Goal

• Develop a structure that will allow user to insert/delete/find records in

constant average time

- structure will be a table (relatively small)
- table completely contained in memory
- implemented by an array
- capitalizes on ability to access any element of the array in *constant* time

Hash Function

- Determines position of key in the array.
- Assume table (array) size is N
- Function f(x) maps any key x to an int between 0 and N-1
- For example, assume that N=15, that key x is a non-negative integer between 0 and MAX_INT, and hash function f(x) = x % 15.
- (Hash functions for strings aggregate the character values --- see Weiss §5.2.)

Hash Function

Let
$$f(x) = x \% 15$$
. Then,
if $x = 25 129 35 2501 47 36$
 $f(x) = 10 9 5 11 2 6$

Storing the keys in the array is straightforward:

Thus, *delete* and *find* can be done in O(1), and also *insert*, except...

Hash Function

What happens when you try to insert: x = 65?

$$x = 65$$

$$f(x) = 5$$

This is called a *collision*.

Handling Collisions

- Separate Chaining
- Open Addressing
 - Linear Probing
 - Quadratic Probing
 - Double Hashing

Handling Collisions

Separate Chaining

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Let each array element be the head of a chain.

Where would you store: 29, 16, 14, 99, 127?

Separate Chaining

Let each array element be the head of a chain:

Where would you store: 29, 16, 14, 99, 127?

New keys go at the front of the relevant chain.

Separate Chaining: Disadvantages

- Parts of the array might never be used.
- As chains get longer, search time increases to O(n) in the worst case.
- Constructing new chain nodes is relatively expensive (still constant time, but the constant is high).
- Is there a way to use the "unused" space in the array instead of using chains to make more space?

Handling Collisions

Linear Probing

Let key x be stored in element f(x)=t of the array

What do you do in case of a collision?

If the hash table is *not full*, attempt to store key in the next array element (in this case (t+1)%N, (t+2)%N, (t+3)%N ...)

until you find an empty slot.

Where do you store 65?

0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 47 35 36 65 129 25 2501
$$\uparrow \quad \uparrow \quad \uparrow \quad \uparrow \quad$$
 attempts

Where would you store: 29?

If the hash table is *not full*, attempt to store key in array elements (t+1)%N, (t+2)%N, ...

Where would you store: 16?

If the hash table is *not full*, attempt to store key in array elements (t+1)%N, (t+2)%N, ...

Where would you store: 14?

If the hash table is *not full*, attempt to store key in array elements (t+1)%N, (t+2)%N, ...

Where would you store: 99?

If the hash table is *not full*, attempt to store key in array elements (t+1)%N, (t+2)%N, ...

0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 14 16 47 35 36 65 129 25 2501 99 29
$$\uparrow \uparrow \uparrow \uparrow \uparrow$$
 attempts

Where would you store: 127?

If the hash table is *not full*, attempt to store key in array elements (t+1)%N, (t+2)%N, ...

- Eliminates need for separate data structures (chains), and the cost of constructing nodes.
- Leads to problem of clustering. Elements tend to *cluster* in dense intervals in the array.

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- Search efficiency problem remains.
- Deletion becomes trickier....

Deletion problem

- H=KEY MOD 10
- Insert 47, 57, 68, 18, 67
- Find 68
- Find 10
- Delete 47
- Find 57

0	
1	
2	
3	
4	
2 3 4 5	
6	
7	
8	
9	_

Deletion Problem -- SOLUTION

- "Lazy" deletion
- Each cell is in one of 3 possible states:
 - active
 - empty
 - deleted
- For Find or Delete
 - only stop search when EMPTY state detected (not DELETED)

Deletion-Aware Algorithms

• Insert

- Cell empty or deleted
- Cell active

insert at H,
$$cell = active$$

H = (H + 1) mod TS

• Find

- cell empty
- cell deleted
- cell active

NOT found

$$H = (H + 1) \mod TS$$

if key == key in cell -> FOUND
else
$$H = (H + 1) \mod TS$$

Delete

- cell active; key != key in cell
- cell active; key == key in cell
- cell deleted
- cell empty

$$H = (H + 1) \mod TS$$

$$H = (H + 1) \mod TS$$

Handling Collisions

Quadratic Probing

Let key x be stored in element f(x)=t of the array

What do you do in case of a collision?

If the hash table is *not full*, attempt to store key in array elements $(t+1^2)\%N$, $(t+2^2)\%N$, $(t+3^2)\%N$... until you find an empty slot.

Where do you store 65? f(65)=t=5

Where would you store: 29?

If the hash table is *not full*, attempt to store key in array elements $(t+1^2)\%N$, $(t+2^2)\%N$...

Where would you store: 16?

If the hash table is *not full*, attempt to store key in array elements $(t+1^2)\%N$, $(t+2^2)\%N$...

Where would you store: 14?

If the hash table is *not full*, attempt to store key in array elements $(t+1^2)\%N$, $(t+2^2)\%N$...

Where would you store: 99?

If the hash table is *not full*, attempt to store key in array elements $(t+1^2)\%N$, $(t+2^2)\%N$...

Where would you store: 127?

If the hash table is *not full*, attempt to store key in array elements $(t+1^2)\%N$, $(t+2^2)\%N$...

Where would you store: 127?

- Tends to distribute keys better than linear probing
- Alleviates problem of clustering
- Runs the risk of an infinite loop on insertion, unless precautions are taken.
- E.g., consider inserting the key 16 into a table of size 16, with positions 0, 1, 4 and 9 already occupied.
- Therefore, table size should be prime.

Handling Collisions

Double Hashing

- Use a hash function for the decrement value
 - Hash(key, i) = $H_1(\text{key}) (H_2(\text{key}) * i)$
- Now the decrement is a function of the key
 - The slots visited by the hash function will vary even if the initial slot was the same
 - Avoids clustering
- Theoretically interesting, but in practice slower than quadratic probing, because of the need to evaluate a second hash function.

Let key x be stored in element f(x)=t of the array

Array:

What do you do in case of a collision?

Define a second hash function $f_2(x)=d$. Attempt to store key in array elements (t+d)%N, (t+2d)%N, (t+3d)%N ...

until you find an empty slot.

Typical second hash function

$$f_2(x) = R - (x \% R)$$

where R is a prime number, R < N

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Where do you store 65 ? f(65)=t=5
Let f_2(x)=11-(x\%11) f_2(65)=d=1
Note: R=11, N=15
Attempt to store key in array elements (t+d)\%N, (t+2d)\%N, (t+3d)\%N ...
```

Array:

If the hash table is *not full*, attempt to store key in array elements (t+d)%N, (t+d)%N ...

Let
$$f_2(x) = 11 - (x \% 11)$$
 $f_2(29) = d = 4$

Where would you store: 29?

Array:

If the hash table is *not full*, attempt to store key in array elements (t+d)%N, (t+d)%N ...

Let
$$f_2(x) = 11 - (x \% 11)$$
 $f_2(16) = d = 6$

Where would you store: 16?

Array:

Where would you store: 14?

If the hash table is *not full*, attempt to store key in array elements (t+d)%N, (t+d)%N ...

Let
$$f_2(x) = 11 - (x \% 11)$$
 $f_2(14) = d = 8$

Array:

Where would you store: 99?

If the hash table is *not full*, attempt to store key in array elements (t+d)%N, (t+d)%N ...

Let
$$f_2(x) = 11 - (x \% 11)$$
 $f_2(99) = d = 11$

Array:

Where would you store: 127?

If the hash table is *not full*, attempt to store key in array elements (t+d)%N, (t+d)%N ...

Let
$$f_2(x) = 11 - (x \% 11)$$
 $f_2(127) = d = 5$

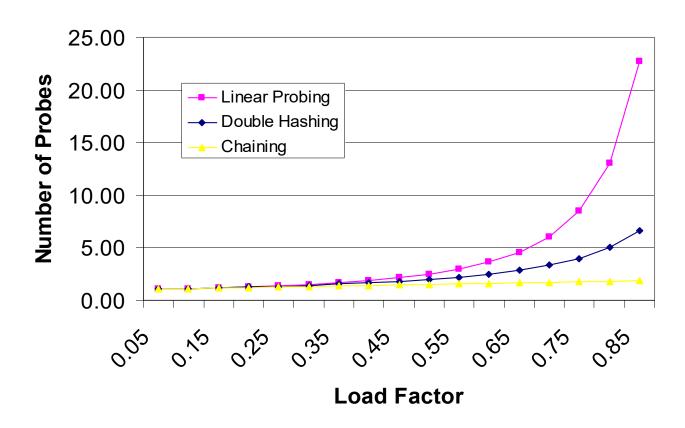
Array:

Infinite loop!

Performance

Load factor = % of table that's occupied.

Unsuccessful Search



REHASHING

- When the load factor exceeds a threshold, double the table size (smallest prime > 2 * old table size).
- Rehash each record in the old table into the new table.
- Expensive: O(N) work done in copying.
- However, if the threshold is large (e.g., ½), then we need to rehash only once per O(N) insertions, so the cost is "amortized" constant-time.

Factors affecting efficiency

- Choice of hash function
- Collision resolution strategy
- Load Factor

• Hashing offers excellent performance for insertion and retrieval of data.

Comparison of Hash Table & BST

BST HashTable

Average Speed $O(log_2N)$ O(1)

Find Min/Max Yes No

Items in a range Yes No

Sorted Input Very Bad No problems

Use HashTable if there is any suspicion of SORTED input & NO ordering information is required.