# **Chapter 7: Deadlocks**

### **CS370 Operating Systems**

### **Objectives:**

- Description of deadlocks, which prevent sets of concurrent processes from completing their tasks
- Different methods for preventing or avoiding deadlocks in a computer system

#### Slides based on

- Text by Silberschatz, Galvin, Gagne
- Berkeley Operating Systems group
- S. Pallikara
- Other sources

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# Chapter 7: Deadlocks

- System Model
- Deadlock Characterization
- Methods for Handling Deadlocks
- Deadlock Prevention
- Deadlock Avoidance
- Deadlock Detection
- Recovery from Deadlock

## A Kansas Law

- Early 20<sup>th</sup> century
- "When two trains approach each other at a crossing, both shall come to a full stop and neither shall start up again until the other has gone"
- Story of the two goats



# A Gridlock





APITOL

GRIDLOCK+

BEEP!

# System Model

- System consists of resources
- Resource types  $R_1, R_2, ..., R_m$ CPU cycles, memory space, I/O devices
- Each resource type  $R_i$  has  $W_i$  instances.
- Each process utilizes a resource as follows:
  - request
  - use
  - release

## **Deadlock Characterization**

Deadlock can arise if four conditions hold simultaneously.

- Mutual exclusion: only one process at a time can use a resource
- Hold and wait: a process holding at least one resource is waiting to acquire additional resources held by other processes
- No preemption: a resource can be released only voluntarily by the process holding it, after that process has completed its task
- Circular wait: there exists a set  $\{P_0, P_1, ..., P_n\}$  of waiting processes such that  $P_0$  is waiting for a resource that is held by  $P_1, P_1$  is waiting for a resource that is held by  $P_2, ..., P_{n-1}$  is waiting for a resource that is held by  $P_n$ , and  $P_n$  is waiting for a resource that is held by  $P_0$ .

## Deadlock with Mutex Locks

- Deadlocks can occur via system calls, locking, etc.
- See example box in text page 318 for mutex deadlock

In this example, thread one attempts to acquire the mutex locks in the order (1) first mutex, (2) second mutex, while thread two attempts to acquire the mutex locks in the order (1) second mutex, (2) first mutex. Deadlock is possible if thread one acquires first mutex while thread two acquires second mutex.

# Resource-Allocation Graph

A set of vertices V and a set of edges E.

- V is partitioned into two types:
  - $-P = \{P_1, P_2, ..., P_n\}$ , the set consisting of all the processes in the system
  - $-R = \{R_1, R_2, ..., R_m\}$ , the set consisting of all resource types in the system
- request edge directed edge  $P_i \rightarrow R_j$
- assignment edge directed edge  $R_j \rightarrow P_i$

# Resource-Allocation Graph (Cont.)

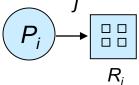
Process



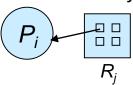
Resource Type with 4 instances



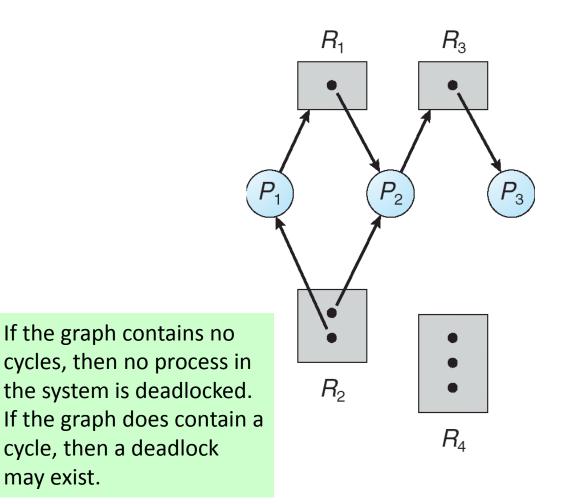
•  $P_i$  requests instance of  $R_i$ 



•  $P_i$  is holding an instance of  $R_i$ 

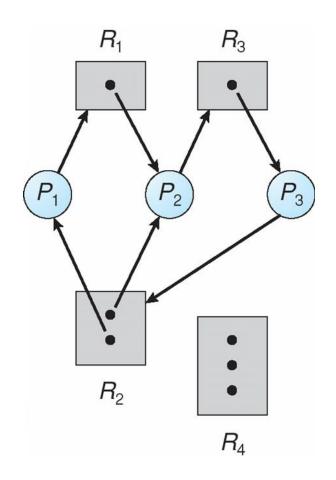


#### Example of a Resource Allocation Graph



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#### Resource Allocation Graph With A Deadlock



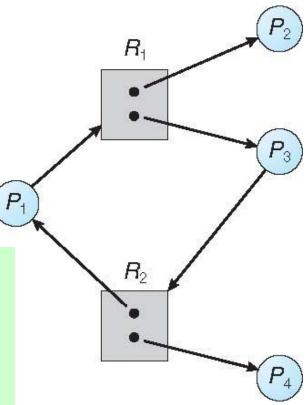
At this point, two minimal cycles exist in the system:  $P1 \rightarrow R1 \rightarrow P2 \rightarrow R3 \rightarrow P3 \rightarrow R2 \rightarrow P1$   $P2 \rightarrow R3 \rightarrow P3 \rightarrow R2 \rightarrow P2$  Processes P1, P2, and P3 are deadlocked.

# Graph With A Cycle But No Deadlock

There is no deadlock. *P4* may release its instance of resource type *R2*. That resource can then be allocated to *P3*, breaking the cycle

If a resource-allocation graph does not have a cycle, then the system is **not** in a deadlocked state.

If there is a cycle, then the system may or may not be in a deadlocked state.



## **Basic Facts**

- If graph contains no cycles ⇒ no deadlock
- If graph contains a cycle ⇒
  - if only one instance per resource type,
     then deadlock
  - if several instances per resource type, possibility of deadlock

# Methods for Handling Deadlocks

- Ensure that the system will never enter a deadlock state:
  - Deadlock prevention
  - Deadlock avoidence
- Allow the system to enter a deadlock state and then recover
- Ignore the problem and pretend that deadlocks never occur in the system; used by most operating systems, including UNIX

# Methods for Handling Deadlocks

- Deterministic: Ensure that the system will never enter a deadlock state at any cost
- Handle if it happens: Allow the system to enter a deadlock state and then recover
- Ostrich algorithm: Stick your head in the sand; pretend there is no problem at all.
  - My be acceptable if it happens only rarely (Probabilistic view)

## **Deadlock Prevention**

For a deadlock to occur, each of the four necessary conditions must hold. By ensuring that at least one of these conditions cannot hold, we can **prevent** the occurrence of a deadlock.

Restrain the ways request can be made:

- Mutual Exclusion not required for sharable resources (e.g., read-only files); must hold for non-sharable resources
- Hold and Wait must guarantee that whenever a process requests a resource, it does not hold any other resources
  - Require process to request and be allocated all its resources before it begins execution, or allow process to request resources only when the process has none allocated to it.
  - Low resource utilization; starvation possible



# Deadlock Prevention (Cont.)

#### No Preemption –

- If a process that is holding some resources requests another resource that cannot be immediately allocated to it, then all resources currently being held are released
- Preempted resources are added to the list of resources for which the process is waiting
- Process will be restarted only when it can regain its old resources, as well as the new ones that it is requesting
- Circular Wait impose a total ordering of all resource types, and require that each process requests resources in an increasing order of enumeration

#### Dining philosophers problem: Necessary conditions for deadlock

- Mutual exclusion
  - 2 philosophers cannot share the same chopstick
- Hold-and-wait
  - A philosopher picks up one chopstick at a time
  - Will not let go of the first while it waits for the second one
- No preemption
  - A philosopher does not snatch chopsticks held by some other philosopher
- Circular wait
  - Could happen if each philosopher picks chopstick with the same hand first

## Deadlock Example

```
/* thread one runs in this function */
void *do work one(void *param)
   pthread mutex lock(&first mutex);
   pthread mutex lock(&second mutex);
   /** * Do some work */
   pthread mutex unlock(&second mutex);
   pthread mutex unlock(&first mutex);
   pthread exit(0);
  thread two runs in this function */
void *do work two(void *param)
   pthread mutex lock(&second mutex);
   pthread mutex lock(&first mutex);
   /** * Do some work */
   pthread mutex unlock(&first mutex);
   pthread mutex unlock(&second mutex);
   pthread exit(0);
```

Assume that thread one is the first to acquire the locks and does so in the order (1) first mutex, (2) second mutex.

Solution: Lock-order verifier,
Witness records the relationship
that first mutex must be
acquired before second mutex.
If thread two later acquires the
locks out of order, witness
generates a warning message
on the system console.

### Deadlock Example with Lock Ordering

```
void transaction(Account from, Account to, double amount)
{
    mutex lock1, lock2;
    lock1 = get_lock(from);
    lock2 = get_lock(to);
    acquire(lock1);
        acquire(lock2);
        withdraw(from, amount);
        deposit(to, amount);
        release(lock2);
    release(lock1);
}
```

Transactions 1 and 2 execute concurrently. Transaction 1 transfers \$25 from account A to account B, and Transaction 2 transfers \$50 from account B to account A. Deadlock is possible, even with lock ordering.

## Questions from last time

- Monitor vs semaphore
- Monitor and processes: entry queue, condition queues
- Monitor as a class
- Is monitor a wrapper around a critical application?
- If x.signal happens and thre is no x.wait process waiting, what will happen?
- Pascal: programming language popular in 80s
- Zombie: "terminated" state

## Questions from last time

- System model: for modeling deadlock
- Multiple cycles in resource allocation graphs?
- Monitor as a class
- Other causes of deadlocks besides resource allocation?
- How do we know how often deadlocks happen?
- Do deadlocks only impact processes involved in the deadlock?

## Deadlock Avoidance

Requires that the system has some additional *a priori* information available

- Simplest and most useful model requires that each process declare the maximum number of resources of each type that it may need
- The deadlock-avoidance algorithm dynamically examines the resource-allocation state to ensure that there can never be a circular-wait condition
- Resource-allocation state is defined by the number of available and allocated resources, and the maximum demands of the processes

## Safe State

- When a process requests an available resource, system must decide if immediate allocation leaves the system in a safe state
- System is in safe state if there exists a sequence  $\langle P_1, P_2, ..., P_n \rangle$  of ALL the processes in the systems such that for each  $P_i$ , the resources that  $P_i$  can still request can be satisfied by currently available resources + resources held by all the  $P_i$ , with j < l

#### That is:

- If  $P_i$  resource needs are not immediately available, then  $P_i$  can wait until all  $P_j$  have finished
- When  $P_j$  is finished,  $P_i$  can obtain needed resources, execute, return allocated resources, and terminate
- When  $P_i$  terminates,  $P_{i+1}$  can obtain its needed resources, and so on



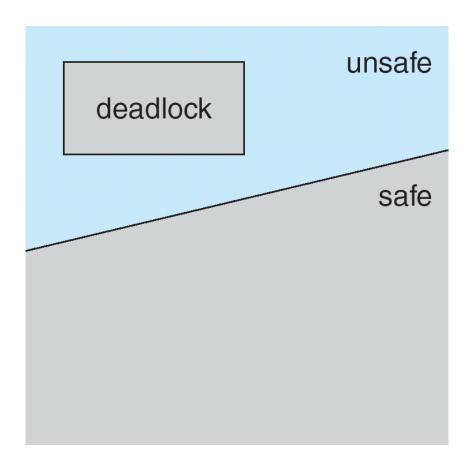
## **Basic Facts**

If a system is in safe state ⇒ no deadlocks

 If a system is in unsafe state ⇒ possibility of deadlock

 Avoidance ⇒ ensure that a system will never enter an unsafe state.

# Safe, Unsafe, Deadlock State



## Example: 12 Tape drives available in the system

	Max need	Current need
P0	10	5
P1	4	2
P2	9	2

#### At TO:

3 drives available

Safe sequence <P1, P0 , P2>

- At time T0 the system is in a safe state
  - P1 can be given 2 tape drives
  - When P1 releases its resources; there are 5 drives
  - P0 uses 5 and subsequently releases them (# 10 now)
  - P2 can then proceed.



## Example: 12 Tape drives available in the system

	Max need	Current need
P0	10	5
P1	4	2
P2	9	2+1

#### **Before T1:**

3 drives available

#### At T1:

2 drives available

- At time T1, P2 is allocated 1 more tape drive
  - Now only P1 can proceed.
  - When P1 releases its resources; there are 4 drives
  - P0 needs 5 and P2 needs 6
    - Mistake in granting P2 additional tape drive



# Avoidance Algorithms

- Single instance of a resource type
  - Use a resource-allocation graph scheme
- Multiple instances of a resource type
  - Use the banker's algorithm



## Questions from Last time

- Resource-allocation graph notation (again)
- System is in safe state if there exists a sequence <P<sub>1</sub>, P<sub>2</sub>, ..., P<sub>n</sub>> of all the processes such that the resources that P<sub>i</sub> can still request can be satisfied by currently available resources + resources held by all the P<sub>j</sub>, with j < l</li>
- Third state between safe and unsafe?
- Avoidance ⇒ ensure that a system will never enter an unsafe state.
- How is max need determined?

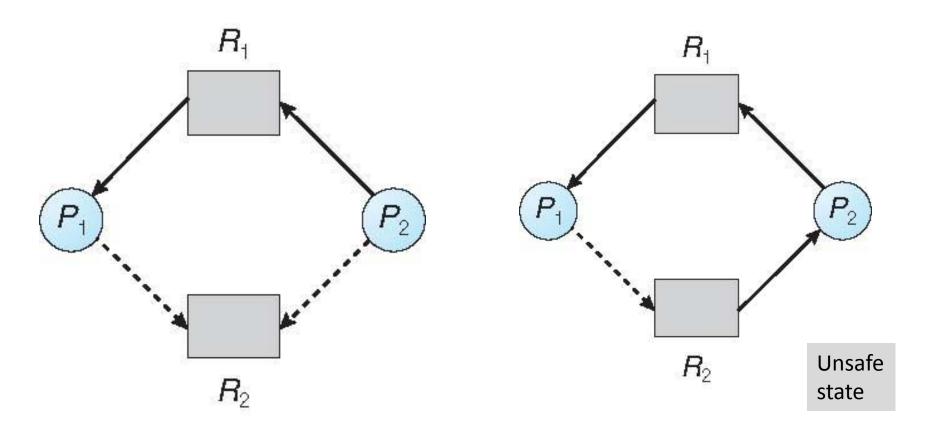
## Questions from Last time

- Why is a process not currently running allocated resources?
- Other ways to end a deadlock? (soon)
- Project groups: You should all be in a project group and working now.

# Resource-Allocation Graph Scheme

- Claim edge  $P_i \rightarrow R_j$  indicated that process  $P_i$  may request resource  $R_j$ ; represented by a dashed line
- Claim edge converts to request edge when a process requests a resource
- Request edge converted to an assignment edge when the resource is allocated to the process
- When a resource is released by a process, assignment edge reconverts to a claim edge
- Resources must be claimed a priori in the system

#### Resource-Allocation Graph



Suppose *P2* requests *R2*. Although *R2* is currently free, we cannot allocate it to *P2*, since this action will create a cycle getting system is in an unsafe state. If *P1* requests *R2*, and *P2* requests *R1*, then a deadlock will occur.

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## Resource-Allocation Graph Algorithm

- Suppose that process  $P_i$  requests a resource  $R_i$
- The request can be granted only if converting the request edge to an assignment edge does not result in the formation of a cycle in the resource allocation graph

# Banker's Algorithm

- Multiple instances of resources.
- Each process must a priori claim maximum use
- When a process requests a resource it may have to wait (resource request algorithm)
- Request not granted if the resulting system state is unsafe (safety algorithm)
- When a process gets all its resources it must return them in a finite amount of time
- Modeled after a banker in a small town making loans

### Data Structures for the Banker's Algorithm

Let n = number of processes, and m = number of resources types.

- Available: Vector of length m. If available [j] = k, there are k instances of resource type  $R_i$  available
- Max:  $n \times m$  matrix. If Max[i,j] = k, then process  $P_i$  may request at most k instances of resource type  $R_i$
- Allocation:  $n \times m$  matrix. If Allocation[i,j] = k then  $P_i$  is currently allocated k instances of  $R_i$
- Need:  $n \times m$  matrix. If Need[i,j] = k, then  $P_i$  may need k more instances of  $R_j$  to complete its task

$$Need[i,j] = Max[i,j] - Allocation[i,j]$$

# Safety Algorithm

1. Let **Work** and **Finish** be vectors of length *m* and *n*, respectively. Initialize:

- 2. Find an *i* such that both:
  - (a) Finish [i] = false
  - (b) Need<sub>i</sub> ≤ WorkIf no such *i* exists, go to step 4

- Need: additional needed
- Work: currently free
- Finish: processes finished

- 3. Work = Work + Allocation; Finish[i] = true go to step 2
- 4. If **Finish** [i] == **true** for all i, then the system is in a safe state

#### Resource-Request Algorithm for Process $P_i$

 $Request_i$  = request vector for process  $P_i$ . If  $Request_i$  [j] = k then process  $P_i$  wants k instances of resource type  $R_i$ 

- 1. If  $Request_i \leq Need_i$  go to step 2. Otherwise, raise error condition, since process has exceeded its maximum claim
- 2. If  $Request_i \leq Available$ , go to step 3. Otherwise  $P_i$  must wait, since resources are not available
- 3. Pretend to allocate requested resources to  $P_i$  by modifying the state as follows:

```
Available = Available - Request;;
Allocation; = Allocation; + Request;;
Need; = Need; - Request;;
```

- If safe  $\Rightarrow$  the resources are allocated to  $P_i$
- If unsafe  $\Rightarrow P_i$  must wait, and the old resource-allocation state is preserved.



# Example of Banker's Algorithm

5 processes P<sub>0</sub> through P<sub>4</sub>;
 3 resource types:
 A (10 instances), B (5 instances), and C (7 instances)

• Snapshot at time  $T_0$ :

	<u> Allocation</u>	<u>Max</u>	<u>Available</u>
	ABC	ABC	ABC
$P_0$	010	753	3 3 2
$P_1$	200	3 2 2	
$P_2$	302	902	
$P_3$	211	222	
$P_4$	002	433	

# Example (Cont.)

The content of the matrix *Need* is defined to be *Max* – *Allocation*

	<u>Need</u>	
	ABC	
$P_0$	743	
$P_1$	122	
$P_2$	600	
$P_3$	011	
$P_4$	431	

Available ABC 332

• The system is in a safe state since the sequence  $\langle P_1, P_3, P_4, P_2, P_0 \rangle$  satisfies safety criteria (see next)

### Example Cont.

The system is in a safe state since the sequence  $\langle P_1, P_3, P_4, P_2, P_0 \rangle$  satisfies safety criteria, since:

<u>Allocation</u>		<u>Need</u>	<u>Available</u>
	ABC	ABC	ABC
$P_0$	010	743	3 3 2
$P_1$	200	122	
$P_2$	302	600	
$P_3$	211	011	
$P_4$	002	431	

```
P1 run completion. Available becomes [3 3 2]+[2 0 0] = [5 3 2]
```

P4 run completion. Available becomes 
$$[7 4 3]+[0 0 2] = [7 4 5]$$

P2 run completion. Available becomes 
$$[7 4 5]+[3 0 2] = [10 4 7]$$

P0 run completion. Available becomes [10 4 7]+[0 1 0] = [10 5 7] Hence state above is safe

P3 run completion. Available becomes  $[5 \ 3 \ 2]+[2 \ 1 \ 1] = [7 \ 4 \ 3]$ 

#### Ex:Assume now $P_1$ Requests (1,0,2)

- Check that Request ≤ Available
  - (1,0,2) ≤ (3,3,2)  $\Rightarrow$  true. Check for safety after pretend allocation.

	<u> Allocation</u>	<u>Need</u>	<u>Available</u>
	ABC	ABC	ABC
$P_{0}$	010	743	230
$P_{2}$	302	02	0
$P_{2}$	302	600	
P	211	011	
$P_{\lambda}$	002	431	

• Executing safety algorithm shows that sequence  $< P_1$ ,  $P_3$ ,  $P_4$ ,  $P_0$ ,  $P_2$ > satisfies safety requirement. Yes, safe state.

#### Additional

Given State is

<u> </u>	<u> Illocation</u>	<u>Need</u>	<u> Available</u>
	ABC	ABC	ABC
$P_0$	010	743	230
$P_1$	302	020	
$P_2$	302	600	
$P_3$	211	011	
$P_4$	002	431	

- P4 request for (3,3,0) cannot be granted resources are not available.
- P0 request for (0,2,0) cannot be granted since the resulting state is unsafe.

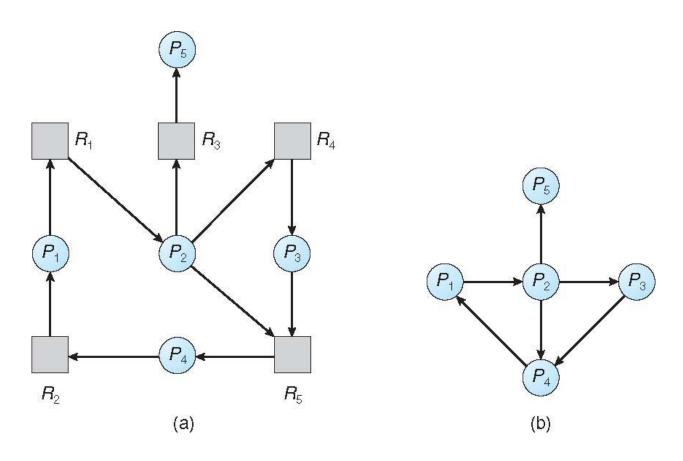
#### **Deadlock Detection**

- Allow system to enter deadlock state
- Detection algorithm
  - Single instance of each resource:
    - wait-for graph
  - Multiple instances:
    - detection algorithm (based on Banker's algorithm)
- Recovery scheme

#### Single Instance of Each Resource Type

- Maintain wait-for graph (based on resource allocation graph)
  - Nodes are processes
  - $-P_i \rightarrow P_j$  if  $P_i$  is waiting for  $P_j$
  - Deadlock if cycles
- Periodically invoke an algorithm that searches for a cycle in the graph. If there is a cycle, there exists a deadlock
- An algorithm to detect a cycle in a graph requires an order of  $n^2$  operations, where n is the number of vertices in the graph

#### Resource-Allocation Graph and Wait-for Graph



Resource-Allocation Graph

Corresponding wait-for graph

3 cycles. Deadlock.

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# Several Instances of a Resource Type

- Available: A vector of length m indicates the number of available (currently free) resources of each type
- Allocation: An n x m matrix defines the number of resources of each type currently allocated to each process
- Request: An  $n \times m$  matrix indicates the current request of each process. If Request[i][j] = k, then process  $P_i$  is requesting k more instances of resource type  $R_i$ .

## **Detection Algorithm**

- 1. Let *Work* and *Finish* be vectors of length *m* and *n*, respectively Initialize:
  - (a) Work = Available
  - (b) For i = 1,2, ..., n, if Allocation; ≠ 0, then
    Finish[i] = false; otherwise, Finish[i] = true
- 2. Find an index *i* such that both:
  - (a) Finish[i] == false
  - (b)  $Request_i \leq Work$

If no such *i* exists, go to step 4

# Detection Algorithm (Cont.)

- 3. Work = Work + Allocation;
  Finish[i] = true
  go to step 2 (find next process)
- 4. If Finish[i] == false, for some i,  $1 \le i \le n$ , then the system is in deadlock state. Moreover, if Finish[i] == false, then  $P_i$  is deadlocked

Algorithm requires an order of  $O(m \times n^2)$  operations to detect whether the system is in deadlocked state

# **Example of Detection Algorithm**

- Five processes  $P_0$  through  $P_4$ ; three resource types A (7 instances), B (2 instances), and C (6 instances)
- Snapshot at time T<sub>0</sub>:

	<u> Allocation</u>	<u>Request</u>	<u>Available</u>
	ABC	ABC	ABC
$P_0$	010	000	000
$P_1$	200	202	
$P_2$	303	000	
$P_3$	211	100	
$P_4$	002	002	

• Sequence  $\langle P_0, P_2, P_3, P_1, P_4 \rangle$  will result in *Finish[i] = true* for all i. *No deadlock* 

# Example (Cont.)

P<sub>2</sub> requests an additional instance of type C

# $\frac{Request}{ABC}$ $P_0 = 000$ $P_1 = 202$ $P_2 = 001$ $P_3 = 100$ $P_4 = 002$

Available A B C O O O

- State of system?
  - Can reclaim resources held by process  $P_0$ , but insufficient resources to fulfill other processes; requests
  - Deadlock exists, consisting of processes  $P_1$ ,  $P_2$ ,  $P_3$ , and  $P_4$

# Detection-Algorithm Usage

- When, and how often, to invoke depends on:
  - How often a deadlock is likely to occur
  - How many processes will need to be rolled back
    - one for each disjoint cycle
- If detection algorithm is invoked arbitrarily, there may be many cycles in the resource graph and so we would not be able to tell which of the many deadlocked processes "caused" the deadlock.

#### Recovery from Deadlock: Process Termination

#### Choices

- Abort all deadlocked processes
- Abort one process at a time until the deadlock cycle is eliminated

#### In which order should we choose to abort?

- 1. Priority of the process
- 2. How long process has computed, and how much longer to completion
- 3. Resources the process has used
- 4. Resources process needs to complete
- 5. How many processes will need to be terminated
- 6. Is process interactive or batch?



#### Recovery from Deadlock: Resource Preemption

- **Selecting a victim** minimize cost
- Rollback return to some safe state, restart process for that state
- Starvation same process may always be picked as victim, include number of rollback in cost factor

#### Deadlock recovery through rollbacks

- Checkpoint process periodically
  - Contains memory image and resource state
- Deadlock detection tells us which resources are needed
- Process owning a needed resource
  - Rolled back to before it acquired needed resource
    - Work done since rolled back checkpoint discarded
  - Assign resource to deadlocked process