

IEEE 802.11 Distribute Coordinator Function Discrete—Event Simulator against State—of—the—Art Analytical Model

Simulation and Performance Evaluation project

Luca Mosetti, Shandy Darma

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► Related works

- ▶ Distribute Coordinator Function
- ▶ Problem definition & Setup
- ▶ Metrics
- ► Analytical Model
- ▶ Results
- ► Appendix
- ▶ Results



Analytical Models 1 Related works

IEEE 802.11-Saturation Throughput Analysis

Performance Analysis of the IEEE 802.11 Distributed Coordination Function

Remarks on IEEE 802.11 DCF Performance Analysis Giovenne Risochi and Donia Timinollo

Refinements on IEEE 802.11 Distributed Coordination Function Modeling Approaches

Abinos. With the pupulosity of the IEEE SCLII standards. Starting in the soid 1997's, many papers have studied analysis of start based analysis of start based analysis of the start based and the start based analysis of the start based and the start based analysis of the start based analysis of the start based analysis of the start based and the start based analysis of the start based and the start based analysis of the start based analysis of the start based and the start based analysis of the start based analysis of the start based and the start based and the start based and the start based analysis of the start based and the start based analysis of the start based and the start based analysis of the start based and the start based and the start based analysis of the start based and the start based and the start based and the sta many analysisal uteravision formulappint similar for the affirminated consideration beaution (E(t)) have been supposed, in this paper, we considerate beaution (E(t)) have been supposed in the high part was sufficient a number of tenses and criticalities varied by previously and the state of tenses and criticalities varied by previously regional uteration between the consideration of the contraction of the contract of the contraction of the contract of the contract of the contract of the contraction of the contract of the contraction o



Table of Contents

2 Distribute Coordinator Function

- ► Related works
- ▶ Distribute Coordinator Function
- ▶ Problem definition & Setup
- ▶ Metrics
- ► Analytical Model
- ▶ Results
- ► Appendix
- ▶ Results



- DCF follows Carrier Sense Multiple Access / Collision Avoidance principles
- Stations (STAs) use a "listen-before-talk" approach
- Key mechanisms: carrier sensing, random backoff, ACK

ACK

- Positive acknowledgment after successful reception
- Transmitted at the end of the packet after a SIFS
- If no ACK, reschedule transmission

Carrier Sensing Mechanism

- STAs sense the medium before transmission
- If a STA senses the channel idle for DIFS, it generates a random backoff period

- Backoff period expressed in backoff slots
- Decreases when the medium is sensed idle
- "Frozen" during a detected transmission

- At each transmission, backoff period uniformly chosen in [0, CW)
- After unsuccessful transmission, $CW = \min \begin{pmatrix} 2 \cdot CW \\ 2^m \cdot W \end{pmatrix}$
- Resets to W after success or retry limit R reached



BAS mode Data Packet SIFS ACK DIFS

- Default mechanism
- Transmit directly the entire packet

RTS/CTS mode

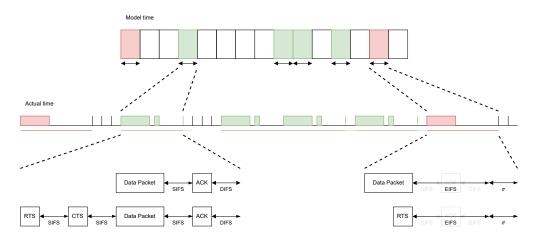


- Four-way handshaking mechanism
- Request-to-Send (RTS)
- Clear-to-Send (CTS)



Times

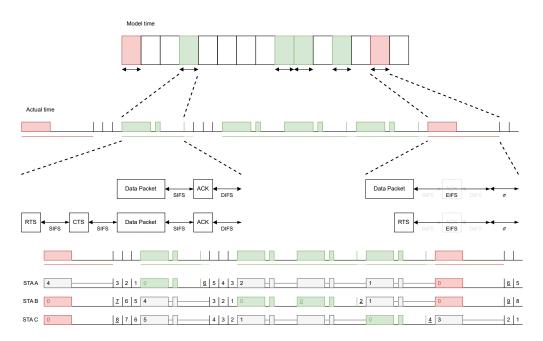
2 Distribute Coordinator Function





Times

2 Distribute Coordinator Function



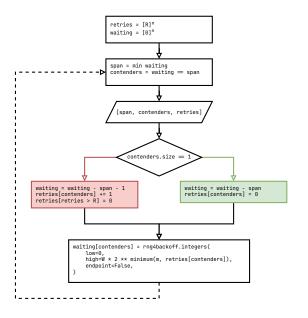


- ► Related works
- ▶ Distribute Coordinator Function
- ▶ Problem definition & Setup
- ▶ Metrics
- ► Analytical Model
- ▶ Results
- ► Appendix
- ▶ Results



Simulator

3 Problem definition & Setup



Characteristics:

- Discrete-Event Simulator
- Independent of any temporal specification
- Python 3.11

Assumptions:

- Constant # of STAs
- Constant payload size
- Transmission queue of each STA is always nonempty
- W/out hidden terminals
- W/out capture effect

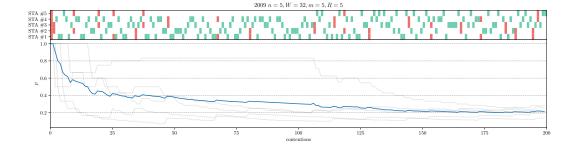


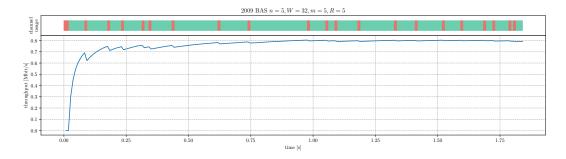
Table of Contents ⁴ Metrics

- Related works
- ▶ Distribute Coordinator Function
- ▶ Problem definition & Setup
- ▶ Metrics
- ► Analytical Model
- ▶ Results
- ► Appendix
- ▶ Results



$\underset{\text{4 Metrics}}{p \text{ and } S}$





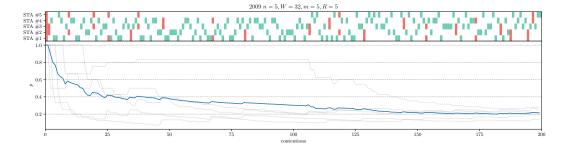


Figure: Measurement of collision probability p. Upper figure shows whether a transmission or a collision occurred in each contention round. Lower figure shows the collision probability, with grey lines describe probability of each stations while blue line describes the final mean of all probabilities.

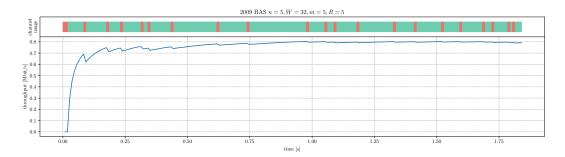
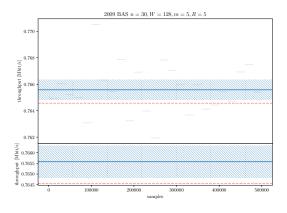


Figure: Measurement of saturated throughput S. Upper figure shows the occurrences of transmissions and collisions. Lower figure shows the saturated throughput of the channel. Each transmission improves throughput while each collision worsens throughput.

Non-overlapping batch over means ⁴ Metrics



$$\underbrace{Y_1, \dots, Y_s}_{B_1}, \underbrace{Y_{s+1}, \dots, Y_{2s}}_{B_2}, \dots, \underbrace{Y_{(b-1)s+1}, \dots, Y_{bs}}_{B_b}$$

$$\overline{Z}_b = \frac{1}{b} \sum_{i}^{b} Z_i \qquad \left[\overline{Z}_b \pm t_{b-1, \frac{1+\gamma}{2}} \sqrt{\frac{\hat{V}}{b}} \right]_{\gamma}$$

$$\hat{V} = \frac{1}{b-1} \sum_{i}^{b} (Z_i - \overline{Z}_b)^2$$



- Related works
- ▶ Distribute Coordinator Function
- ▶ Problem definition & Setup
- ▶ Metrics
- ▶ Analytical Model
- ▶ Results
- ► Appendix
- ▶ Results



Formulae

5 Analytical Model

 σ slot time

L payload size

 T_{MPDU} the time to transmit the MPDU

 $T_{\rm ACK}$ the time to transmit an ACK

 $T_{\rm RTS}$ the time to transmit a RTS frame

 $T_{\rm CTS}$ the time to transmit a CTS frame

SIFS the SIFS time

DIFS the DIFS time

n number of stations

W minimum contention window

m maximum backoff stage, where maximum contention window is $2^m W$

R maximum number of retries, after which the transmission is dropped

p probability of collision

au probability that a station will transmit

S saturation throughput



Formulae

5 Analytical Model

$$p = 1 - (1 - \tau)^{n-1}$$

$$\tau = \frac{1}{1 + \frac{1 - p}{2(1 - p^{R+1})} \left[\sum_{j=0}^{R} p^{j} \cdot (2^{j}W - 1) - (1 - p^{R+1}) \right]}$$

$$\mathbf{S} = \frac{\mathbf{P_s}\overline{\mathbf{E}[L]}}{(1 - \mathbf{P_b})\sigma + \mathbf{P_s}\overline{\mathbf{T_s}} + (\mathbf{P_b} - \mathbf{P_s})\overline{\mathbf{T_c}}}$$

$$\mathbf{P_b} = 1 - (1 - \tau)^{n} \qquad \mathbf{P_s} = n\tau(1 - \tau)^{n-1}$$

$$\overline{\mathbf{E}[L]} = L\frac{W}{W - 1} \qquad \overline{\mathbf{T_s}} = \mathbf{T_s}\frac{W}{W - 1} + \sigma \qquad \overline{\mathbf{T_c}} = \mathbf{T_c} + \sigma$$

$$\mathbf{T_s^{BAS}} = T_{\text{MPDU}} + \text{SIFS} + T_{\text{ACK}} + \text{DIFS}$$

$$\mathbf{T_c^{BAS}} = \mathbf{T_{BAS}}$$

$$\mathbf{T_s^{RTS/CTS}} = T_{RTS} + \text{SIFS} + T_{CTS} + \text{SIFS} + T_{MPDU} + \text{SIFS} + T_{ACK} + \text{DIFS}$$

$$\mathbf{T_c^{RTS/CTS}} = T_{RTS} + \text{SIFS} + T_{ACK} + \text{DIFS}$$



Formulae

5 Analytical Model

$$\tau = \frac{1}{1 + \frac{1-p}{2(1-p^{R+1})} \left[\sum_{j=0}^{R} p^{j} \cdot (2^{j}W - 1) - (1-p^{R+1}) \right]} \downarrow$$

$$\tau = \frac{1}{1 + \frac{1-p}{2(1-p^{R+1})} \left[\sum_{j=0}^{R} p^{j} \cdot (\mathfrak{W}_{j} - 1) - (1-p^{R+1}) \right]}$$

$$\mathfrak{W}_{j} = W \cdot 2^{\min(m,j)} \quad j \in [0, R]$$



Table of Contents ⁶ Results

- ► Related works
- ▶ Distribute Coordinator Function
- ▶ Problem definition & Setup
- ▶ Metrics
- ► Analytical Model
- ► Results
- ► Appendix
- ▶ Results

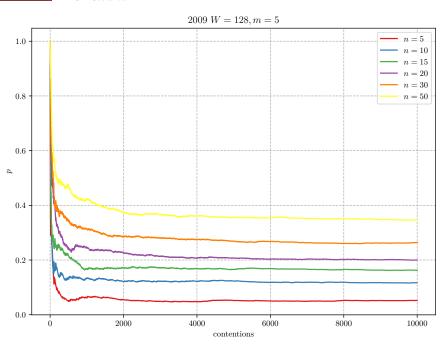


Parameters

Parameter	2009 Simulator
L	1023 Byte
MAC header	34 Byte
PHY header	16 Byte
ACK	14 Byte + PHY header
RTS	20 Byte + PHY header
CTS	14 Byte + PHY header
Channel Bit Rate	1 Mbit/s
σ	$50 \mu\mathrm{s}$
SIFS	$28 \mu\mathrm{s}$
DIFS	$SIFS + 2 \cdot \sigma$

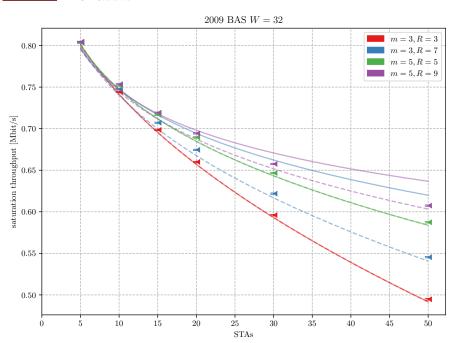


Initialisation bias



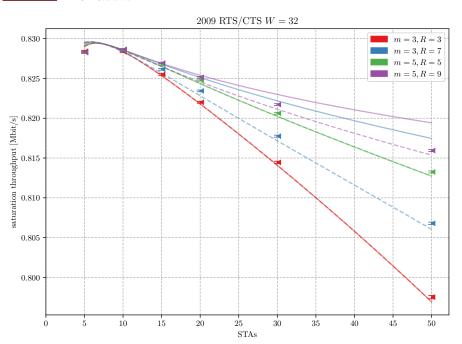


Saturation throughput



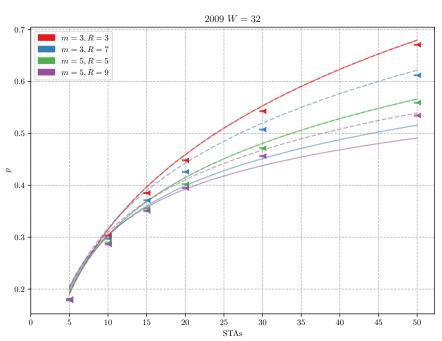


Saturation throughput



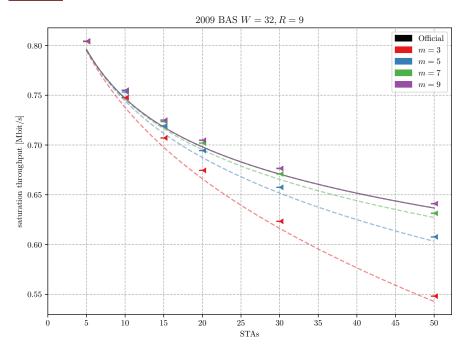


Probability of collision 6 Results



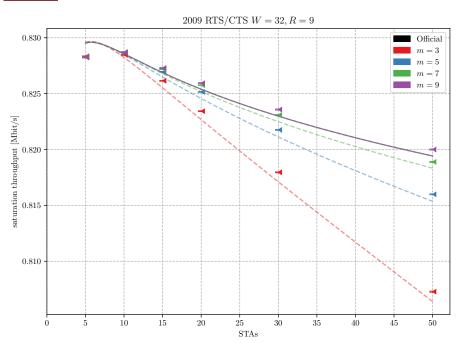


Focus 6 Results



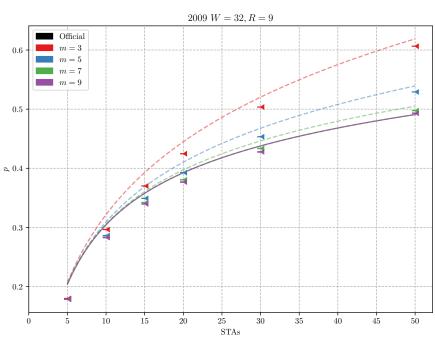


Focus 6 Results





Focus 6 Results





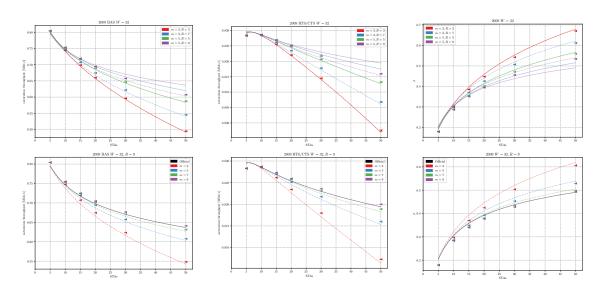




Table of Contents 7 Appendix

- ► Related works
- ▶ Distribute Coordinator Function
- ▶ Problem definition & Setup
- ▶ Metrics
- ► Analytical Model
- ▶ Results
- ► Appendix
- ▶ Results



Differences between analytical models

7 Appendix

$$p = 1 - (1 - \tau)^{n-1}$$

$$\tau = \frac{2}{1 + W + pW \sum_{i=0}^{m-1} (2p)^i}$$

$$S = \frac{P_s P_{tr} L}{(1 - P_{tr})\sigma + P_{tr} P_s T_s + P_{tr} (1 - P_s) T_c}$$

$$P_{tr} = 1 - (1 - \tau)^n$$
 $P_s = \frac{n\tau(1 - \tau)^{n-1}}{P_{tr}}$ $P_b = 1 - (1 - \tau)^n$ $P_s = n\tau(1 - \tau)^{n-1}$

$$\frac{\boldsymbol{\tau} = \frac{1}{1 + \frac{1-p}{2(1-p^{R+1})} \left[\sum_{j=0}^{R} p^{j} \cdot (2^{j}W - 1) - (1-p^{R+1}) \right]}$$

$$S = \frac{P_s P_{tr} L}{(1 - P_{tr})\sigma + P_{tr} P_s T_s + P_{tr} (1 - P_s) T_c} \qquad S = \frac{P_s E[L]}{(1 - P_b)\sigma + P_s \overline{T_s} + (P_b - P_s) \overline{T_c}}$$

$$\mathbf{P_b} = 1 - (1 - \boldsymbol{\tau})^n$$
 $\mathbf{P_s} = n\boldsymbol{\tau}(1 - \boldsymbol{\tau})^{n-1}$

$$\overline{\mathbf{E}[L]} = L \frac{W}{W - 1} \qquad \overline{\mathbf{T_s}} = \mathbf{T_s} \frac{W}{W - 1} + \sigma \qquad \overline{\mathbf{T_c}} = \mathbf{T_c} + \sigma$$



Differences between analytical models 7 Appendix

$$\begin{split} \mathsf{T}_{\mathsf{s}}^{\mathsf{BAS}} &= T_{\mathsf{MPDU}} + \delta + \mathsf{SIFS} + T_{\mathsf{ACK}} + \delta + \mathsf{DIFS} \\ \mathsf{T}_{\mathsf{c}}^{\mathsf{BAS}} &= T_{\mathsf{MPDU}} + \delta + \mathsf{DIFS} \\ \end{split}$$

$$\begin{split} \mathsf{T}_{\mathsf{s}}^{\mathsf{RTS/CTS}} &= T_{\mathsf{RTS}} + \delta + \mathsf{SIFS} + T_{\mathsf{CTS}} + \delta + \mathsf{SIFS} \\ &\quad + T_{\mathsf{MPDU}} + \delta + \mathsf{SIFS} + T_{\mathsf{ACK}} + \delta + \mathsf{DIFS} \\ \end{split}$$

$$\begin{split} \mathsf{T}_{\mathsf{c}}^{\mathsf{RTS/CTS}} &= T_{\mathsf{RTS}} + \delta + \mathsf{DIFS} \end{split}$$

$$\mathbf{T_s^{BAS}} = T_{\text{MPDU}} + \text{SIFS} + T_{\text{ACK}} + \text{DIFS}$$

$$\mathbf{T_c^{BAS}} = \mathbf{T_s^{BAS}}$$

$$\mathbf{T_s^{RTS/CTS}} = T_{RTS} + \text{SIFS} + T_{CTS} + \text{SIFS}$$

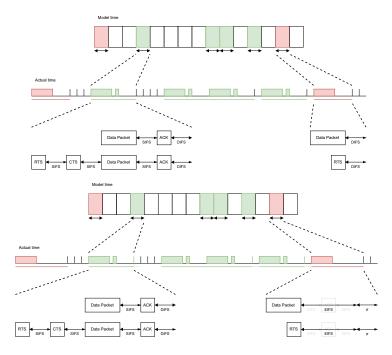
$$+ T_{\text{MPDU}} + \text{SIFS} + T_{ACK} + \text{DIFS}$$

$$\mathbf{T_c^{RTS/CTS}} = T_{RTS} + \text{SIFS} + T_{ACK} + \text{DIFS}$$



Differences between simulators

7 Appendix





Differences between simulators 7 Appendix

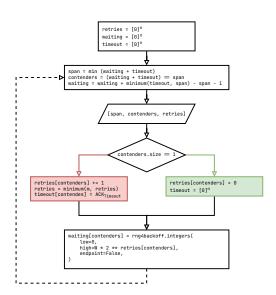


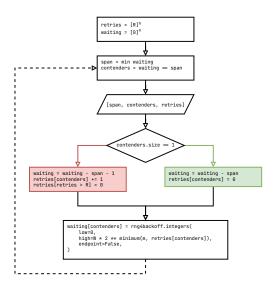




Differences between simulators

7 Appendix





simulation()	0 0 0 0 0 0 0		simulation()
seeds: t.Iterator[NDArray[np.uint32]],	27	27	seeds: t.Iterator[NDArray[np.uint32]],
m: int,	28	28	m: int,
W: int,	29	29	W: int,
m: int,	38	30	m: int,
ack_timeout: int,	>> 31	31 <	R: int,
→ t.Iterator[Log]:	32	32) → t.Iterator[Log]:
rng4backoff: np.random.Generator = np.random.default_rng(next(seeds))	33	33	rng4backoff: np.random.Generator = np.random.default_rng(next(seeds))
	34	34	
timeouts: NDArray[bool] = np.full(n, fill_value=False)	≫ 35	35 ≪	retries: NDArray[int] = np.full(n, R, dtype=int)
retries: NDArray[int] = np.zeros(n, dtype=int)		36	waiting: NDArray[int] = np.zeros(n, dtype=int)
waiting: NDArray[int] = np.zeros(n, dtype=int)	37	37	
	38	38	while True:
while True:	39	39	
	48	40 <<	span: int = np.amin(waiting)
span: int = np.amin(waiting + timeouts * ack_timeout)	>> 41		mask: NDArray[bool] = waiting = span
mask: NDArray[bool] = (waiting + timeouts * ack_timeout) = span		42	contenders: NDArray[int] = np.flatnonzero(mask)
contenders: NDArray[int] = np.flatnonzero(mask)	43	43	
	44	44	yield Log(
yield Log(45	45	span=span,
span=span,	46	46	contenders=mask,
contenders=mask,	47	47	attempt=retries.copy(),
attempt=retries.copy(),	48	48)
)	49	49	,
,	58	50 <<	waiting = waiting - span
waiting = waiting + np.minimum(timeouts * ack timeout, span) - span - 1	>> 51	51	,
	52	52	match contenders.size:
match contenders.size:	53	53	case 1:
case 1:	54	54 <<	retries[contenders] = 0
timeouts = np.full(n, fill_value=False)	>> 55	55	case _:
retries[contenders] = 0	56	56 《	waiting -= 1
case _:	57	57	retries[contenders] += 1
timeouts = mask	>> 58	58 《	retries[retries > R] = 0
retries[contenders] += 1	59	59	
retries.clip(max=m, out=retries)	>> 68	69	<pre>waiting[contenders] = rng4backoff.integers(</pre>
Total according to the state of	61	61	low=0.
waiting[contenders] = rng4backoff.integers(62	62 《	high=W * 2 ** np.minimum(m, retries[contenders]),
low=0,	63	63	endpoint=False,
high=W * 2 ** retries[contenders],	>> 64	64)
endpoint=False,	65	65	*
)	66	66	
,	00	00	

å simulation() simulation()



Table of Contents 8 Results

- ► Related works
- ▶ Distribute Coordinator Function
- ▶ Problem definition & Setup
- ▶ Metrics
- ► Analytical Model
- ▶ Results
- ► Appendix
- ► Results

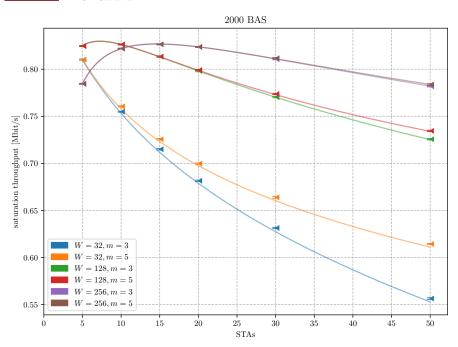


Parameter	2000 Simulator	2009 Simulator
\overline{L}	1023 Byte	1023 Byte
MAC header	34 Byte	34 Byte
PHY header	16 Byte	16 Byte
ACK	14 Byte + PHY header	14 Byte + PHY header
RTS	20 Byte + PHY header	20 Byte + PHY header
CTS	14 Byte + PHY header	14 Byte + PHY header
Channel Bit Rate	1 Mbit/s	1 Mbit/s
σ	$50\mu\mathrm{s}$	$50\mu\mathrm{s}$
SIFS	$28\mu\mathrm{s}$	$28\mu\mathrm{s}$
DIFS	$SIFS + 2 \cdot \sigma$	$SIFS + 2 \cdot \sigma$
δ	$1 \mu\mathrm{s}$	_
ACK _{Timeout}	$300 \mu \mathrm{s}$	_



Saturation throughput

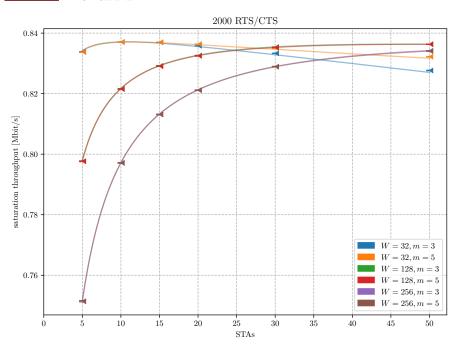
8 Results





Saturation throughput

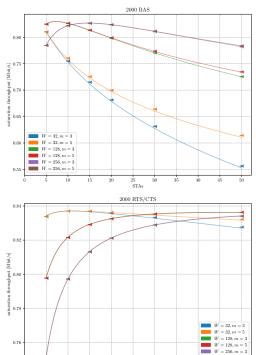
8 Results



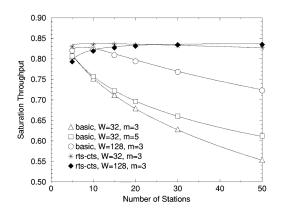


Saturation throughput

8 Results

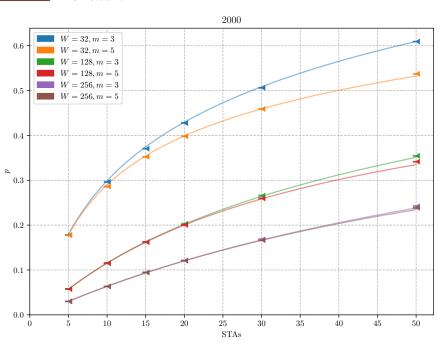


STAs



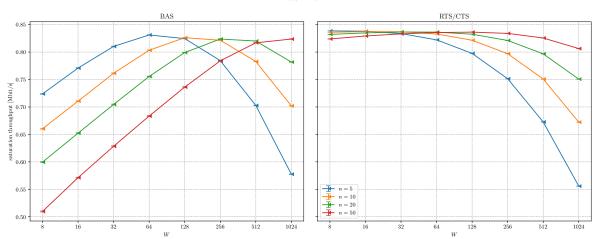


Probability of collision 8 Results

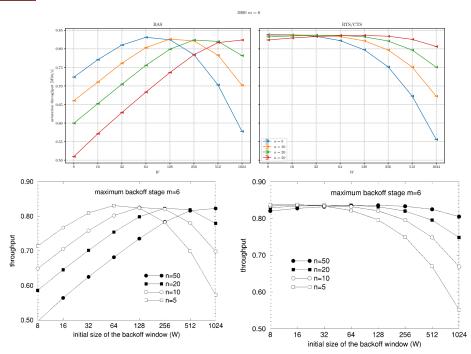






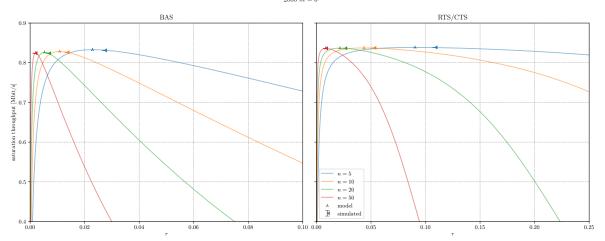




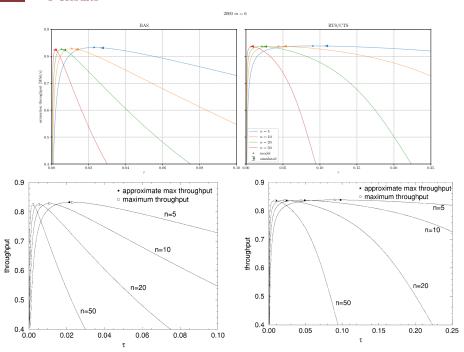




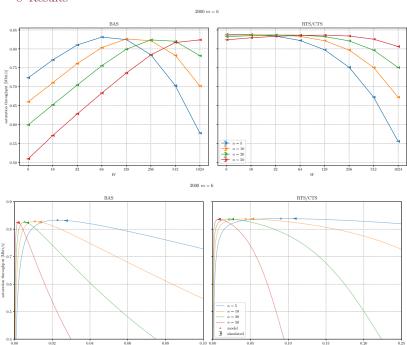














Q&A