

**01:640:252 ELEMENTARY DIFFERENTIAL EQUATIONS: HW6  
SOLUTION**

(1) For the following system, find and classify all equilibrium points.

$$\begin{cases} \frac{dx}{dt} = x(-x - 3y + 150), \\ \frac{dy}{dt} = y(-2x - y + 100). \end{cases}$$

**Solution** To find the equilibria, set

$$\begin{aligned} x(-x - 3y + 150) &= 0, \\ y(-2x - y + 100) &= 0. \end{aligned}$$

The first equation implies  $x = 0$  or  $-x - 3y + 150 = 0$ . If  $x = 0$ , then the second equation becomes

$$y(-y + 100) = 0 \Rightarrow y = 0 \text{ or } y = 100$$

and thus  $(0, 0)$ ,  $(0, 100)$  are two equilibria. If  $-x - 3y + 150 = 0$ , then  $x = -3y + 150$  and so

$$y(-2(-3y + 150) - y + 100) = 0 \Rightarrow y = 0 \text{ or } 40.$$

Putting it back to the first equations give another two equilibria  $(150, 0)$ ,  $(30, 40)$ .

The linearization is

$$D\mathcal{F}_{(x,y)} = \begin{pmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} \end{pmatrix} = \begin{pmatrix} -2x - 3y + 150 & -3x \\ -2y & -2x - 2y + 100 \end{pmatrix}$$

Next we calculate the trace and determinand at each equilibrium to find the type:

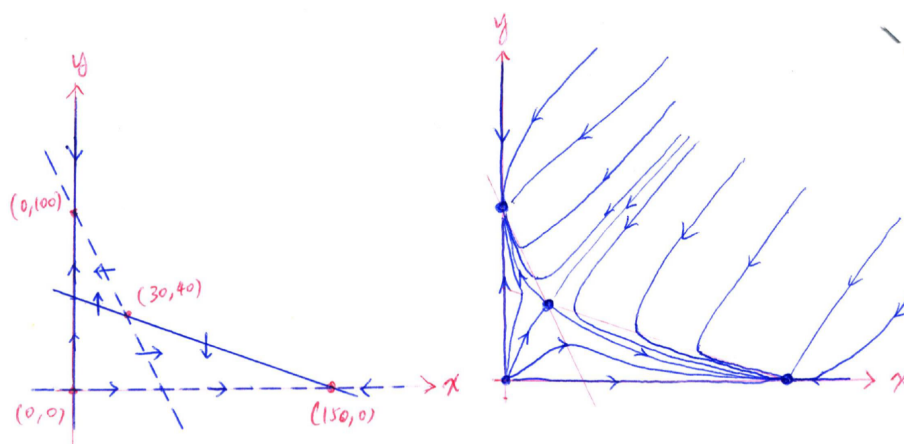
$$D\mathcal{F}_{(0,0)} = \begin{pmatrix} 150 & 0 \\ 0 & 100 \end{pmatrix} \Rightarrow \lambda = 150, 100 \Rightarrow \text{Source},$$

$$D\mathcal{F}_{(0,100)} = \begin{pmatrix} -150 & 0 \\ -200 & -100 \end{pmatrix} \Rightarrow \lambda = -150, -100 \Rightarrow \text{Sink},$$

$$D\mathcal{F}_{(150,0)} = \begin{pmatrix} -150 & -450 \\ 0 & -200 \end{pmatrix} \Rightarrow \lambda = -150, -450 \Rightarrow \text{Sink},$$

$$D\mathcal{F}_{(30,40)} = \begin{pmatrix} -30 & -90 \\ -80 & -40 \end{pmatrix} \Rightarrow \lambda = 120, -50 \Rightarrow \text{Saddle}.$$

(2) Sketch the  $x$ -nullcline and  $y$ -nullcline of the system in the previous question. Sketch the phase portrait.



(3) For the following system, find all equilibria.

$$\begin{cases} \frac{dx}{dt} = x(2 - x - y), \\ \frac{dy}{dt} = y(y - x^2). \end{cases}$$

**Solution** To find the equilibria, set

$$x(2 - x - y) = 0,$$

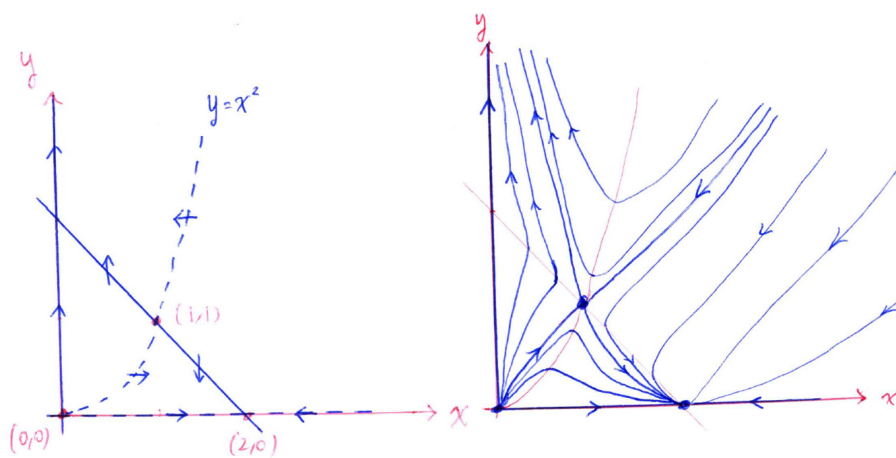
$$y(y - x^2) = 0.$$

The first equation implies  $x = 0$  or  $2 - x - y = 0$ . If  $x = 0$ , then the second equation becomes  $y^2 = 0$ , thus  $(0, 0)$  is one of the equilibrium. If  $2 - x - y = 0$ , then  $y = 2 - x$  and so

$$(2 - x)(2 - x - x^2) = 0 \Rightarrow x = 2 \text{ or } 1.$$

Putting it back to the first equations give another two equilibria  $(2, 0)$ ,  $(1, 1)$ .

(4) Sketch the  $x$ -nullcline and  $y$ -nullcline of the system in the previous question. Sketch the phase portrait.



- (5) For the following systems, check if it is Hamiltonian. If yes, find a Hamiltonian function.

$$(a) \begin{cases} x' = 3xy^2 + e^x + 1 \\ y' = -y^3 - e^x \end{cases}$$

**Solution:** Write

$$\begin{aligned} f &= 3xy^2 + e^x + 1, \\ g &= -y^3 - ye^x. \end{aligned}$$

Then

$$\begin{aligned} \frac{\partial f}{\partial x} &= 3y^2 + e^x, \\ \frac{\partial g}{\partial y} &= -3y^2 - e^x. \end{aligned}$$

Hence  $\frac{\partial f}{\partial x} \neq -\frac{\partial g}{\partial y}$  and the system is not Hamiltonian. To find the Hamiltonian function, let

$$\frac{\partial H}{\partial y} = 3xy^2 + e^x + 1,$$

integrating with respect to  $y$  gives

$$H = xy^3 + ye^x + y + C(x).$$

Then

$$\frac{\partial H}{\partial x} = y^3 + ye^x + C'(x)$$

since  $\frac{\partial H}{\partial x} = -g = y^3 + ye^x$ , we obtain  $C'(x) = 0$  and we choose  $C(x) = 0$ . Thus

$$H = xy^3 + ye^x + y.$$

is a Hamiltonian.

$$(b) \begin{cases} x' = 2y \cos(y^2) + x^2 e^y \\ y' = -2xe^y \end{cases},$$

**Solution:** Again this is Hamiltonian since

$$\frac{\partial f}{\partial x} = 2xe^y = -\frac{\partial g}{\partial y}$$

To find the Hamiltonian function, let

$$\frac{\partial H}{\partial y} = 2y \cos(y^2) + x^2 e^y,$$

integrating with respect to  $y$  gives

$$H = \sin(y^2) + x^2 e^y + C(x).$$

Then

$$\frac{\partial H}{\partial x} = 2xe^y + C'(x)$$

since  $\frac{\partial H}{\partial x} = -g = 2xe^y$ , we obtain  $C'(x) = 0$  and we choose  $C(x) = 0$ . Thus

$$H = \sin(y^2) + x^2 e^y.$$