

## Systems of D.E.s.

### 1st order systems of D.E.s.

$$(*) \begin{cases} x' = f(t, x, y) \\ y' = g(t, x, y) \end{cases}$$

Where  $t$  is the variable,  $f(t, x, y)$ ,  $g(t, x, y)$  are given functions, and  $x = x(t)$ ,  $y = y(t)$  are to be determined.

$(x(t), y(t))$  is called a solution to  $(*)$ , if

$$\begin{cases} x'(t) = f(t, x(t), y(t)) \\ y'(t) = g(t, x(t), y(t)) \end{cases}$$

are both satisfied for all  $t$  (in the domain of  $x(t), y(t)$ ).

eg. 
$$\begin{cases} x' = x^2 + y^2 + \sin(tx) \\ y' = x^2 - y + e^t + 1. \end{cases}$$

eg. Predator-Prey system

$$\begin{cases} R' = 2R - 1.2RF, \\ F' = -F + 0.9RF. \end{cases}$$

Equivalence between Higher order D.E.s and 1st order system:

Given a ~~higher~~ second order D.E. .

$$y'' = f(t, y, y'),$$

one can defined an extra variable .

$$v = y',$$

and write

$$\begin{cases} y' = v. \end{cases}$$

$$\begin{cases} v' = f(t, y, v) \end{cases}$$

$$(\because v' = (y')' = y'' = f(t, y, y') = f(t, y, v))$$

e.g. The equation

$$y'' = ky$$

is equivalent to the system

$$\begin{cases} y' = v \end{cases}$$

$$\begin{cases} v' = ky. \end{cases}$$

Checking solution:

$$\begin{cases} x' = -x + y \\ y' = -3x - 5y \end{cases}$$

check:  $(x(t), y(t)) = (e^{-4t} - 3e^{-2t}, -3e^{-4t} + 3e^{-2t})$   
is a solution:

$$\begin{aligned} x' &= -4e^{-4t} + 6e^{-2t} \\ -x + y &= (-e^{-4t} + 3e^{-2t}) + (-3e^{-4t} + 3e^{-2t}) \\ &= -4e^{-4t} + 6e^{-2t} \end{aligned}$$

$$\Rightarrow x' = -x + y$$

(Similarly  $y' = -3x - 5y$ .)

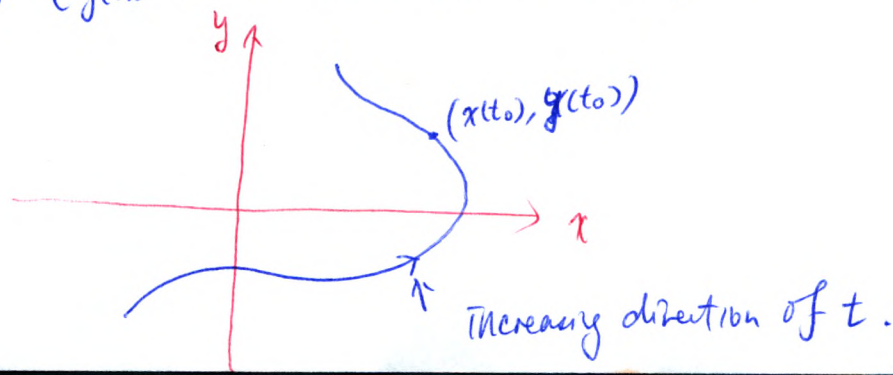
Geometric Interpretations:

Write  $Y(t) = \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}$ ,  $F(Y) = \begin{pmatrix} f(x, y) \\ g(x, y) \end{pmatrix}$ ,  $Y'(t) = \begin{pmatrix} x'(t) \\ y'(t) \end{pmatrix}$ .

Q: How to interpret

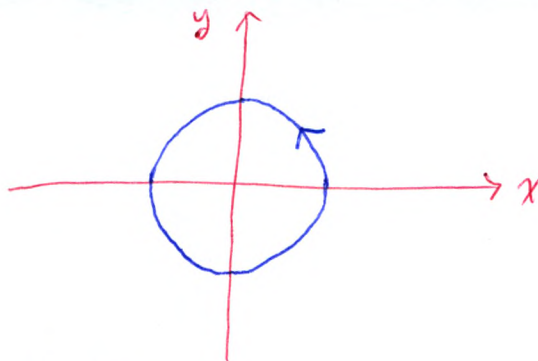
$$Y'(t) = \vec{F}(Y) \quad ?$$

①  $Y(t)$ : Think of  $\begin{pmatrix} x(t) \\ y(t) \end{pmatrix}$  as a curve in the  $x$ - $y$  plane:



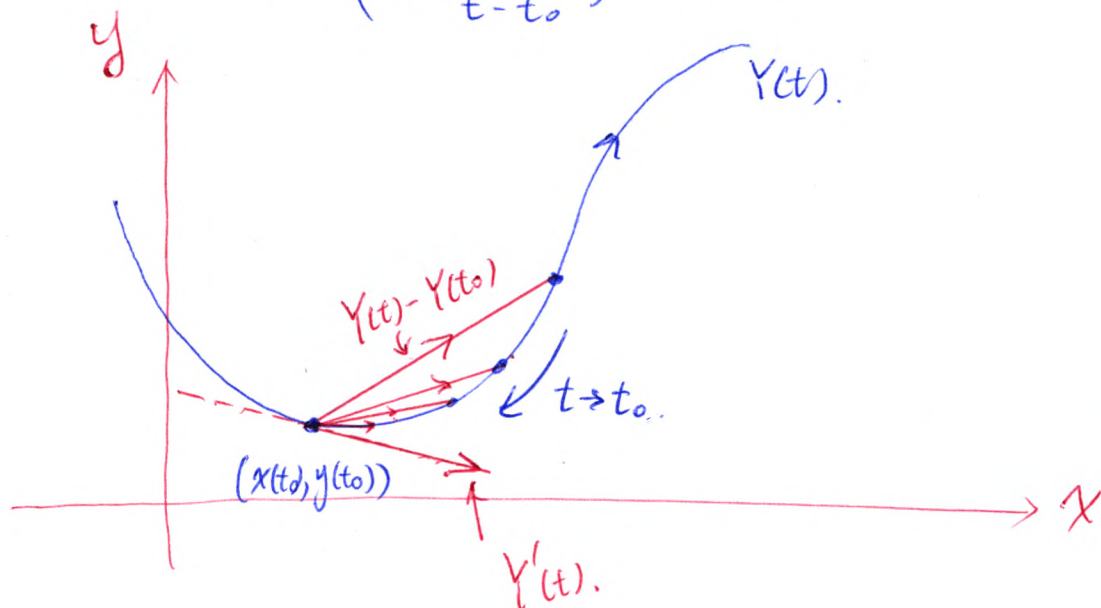
e.g.

$$Y(t) = \begin{pmatrix} \cos t \\ \sin t \end{pmatrix}$$

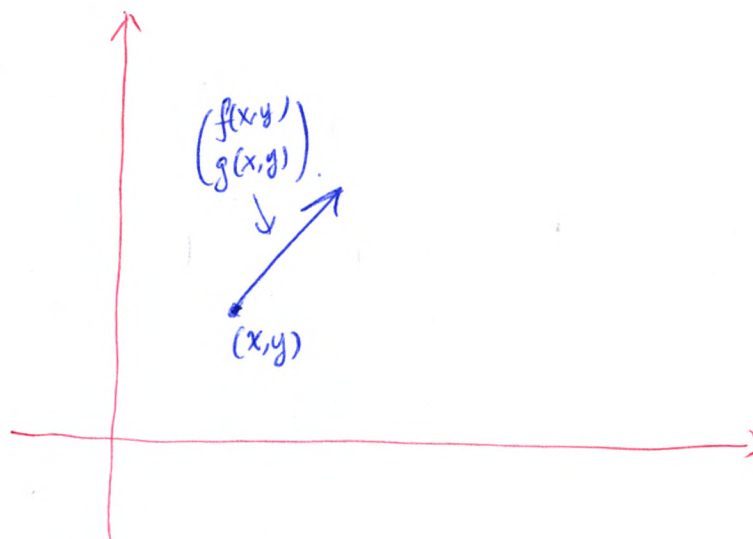


②  $Y'(t)$ : tangent vectors at  $Y(t)$ .

Reason: 
$$Y'(t_0) = \lim_{t \rightarrow t_0} \begin{pmatrix} \frac{x(t) - x(t_0)}{t - t_0} \\ \frac{y(t) - y(t_0)}{t - t_0} \end{pmatrix} = \lim_{t \rightarrow t_0} \frac{1}{t - t_0} \left( \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} - \begin{pmatrix} x(t_0) \\ y(t_0) \end{pmatrix} \right)$$

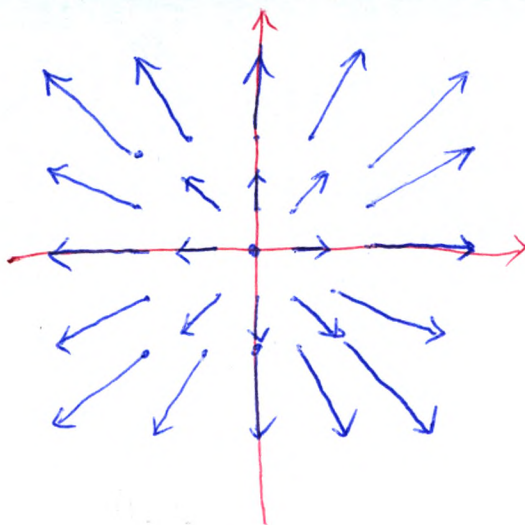


③  $F(Y)$ : Vector fields: at each  $Y = \begin{pmatrix} x \\ y \end{pmatrix}$ , attach to it the vector  $\begin{pmatrix} f(x,y) \\ g(x,y) \end{pmatrix}$ .





eg.  $\vec{F}(x,y) = \begin{pmatrix} x \\ y \end{pmatrix}$ .



$$Y'(t) = \vec{F}(Y) :$$

$\uparrow$   
 ~~$Y(t)$~~  tangent vectors.

ie. the curve  $Y(t)$   
 moves along the vector  
 field.

