

# Some LS Outputs

Prediction at a new point  $\mathbf{x}^*$

$$\hat{y}^* = \hat{\beta}_0 + x_{i1}^* \hat{\beta}_1 + \cdots + x_{ip}^* \hat{\beta}_p.$$

Fitted value at  $\mathbf{x}_i$ :

$$\hat{y}_i = \hat{\beta}_0 + x_{i1} \hat{\beta}_1 + \cdots + x_{ip} \hat{\beta}_p.$$

Residual at  $\mathbf{x}_i$ :  $r_i = y_i - \hat{y}_i$ .

$$\text{RSS} = \sum_{i=1}^n r_i^2.$$

The error variance is estimated by

$$\hat{\sigma}^2 = \frac{\text{RSS}}{n - p - 1} = \frac{\sum_{i=1}^n r_i^2}{n - p - 1}$$

The degree of freedom (df) of the residuals is  $n - (p + 1)$ . In general

$$\begin{aligned} df(\text{residuals}) &= (\text{sample-size}) \\ &\quad - (\text{number-of-linear-coefs}) \end{aligned}$$

## The Residual Vector

$\mathbf{X}^t \mathbf{r} = \mathbf{0}_{(p+1) \times 1}$  implies that the residual vector  $\mathbf{r}$  is subject to  $(p + 1)$  equality constraints, therefore it loses  $(p + 1)$  degrees of freedom.

$$\begin{pmatrix} \text{Green Matrix} \end{pmatrix}^T \begin{pmatrix} \text{Blue Vector} \end{pmatrix} = \begin{pmatrix} \text{Green Matrix} \end{pmatrix} \begin{pmatrix} \text{Blue Vector} \end{pmatrix} = \mathbf{0}$$