MATH252 NOTES ON EIGENVALUES AND EIGENVECTORS

In this short note we recall the definition of eigenvalues and eigenvectors.

1. Definition of eigenvalues and eigenvectors

Definition 1.1. Let A be a $n \times n$ matrix. Then a number λ is called an **eigenvalue** of A if there is an non-zero vectors \vec{v} so that $A\vec{v} = \lambda \vec{v}$. In this case we call \vec{v} an **eigenvector** of A corresponding to λ .

Example 1.1. Let $A = \begin{pmatrix} 1 & 4 \\ 1 & 1 \end{pmatrix}$. Then $\lambda = 3$, and $\vec{v} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$ is an eigenvector since $A\vec{v} = \begin{pmatrix} 1 & 4 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix}$

$$= \begin{pmatrix} 1 \cdot 2 + 4 \cdot 1 \\ 1 \cdot 2 + 1 \cdot 1 \end{pmatrix}$$
$$= \begin{pmatrix} 6 \\ 3 \end{pmatrix}$$
$$= 3 \begin{pmatrix} 2 \\ 1 \end{pmatrix} = 3\vec{v}.$$

Remark 1. For a fixed eigenvalues, the eigenvectors are not unique: \vec{v} is an eigenvector, then so is $c\vec{v}$ for any non-zero number c.

Example 1.2. We will allow λ to be complex numbers and \vec{v} to be complex vectors (that is, the entries might be complex). For example, if

$$A = \begin{pmatrix} 2 & -1 \\ 1 & 2 \end{pmatrix},$$

then $\lambda = 2 + i$ is an eigenvalue of A with corresponding eigenvector $\vec{v} = \begin{pmatrix} i \\ 1 \end{pmatrix}$, since

$$A\vec{v} = \begin{pmatrix} 2 & -1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} i \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} 2i - 1 \\ i + 2 \end{pmatrix}$$

$$= \begin{pmatrix} 2i + i^2 \\ 2 + i \end{pmatrix} \qquad \text{(note that } i^2 = -1\text{)}$$

$$= (2+i) \begin{pmatrix} i \\ 1 \end{pmatrix} = (2+i)\vec{v}.$$

2. To find eigenvalues, eigenvectors

Given an $n \times n$ matrix A, the characteristic polynomial of A is given by

$$(2.1) p(\lambda) = \det(A - \lambda I),$$

where I is the identity matrix and det denote the determinant: we will recall the case for n=2: given a 2×2 matrix $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$, its determinant is given by

(2.2)
$$\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc.$$

One important properties of determinant is that an $n \times n$ matrix B is invertible if and only if $\det B \neq 0$. Indeed we have a formula for the inverse B^{-1} in terms of B and $\det B$. We recall only the formula for n = 2, which is

Example 2.1. If $A = \begin{pmatrix} 1 & 4 \\ 1 & 1 \end{pmatrix}$, then its characteristic polynomial is

$$p(\lambda) = \det(A - \lambda I)$$

$$= \det\begin{pmatrix} \begin{pmatrix} 1 & 4 \\ 1 & 1 \end{pmatrix} - \lambda \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \end{pmatrix}$$

$$= \det\begin{pmatrix} 1 - \lambda & 4 \\ 1 & 1 - \lambda \end{pmatrix}$$

$$= (1 - \lambda)(1 - \lambda) - 4$$

$$= \lambda^2 - 2\lambda - 3.$$

If λ is an eigenvalue of A with corresponding eigenvector \vec{v} , then $A\vec{v} = \lambda \vec{v}$, or

$$A\vec{v} - \lambda \vec{v} = 0.$$

Writing $\vec{v} = I\vec{v}$, where I is the identity matrix, we have

$$(2.4) (A - \lambda I)\vec{v} = 0.$$

In particular, we have

Theorem 2.1. A number λ is an eigenvalue of A if and only if λ is a root of the characteristic polynomial.

Proof. If λ is an eigenvalue, then (2.4) is satisfied. In particular, $\det(A - \lambda I)$ must be zero: if not, then $(A - \lambda I)^{-1}$ exists. Multiplying $(A - \lambda I)^{-1}$ to both sides of (2.4) gives $\vec{v} = 0$, which is not true by the definition of an eigenvector. Thus $\det(A - \lambda I)$ has to be zero.

This gives us a convenient way to find all possible eigenvalues.

Example 2.2. In example 2.1 we calculated the characteristic polynomial of $\begin{pmatrix} 1 & 4 \\ 1 & 1 \end{pmatrix}$, which is $\lambda^2 - 2\lambda - 3$. Either using factorization

$$\lambda^2 - 2\lambda - 3 = (\lambda - 3)(\lambda + 1)$$

or the quadratic formula, we found by Theorem 2.1 that 3 and -1 are the only eigenvalues of the matrix.

Next we indicate how to find an eigenvector corresponding to an eigenvalue. In general, when an eigenvalue λ is given, one can think of (2.4) as n linear equations with n-unknowns (given by the entries of \vec{v}), so that (2.4) can be solved by (e.g.) row reduction. We remark that in the simple situation n = 2, one can read off \vec{v} directly from the matrix $A - \lambda I$, using the following observations:

Lemma 2.1. Let B be a 2×2 matrix with det B = 0, then either

$$B = \begin{pmatrix} a & b \\ ka & kb \end{pmatrix} \quad or \quad \begin{pmatrix} ka & kb \\ a & b \end{pmatrix},$$

that is, the two row vectors are proportional to each other.

Proof. Write $B = \begin{pmatrix} a & b \\ ka & kb \end{pmatrix}$. Since det B = 0, we have ad = bc, or d/b = c/a. Write k = d/b (= c/a). Then

$$c = (d/b)a = ka$$
, $d = (c/a)b = kb$.

Using the above lemma, we have:

Proposition 2.1. If λ is an eigenvalue of A and

$$A - \lambda I = \begin{pmatrix} a & b \\ ka & kb \end{pmatrix},$$

then $\vec{v} = \begin{pmatrix} b \\ -a \end{pmatrix}$ is an eigenvector of A corresponding to λ .

Proof. To find the eigenvector, write $\vec{v} = \begin{pmatrix} x \\ y \end{pmatrix}$. Then (2.4) becomes

$$\begin{pmatrix} a & b \\ ka & kb \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix},$$

which is the same as

$$\begin{cases} ax + by = 0, \\ kax + kby = 0. \end{cases}$$

Note that the second equation is redundant since kax+kby=k(ax+by). Thus it suffices to find x,y so that ax+by=0. This is satisfied when $x=b,\ y=-a$. Thus $\vec{v}=\begin{pmatrix}b\\-a\end{pmatrix}$ is an eigenvector of A corresponding to λ .

Example 2.3. Using the same example $A = \begin{pmatrix} 1 & 4 \\ 1 & 1 \end{pmatrix}$, we calculated that the eigenvalues are 3 and -1. Next we find the corresponding eigenvectors:

• When $\lambda = 3$,

$$A - 3I = \begin{pmatrix} 1 - 3 & 4 \\ 1 & 1 - 3 \end{pmatrix} = \begin{pmatrix} -2 & 4 \\ 1 & -2 \end{pmatrix},$$

then $\vec{v} = \begin{pmatrix} 4 \\ 2 \end{pmatrix}$ is an eigenvector.

• When $\lambda = -1$,

$$A - (-1)I = \begin{pmatrix} 1 - (-1) & 4 \\ 1 & 1 - (-1) \end{pmatrix} = \begin{pmatrix} 2 & 4 \\ 1 & 2 \end{pmatrix},$$

then $\vec{v} = \begin{pmatrix} 4 \\ -2 \end{pmatrix}$ is an eigenvector.