

Low initial diligence, nonunion, high operator cost internalization

$$(x_1, x_2, x_3)|_{t=0} = (0.2, 0.2, 0.2)$$

$$(f_1, f_2, f_3, f_u, c_1, c_2, c_3) = (3, 3.1, 0.05, 0, 0.9, 0.8, 0.1)$$

