Mode jumping MCMC
Particle MCMC
Reversible jump MCMC
Non-reversible MCMC
Continuous time Markov processes
Additional topics in MCMC
Practice

#### Additional topics on Monte Carlo

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Geilo Winter school 2023



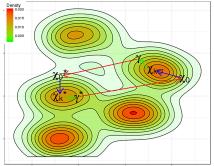
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#### Outline

- Mode jumping MCMC
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- MCMC: Work reasonable well for unimodal distributions
  - Struggle more with multimodal distributions



- Several possible approaches:
  - Simulated tempering: Use  $\pi_k(\mathbf{x}) = \pi_k(\mathbf{x})^{T_k}$ ,  $T_k \leq 1$ , move between differet "models"
  - SMC: Similar sequence
- Here: Mode jumping MCMC Tjelmeland and Hegstad (2001)

3/23

### Mode jumping MCMC

- Aim: Allow for large changes
- Main problem: Large move in space will typically result in low density value
  - M-H: Very low acceptance rate
- Main idea
  - Make a large change  $\mathbf{x} \to \mathbf{x}_0^*$
  - 2 Perform a local optimization  $\mathbf{x}_0^* \to \mathbf{x}_k^*$ 
    - Possibly through k steps of some optimization routine
  - **3** Small perturbation:  $\mathbf{x}_k^* \to \mathbf{x}^*$
  - Accept x\* through an M-H step
- M-H: Detailed balance require possibility for moving backwards as well
  - The small perturbation in step 3 makes this possible



### Algorithm

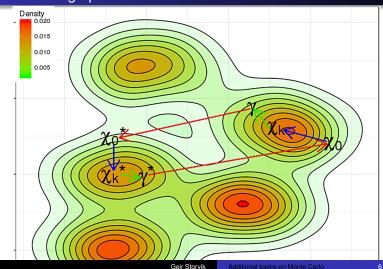
#### Algorithm 1 MJMCMC step from current state x

- 1: Generate  $\mathbf{x}_0^* = \mathbf{x}^* + \varepsilon^*, \, \varepsilon^* \sim \textit{N}(\mathbf{0}, \sigma_L^2 \mathbf{R}), \, \sigma_L \, \text{large}$
- 2: Optimize  $\mathbf{x}_0^* \to \mathbf{x}_k^*$
- 3: Small perturbation:  $\mathbf{x}^* \sim g_S(\mathbf{x}^* | \mathbf{x}_k^*)$
- 4: Generate  $\mathbf{x}_0 = \mathbf{x}^* \varepsilon^*$
- 5: Optimize  $\mathbf{x}_0 \rightarrow \mathbf{x}_k$
- 6: Calculate

$$r = \frac{\pi(\mathbf{x}^*)q_r(\mathbf{x}|\mathbf{x}_k)}{\pi(\mathbf{x})q_r(\mathbf{x}^*|\mathbf{x}_k^*)}$$

7: Accept  $x^*$  with probability min{1, r}

## MJMCMC - graphical illustration



#### MCMCMC for model selection

Consider a model

$$egin{align} y_i \sim & f(y_i; \eta_i, \phi) \ & \eta_i = & eta_0 + \sum_{j=1}^p \gamma_j eta_j z_{i,j} \ & \gamma_j \sim & \mathsf{Bern}(q) \ & eta_j | \gamma_j = 1 \sim & \mathsf{N}(0, \sigma_eta^2) \ \end{pmatrix}$$

- Aim:  $p(\gamma|y)$ .
- $2^p$  possible models, in addtion unknown  $\beta_j$ 's
- Possible:  $p(\gamma, \beta|y)$  through Reversible jump MCMC
- Pseudo-Marginal MCMC:
  - lacktriangle Generate proposal  $oldsymbol{\gamma}^*$  from  $oldsymbol{\gamma}$
  - ② Accept  $\gamma^*$  with probability min{1, r} where

$$r = \frac{p(\boldsymbol{\gamma}^*|\boldsymbol{y})g(\boldsymbol{\gamma}|\boldsymbol{\gamma}^*)}{p(\boldsymbol{\gamma}|\boldsymbol{y})g(\boldsymbol{\gamma}^*|\boldsymbol{\gamma})}$$

- Hubin and Storvik (2018): Linear models
- Hubin et al. (2021): Neural network type modes



### Particle MCMC

- Andrieu et al. (2010)
- Ideal MCMC  $(p(\theta|\mathbf{y}) \propto p(\theta)L(\theta))$ :
  - **1** Sample  $\theta^* \sim g(\theta^*|\theta)$
  - 2 Calculate M-H ratio  $r = \frac{p(\theta^*)L(\theta^*)g(\theta|\theta^*)}{p(\theta)L(\theta)g(\theta^*|\theta)}$
  - **3** Accept  $\theta^*$  with prob min $\{1, r\}$

#### Particle MCMC

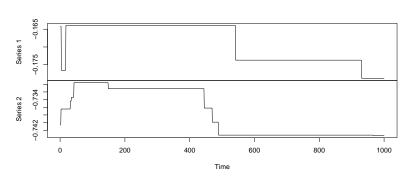
- Andrieu et al. (2010)
- Ideal MCMC  $(p(\theta|\mathbf{y}) \propto p(\theta)L(\theta))$ :
  - **1** Sample  $\theta^* \sim g(\theta^*|\theta)$
  - 2 Calculate M-H ratio  $r = \frac{p(\theta^*)L(\theta^*)g(\theta|\theta^*)}{p(\theta)L(\theta)a(\theta^*|\theta)}$
  - **3** Accept  $\theta^*$  with prob min $\{1, r\}$
- Pseudo-Marginal algorithm:
  - **1** Sample  $\theta^* \sim g(\theta^*|\theta)$
  - ② Calculate  $\hat{L}(\theta^*)$
  - **3** Calculate M-H ratio  $\hat{r} = \frac{\pi(\theta^*)p(\theta|\theta^*)}{\pi(\theta)p(\theta^*|\theta)}$
  - 4 Accept  $\theta^*$  with prob min $\{1, \hat{r}\}$
- Particle MCMC: Use SMC to calculate  $\hat{L}(\theta^*)$



### Lemmings - AR(2) process

Now: 
$$x_t = a_1 x_{t-1} + a_2 x_{t-2} + \varepsilon_t$$

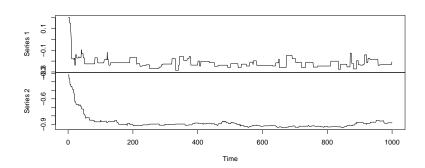
a.M



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a.M



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### Reversible jump MCMC

- Examples of changing dimensions
  - $Y_i = \beta_0 + \sum_{i=1}^p \gamma_i \beta_i x_{ii} + \varepsilon_i$
  - Neural networks with some weights put to zero.
- Reversible Jump MCMC
  - Assume several models M<sub>1</sub>, ..., M<sub>K</sub>
  - Corresponding parameters  $\theta_1, ..., \theta_K$  of different dimensions!
  - Aim: Simulate  $\mathbf{x} = (\mathcal{M}, \theta_{\mathcal{M}})$
  - RJMCMC: Green (1995)
  - RJMCMC: M-H method for moving between spaces of different dimensions
  - Main challenge: When changing  $\mathcal{M} \to \mathcal{M}^*$ , how to propose  $\theta_{\mathcal{M}^*}$ ?



Non-reversible MCMC Continuous time Markov processes Additional topics in MCMC

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Non-reversible MCMC Continuous time Markov processes Additional topics in MCMC Practice

### Changing dimensions

- Assume several models  $\mathcal{M}_1, ..., \mathcal{M}_K$
- Corresponding parameters  $\theta_1, ..., \theta_K$  of different dimensions!
- Aim: Simulate  $\mathbf{x} = (\mathcal{M}, \boldsymbol{\theta}_{\mathcal{M}})$
- RJMCMC: M-H method for moving between spaces of different dimensions
- Main challenges:
  - When changing dimensions, how to compare densities on different spaces?
  - When changing  $\mathcal{M} \to \mathcal{M}^*$ , how to propose  $\theta_{\mathcal{M}^*}$ ?



Non-reversible MCMC Continuous time Markov processes Additional topics in MCMC

Practice

### Reversible jump MCMC

- Green (1995): Include auxiliary variables to match dimensions.
- $\bullet$  Consider change  $(\mathcal{M}_1,\theta_1)$  to  $(\mathcal{M}_2,\theta_2)$  with  $|\theta_1|<|\theta_2|$ 
  - $j(1 \rightarrow 2)$  probability for moving from  $\mathcal{M}_1$  to  $\mathcal{M}_2$
- Algorithm
  - Generate  $\mathbf{u}_1$  such that  $|\theta_1| + |\mathbf{u}_1| = |\theta_2|$
  - 2 Propose  $\theta_2 = \theta_2(\theta_1, \mathbf{u}_1)$  (bijective)
  - Calculate acceptance ratio

$$r = \frac{\pi(\mathcal{M}_2, \theta_2)q(2 \to 1)}{\pi(\mathcal{M}_1, \theta_1)q(1 \to 2)q(\mathbf{u}_1)} \left| \frac{\partial(\theta_2)}{\partial(\theta_1, \mathbf{u}_1)} \right|$$

- Accept with probability min{1, r}.
- Use 1/r for opposite move
- More general settings possible



Non-reversible MCMC

Continuous time Markov processes

Additional topics in IviCivi

Practice

### Logistic regression

Assume model

$$Y_i \sim \mathsf{Binom}(p_i)$$
  $\mathsf{logit}(p_i) = eta_0 + \sum_{j=1}^p \gamma_j eta_j x_{ij}$   $\mathsf{Pr}(\gamma_j = 1) = q$   $eta_j | \gamma_j = 1 \sim \mathcal{N}(0, \sigma_eta^2)$ 

- Assume  $\gamma_i = 0$ , want to change to  $\gamma_i^* = 1$
- Generate  $u_1 \sim g_j()$
- Put

$$\beta_k^* = \begin{cases} \beta_k & k \neq j; \\ u_1 & k = j. \end{cases}$$

Accept with probabilty min{1, r} where

$$r = \frac{\pi(\boldsymbol{\beta}^*, \boldsymbol{\gamma}^*)}{\pi(\boldsymbol{\beta}, \boldsymbol{\gamma})g_j(\boldsymbol{\beta}_i^*)} \times 1$$

Script Log\_reg\_RJ.R



Continuous time Markov processes Additional topics in MCMC

Practice

#### Non-reversible MCMC

• Main criterion ( $\pi$ -invariance)

$$\pi(\mathbf{x}^*) = \int_{\mathbf{x}} \pi(\mathbf{x}) P(\mathbf{x}^* | \mathbf{x}) d\mathbf{x}$$

Sufficient criterion for stationarity

$$\pi(\mathbf{x})P(\mathbf{x}^*|\mathbf{x}) = \pi(\mathbf{x}^*)P(\mathbf{x}|\mathbf{x}^*)$$
 Detailed balance

 Results in a reversible MCMC (moving backwards is similar to moving forwards) Continuous time Markov processes

Additional topics in MCMC

Practice

#### Non-reversible MCMC

Main criterion (π-invariance)

$$\pi(\mathbf{x}^*) = \int_{\mathbf{x}} \pi(\mathbf{x}) P(\mathbf{x}^* | \mathbf{x}) d\mathbf{x}$$

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 Detailed balance

- Results in a reversible MCMC (moving backwards is similar to moving forwards)
- Assume now  $x \in \mathcal{Z}$
- Introduce  $v \in \{-1, 1\}$  and consider extended distribution  $\bar{\pi}(x, v) = 0.5\pi(x)I(v \in \{-1, 1\})$ .
- Define Markov chain

$$P(x^*, v|x, w) = \alpha(x, v)I(x^* = x + v, w = v) + (1 - \alpha(x, v))I(x^* = x, w = -v)$$

with  $\alpha(x, v) = \min\{1, \pi(x + v)/\pi(x)\}$ 



Additional topics in MCMC Practice

### The zig-zag process

- Continuous-time Markov process
- Can use sub-sampling with an exact approximate scheme
- Can be super-efficient when combined with control-covariate ideas
- References: Bierkens et al. (2019) (and references therein)
- Main idea:
  - Move all components lineary in a given direction:  $x_i(t) = x_i^k + z_i^k t$
  - Change direction of  $z_i^k$  at random (continuous) time points

#### Additional topics in MCMC

Practice

### Algorithm

Let 
$$(T^0, \mathbf{x}^0, \boldsymbol{\theta}^0) = (0, \xi, \theta)$$
 for  $k = 1, 2, \cdots$  do

Let  $\boldsymbol{\xi}^k(t) \equiv \mathbf{x}^{k-1} + \boldsymbol{\theta}^{k-1}t, t \geq 0$ 
For  $i = 1, ..., p$ , let  $\tau_i^k$  be distributed according to

$$\Pr(\tau_i^k \geq t) = \exp\left(-\int_0^t \lambda_i(\boldsymbol{\xi}^k(s), \mathbf{z}^{k-1})ds\right)$$
Let  $i_0 \equiv \arg\min_{i \in \{1, ..., p\}} \tau_i^k$ 
Let  $T^k \equiv T^{k-1} + \tau_{i_0}^k$ 
Let  $\mathbf{x}^k \equiv \boldsymbol{\xi}^k(T^k)$ 
Let
$$z_i^k = \begin{cases} z_i^{k-1} & \text{if } i \neq i_0 \\ -z_i^{k-1} & \text{if } i = i_0 \end{cases}$$

end for



### Trajectories

• Piecewise deterministic trajectories ( $\mathbf{x}(t)$ ,  $\theta(t)$ ):

$$(\mathbf{x}(t), \theta(t)) = (\mathbf{x}^k + \mathbf{z}^k(t - T^k), \mathbf{z}^k)$$
 for  $t \in [T^k, T^{k+1}), k = 0, 1, 2 \cdots$ 

Monte Carlo estimate:

$$\hat{\mu}_{i} = \frac{1}{T} \int_{0}^{T} x_{i}(t)dt$$

$$= \frac{1}{T} \sum_{k=0}^{K} \int_{T^{k}}^{T^{k+1}} [x_{i}^{k} + z_{i}^{k}(t - T^{k})]dt$$

$$= x_{i}^{k} (T^{k+1} - T^{k}) + 0.5z_{i}^{k} (T^{k+1} - T^{k})^{2}$$

#### Additional topics in MCMC Practice

### What does it converge to?

- Distribution depending om the functions  $\lambda_i(\xi, \mathbf{z})$ .
- **●** Assume  $\theta_i$  ∈ {−1, 1}
- Assume a Bayesian setting:

$$p(\mathbf{x}|\mathbf{y}) \propto p(\mathbf{x})p(\mathbf{y}|\mathbf{x})$$

Define

$$\Psi(\mathbf{x}) = -\log p(\mathbf{x}) - \log p(\mathbf{y}|\mathbf{x})$$

$$\lambda_i(\boldsymbol{x}, \boldsymbol{\theta}) = (\theta_i \partial_i \Psi(\boldsymbol{x}))^+ + \gamma_i(\boldsymbol{x}, \boldsymbol{\theta})$$

where  $\gamma_i$  is non-negative and  $\gamma_i(\mathbf{x}, \theta) = \gamma_i(\mathbf{x}, \theta_{-i})$  with  $\theta_{-i}$  is equal to  $\theta$  except for the *i*th component which is flipped.

- Then (under some regularity conditions)
  - The Zig-Zag process has p(x|y) as invariant distribution
  - The process is ergodic:

$$\lim_{t\to\infty}\int_0^t f(\boldsymbol{x}(s))ds = \int f(\boldsymbol{x})\pi(\boldsymbol{x}|\boldsymbol{y})d\boldsymbol{x}$$



Practice

### Additional topics in MCMC

- Adaptive MCMC: Automatic tuning of proposal distributions
  - Main challenge: Specifying proposal based on history of chain breaks down the Markov property
  - Solution: Reduce the amount of tuning as the number of iterations increases

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  - Solution: Reduce the amount of tuning as the number of iterations increases
- Simulated tempering
  - Define  $f^i(\mathbf{x}) \propto \pi(\mathbf{x})^{1/\tau_i}$ ,  $1 = \tau_1 < \tau_2 < \cdots < \tau_m$
  - Simulate (x, I), where I changes distribution
  - Easier to move around when  $\tau_i > 1$
  - Keep samples for which I = 1

### Additional topics in MCMC

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  - Simulate (x, I), where I changes distribution
  - Easier to move around when  $\tau_i > 1$
  - Keep samples for which I = 1
- Multiple-Try M-H
  - Generate k proposals  $\mathbf{x}_1^*$ , ...,  $\mathbf{x}_k^*$  from  $g(\cdot|\mathbf{x}^{(t)})$
  - Select  $\pmb{x}_j^*$  with probability  $w(\pmb{x}^{(t)}, \pmb{x}_j^*) = \pi(\pmb{x}^{(t)})g(\pmb{x}_j^*|\pmb{x}^{(t)})\lambda(\pmb{x}^{(t)}, \pmb{x}_j^*)$ ,  $\lambda$  symmetric
  - Sample  $\mathbf{x}_1^{**},...,\mathbf{x}_{k-1}^{**}$  from  $g(\cdot|\mathbf{x}_i^*)$ , put  $\mathbf{x}_k^{**}=\mathbf{x}^{(t)}$
  - Use Generalized M-H ratio

$$R_g = \frac{\sum_{i=1}^{k} w(\mathbf{x}^{(t)}, \mathbf{x}_i^*)}{\sum_{i=1}^{k} w(\mathbf{x}_i^*, \mathbf{x}_i^{**})}$$



# Implement your SMC algorithm

- Consider the model for lemmings data
- Model

$$\begin{aligned} & \mathbf{y}_{t} \sim & \mathsf{Binom}\left(1, \frac{\exp(\mathbf{x}_{t})}{1 + \exp(\mathbf{x}_{t})}\right) \\ & \mathbf{x}_{t} = & \mathbf{a}\mathbf{x}_{t-1} + \varepsilon_{t}, \quad \varepsilon_{t} \sim N(0, \sigma^{2}) \\ & a \sim & \mathsf{Uniform}[0, 1] \end{aligned}$$

Use 
$$a = 0.5$$
,  $\sigma = 1$ 

• Some data are missing: How to handle this?



### Implement your MCMC algorithm

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Use 
$$a = 0.5$$
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• Note: if only changing  $x_t \to x_t^*$ :

$$\frac{\pi(\mathbf{x}^*)}{\pi(\mathbf{x})} = \frac{p(x_t^*|x_{t-1})p(x_{t+1}|x_t^*)p(y_t|x_t^*)}{p(x_t|x_{t-1})p(x_{t+1}|x_t)p(y_t|x_t)}$$



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#### References

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