Attendance Barcode

COMP2007: Operating Systems & Concurrency Week 3 – 3:00pm Monday – 09 October 2023



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Operating Systems and Concurrency

Processes 1 COMP2007

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Recap Last Lecture

- Kernel mode code has more privileges than user code
- Interrupts change the flow of execution to invoke kernel code
- System calls allow us to run kernel code to access services of the operating system

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Goals for Today

Overview

- Introduction to processes and their implementation
- Process states and state transitions
- System calls for process management

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Definition

- A process is an abstraction of a running instance of a program
 - A program is **passive** and "sits" on a disk
 - A process has control structures associated with it, may be active, and may have resources assigned to it (e.g. I/O devices, memory, processor)
- All the information necessary to administer a process is stored by the kernel in a process control block (PCB).
- All the process control blocks are recorded in the process table.

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Memory Image of Processes

- A process' memory image contains:
 - The program code (could be shared between multiple processes running the same code)
 - A data segment, stack and heap
- Every process has its own logical address space, in which the stack and heap are placed at opposite sides to allow them to grow

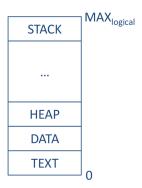
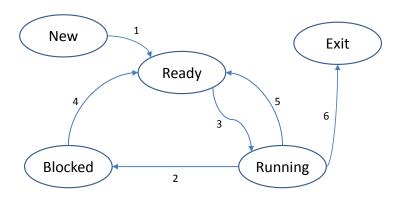


Figure: Representation of a process in memory

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Diagram



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States

- A new process has just been created. It has a PCB and is waiting to be admitted, although it may not yet be in memory.
- A ready process is waiting for CPU to become available.
- A running process is currently having its instructions executed by the CPU.
- A blocked process cannot continue, e.g. is waiting for I/O
- A terminated process is no longer executable. The data structures PCB
 - may be temporarily preserved.

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- A suspended process is swapped out (not discussed further)

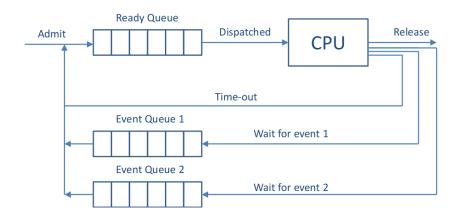
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Transitions

- State transitions include:
 - **1** New \rightarrow ready: admit the process and commit to execution
 - Running → blocked: e.g. process is waiting for input or carried out a system call
 - Ready → running: the process is selected by the process scheduler
 - **Blocked** \rightarrow **ready**: event happens, e.g. I/O operation has finished
 - Running → ready: the process surrenders the CPU, for example due to an interrupt or by pause
 - Running → exit: process has finished, e.g. program ended or exception encountered
- Interrupts and system calls drive these transitions.

Exam 2013-2014: List the 5 process states and explain the transitions between them ©University of Nottingham

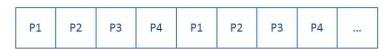
OS Queues



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Multi-programming

- Modern computers are multi-programming systems
- Assuming a single processor system, the instructions of individual processes are executed sequentially
 - Multi-programming goes back to the "MULTICS" age
 - Multi-programming is achieved by interleaving the execution of processes, dividing the CPU time into time-slices
 - Control is exchanged between processes via a procedure known as context switching
 - A trade-off exists between the length of the time-slice and the context switch time
 - True parallelism requires hardware support



TIME

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Multi-programming (Cont'ed)

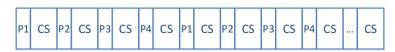
- When a context switch takes place, the system saves the state of the old process and loads the state of the new process (creates overhead)
 - Saved ⇒ the process control block is updated
 - (Re-)started ⇒ the process control block read

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Multi-programming (Cont'ed)

Short time slices result in **good response times** but **low effective utilisation**. For example, assume both context switches and time slices take 1 ms. Then:

- It will take $99 \times (1+1) = 198 ms$ for the last of 100 processes to start running.
- $\frac{1}{1.1}$ = 0.5 of the CPU time is doing useful work.



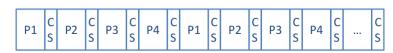
TIME

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Multi-programming (Cont'ed)

Long time slices result in **poor response times** but **better effective utilisation**. For example, assume context switches take 1 *ms* and time slices are 100 *ms*. Then:

- It will take $99 \times (100 + 1) = 9999 ms$ for the last of 100 processes to start running.
- $\frac{100}{1+100} = 0.99$ of the CPU time is doing useful work



TIME

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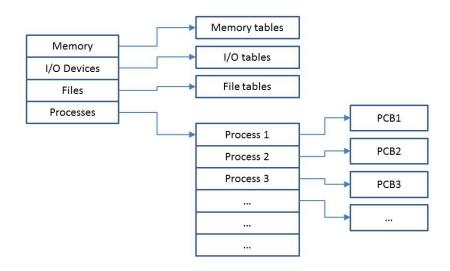
Multi-programming (Cont'ed)

- A process control block contains three types of attributes:
 - Process identification (PID, UID, Parent PID)
 - Process control information (process state, scheduling information, etc.)
 - Process state information (user registers, program counter, stack pointer, program status word, memory management information, files, etc.)
- Process control blocks are kernel data structures, i.e. they are protected and only accessible in kernel mode!
 - Allowing user applications to access them directly could compromise their integrity
 - The operating system manages them on the user's behalf through system calls (e.g. to set process priority)

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Process Implementation

Tables and Control Blocks



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Process Implementation

Tables and Control Blocks

- An operating system maintains information about the status of "resources" in tables
 - Process tables (process control blocks)
 - Memory tables (memory allocation, memory protection, virtual memory)
 - I/O tables (availability, status, transfer information)
 - File tables (location, status)
- The process table holds a process control block for each process, allocated upon process creation
- Tables are maintained by the kernel and are usually cross referenced

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Switching Processes

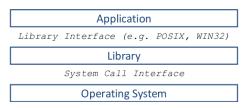
- 1. Save process state (program counter, registers)
- 2. Update PCB (running -> ready/blocked)
- 3. Move PCB to appropriate queue (ready/blocked)
- 4. Run scheduler, select new process
- 5. Update to running state in the new PCB
- 6. Update memory management unit (MMU)
- 7. Restore process

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System Calls

Process Creation

- The true system calls are "wrapped" in the OS libraries (e.g. libc) following a well defined interface (e.g. POSIX, WIN32 API)
- For example, on Unix-like operating systems fork is called to create a copy of a process. On Linux, the underlying system call used to implement fork is clone.



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System Calls

Process Termination

- System calls via exit and abort can be used to explicitly notify the OS
 that the process has terminated
 - Resources must be de-allocated
 - Output must be flushed
 - Process admin may have to be carried out
- A system calls to terminate other processes:
 - UNIX/Linux: kill()
 - Windows: TerminateProcess()

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- fork() creates an exact copy of the current process
 - The first instruction carried out by the child is the first one after the fork call
- fork() returns the process identifier of the child process to the parent process.
- fork() returns 0 to the child process.

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The Fork and Exec Pattern

A common pattern is the following sequence:

- O Call fork() to create an exact copy of the current process.
- ② In the child process call one of the "exec" functions to replace the current process with a new program.

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The Fork and Exec Pattern

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This is a typical pattern of calls in a Unix shell such as bash.

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Process Creation in Linux

```
#include <stdio.h>
#include <unistd.h>
#include <svs/wait.h>
int main() {
 pid_t const pid = fork();
 if(pid < 0){
    printf("Fork failure\n");
    return -1:
  } else if(pid == 0) {
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Test your understanding

- Why might you run fork without running a subsequent exec?
- Do you always need to call exit to end a process?
- Why does a process control block contain data about register contents?
- Why might it be useful to retain a process control block for a terminated process?

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