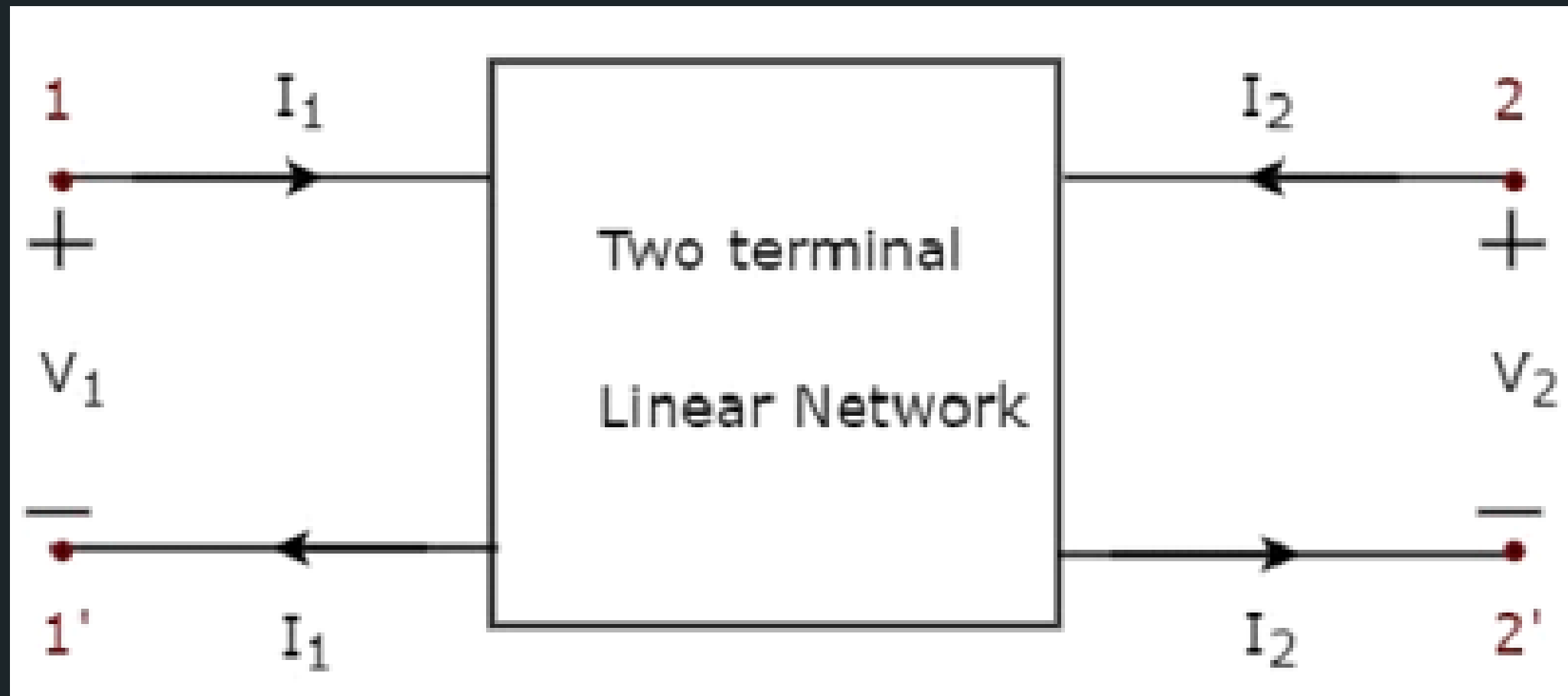


NAS PROJECT PRESENTATION



TWO PORT NETWORKS & IT'S APPLICATION

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PROJECT OUTLINE



POINTS FOR DISCUSSION

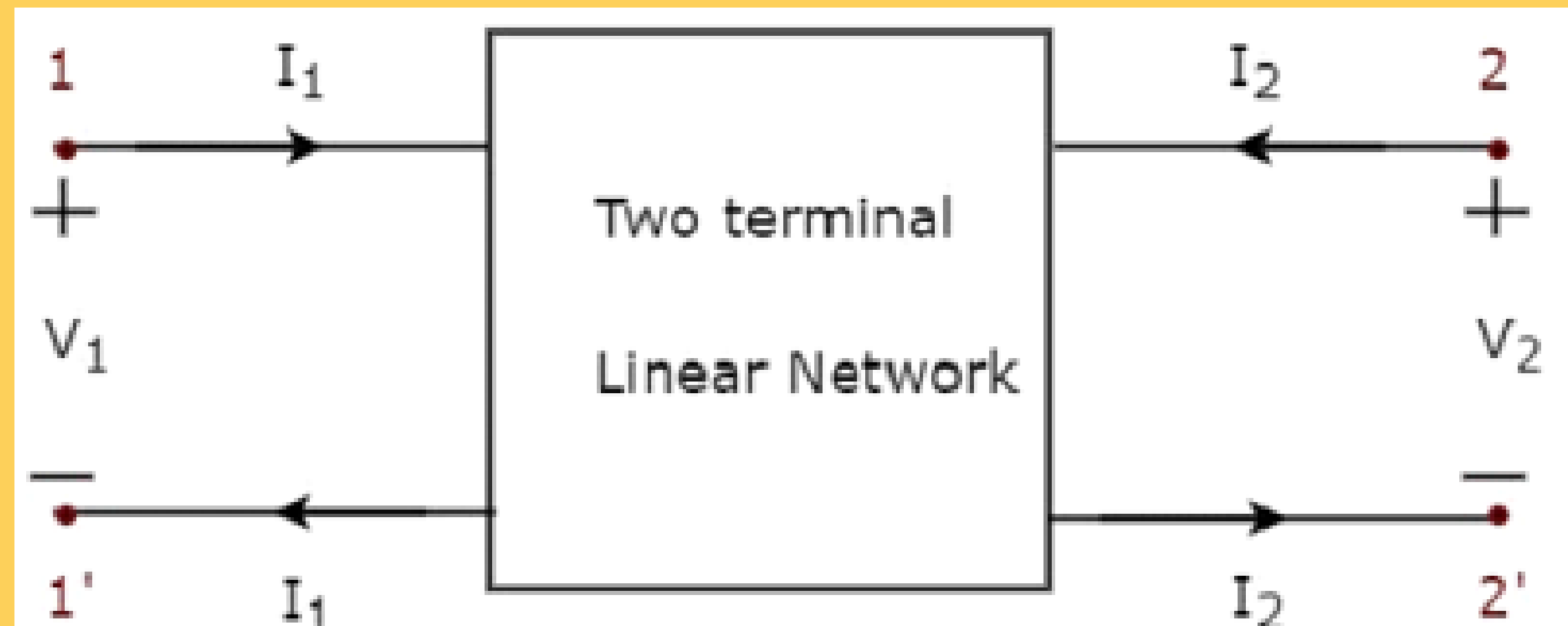
- INTRODUCTION- TWO PORT NETWORKS
- TWO PORT NETWORK PARAMETERS
- APPLICATION
- Two port network analysis for Wireless Power Transfer Systems (WPT)
- SIMULATIONS
- Two port network parameters using Proteus

INTRODUCTION- TWO PORT NETWORKS

- A two port network is an electrical network model with one pair of input terminals and one pair of output terminals.
- Commonly used to model the voltage and current characteristics of complex electrical networks.
- When an electrical signal is applied across the input ports, there would be an electrical signal across output ports.
- The relation between input and output signals of the network can be determined by transferring various network parameters.



- V_1 , voltage across port 1.
- I_1 , current into port 1.
- V_2 , voltage across port 2.
- I_2 , current into port 2.



TWO PORT NETWORKS PARAMETERS

$$\begin{aligned} z_{11} &\stackrel{\text{def}}{=} \left. \frac{V_1}{I_1} \right|_{I_2=0} & z_{12} &\stackrel{\text{def}}{=} \left. \frac{V_1}{I_2} \right|_{I_1=0} \\ z_{21} &\stackrel{\text{def}}{=} \left. \frac{V_2}{I_1} \right|_{I_2=0} & z_{22} &\stackrel{\text{def}}{=} \left. \frac{V_2}{I_2} \right|_{I_1=0} \end{aligned}$$

Z Parameters

- Also known as impedance parameters.
- The voltages are represented as the function of currents.
- They are also known as open-circuit impedance parameters.

The voltages are represented as-

$$\begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} z_{11} & z_{12} \\ z_{21} & z_{22} \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \end{bmatrix}$$

Y Parameters

$$\begin{aligned} y_{11} &\stackrel{\text{def}}{=} \left. \frac{I_1}{V_1} \right|_{V_2=0} & y_{12} &\stackrel{\text{def}}{=} \left. \frac{I_1}{V_2} \right|_{V_1=0} \\ y_{21} &\stackrel{\text{def}}{=} \left. \frac{I_2}{V_1} \right|_{V_2=0} & y_{22} &\stackrel{\text{def}}{=} \left. \frac{I_2}{V_2} \right|_{V_1=0} \end{aligned}$$

- Y parameter of is an admittance matrix.
- Matrix gives the relationship between input, output current and voltage of the network.
- Also known as short circuit admittance parameter.

In Y parameter, the current and voltage related by the following equations,

$$\begin{bmatrix} I_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} y_{11} & y_{12} \\ y_{21} & y_{22} \end{bmatrix} \begin{bmatrix} V_1 \\ V_2 \end{bmatrix}$$

“

$$\begin{aligned}
 h_{11} &\stackrel{\text{def}}{=} \left. \frac{V_1}{I_1} \right|_{V_2=0} & h_{12} &\stackrel{\text{def}}{=} \left. \frac{V_1}{V_2} \right|_{I_1=0} \\
 h_{21} &\stackrel{\text{def}}{=} \left. \frac{I_2}{I_1} \right|_{V_2=0} & h_{22} &\stackrel{\text{def}}{=} \left. \frac{I_2}{V_2} \right|_{I_1=0}
 \end{aligned}$$

H PARAMETER

- Also known as hybrid parameters.
- Voltage gain, current gain, impedance and admittance are used to determine relation between current and voltage of two port network.

Hence;

$$\begin{bmatrix} V_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{bmatrix} \begin{bmatrix} I_1 \\ V_2 \end{bmatrix}$$

$$A \stackrel{\text{def}}{=} \left. \frac{V_1}{V_2} \right|_{I_2=0} \quad B \stackrel{\text{def}}{=} - \left. \frac{V_1}{I_2} \right|_{V_2=0}$$

$$C \stackrel{\text{def}}{=} \left. \frac{I_1}{V_2} \right|_{I_2=0} \quad D \stackrel{\text{def}}{=} - \left. \frac{I_1}{I_2} \right|_{V_2=0}$$

ABCD PARAMETER

- The ABCD-parameters are known variously as chain, cascade, or transmission line parameters.
- For reciprocal networks $A.D-B.C=1$.
- For symmetrical networks $A=D$.

In matrix form it can be written as,

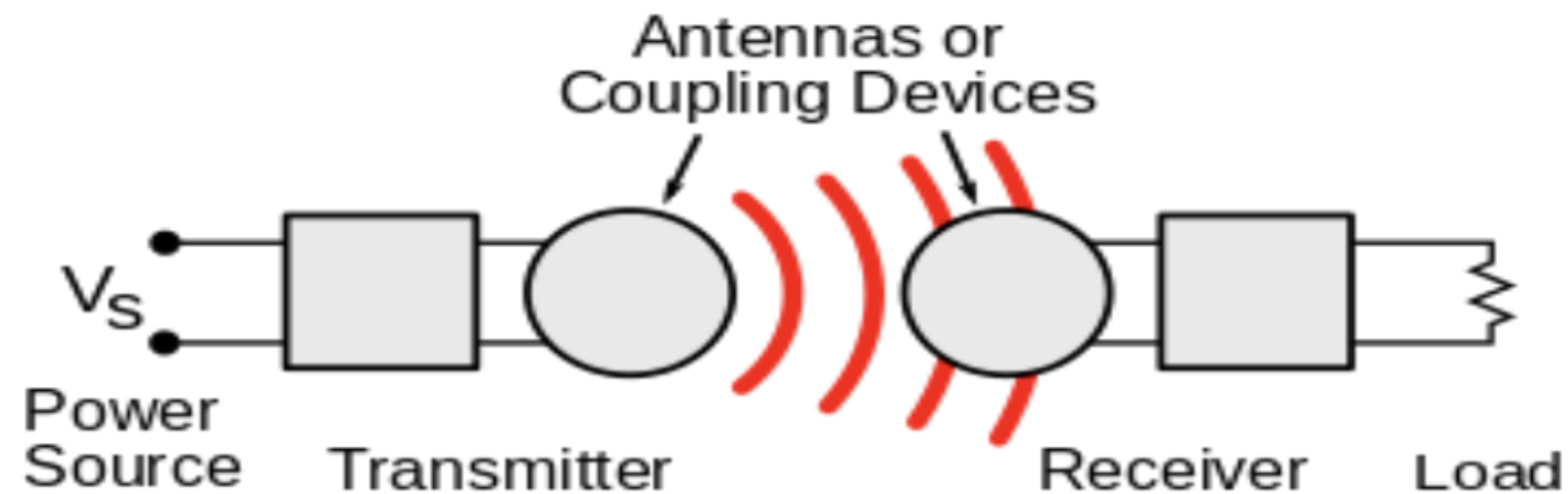
$$\begin{bmatrix} V_1 \\ I_1 \end{bmatrix} = \begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} V_2 \\ -I_2 \end{bmatrix}$$



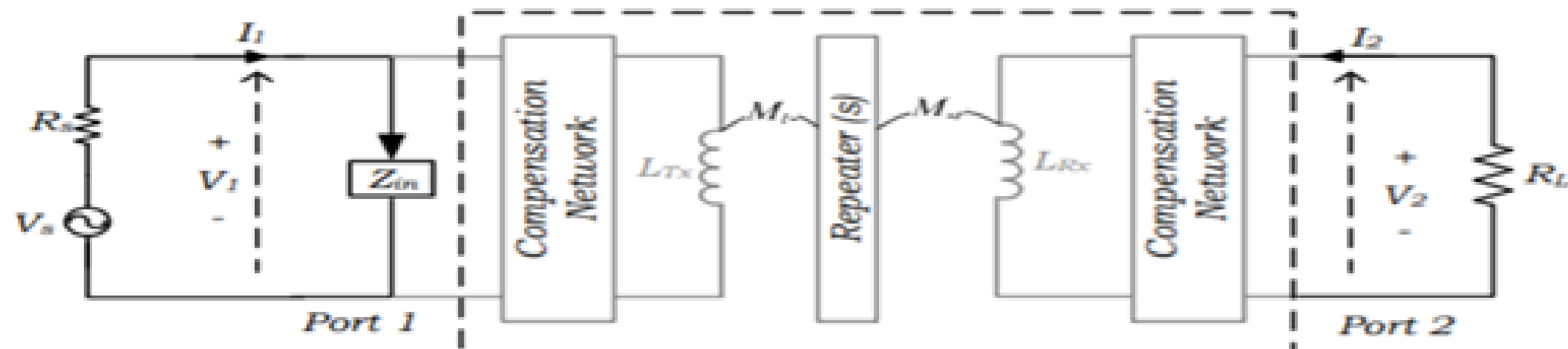
APPLICATION

WIRELESS POWER TRANSFER (WPT) SYSTEMS

- WPT is transmission of electrical energy without wires as a physical link.
- A transmitter device, driven by electric power generates a time-varying electromagnetic field, which transmits power across space to a receiver device.



- Regardless of the complexity of the WPT system, any single-Tx – single-Rx WPT system can be represented as a two-port network.



- The two-port network can be modelled using the impedance parameter matrix where Z_{11} , Z_{12} , Z_{21} , and Z_{22} are impedance parameters.

$$\begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} Z_{11} & Z_{12} \\ Z_{21} & Z_{22} \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \end{bmatrix}$$

- The input impedance, Z_{in} , seen at port 1, can be determined using,

$$Z_{in} = \frac{V_1}{I_1} = Z_{11} - \frac{Z_{12}Z_{21}}{Z_{22} + R_L}$$

- The input power (P_{in}) flowing into the two-port network, and the output power (P_{out}) received at the load are calculated.

$$P_{in} = |I_1|^2 \operatorname{Re}\{Z_{in}\} = \frac{|V_s|^2}{|Z_{in} + R_s|^2} \operatorname{Re}\{Z_{in}\}$$

and

$$P_{out} = |I_2|^2 R_L = \frac{|Z_{21}|^2 |V_s|^2}{|(Z_{in} + R_s)(Z_{22} + R_L)|^2} R_L$$

- The powers P_{in} , and P_{out} are dependent on the source voltage, Therefore, a number of gain parameters have been defined to represent normalized performance indices.
- Power gain (G_p), available gain (G_a) and transducer gain (G_t)

$$G_p = \frac{P_{out}}{P_{in}} = PTE$$

$$G_A = \frac{P_{out-max}}{P_{s-max}} = \frac{P_{out-max}}{|V_s|^2 / 8R_s}$$

$$G_T = \frac{P_{out}}{P_{s-max}} = \frac{P_{out}}{|V_s|^2 / 8R_s}$$

- G_p represents power transfer efficiency (PTE) of the WPT systems.
- Gain terms, G_a and G_t represent the maximum available output power ($P_{out-max}$) and output power (P_{out}) at a given operating point normalized to the maximum available input power at the source (P_{s-max}), respectively.

- The source impedance is negligibly small (i.e., a nearly ideal voltage source).
- Square voltage gain represents the ratio between the output power of the WPT system and the output power when the load is directly connected to the source.

$$PTE = \frac{P_{out}}{P_{in}} = \frac{|Z_{21}|^2}{|Z_{22} + R_L|^2} \frac{R_L}{(R_{in} + R_s)}$$

$$G_{V^2} = \left| \frac{V_2}{V_1} \right|^2 = \frac{|Z_{21}|^2 R_L^2}{|(Z_{in} + R_s)(Z_{22} + R_L)|^2}$$

- Therefore, it compares the power capability of the WPT system with the direct wired connection with the source. Hence, the source impedance is neglected for the subsequent analysis.

- The equivalent impedance parameters are written as where r_{ij} and x_{ij} are the real and imaginary parts, respectively.

$$Z_{11} = r_{11} + jx_{11}, Z_{22} = r_{22} + jx_{22}$$

$$Z_{12} = Z_{21} = r_{12} + jx_{12}$$

- The optimum value of x_{22} which gives maximum PTE, is computed by equating the derivative to zero, as

$$\frac{\partial(PTE)}{\partial x_{22}} = 0 \rightarrow x_{22,PTE_max} = \frac{r_{12}x_{12}}{r_{11}}$$

- The respective maximum PTE is found using-

$$PTE = \frac{r_{11} (x_{12}^2 + r_{12}^2) R_L}{(r_{11} (R_L + r_{22}) + x_{12}^2) (r_{11} (R_L + r_{22}) - r_{12}^2)}$$

- For a classical 2-coil WPT, x_{22} represents the reactive impedance of the Rx coil. Accordingly, for the classical 2-coil WPT, x_{22,PTE_max} is zero, since the value of r_{12} is made zero for to coincides with the well-known relation of maximum PTE at the resonance frequency of Rx.

- Since, x_{11} determines the reactive component of the input impedance. Therefore, the value of x_{11} can be chosen to make Z_{in} purely real,

$$\Im(Z_{in}) = 0 \rightarrow$$

$$x_{11, \Im(Z_{in})=0} = \frac{x_{22} (x_{12}^2 - r_{12}^2) + 2r_{12}x_{12} (R_L + r_{22})}{(R_L + r_{22})^2 + x_{22}^2}$$

- With the optimal values of x_{11} and x_{22} , G_{v2} reduces to-

$$G_{v2} = \frac{(r_{12}^2 + x_{12}^2) (r_{12}^2 x_{12}^2 + r_{11}^2 (R_L + r_{22})^2) R_L^2}{(x_{12}^2 + r_{11} (R_L + r_{22}))^2 (r_{11} (R_L + r_{22}) - r_{12}^2)^2}$$

- The optimal load which gives maximum efficiency can be derived as-

$$R_{22, PTE_max} = \frac{\sqrt{(r_{11}r_{22} + x_{12}^2)(r_{11}r_{22} - r_{12}^2)}}{r_{11}}$$

- If the load is assumed to be at its optimal value, the maximum efficiency (PTE_{max}) can be derived as-

$$PTE_{max} = 1 - \frac{2}{1 + \sqrt{1 + \left(\frac{x_{12}^2 + r_{12}^2}{r_{11}r_{22} - r_{12}^2} \right)}}$$

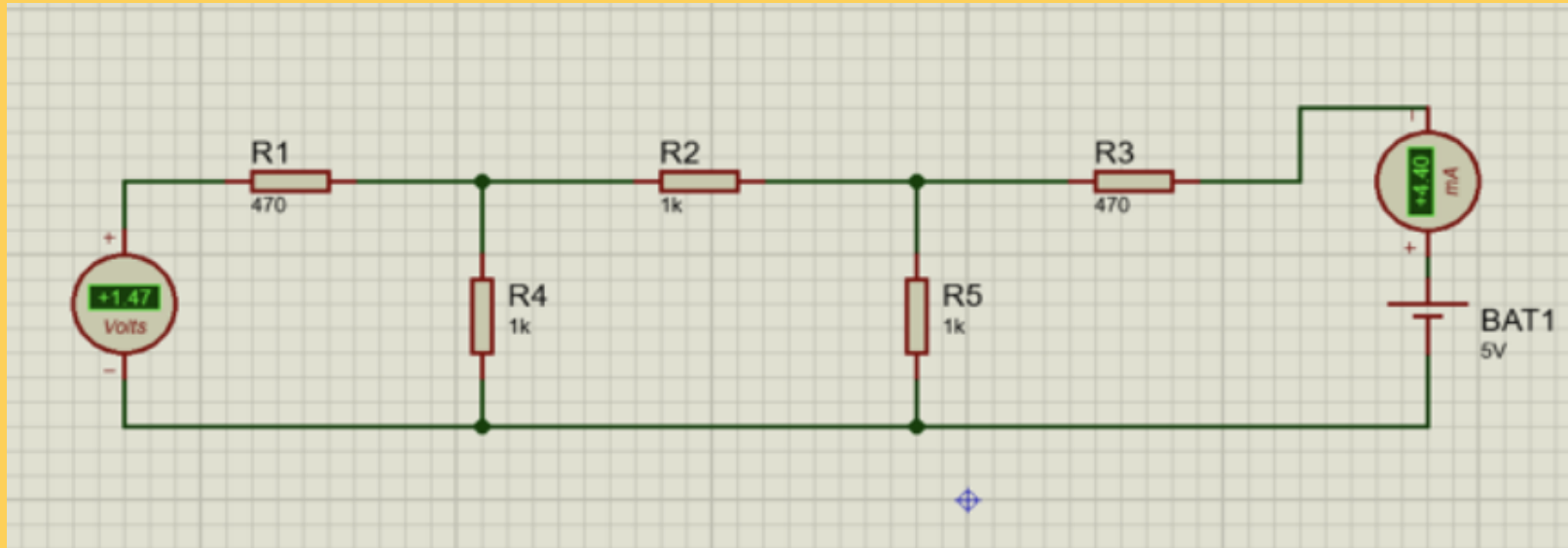
CONCLUSION

- It is observed from the above equations that GV2 is monotonically increasing with the increase of load resistance.
- Therefore, in terms of high Gv2, higher load resistance is always better. However, in practice, it is not required to maximize the voltage ratio.
- Instead, it is only required to keep the voltage ratio at a realistic value close to unity.
- One cannot maximize both PTE and the voltage ratio at the same time. The maximum efficiency condition may result in a lower voltage ratio.
- Therefore, a balance between PTE and GV2 should be considered.

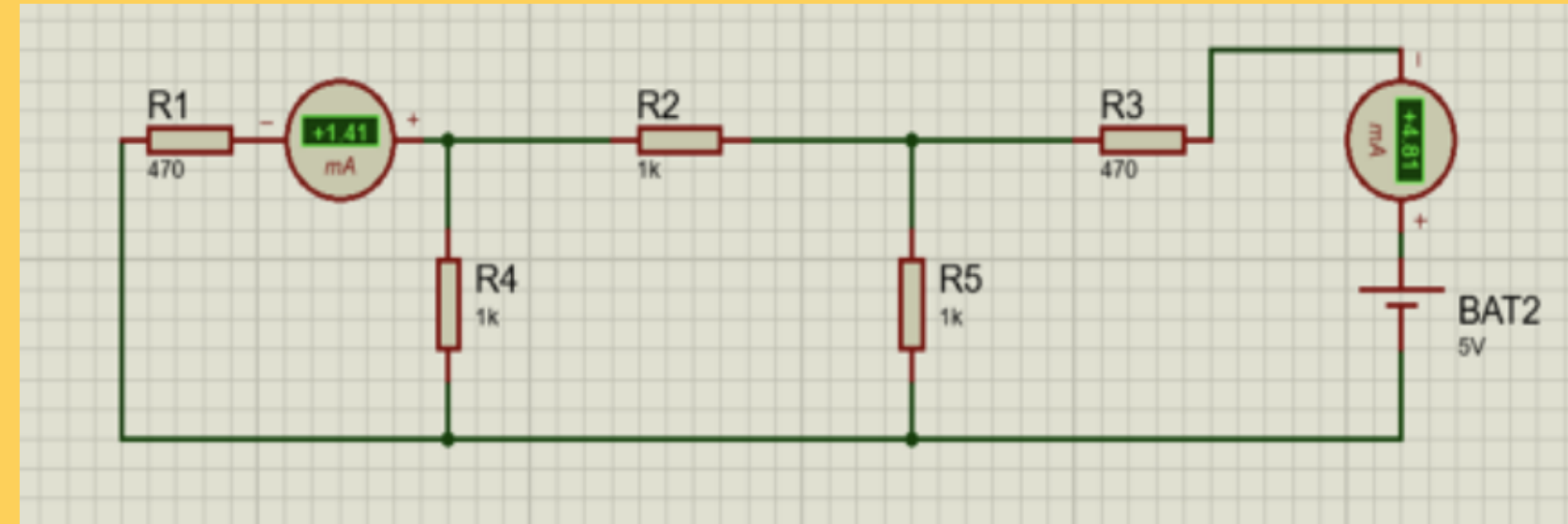
SIMULATIONS

Two port network parameters using Proteus

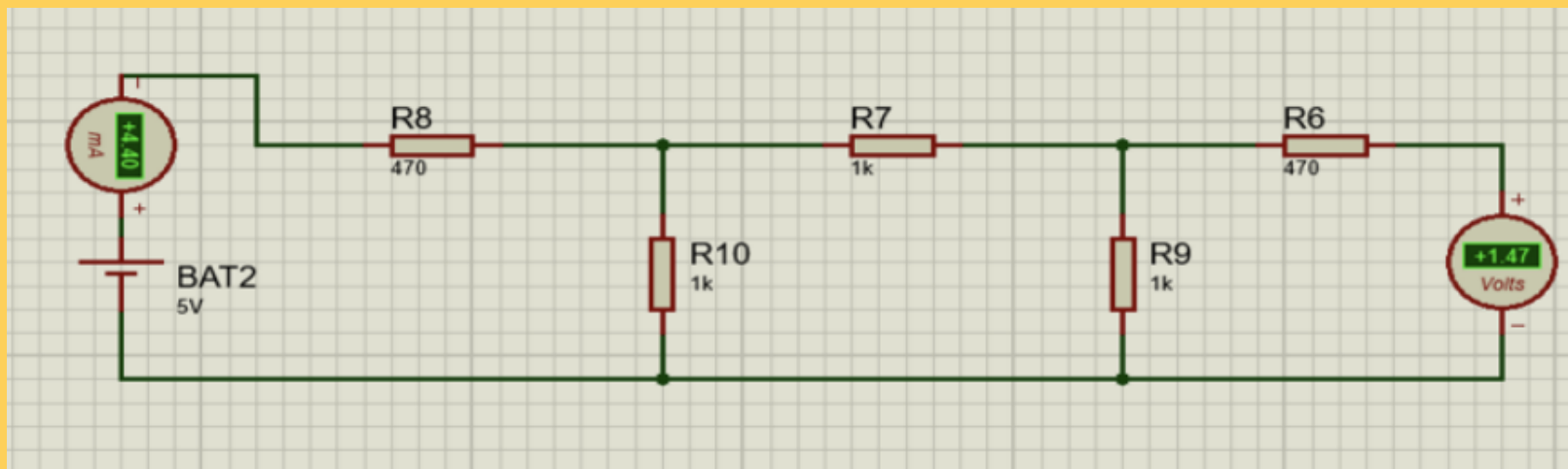
Z Parameter I/P is Open circuit



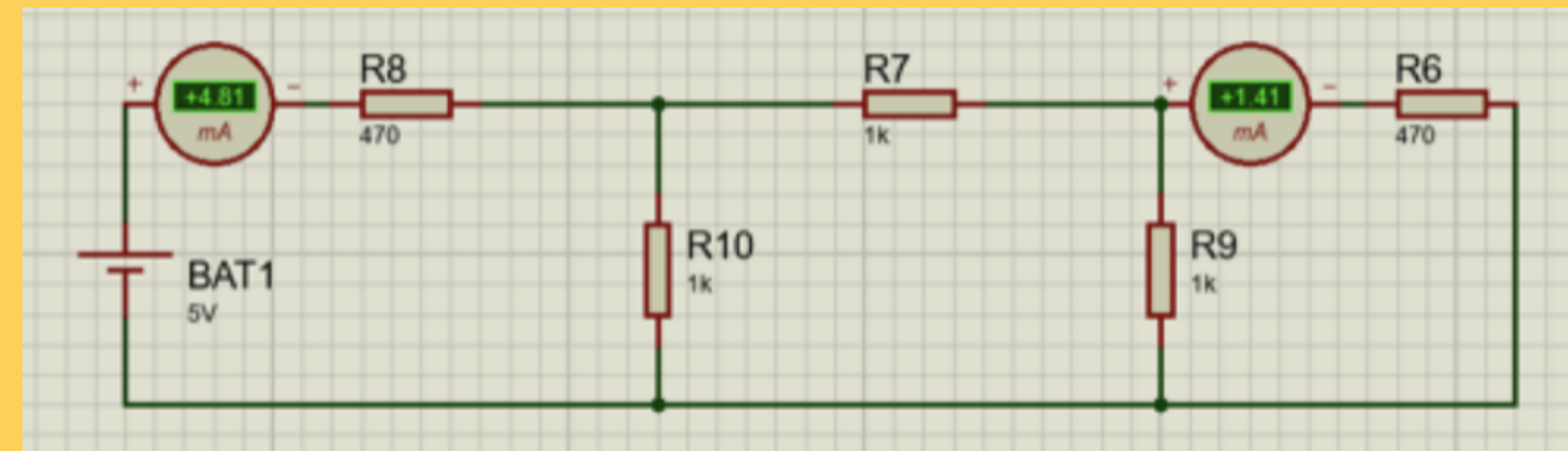
Y Parameter I/P is Short Circuit



Z Parameter O/P is Open circuit



Y Parameter O/P is Short Circuit



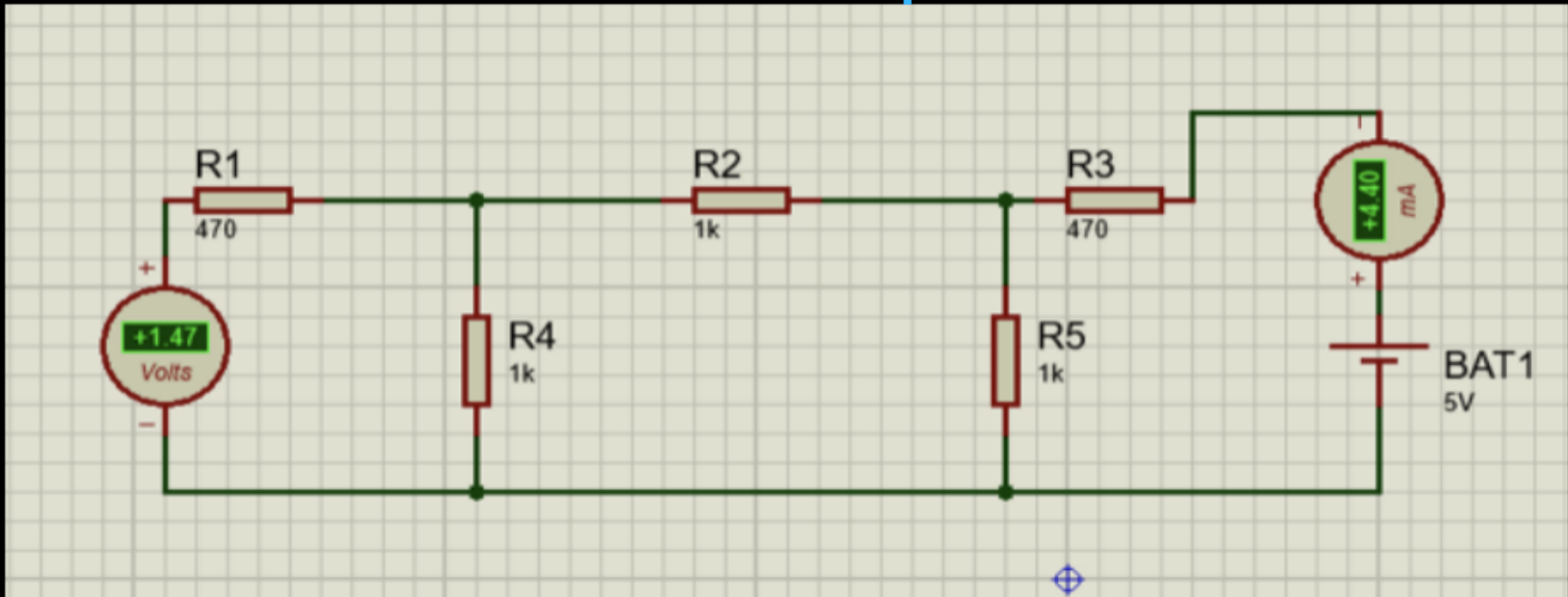
I/P Open Circuit			O/P Open Circuit		
V2	V1	I2	V2	V1	I1
5 V	1.47 V	4.40 mA	1.47 V	5 V	4.40 mA

Z11	Z12	Z21	Z22
1136.7	334.1	334.1	1136.7

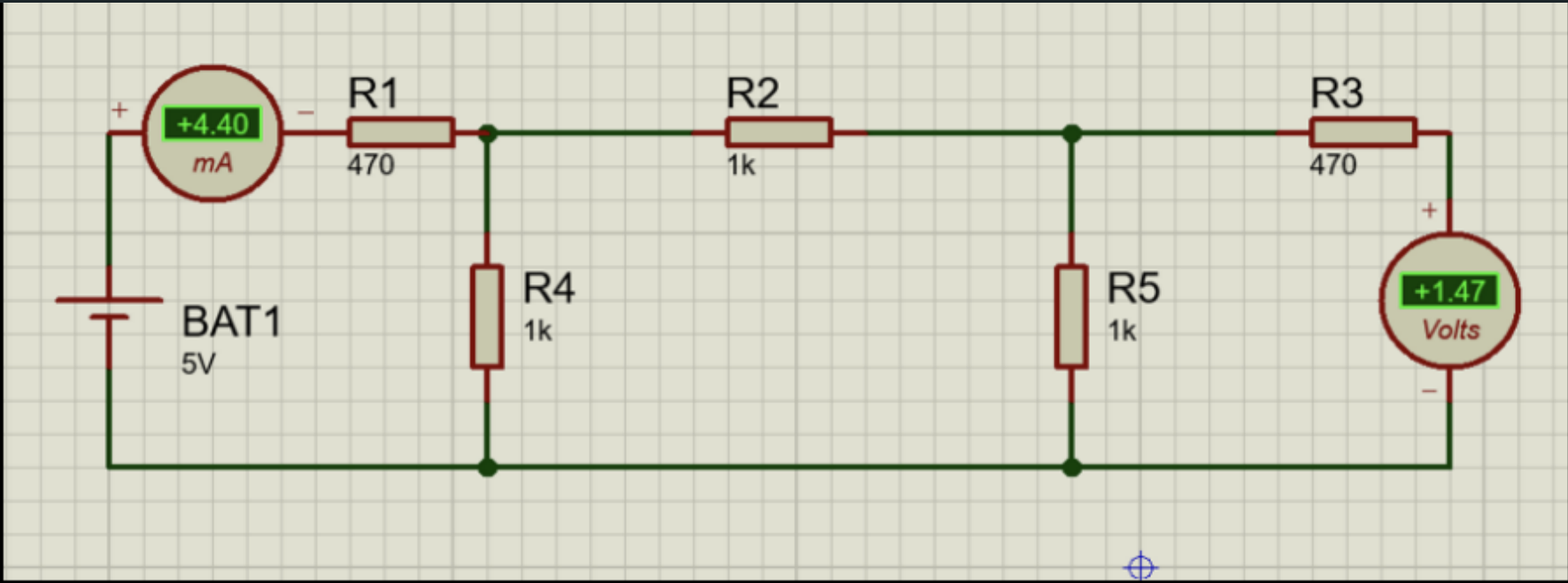
I/P Short Circuit			O/P Short Circuit		
V2	I1	I2	V1	I1	I2
5 V	1.41 mA	4.81 mA	5 V	4.81 mA	1.41 mA

Y11	Y12	Y21	Y22
9.62×10^{-4}	2.82×10^{-4}	2.82×10^{-4}	9.62×10^{-4}

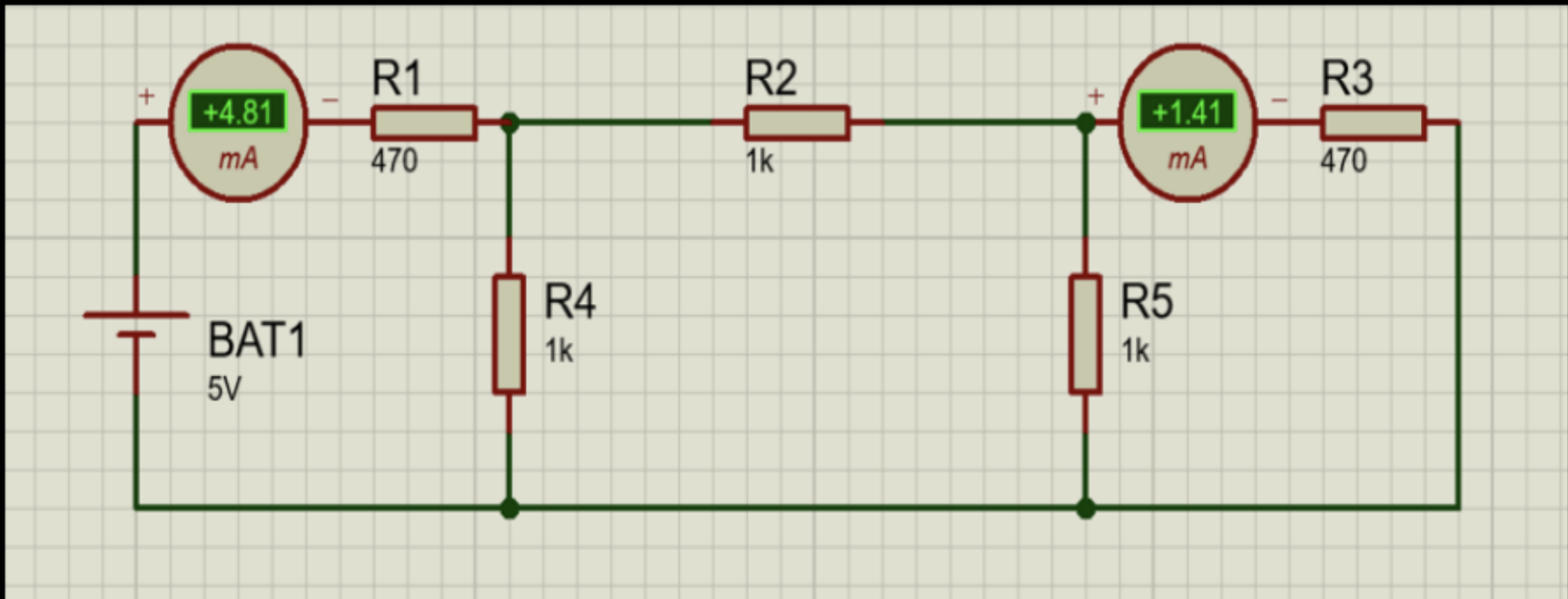
H Parameter I/P is Open circuit



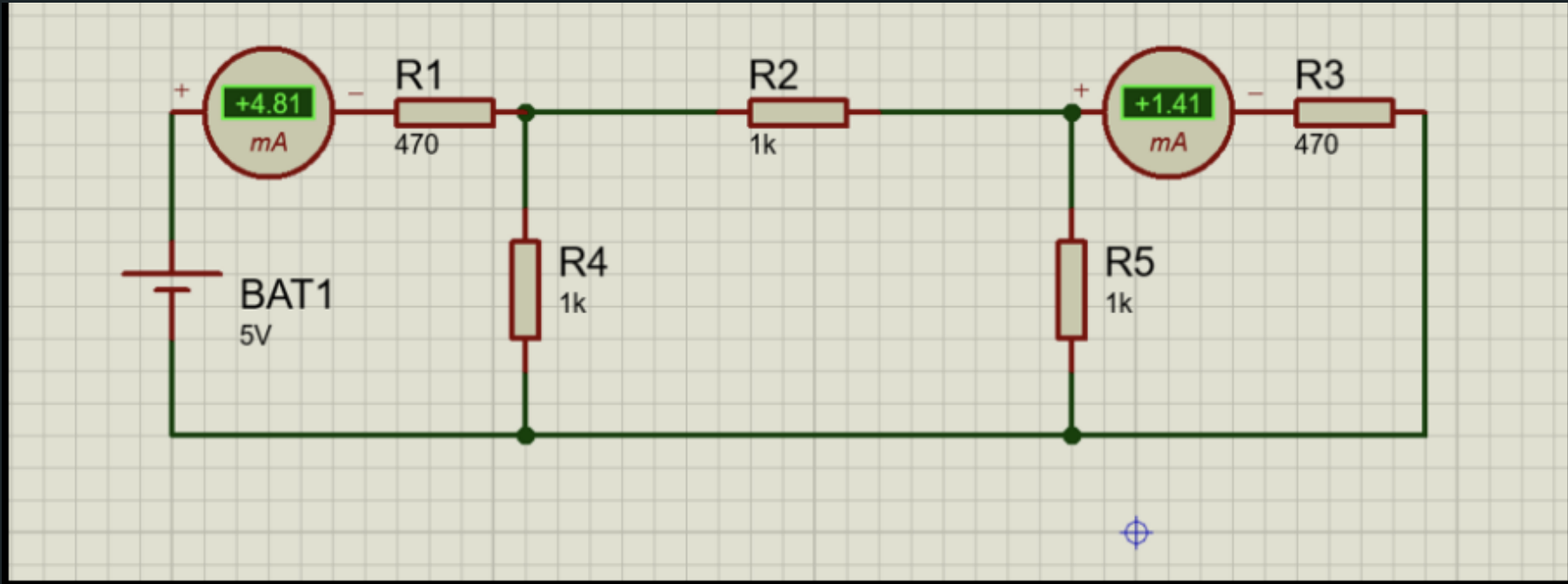
ABCD Parameter O/P is Open Circuit



H Parameter O/P is Short circuit



ABCD Parameter O/P is Short Circuit



I/P Open Circuit			O/P Short Circuit		
V1	V2	I2	V1	I1	I2
1.47 V	5 V	4.40 <u>mA</u>	5 V	4.81 <u>mA</u>	1.41 <u>mA</u>

H11	H12	H21	H22
1039.5	0.294	0.2931	8.8*10^-4

O/P Open Circuit			O/P Short Circuit		
V1	V2	I1	V1	I1	I2
5 V	1.47 V	4.40 <u>mA</u>	5 V	4.81 <u>mA</u>	1.41 <u>mA</u>

A	B	C	D
3.401	-3546.1	2.993*10^-3	-3.411

REFERENCES

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THANK

YOU