Python Conference ID

Rishaldy Prisly

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Who am i?

Mochamad Rishaldy Prisliyanto
Students, Hardware Enthusiast
https://github.com/rishaldyprisly

Lets get started

Build an Artificial Intelligence System in IOT With Python

Background

Python has changed my life

That's why I loved Python so much

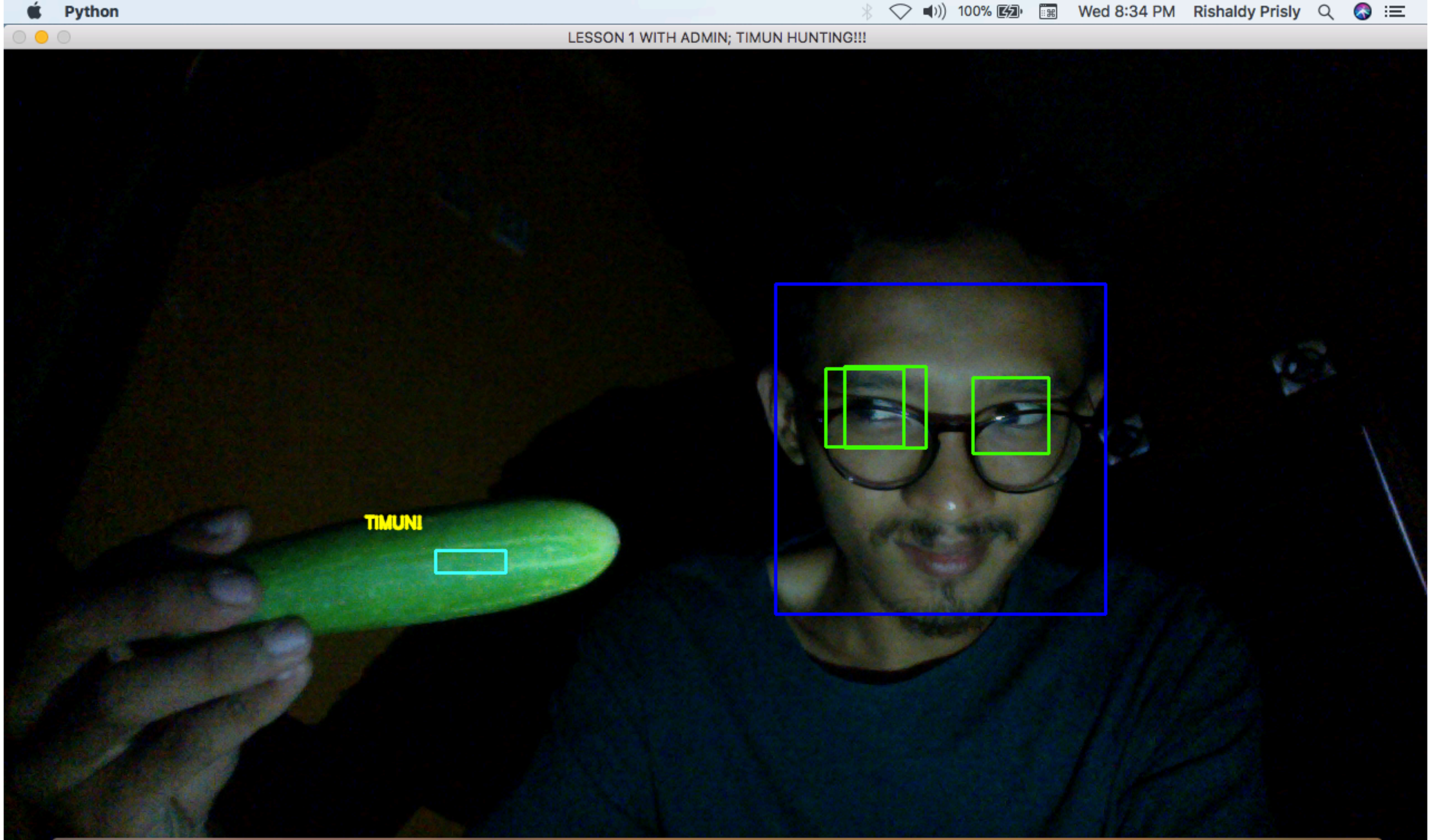
About my project

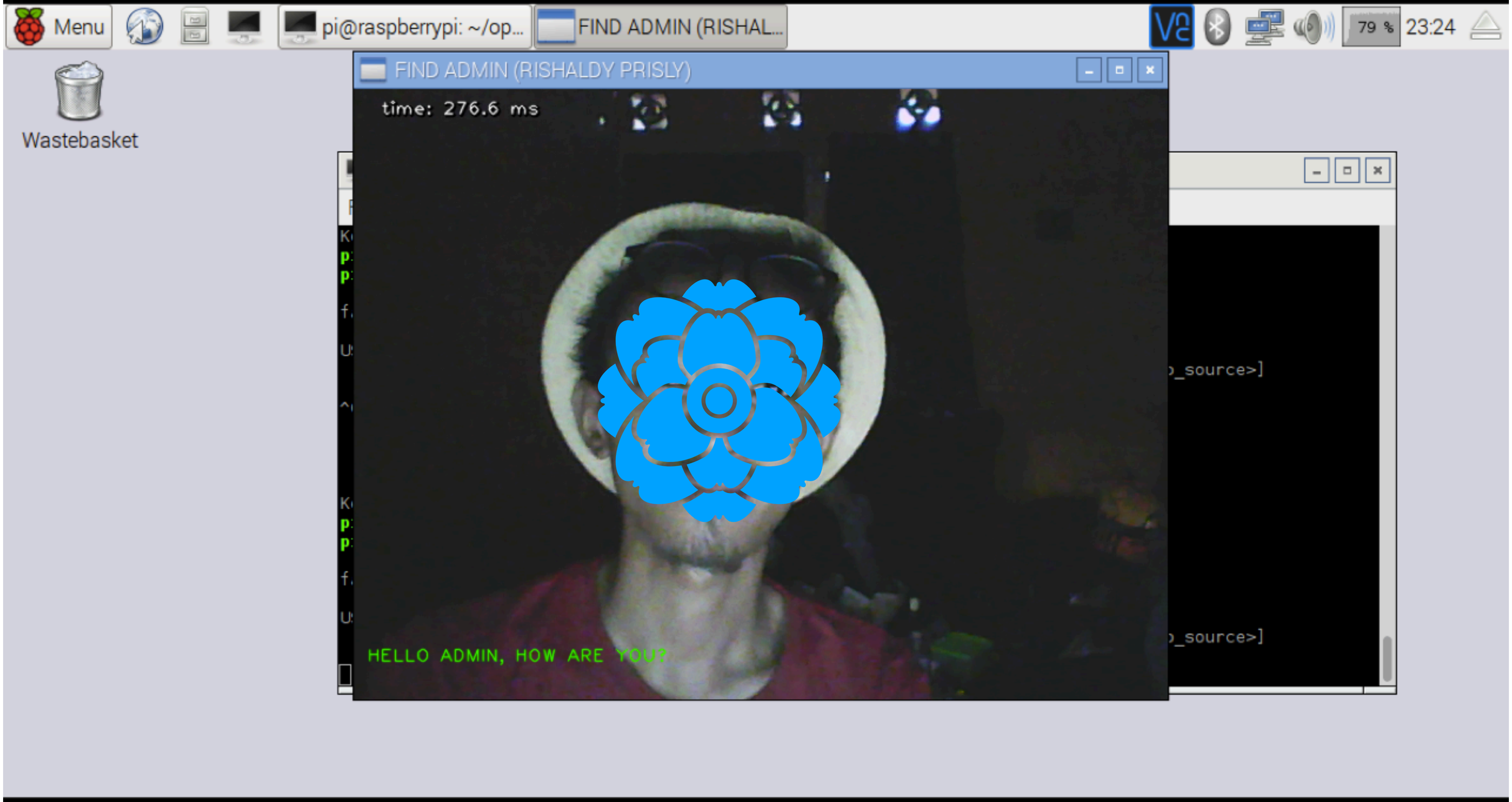
What's the purpose?

Does it really have artificial intelligence?

Feature

Recognition With Image Processing


Python
100%
Wed 8:34 PM
Rishaldy Prisly
LESSON 1 WITH ADMIN; TIMUN HUNTING!!!
TIMUN!


Menu
pi@raspberrypi: ~/op...
FIND ADMIN (RISHAL...
79 %
23:24
Wastebasket
FIND ADMIN (RISHALDY PRISLY)
time: 276.6 ms
HELLO ADMIN, HOW ARE YOU?
_source>]
_source>]

It can talks, of course, voice command

Just like a friend

Wait, where's Python?

stdlib, function, Python through processor

Python and General Purpose Input Output

```
#                 MANUAL CONTROL                  #
#      AUTHOR : MOCHAMAD RISHALDY PRISLIYANTO     #
#                     2017                        #
#             LICENSE : PUBLIC DOMAIN             #
#               www.sparkintech.com               #
#           www.rishaldy.sparkintech.com          #
#   PLEASE READ THE README FOR FURTHER INFORMATION  #

from __future__ import division
import webiopi
import os
import sys
import time
import pigpio
import Adafruit_PCA9685
pi = pigpio.pi()
pwm = Adafruit_PCA9685.PCA9685()

L1=22 # H-Bridge Input Pin 1
L2=23 # H-Bridge Input Pin 2

R1=24 # H-Bridge Input Pin 3
R2=25 # H-Bridge Input Pin 4

pi.set_mode(L1, pigpio.OUTPUT)
pi.set_mode(L2, pigpio.OUTPUT)
pi.set_mode(R1, pigpio.OUTPUT)
pi.set_mode(R2, pigpio.OUTPUT)


# ------------------------------------------------ #
#                    PWM SETUP                     #
# ------------------------------------------------ #
servo_min = 150  # Min pulse length out of 4096
servo_max = 600  # Max pulse length out of 4096
servo_mid = 375
servo_take = 50
servo_max1 = 550
servo_min1 = 200
# Helper function to make setting a servo pulse width simpler.
def set_servo_pulse(channel, pulse):
    pulse_length = 1000000    # 1,000,000 us per second
    pulse_length //= 60       # 60 Hz
    print('{0}us per period'.format(pulse_length))
    pulse_length //= 4096     # 12 bits of resolution
    print('{0}us per bit'.format(pulse_length))
    pulse *= 1000
```

Single Board Computer

Micro Python For Micro Controllers

They communicate

Im talking about the implementation

I hope I have much time

And let me show you

Here’s my friend, my robot

Question Time

I'm Rishaldy Prisly

Thank You