# CS 344: Design and Analysis of Computer Algorithms

(Spring 2022 — Sections 5,6,7,8)

# Lecture 16: Graph Search and Shortest Paths: BFS

# Graph Search Algorithm 2: Breadth-First-Search (BFS)

- Another natural strategy for exploring the graph:
- Mark s; then all neighbors of s; then neighbors of neighbors of s, and continue like this...

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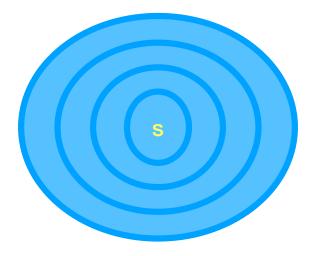
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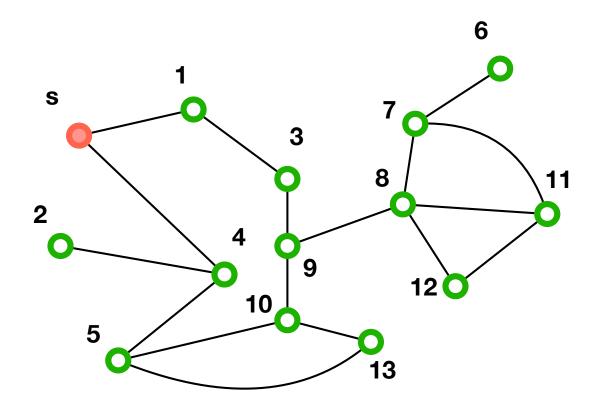
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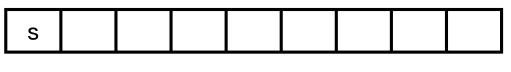
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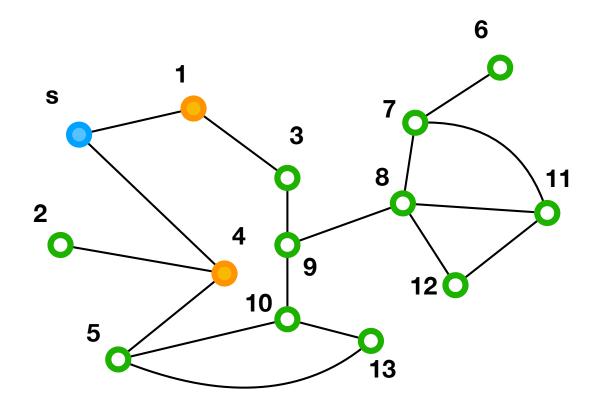


- Initialize mark[1:n] = 'false' for every vertex v
- Create a queue data structure Q and insert s to Q
- While Q is not empty;
  - Remove v from the top of the queue
  - If mark[v] = 'true' continue to the next iteration of the while-loop
  - Otherwise, mark[v] = 'true'; add all neighbors N(v) to queue Q
- Return all vertices that are marked (true).

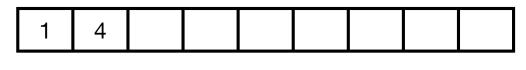


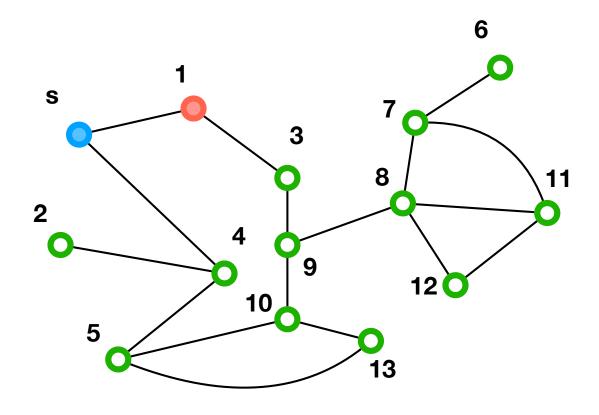
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- current vertex in while-loop
- vertices to be added to Q



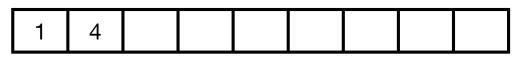


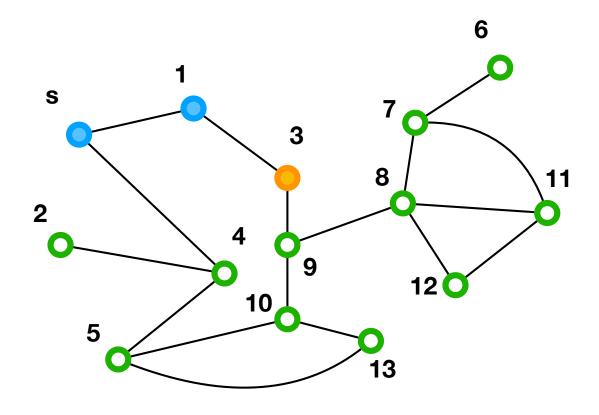
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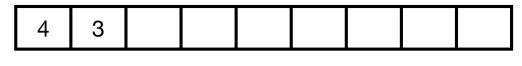


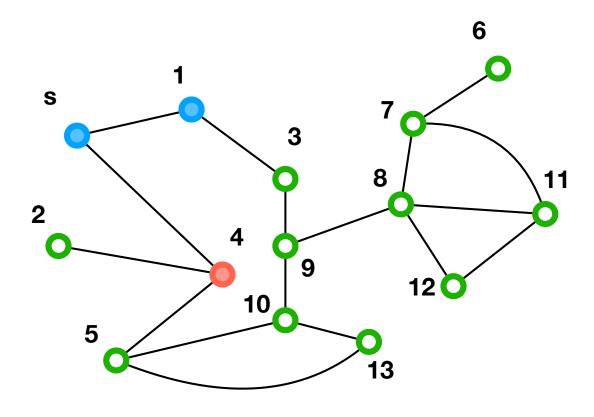
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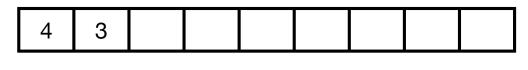


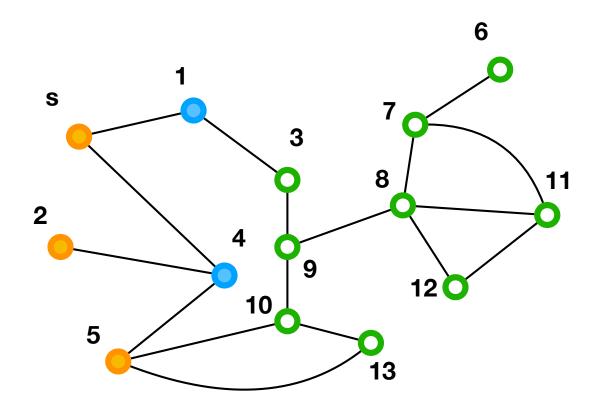
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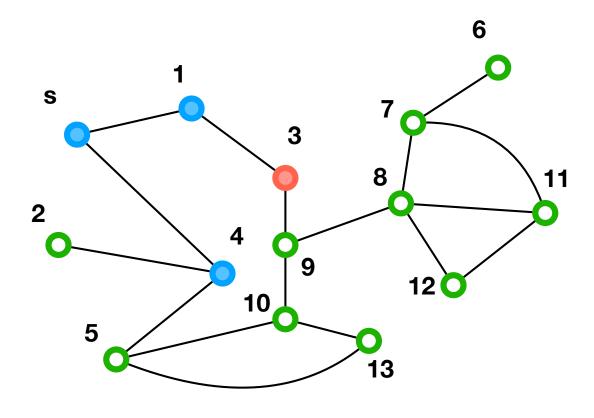
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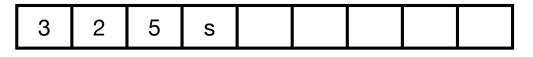


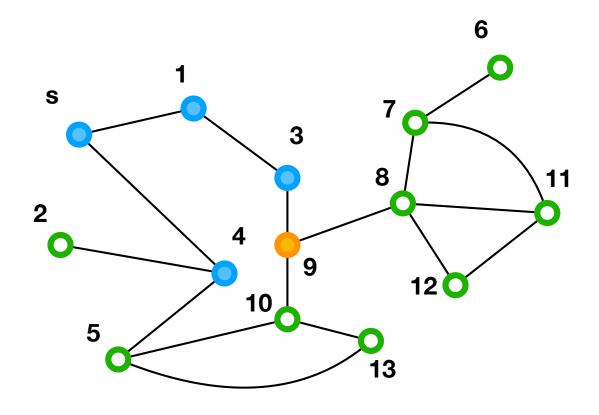
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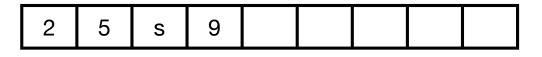


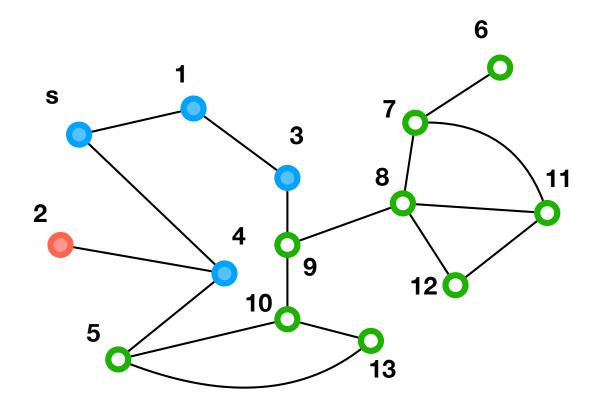
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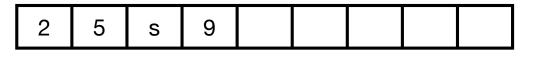


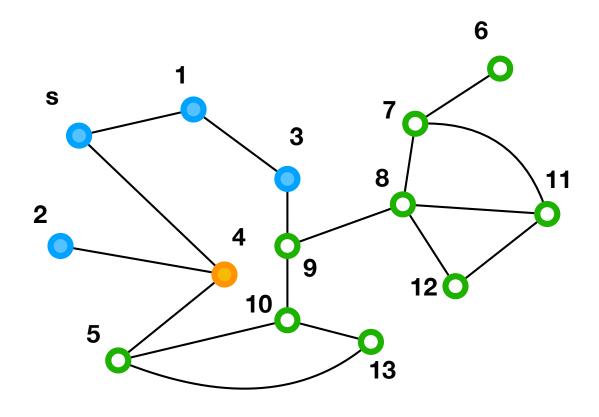
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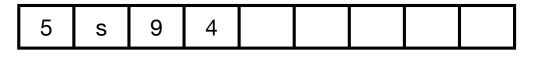


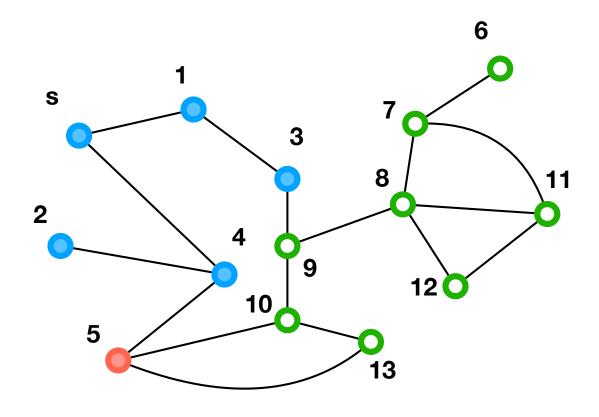
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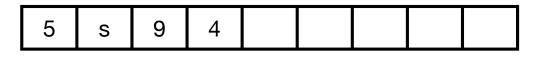


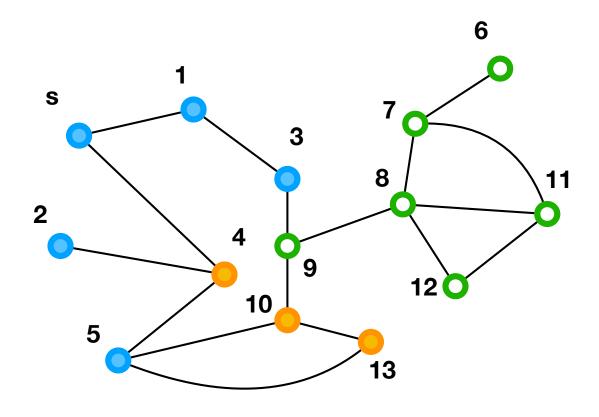
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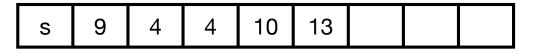


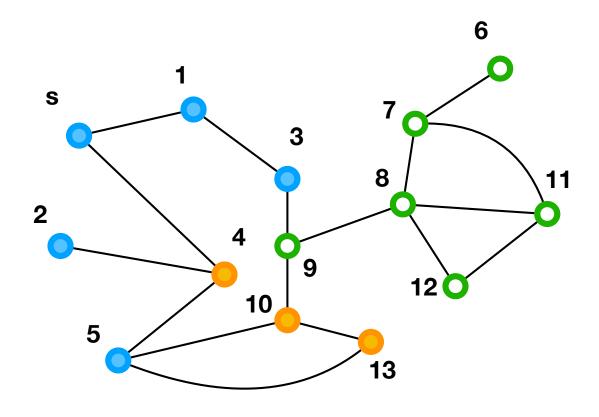
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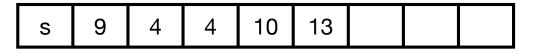


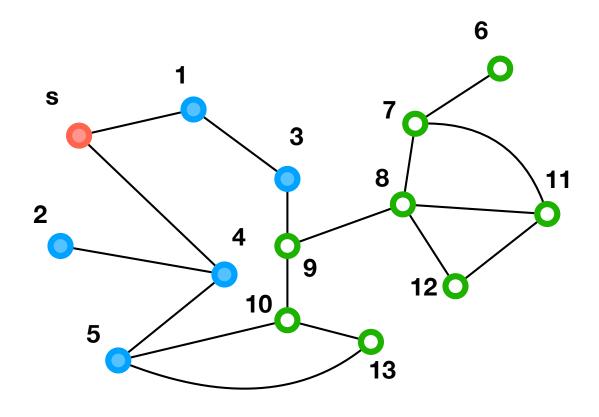
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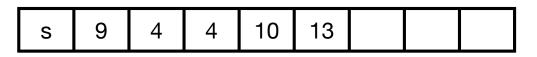


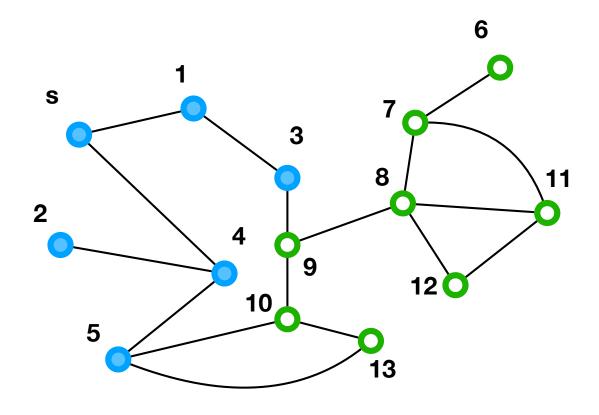
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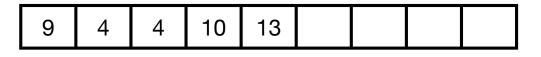


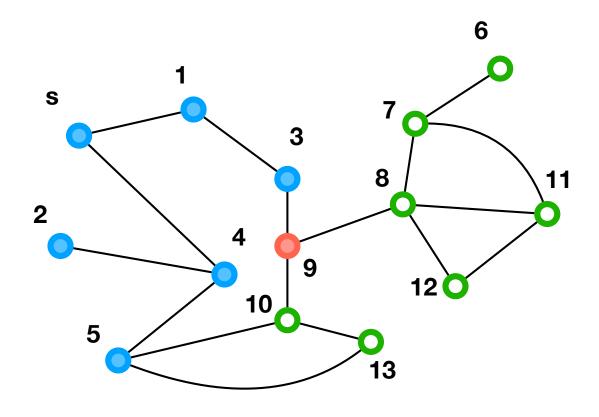
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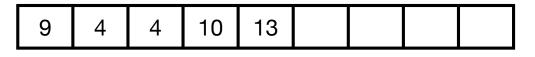


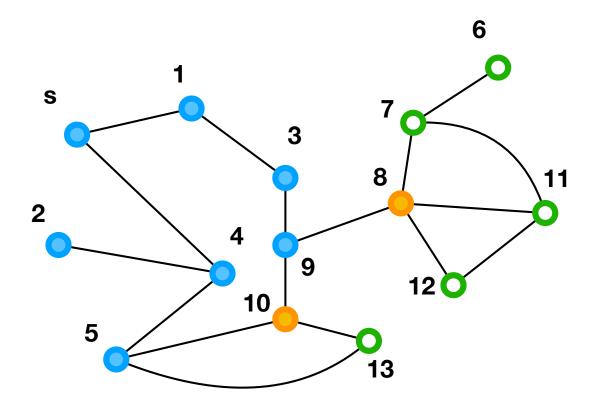
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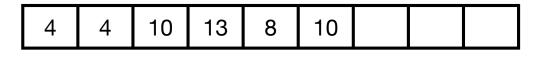


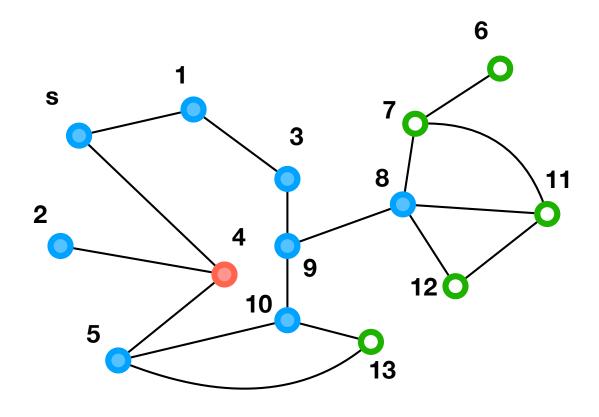
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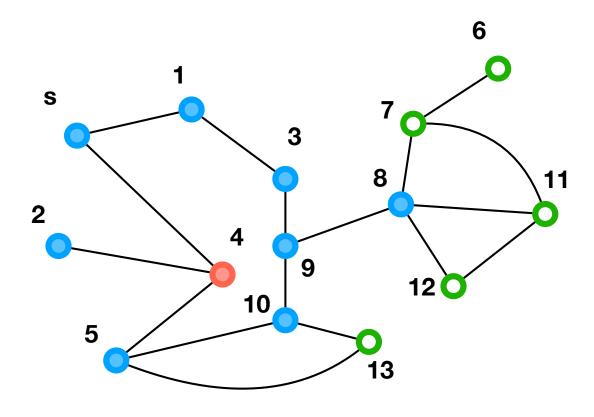
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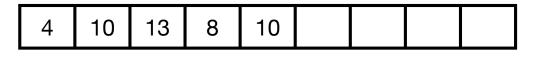


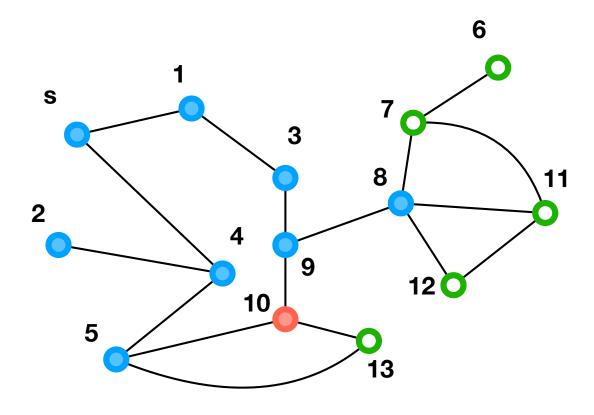
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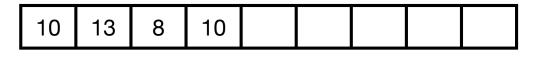


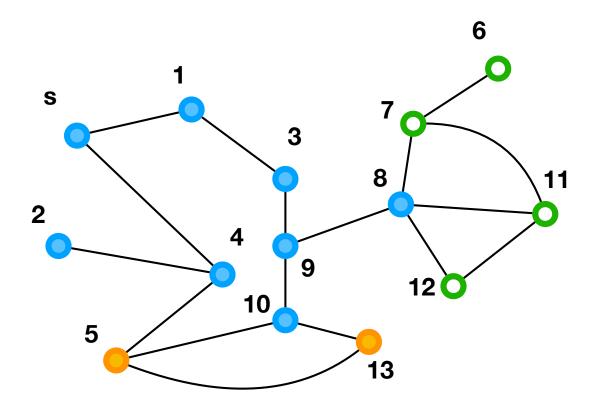
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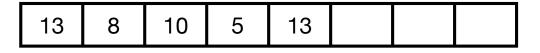


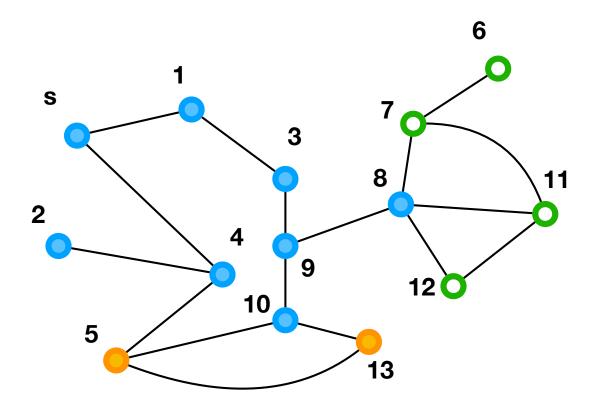
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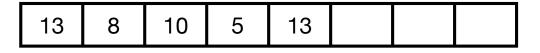


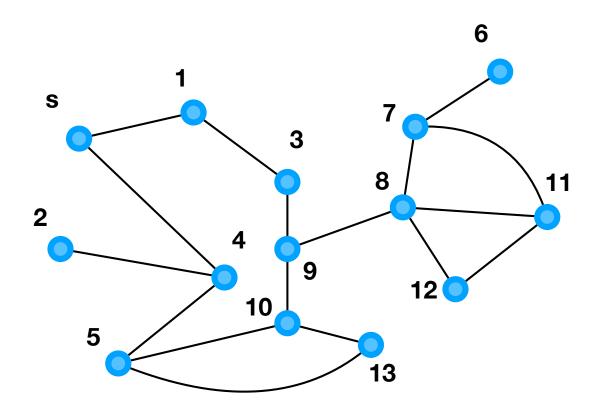
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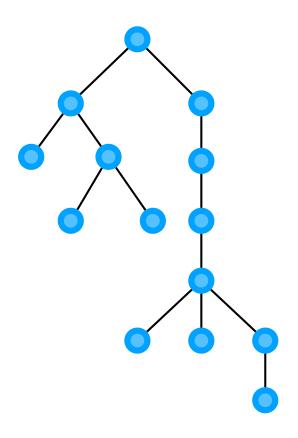
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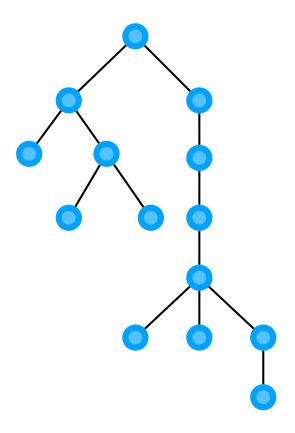


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# **BFS Tree**



#### **BFS Tree**



BFS tends to create very shallow trees

- Initialize mark[1:n] = 'false' for every vertex v
- Create a queue data structure Q and insert s to Q
- While Q is not empty;
  - Remove v from the top of the queue
  - If mark[v] = 'true' continue to the next iteration of the while-loop
  - Otherwise, mark[v] = 'true'; add all neighbors N(v) to queue Q
- Return all vertices that are marked (true).

#### **Proof of Correctness**

Postponed for now — we will prove a generalization soon

#### **Runtime Analysis**

- Initialize mark[1:n] = 'false'
- Create a queue data structure Q and insert s to Q
- While Q is not empty;
  - Remove v from the top of the queue
  - If mark[v] = 'true' continue
  - Otherwise, mark[v] = 'true'; add all neighbors N(v) to queue Q
- Return all vertices that are marked (true).

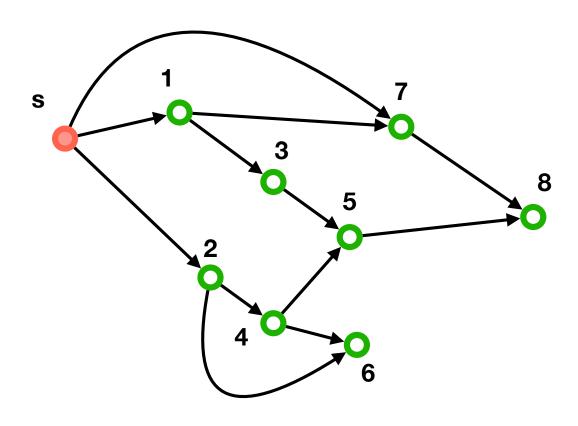
- Any vertex is only inserted to the Q once effectively
- Any other time it is inserted, ignore its time and instead "charge" the time to the vertex that inserted it
- The time spent for vertex v is then O(1+deg(v))
- Total runtime O(n+m) as before

# **Unweighted Shortest Path**

#### **BFS finds Shortest Paths**

- For any vertex  $v \in V$ :
  - dist(s,v): distance of v from s
  - length of shortest path from s to v.

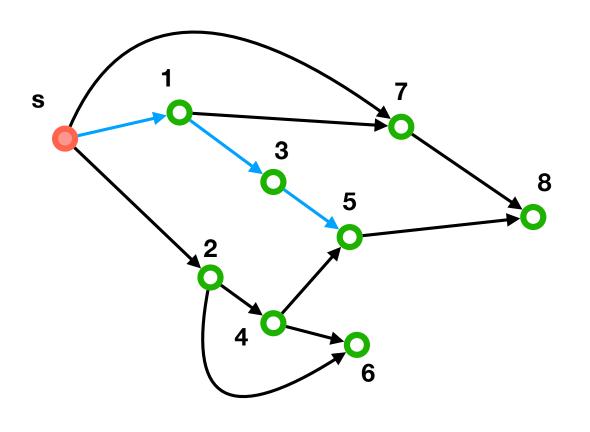
## **BFS: Example**

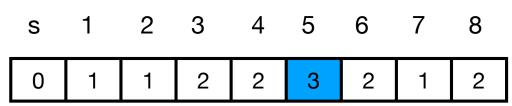


 s
 1
 2
 3
 4
 5
 6
 7
 8

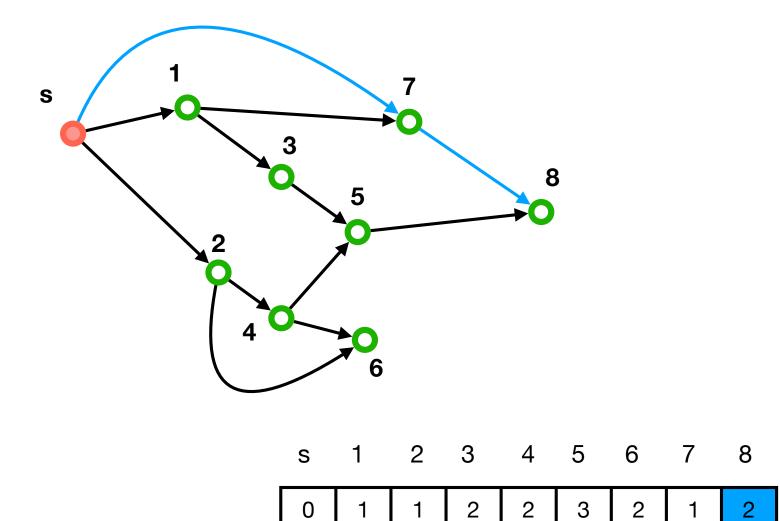
 0
 1
 1
 2
 2
 3
 2
 1
 2

## **BFS: Example**



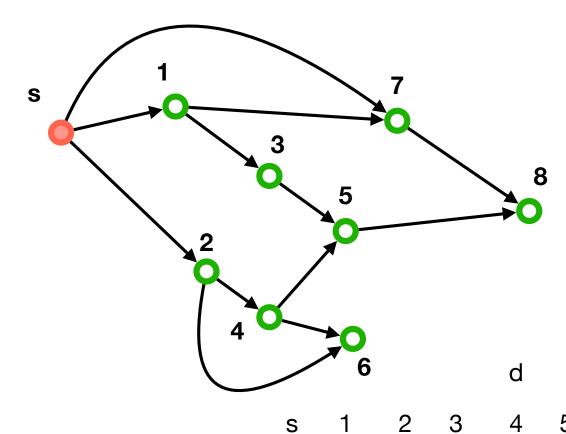


## **BFS: Example**

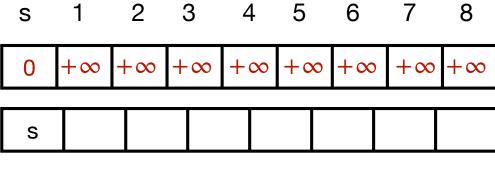


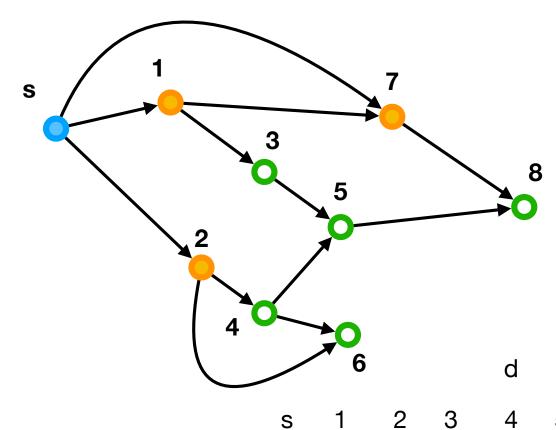
#### **Shortest-Path-BFS**

- Initialize  $d[1:n] = +\infty$  for every vertex v
- Create a queue data structure Q and insert s to Q; set d[s] = 0
- While Q is not empty;
  - Remove u from the top of the queue
  - For any  $v \in N(u)$ :
    - If  $d[v] \neq +\infty$  continue to the next neighbor
    - Otherwise, let d[v] = d[u] + 1 and add v to Q

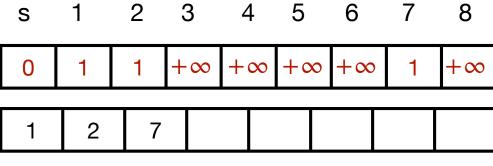


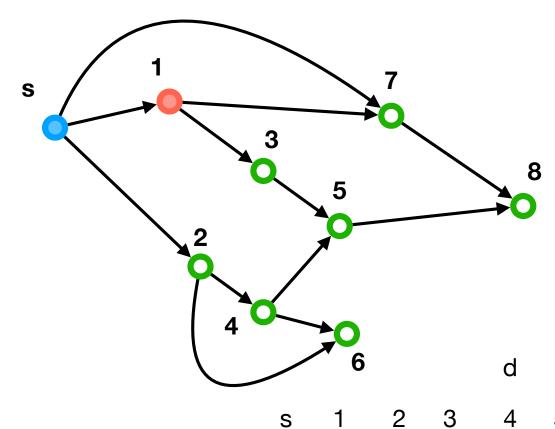
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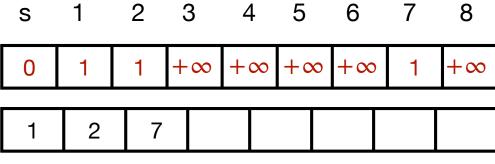


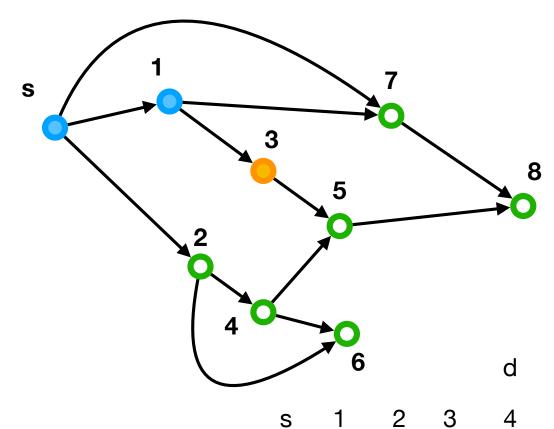
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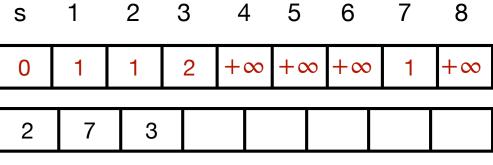


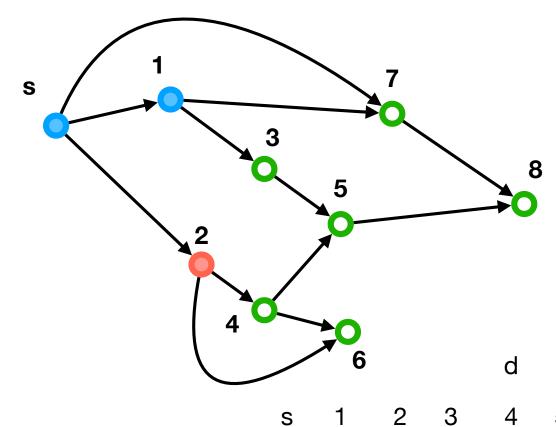
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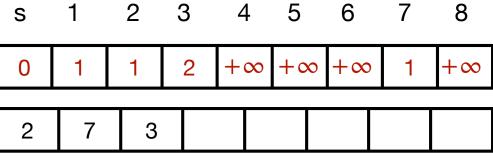


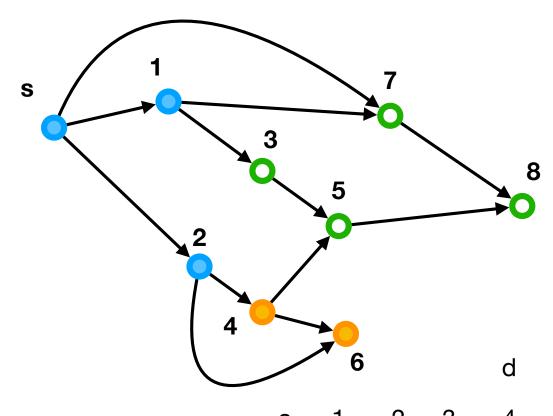
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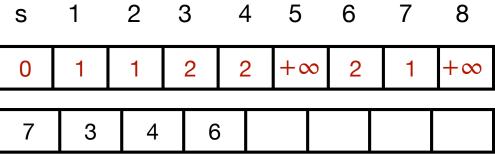


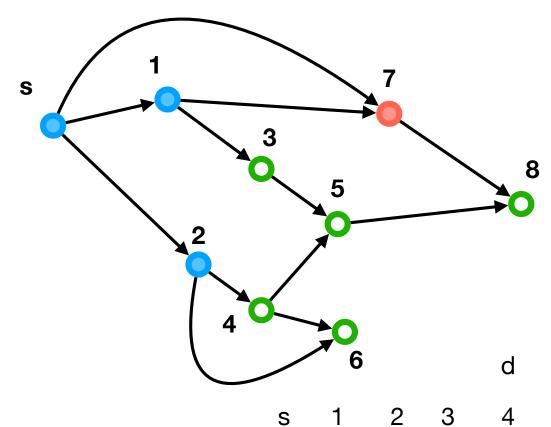
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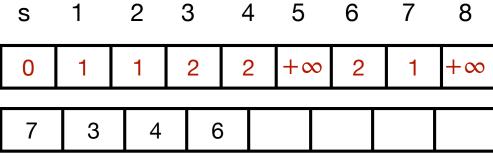


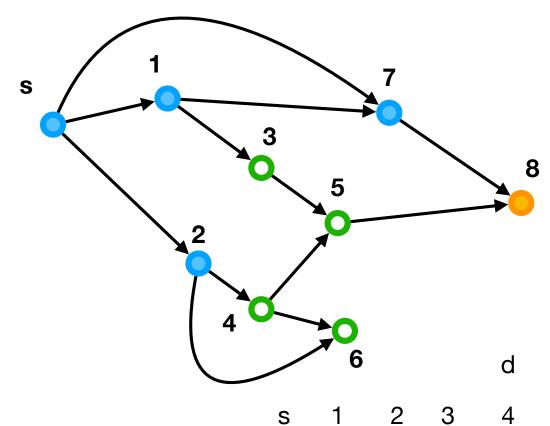
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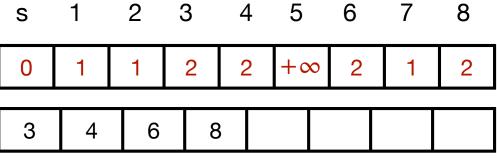


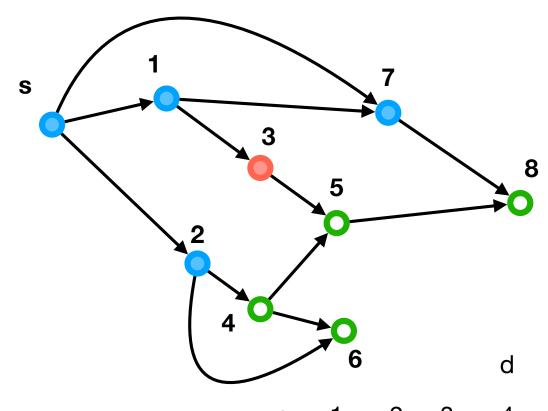
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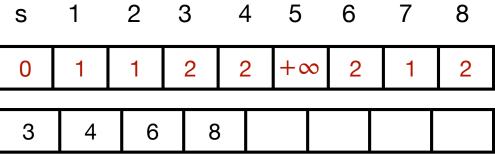


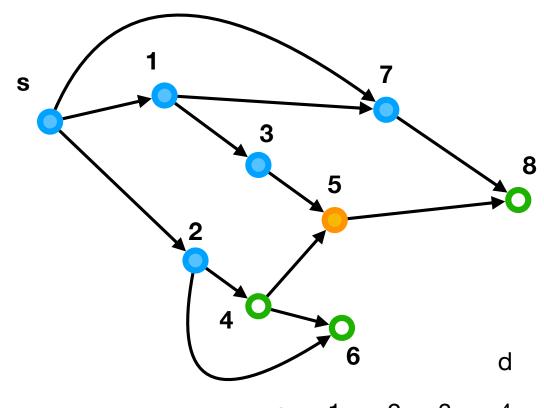
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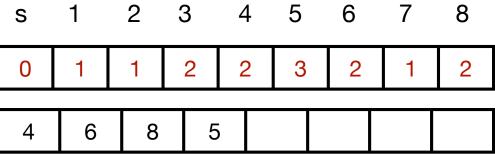


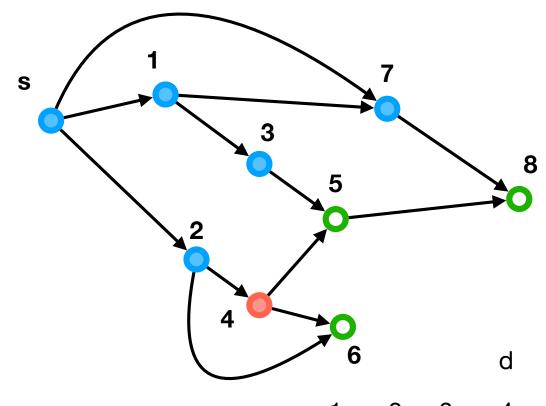
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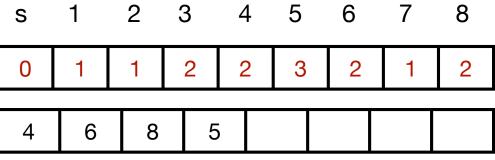


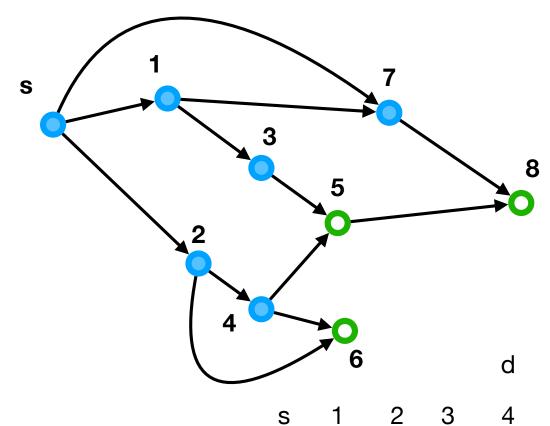
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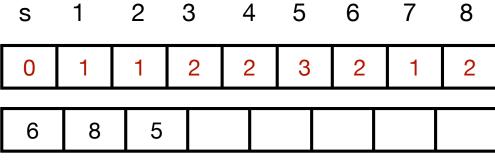


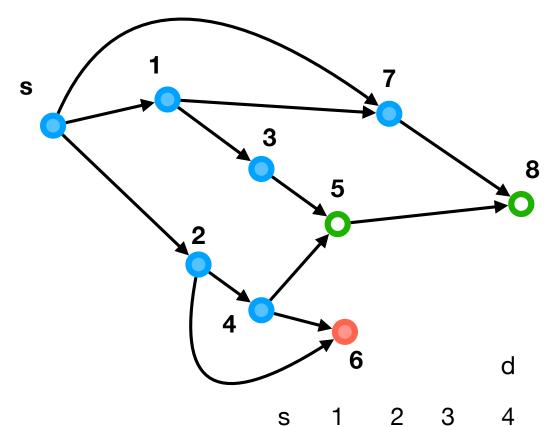
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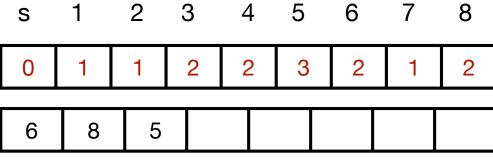


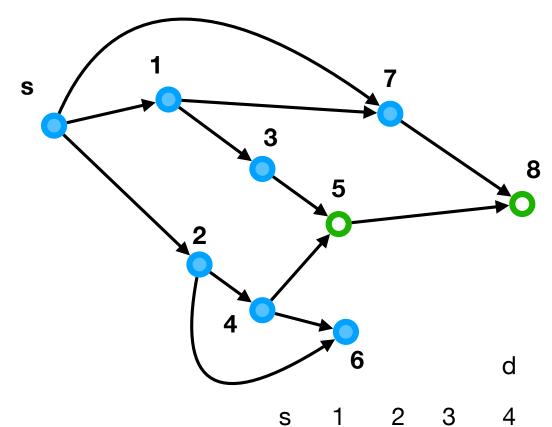
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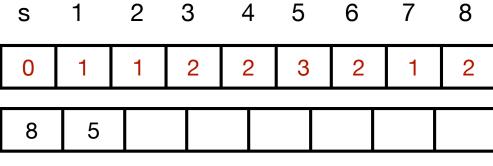


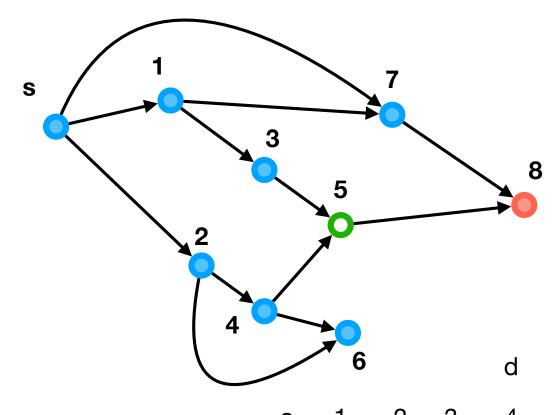
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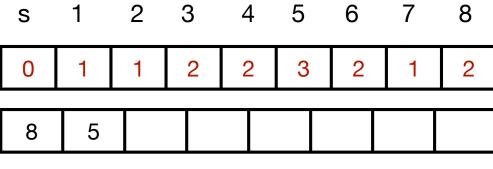


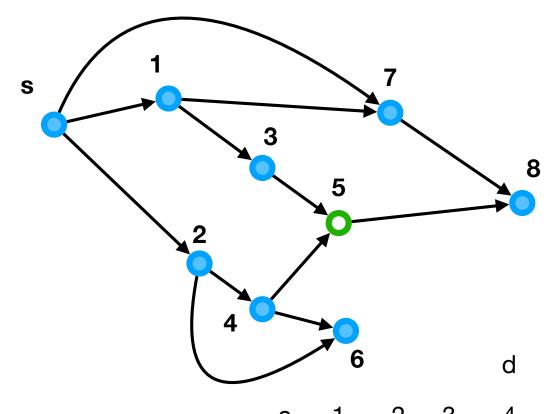
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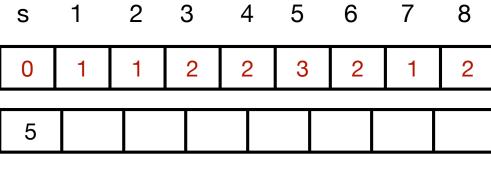


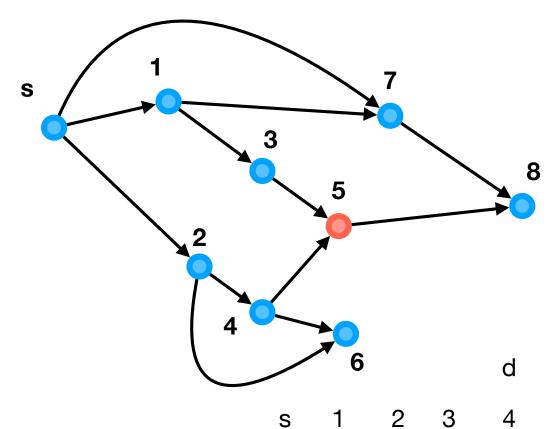
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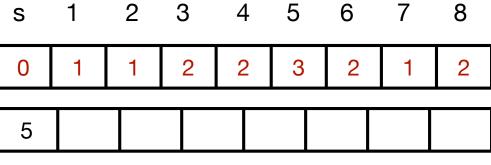


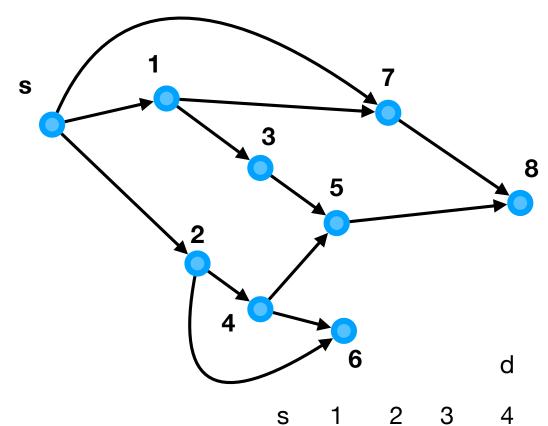
- "marked" vertices
- unmarked vertices
- current vertex in while-loop
- vertices to be added to Q



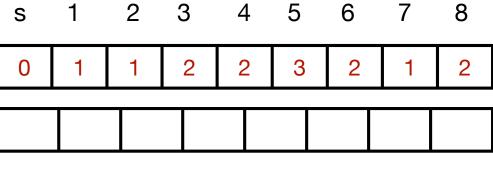


- "marked" vertices
- unmarked vertices
- current vertex in while-loop
- vertices to be added to Q





- "marked" vertices
- unmarked vertices
- current vertex in while-loop
- vertices to be added to Q



#### **Shortest-Path-BFS**

- Initialize  $d[1:n] = +\infty$  for every vertex v
- Create a queue data structure Q and insert s to Q; set d[s] = 0
- While Q is not empty;
  - Remove u from the top of the queue
  - For any  $v \in N(u)$ :
    - If  $d[v] \neq +\infty$  continue to the next neighbor
    - Otherwise, let d[v] = d[u] + 1 and add v to Q

#### **Proof of Correctness**

### **Runtime Analysis**

- Initialize d[1:n] = +∞ for every vertex v
- Create a queue data structure Q and insert s to Q; set d[s] = 0
- While Q is not empty;
  - Remove u from the top of the queue
  - For any  $v \in N(u)$ :
    - If  $d[v] \neq +\infty$  continue to the next neighbor
    - Otherwise, let d[v] = d[u] + 1and add v to Q

- Asymptotically the same as the original BFS
- So O(n+m)