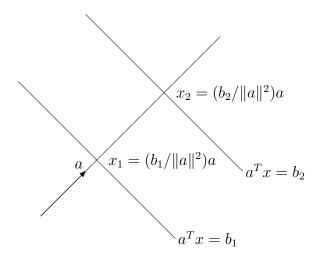
CVX101 Homework 1 solutions

2.5 What is the distance between two parallel hyperplanes $\{x \in \mathbf{R}^n \mid a^T x = b_1\}$ and $\{x \in \mathbf{R}^n \mid a^T x = b_2\}$?

Solution. The distance between the two hyperplanes is $|b_1 - b_2|/||a||_2$. To see this, consider the construction in the figure below.



The distance between the two hyperplanes is also the distance between the two points x_1 and x_2 where the hyperplane intersects the line through the origin and parallel to the normal vector a. These points are given by

$$x_1 = (b_1/||a||_2^2)a, x_2 = (b_2/||a||_2^2)a,$$

and the distance is

$$||x_1 - x_2||_2 = |b_1 - b_2|/||a||_2.$$

2.7 Voronoi description of halfspace. Let a and b be distinct points in \mathbf{R}^n . Show that the set of all points that are closer (in Euclidean norm) to a than b, i.e., $\{x \mid ||x-a||_2 \leq ||x-b||_2\}$, is a halfspace. Describe it explicitly as an inequality of the form $c^T x \leq d$. Draw a picture.

Solution. Since a norm is always nonnegative, we have $||x - a||_2 \le ||x - b||_2$ if and only if $||x - a||_2^2 \le ||x - b||_2^2$, so

$$||x - a||_2^2 \le ||x - b||_2^2 \iff (x - a)^T (x - a) \le (x - b)^T (x - b) \\ \iff x^T x - 2a^T x + a^T a \le x^T x - 2b^T x + b^T b \\ \iff 2(b - a)^T x \le b^T b - a^T a.$$

Therefore, the set is indeed a halfspace. We can take c = 2(b - a) and $d = b^T b - a^T a$. This makes good geometric sense: the points that are equidistant to a and b are given by a hyperplane whose normal is in the direction b - a.

2.12 Which of the following sets are convex?

- (a) A slab, i.e., a set of the form $\{x \in \mathbf{R}^n \mid \alpha \leq a^T x \leq \beta\}$.
- (b) A rectangle, i.e., a set of the form $\{x \in \mathbf{R}^n \mid \alpha_i \leq x_i \leq \beta_i, i = 1, \dots, n\}$. A rectangle is sometimes called a hyperrectangle when n > 2.
- (c) A wedge, i.e., $\{x \in \mathbf{R}^n \mid a_1^T x \le b_1, \ a_2^T x \le b_2\}.$
- (d) The set of points closer to a given point than a given set, i.e.,

$$\{x \mid ||x - x_0||_2 < ||x - y||_2 \text{ for all } y \in S\}$$

where $S \subseteq \mathbf{R}^n$.

(e) The set of points closer to one set than another, i.e.,

$$\{x \mid \mathbf{dist}(x, S) \leq \mathbf{dist}(x, T)\},\$$

where $S, T \subseteq \mathbf{R}^n$, and

$$\mathbf{dist}(x, S) = \inf\{ \|x - z\|_2 \mid z \in S \}.$$

- (f) [HUL93, volume 1, page 93] The set $\{x \mid x + S_2 \subseteq S_1\}$, where $S_1, S_2 \subseteq \mathbf{R}^n$ with S_1 convex.
- (g) The set of points whose distance to a does not exceed a fixed fraction θ of the distance to b, *i.e.*, the set $\{x \mid \|x-a\|_2 \leq \theta \|x-b\|_2\}$. You can assume $a \neq b$ and $0 \leq \theta \leq 1$.

Solution.

- (a) A slab is an intersection of two halfspaces, hence it is a convex set (and a polyhedron).
- (b) As in part (a), a rectangle is a convex set and a polyhedron because it is a finite intersection of halfspaces.
- (c) A wedge is an intersection of two halfspaces, so it is convex set. It is also a polyhedron. It is a cone if $b_1 = 0$ and $b_2 = 0$.
- (d) This set is convex because it can be expressed as

$$\bigcap_{y \in S} \{ x \mid ||x - x_0||_2 \le ||x - y||_2 \},$$

i.e., an intersection of halfspaces. (For fixed y, the set

$$\{x \mid ||x - x_0||_2 \le ||x - y||_2\}$$

is a halfspace; see exercise 2.9).

(e) In general this set is not convex, as the following example in **R** shows. With $S = \{-1, 1\}$ and $T = \{0\}$, we have

$$\{x \mid \mathbf{dist}(x, S) \le \mathbf{dist}(x, T)\} = \{x \in \mathbf{R} \mid x \le -1/2 \text{ or } x \ge 1/2\}$$

which clearly is not convex.

(f) This set is convex. $x + S_2 \subseteq S_1$ if $x + y \in S_1$ for all $y \in S_2$. Therefore

$${x \mid x + S_2 \subseteq S_1} = \bigcap_{y \in S_2} {x \mid x + y \in S_1} = \bigcap_{y \in S_2} (S_1 - y),$$

the intersection of convex sets $S_1 - y$.

(g) The set is convex, in fact a ball.

$$\{x \mid ||x - a||_2 \le \theta ||x - b||_2 \}$$

$$= \{x \mid ||x - a||_2^2 \le \theta^2 ||x - b||_2^2 \}$$

$$= \{x \mid (1 - \theta^2) x^T x - 2(a - \theta^2 b)^T x + (a^T a - \theta^2 b^T b) \le 0 \}$$

If $\theta = 1$, this is a halfspace. If $\theta < 1$, it is a ball

$$\{x \mid (x - x_0)^T (x - x_0) \le R^2\},\$$

with center x_0 and radius R given by

$$x_0 = \frac{a - \theta^2 b}{1 - \theta^2}, \qquad R = \left(\frac{\theta^2 \|b\|_2^2 - \|a\|_2^2}{1 - \theta^2} + \|x_0\|_2^2\right)^{1/2}.$$

- 2.15 Some sets of probability distributions. Let x be a real-valued random variable with $\mathbf{prob}(x=a_i)=p_i, i=1,\ldots,n$, where $a_1 < a_2 < \cdots < a_n$. Of course $p \in \mathbf{R}^n$ lies in the standard probability simplex $P=\{p \mid \mathbf{1}^T p=1, p \succeq 0\}$. Which of the following conditions are convex in p? (That is, for which of the following conditions is the set of $p \in P$ that satisfy the condition convex?)
 - (a) $\alpha \leq \mathbf{E} f(x) \leq \beta$, where $\mathbf{E} f(x)$ is the expected value of f(x), *i.e.*, $\mathbf{E} f(x) = \sum_{i=1}^{n} p_i f(a_i)$. (The function $f: \mathbf{R} \to \mathbf{R}$ is given.)
 - (b) $\operatorname{prob}(x > \alpha) \le \beta$.
 - (c) $\mathbf{E}|x^3| \le \alpha \mathbf{E}|x|$.
 - (d) $\mathbf{E} x^2 \le \alpha$.
 - (e) $\mathbf{E} x^2 \ge \alpha$.
 - (f) $\mathbf{var}(x) \le \alpha$, where $\mathbf{var}(x) = \mathbf{E}(x \mathbf{E} x)^2$ is the variance of x.
 - (g) $\operatorname{var}(x) \ge \alpha$.
 - (h) $\mathbf{quartile}(x) \ge \alpha$, where $\mathbf{quartile}(x) = \inf\{\beta \mid \mathbf{prob}(x \le \beta) \ge 0.25\}$.

(i) quartile(x) $\leq \alpha$.

Solution. We first note that the constraints $p_i \geq 0$, i = 1, ..., n, define halfspaces, and $\sum_{i=1}^{n} p_i = 1$ defines a hyperplane, so P is a polyhedron.

The first five constraints are, in fact, linear inequalities in the probabilities p_i .

(a) $\mathbf{E} f(x) = \sum_{i=1}^{n} p_i f(a_i)$, so the constraint is equivalent to two linear inequalities

$$\alpha \le \sum_{i=1}^{n} p_i f(a_i) \le \beta.$$

(b) $\operatorname{\mathbf{prob}}(x \geq \alpha) = \sum_{i: a_i \geq \alpha} p_i$, so the constraint is equivalent to a linear inequality

$$\sum_{i: a_i > \alpha} p_i \le \beta.$$

(c) The constraint is equivalent to a linear inequality

$$\sum_{i=1}^{n} p_i(|a_i^3| - \alpha |a_i|) \le 0.$$

(d) The constraint is equivalent to a linear inequality

$$\sum_{i=1}^{n} p_i a_i^2 \le \alpha.$$

(e) The constraint is equivalent to a linear inequality

$$\sum_{i=1}^{n} p_i a_i^2 \ge \alpha.$$

The first five constraints therefore define convex sets.

(f) The constraint

$$\operatorname{var}(x) = \mathbf{E} x^2 - (\mathbf{E} x)^2 = \sum_{i=1}^n p_i a_i^2 - (\sum_{i=1}^n p_i a_i)^2 \le \alpha$$

is not convex in general. As a counterexample, we can take n=2, $a_1=0$, $a_2=1$, and $\alpha=1/5$. p=(1,0) and p=(0,1) are two points that satisfy $\mathbf{var}(x) \leq \alpha$, but the convex combination p=(1/2,1/2) does not.

(g) This constraint is equivalent to

$$\sum_{i=1}^{n} p_i a_i^2 - (\sum_{i=1}^{n} p_i a_i)^2 = b^T p - p^T A p \ge \alpha,$$

where $b_i = a_i^2$ and $A = aa^T$. We write this as

$$p^T A p - b^T p + \alpha \le 0.$$

This defines a convex set, since the matrix aa^T is positive semidefinite. (See exercise 2.10.)

Let us denote $\mathbf{quartile}(x) = f(p)$ to emphasize it is a function of p. The figure illustrates the definition. It shows the cumulative distribution for a distribution p with $f(p) = a_2$.

(h) The constraint $f(p) \ge \alpha$ is equivalent to

$$\operatorname{prob}(x \leq \beta) < 0.25 \text{ for all } \beta < \alpha.$$

If $\alpha \leq a_1$, this is always true. Otherwise, define $k = \max\{i \mid a_i < \alpha\}$. This is a fixed integer, independent of p. The constraint $f(p) \geq \alpha$ holds if and only if

$$\operatorname{prob}(x \le a_k) = \sum_{i=1}^k p_i < 0.25.$$

This is a strict linear inequality in p, which defines an open halfspace.

(i) The constraint $f(p) \leq \alpha$ is equivalent to

$$\operatorname{\mathbf{prob}}(x \leq \beta) \geq 0.25 \text{ for all } \beta \geq \alpha.$$

Here, let us define $k = \max\{i \mid a_i \leq \alpha\}$. Again, this is a fixed integer, independent of p. The constraint $f(p) \leq \alpha$ holds if and only if

$$\operatorname{prob}(x \le a_k) = \sum_{i=1}^k p_i \ge 0.25.$$

If $\alpha < a_1$, then no p satisfies $f(p) \leq \alpha$, which means that the set is empty. Thus, the constraint $f(p) \leq \alpha$ is a linear inequality on p.

2.28 Positive semidefinite cone for n = 1, 2, 3. Give an explicit description of the positive semidefinite cone \mathbf{S}_{+}^{n} , in terms of the matrix coefficients and ordinary inequalities, for n = 1, 2, 3. To describe a general element of \mathbf{S}^{n} , for n = 1, 2, 3, use the notation

$$x_1, \qquad \left[\begin{array}{ccc} x_1 & x_2 \\ x_2 & x_3 \end{array} \right], \qquad \left[\begin{array}{cccc} x_1 & x_2 & x_3 \\ x_2 & x_4 & x_5 \\ x_3 & x_5 & x_6 \end{array} \right].$$

Solution. A symmetric matrix X is positive semidefinite if and only if all principal minors (determinants of symmetric submatrices) are nonnegative. For n = 1 the condition is just $x_1 \ge 0$. For n = 2 the condition is

$$x_1 \ge 0,$$
 $x_3 \ge 0,$ $x_1 x_3 - x_2^2 \ge 0.$

For n=3 the condition is

$$x_1 \ge 0,$$
 $x_4 \ge 0,$ $x_6 \ge 0,$ $x_1 x_4 - x_2^2 \ge 0,$ $x_4 x_6 - x_5^2 \ge 0,$ $x_1 x_6 - x_3^2 \ge 0$

and

$$x_1 x_4 x_6 + 2x_2 x_3 x_5 - x_1 x_5^2 - x_6 x_2^2 - x_4 x_3^2 \ge 0.$$

A1.7 Dual cones in \mathbb{R}^2 . Describe the dual cone for each of the following cones.

- (a) $K = \{0\}.$
- (b) $K = \mathbf{R}^2$.
- (c) $K = \{(x_1, x_2) \mid |x_1| \le x_2\}.$
- (d) $K = \{(x_1, x_2) \mid x_1 + x_2 = 0\}.$

Solution.

(a) $K^* = \mathbf{R}^2$. To see this:

$$K^* = \{ y \mid y^T x \ge 0 \text{ for all } x \in K \}$$
$$= \{ y \mid y^T 0 \ge 0 \}$$
$$= \mathbf{R}^2.$$

- (b) $K^* = \{0\}$. To see this, we need to identify the values of $y \in \mathbf{R}^2$ for which $y^T x \ge 0$ for all $x \in \mathbf{R}^2$. But given any $y \ne 0$, consider the choice x = -y, for which we have $y^T x = -\|y\|_2^2 < 0$. So the only possible choice is y = 0 (which indeed satisfies $y^T x \ge 0$ for all $x \in \mathbf{R}^2$).
- (c) $K^* = K$. (This cone is self-dual.)
- (d) $K^* = \{(x_1, x_2) \mid x_1 x_2 = 0\}$. Here K is a line, and K^* is the line orthogonal to it.