

Stability demonstration : (1, 1, 0)

$$(x_1, x_2, x_3)|_{t=0} = (0.99, 0.99, 0.01)$$

$$(f_1, f_2, f_3, f_u, c_1, c_2, c_3) = (1.5, 1, 0.2, 0, 0.9, 0.9, 0.7)$$

