Low operator cost internalization, high initial MSHA diligence, nonunion $(x_1, x_2, x_3)|_{t=0} = (0.9, 0.3, 0.9)$

 $(f_1, f_2, f_3, f_u, c_1, c_2, c_3) = (3,0.1,0.05,0,0.4,1.3,0.1)$

