

Lecture 6

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1 Another Divide and Conquer Sorting Algorithm: Quick Sort

Another efficient sorting algorithm is quick sort. Quick sort is also based on the technique of divide and conquer. Remember the technique: we partition the instance into several *disjoint* subproblems, we solve each subproblem recursively, and we combine the solutions together. In the merge sort algorithm, the partitioning step was trivial (pick the first and second half of the array simply) and the main idea was on how to combine the solutions (using the merge algorithm). On the other hand, in quick sort, the main step is in the partition part (using an algorithm called partition) and after that there is essentially no combine step.

The Partition Algorithm

The partition algorithm solves the following problem: Given an array $A[1 : n]$ and an index p in $[1 : n]$ (called the *pivot*), *rearrange* A such that $A[p]$ is in its correct position q in the sorted order, and in the rearranged array, for all $i < q$, $A[i] \leq A[q]$ and for all $j > q$, $A[j] \geq A[q]$.

Example: For an input array $A = [20, 30, 70, 10, 80, \underline{40}, 50, 60]$ and $p = 6$ (the underlined index, i.e., $A[6] = 40$), the output can be any of the following arrays:

$[20, 30, 10, \underline{40}, 80, 50, 60, 80]$ $[10, 20, 30, \underline{40}, 50, 60, 70, 80]$ $[2, 3, 1, \underline{40}, 70, 60, 50, 80]$ \dots

The important thing to note that the pivot element should always be placed in its correct position in the sorted order; for instance in the examples above, we will always place the number 40 in the 4-th position of the output array.

We now design an algorithm for this problem. The idea is to first swap $A[p]$ with the last element of the array, i.e., $A[n]$ for simplicity. So from now on, we will work with $A[n]$ as the pivot and can forget about p . Then go over all the elements and count how many of them are smaller than $A[n]$ to be able to find in which position we should place $A[n]$. During the same procedure, we should also start swapping elements that are smaller than $A[n]$ with the larger ones in a way to ensure that at the end, all smaller elements appear before the correct position of $A[n]$. There is a very slick way to do this using a single for-loop iteration as we describe below.

Partition Algorithm: The input is an array $A[1 : n]$ and a pivot p in $[1 : n]$.

1. Swap $A[p]$ and $A[n]$ with each other. Let $j = 1$.
2. For $i = 1$ to $n - 1$ do as follows:
 - (a) If $A[i] < A[n]$, then swap $A[i]$ and $A[j]$ and let $j \leftarrow j + 1$.
3. Swap $A[n]$ and $A[j]$.

Example: Let us consider running this algorithm on the array $[20, 50, 70, 80, 10, 40, 30, 60]$ with pivot $p = 6$ ($A[6] = 40$) again. In the following, the underline denote the index i of the for-loop (before being incremented in that iteration) and the overline corresponds to index j .

- At the beginning (after swapping $A[6]$ with $A[8]$):

$$A = [\underline{20}, 50, 70, 80, 10, 60, 30, 40]$$

- In iteration $i = 1$ we swap $A[i = 1]$ with $A[j = 1]$ (!) since $A[1] < A[8]$ and increase j to 2.

$$A = [\underline{20}, \overline{50}, 70, 80, 10, 60, 30, 40]$$

- In iteration $i = 2$ we do nothing since $A[i = 2] > A[8]$:

$$A = [20, \underline{\overline{50}}, 70, 80, 10, 60, 30, 40]$$

- In iteration $i = 3$ we do nothing since $A[i = 3] > A[8]$:

$$A = [20, \overline{50}, \underline{70}, 80, 10, 60, 30, 40]$$

- In iteration $i = 4$ we do nothing since $A[i = 4] > A[8]$:

$$A = [20, \overline{50}, 70, \underline{80}, 10, 60, 30, 40]$$

- In iteration $i = 5$ we swap $A[i = 5]$ with $A[j = 2]$ since $A[5] < A[8]$ and increase j to 3:

$$A = [20, 10, \overline{70}, 80, \underline{50}, 60, 30, 40]$$

- In iteration $i = 6$ we do nothing since $A[i = 6] > A[8]$:

$$A = [20, 10, \overline{70}, 80, 50, \underline{60}, 30, 40]$$

- In iteration $i = 7$ we swap $A[i = 7]$ with $A[j = 3]$ since $A[7] < A[8]$ and increase j to 4:

$$A = [20, 10, 30, \overline{80}, 50, 60, \underline{70}, 40]$$

- Finally, we swap $A[n]$ with $A[j = 4]$:

$$A = [20, 10, 30, \overline{40}, 50, 60, 70, 80]$$

Remark: This algorithm is *not* for sorting the array (yet) as can be seen by the example above.

Proof of Correctness: We now prove that the partition algorithm correctly partitions any array $A[1 : n]$ and given pivot p for all values of n . This is done using an induction over the index i of the for-loop of the array. In the following, we use j_i to denote the value of index j at the end of the iteration i .

Our induction hypothesis is that after every iteration i of the partition algorithm, the *current* array $A[1 : j_i - 1]$ contains all the elements smaller than $A[p]$ in the *original* array $A[1 : i]$. Before proving the induction hypothesis, let us note why this concludes the proof. For $i = n$, the induction hypothesis implies that all the elements smaller than $A[p]$ (in the original array) are now placed in $A[1 : j_n - 1]$. The algorithm then swaps $A[j_n]$ with $A[n]$ (recall that $A[n]$ contains the element $A[p]$ in the original array). Since $A[j_n] \geq A[n]$ (by induction hypothesis), we now know that all elements in $A[1 : j_n - 1]$ are smaller than $A[j_n]$ (again $A[j_n]$ now contains the pivot $A[p]$) and all elements in $A[j_n + 1 : n]$ are at least as large as $A[j_n]$, as desired. This also implies that we placed $A[p]$ in its correct position which is $A[j_n]$, proving the correctness.

We now prove the induction hypothesis. The base case of $i = 1$ is as follows: If $A[1] < A[n]$, we swap $A[1]$ with $A[n]$ (again!) and increase j by one, i.e., $j_1 = 2$ – this ensures that the induction hypothesis holds in this case as now $A[1]$ contains the only element smaller than $A[n]$ in $A[1 : 1]$. Otherwise, if $A[1] \geq A[n]$ we do nothing which again ensures the induction hypothesis. The proof of the induction step is also similar: Suppose this is true up until iteration i and we prove it for iteration $i + 1$:

- If $A[i+1] < A[n]$, we swap $A[i+1]$ and $A[j_i]$ and let $j_{i+1} = j_i + 1$: by induction hypothesis, $A[1 : j_i - 1]$ contains all the smaller elements in $A[1 : i]$ and thus $A[j_i]$ is at least as large as $A[n]$. Hence, after this swap $A[1 : j_i] = A[1 : j_{i+1} - 1]$ contains all the smaller elements from $A[1 : i + 1]$ proving the step.
- If $A[i+1] \geq A[n]$, we do nothing and $j_{i+1} = j_i$: in this case, since by induction $A[1 : j_i - 1]$ contained all the smaller elements in $A[1 : i]$ and $A[i+1]$ is *not* smaller, $A[1 : j_{i+1} - 1]$ will continue to contain all the smaller elements in $A[1 : i + 1]$.

This proves the induction step and concludes the correctness proof of this algorithm.

Runtime analysis: The runtime is clearly $\Theta(n)$ because we run a simple $n - 1$ iteration loop and each iteration takes $\Theta(1)$ time.

The Quick Sort Algorithm

Considering all we learned about the partition algorithm and the divide and conquer technique, the way the quick sort algorithm should work is almost straightforward: we pick an *arbitrary* pivot and partition the array around the pivot using the partition algorithm; we then recursively sort the array for the two different subarrays consisting of smaller elements than pivot and larger ones that are identified already by partition. The algorithm is formally as follows:

Quick Sort Algorithm: The input is an array $A[1 : n]$.

1. If $n = 0$ or $n = 1$ return the current array.
2. Let $p = n$ (or *any* other index – at this point, this does *not* matter).
3. Use the partition algorithm to partition A with pivot p . Let q be the correct position of $A[p]$ in the sorted array computed by the partition algorithm.
4. Recursively quick sort $A[1 : q - 1]$ and $A[q + 1 : n]$.

Example: Let us consider running the quick sort algorithm on the array $[20, 50, 70, 80, 10, 40, 30, 60]$ (by always picking the last element of the array as pivot in the recursive calls). In the following, the underline denote the pivot element.

- We pick 40 as pivot and this partitions the array into two arrays for recursive calls:

$$[20, 50, 70, 80, 10, 60, 30, \underline{40}] \implies [20, 10, 30, \underline{40}, 50, 70, 80, 60]$$

- We pick 30 as pivot in the first recursive call (over $[20, 10, 30]$) and 60 as pivot in the second recursive call (for $[50, 70, 80, 60]$):

$$\begin{aligned} [20, 10, \underline{30}] &\implies [20, 10, \underline{30}] \\ [50, 70, 80, \underline{60}] &\implies [50, \underline{60}, 70, 80] \\ [20, 10, \underline{30}, 40, 50, 70, 80, \underline{60}] &\implies [20, 10, \underline{30}, 40, 50, \underline{60}, 70, 80] \end{aligned}$$

- By continuing like this, we sort the entire array.

Proof of Correctness: Proof is by ... induction! (Seriously, almost all divide and conquer algorithms are analyzed using induction). Our inductive hypothesis is simply that the quick sort correctly sorts any array of length n . The base case for $n = 0$ and $n = 1$ follows immediately from the algorithm since any array of size 0 or 1 is sorted anyway.

We now prove the induction step: suppose quick sort can sort all arrays of length $n \leq k$ and we prove it also correctly sorts any array of size $n = k + 1$. Let A be any array of size $n = k + 1$. Quick sort first runs partition (with an arbitrarily chosen pivot) to partition the array into $A[1 : q - 1]$, $A[q]$ and $A[q + 1 : n]$, where $A[q]$ is in its correct position and every element in $A[1 : q - 1]$ is at most as large as $A[q]$ while every element in $A[q + 1 : n]$ is at least as large as $A[q]$. The algorithm then recursively sorts $A[1 : q - 1]$ and $A[q + 1 : n]$ – since size of both array is smaller than $k + 1$, by induction hypothesis, both arrays are sorted correctly. By the guarantee of the partition algorithm and this sorting step, we have $A[1 : q - 1]$ is sorted array of elements $\leq A[q]$, and $A[q + 1 : n]$ is the sorted array of elements $\geq A[q]$; hence A is also now sorted. This proves the induction step and the correctness of the algorithm.

Runtime of Quick Sort: In the quick sort algorithm introduced before, we can take any element as the pivot. Partitioning the array using this pivot takes $O(n)$ time. Also, assuming we pick the element with correct position q as pivot, we then need to recursively sort the arrays $A[1 : q - 1]$ and $A[q + 1 : n]$. Hence, if we use $T(n)$ to denote the worst-case runtime of quick sort, we have,

$$T(n) \leq \max_{q \in \{1, \dots, n\}} \{T(q - 1) + T(n - q)\} + O(n).$$

We can verify that the maximum value of the right hand side equation happens when $q = 1$ or $q = n$ (we will do so shortly). Using that, we have,

$$T(n) \leq T(n - 1) + O(n) \implies T(n) = O(n^2). \quad (\text{this is the same recurrence as insertion sort!})$$

So first, why did we say $q = 1$ or $q = n$ which results in $O(n^2)$ runtime is the worst example? In other words, can quick sort run even slower? The answer is *no* because after each run of the partition algorithm that takes $O(n)$ time, we remove one element from consideration in recursive calls (the pivot element). Hence, for each of the n elements, we may spend at most $O(n)$ time processing it (in partition) and so we can only spend $O(n^2)$ time. Hence, quick sort runs in $O(n^2)$ time.

Now the second question is that whether $T(n) = O(n^2)$ is *too pessimistic* (and not accurate) and we could prove a better upper bound? The answer to this question is also *no*: consider an array that is sorted in non-increasing order, i.e., exactly the reverse order of what we want – for this array, by picking the last element as pivot, we have to recursively solve the problem for $n - 1$ elements (on a subarray that is still sorted in the non-decreasing order); hence, for such an array we have to spend $\Omega(n)$ time for running the partition algorithm for $\Omega(n)$ first choices of pivot, making the total runtime $\Omega(n^2)$.

The above implies that the runtime of quick sort is $\Theta(n^2)$ in the worst case. Wait what? Something must be wrong because quick sort is supposed to be “quick”, namely, $O(n \log n)$ time; so what just happened? The catch is that quick sort can be really slow if we “end up unlucky” and pick a “bad” pivot in every step (roughly speaking, a bad pivot is a one which partitions the array in a very lopsided way, the extreme example being $n - 1$ elements in one side and none in the other – this corresponds to picking either the *maximum* or *minimum* of the array as the pivot). What would happen instead if we are really “lucky” and get the “best” pivot in every step (the best pivot is when we partition the array into two roughly the same size subarrays – this corresponds to picking the *median* of the array as the pivot): *for this particular example*, we can write $T(n) \leq 2T(n/2) + O(n)$; this is the same as the recurrence for merge sort and thus we get $T(n) = O(n \log n)$ which would be good.

The above part tells us we need to have some “luck” on our side, but how can we do that? By picking the pivot *randomly* instead of arbitrarily! We thus need to consider a *randomized* quick sort. This is the content of next lecture.