# Operating Systems and Concurrency

Processes 2, Scheduling COMP2007

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# Recap Last Lecture

- Processes have "control structures" associated with them, the process control blocks and process tables.
- Processes can have different states and the kernel triggers transitions between these states.
- The operating system maintains multiple process queues.
- The operating system manages processes on the user's behalf.

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## Goals for Today

Overview

- Introduction to process scheduling
- Types of process schedulers
- Evaluation criteria for scheduling algorithms
- Typical process scheduling algorithms

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# **Process Scheduling**

Context

- The OS is responsible for managing and scheduling processes
  - Decide when to **admit** processes to the system (new  $\rightarrow$  ready)
  - Decide which process to run next (ready → run)
  - Decide when and which processes to interrupt (running → ready)
- It relies on the scheduler (dispatcher) to decide which process to run next, which uses a scheduling algorithm to do so
- The type of algorithm used by the scheduler is influenced by the type of operating system (e.g., real time vs. batch)

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#### **Process Schedulers**

#### Classification by Time Horizon

- Long term: applies to new processes and controls the degree of multiprogramming by deciding which processes to admit to the system when
  - A good mix of CPU and I/O bound processes is favourable to keep all resources as busy as possible
  - Usually absent in popular modern OS
- Medium term: controls swapping and the degree of multi-programming
- Short term: decide which process to run next
  - Manages the ready queue
  - Invoked very frequently, hence must be fast
  - Usually called in response to clock interrupts, I/O interrupts, or blocking system calls

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#### **Process Schedulers**

#### Classification by Time Horizon

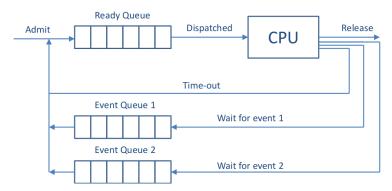


Figure: Queues in OS

Exam 2013-2014: Where do the process schedulers fit in with the state transitions? ©University of Nottingham

#### **Process Schedulers**

#### Classification by Approach

- Non-preemptive: processes are only interrupted voluntarily (e.g., I/O operation or "nice" system call yield())
  - Windows 3.1 and DOS were non-preemtive
- Preemptive: processes can be interrupted forcefully or voluntarily
  - Typically driven by interrupts from a system clock.
  - Requires additional context switches which generate overhead, too many of them should be avoided (recall last lecture)
  - Prevents processes from monopolising the CPU
  - Most popular modern operating systems are preemptive

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#### Performance Assessment

Criteria

- User oriented criteria:
  - Response time: minimise the time between creating the job and its first execution
  - Turnaround time: minimise the time between job creation and completion
  - Predictability: minimise the variance in processing times
- System oriented criteria:
  - Throughput: maximise the number of jobs processed per hour
  - Fairness:
    - Are processing power/waiting time equally distributed?
    - Are some processes kept waiting excessively long (starvation)
- Evaluation criteria can be conflicting, i.e., improving the response time
  may require more context switches, and hence worsen the throughput
  and increase the turn around time

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Overview

- Algorithms considered:
  - First Come First Served (FCFS)/ First In First Out (FIFO)
  - Shortest job first
  - Round robin
  - Priority queues
- Performance measures used:
  - Average response time: the average of the time taken for all the processes to start
  - Average turnaround time: the average time taken for all the processes to finish

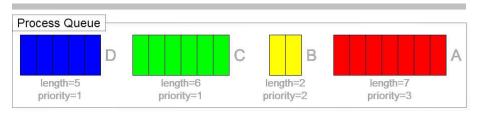
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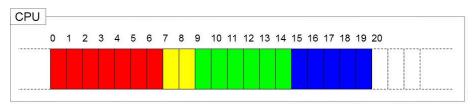
First Come First Served

- Concept: a non-preemtive algorithm that operates as a strict queueing mechanism and schedules the processes in the same order that they were added to the queue
- Advantages: positional fairness and easy to implement
- Disadvantages:
  - Favours long processes over short ones (think of the supermarket checkout!)
  - Could compromise resource utilisation, i.e., CPU vs. I/O devices

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First Come First Served





- Average response time =  $0 + 7 + 9 + 15 = \frac{31}{4} = 7.75$
- Average turn around time =  $7 + 9 + 15 + 20 = \frac{51}{4} = 12.75$

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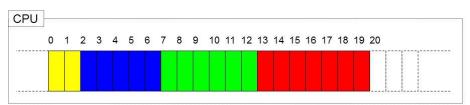
Shortest Job First

- Concept: A non-preemtive algorithm that starts processes in order of ascending processing time using a provided/known estimate of the processing
- Advantages: always result in the optimal turn around time
- Disadvantages:
  - Starvation might occur
  - Fairness and predictability are compromised
  - Processing times have to be known beforehand

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**Shortest Job First** 





- Average response time =  $0 + 2 + 7 + 13 = \frac{22}{4} = 5.5$
- Average turn around time =  $2+7+13+20=\frac{42}{4}=10.5$

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Round Robin

- Concept: a preemptive version of FCFS that forces context switches at periodic intervals or time slices
  - Processes run in the order that they were added to the queue
  - Processes are forcefully interrupted by the timer
- Advantages:
  - Improved response time
  - Effective for general purpose interactive/time sharing systems
- Disadvantages:
  - Increased context switching and thus overhead
  - Favours CPU bound processes (which usually run long) over I/O processes (which do not run long)
    - Can be prevented by working with multiple queues?
  - Can reduce to FCFS

Exam 2013-2014: Round Robin is said to favour CPU bound processes over I/O bound processes. Explain why may this be the case (if this is the case at all)?

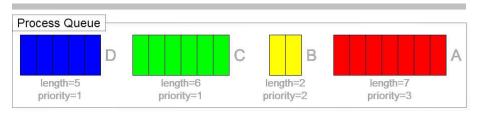
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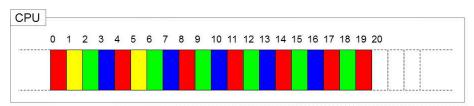
Round Robin

- The length of the time slice must be carefully considered!
- For instance, assuming a multi-programming system with preemptive scheduling and a context switch time of 1ms:
  - E.g., a good (low) response time is achieved with a small time slice (e.g. 1ms) ⇒ low throughput
  - E.g., a high throughput is achieved with a large time slice (e.g. 1000ms)
     ⇒ high response time
- If a time slice is only used partially, the next process starts immediately

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Round Robin





- Average response time =  $0 + 1 + 2 + 3 = \frac{6}{4} = 1.5$
- Average turn around time =  $6 + 17 + 19 + 20 = \frac{62}{4} = 15.5$

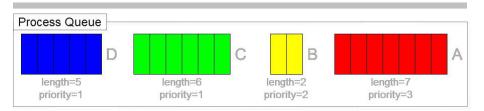
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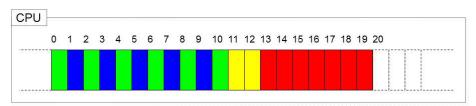
**Priority Queues** 

- Concept: A preemptive algorithm that schedules processes by priority (high → low)
  - A round robin is used within the same priority levels
  - The process priority is saved in the process control block
- Advantages: can prioritise I/O bound jobs
- Disadvantages: low priority processes may suffer from starvation (when priorities are static)

Exam 2013-2014: Out of the following four scheduling algorithms, which one can lead to starvation: FCFS, shortest job first, round robin, highest priority first? Explain your answer. ©University of Nottingham

**Priority Queues** 





- Average response time =  $0 + 1 + 11 + 13 = \frac{25}{4} = 6.25$
- Average turn around time =  $10 + 11 + 13 + 20 = \frac{54}{4} = 13.5$

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#### **Priority Queues**

- Give the order in which the processes are scheduled when using priority queues, together with the times at which they will start, end, and are interrupted (all processes are available at the time of scheduling)
- You can assume a time slice of 15 milliseconds
- Calculate the average response and turn around time

	FCFS Position	CPU burst time	Priority
Process A	1	67	1 (high)
Process B	2	37	1 (high)
Process C	3	14	2 (low)
Process D	4	16	2 (low)

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**Priority Queues** 

- Solution:
  - Sequence: A(15)  $\Rightarrow$  B(15)  $\Rightarrow$  A(15)  $\Rightarrow$  B(15)  $\Rightarrow$  A(15)  $\Rightarrow$  B(7)  $\Rightarrow$  A(15)  $\Rightarrow$  A(15
  - Average response time = (0 + 15 + 104 + 118) / 4
  - Average turnaround time = (82 + 104 + 118 + 134) / 4
- Note: we ignore context switch time

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# Test your understanding

- On a non-preemptive operating systems, what sort of things can a process do without potentially "volunteering" to cede the CPU to another process.
- Using the non-preemptive shortest job first scheduler, does the shortest job run on the CPU until it is completed?

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