(x/z)$  and  $q_{\phi}(z/x)$  as neural networks