Low initial diligence, nonunion, low operator cost internalization $(x_1, x_2, x_3)|_{t=0} = (0.2, 0.2, 0.2)$ $(f_1, f_2, f_3, f_u, c_1, c_2, c_3) = (3, 0.1, 0.05, 0, 0.9, 0.8, 0.1)$

