

# 8Servos Unit

SKU:U165



## Description

**8Servos Unit** is an 8-channel servo driver unit that uses the **STM32F030F4** master control to generate multiple PWM signals for servo drive and communicate with the M5 host through I2C (addr: 0x25). Built-in total power MOSTUBE switch circuit, support programming dynamic control motor release/lock; Built-in total current acquisition circuit, the total circuit parameters can be known. Supports two sets of power inputs (9-24V / 5V). This product is suitable for servo control, robot control, intelligent toys, etc.

## Features

- 8-channel servo drive
- Programmable motor power supply
- I2C Protocol Control (0x25)
- Reverse power supply protection
- Total current harvesting function

# Includes

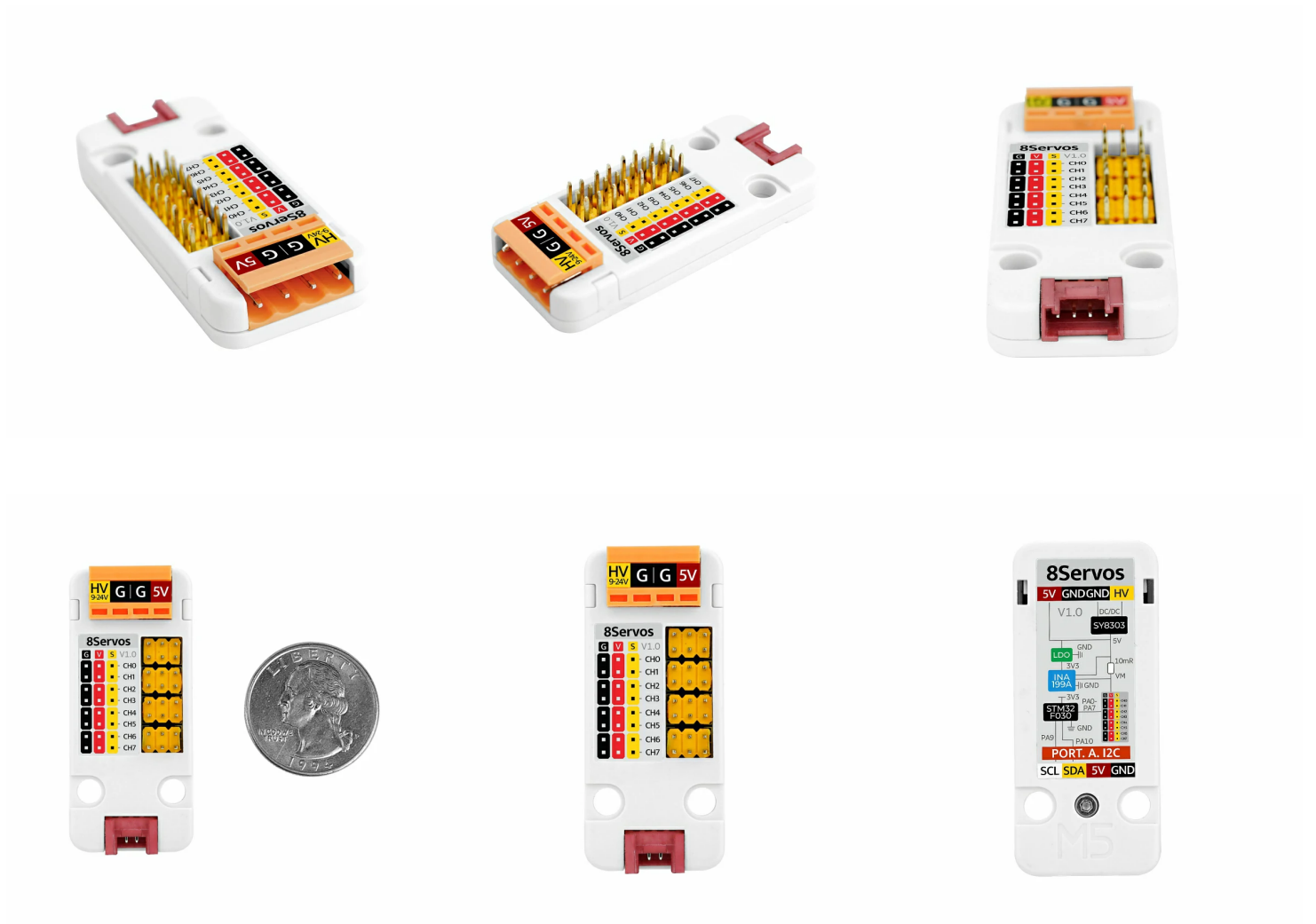
- 1 × 8Servo Unit
- 1 × HT3.96-4P
- 1 × HY2.0-4 Cable

# Applications

- Servo controller
- Robot control

# Specification

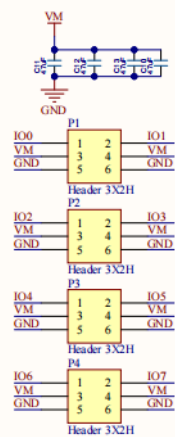
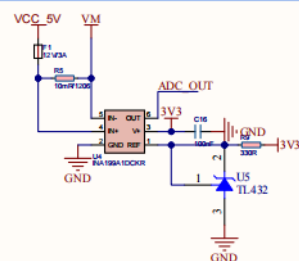
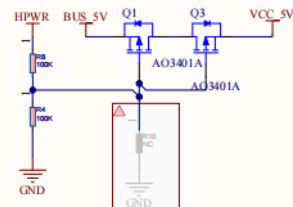
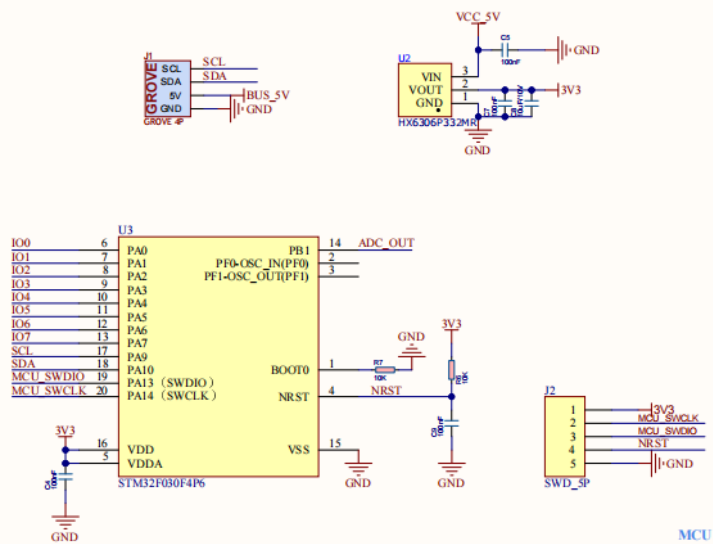
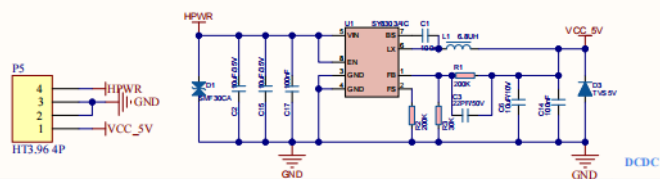
Resources	Parameters
Current acquisition chip	INA199A1DCKR
Servo drive channel	8-channel
Maximum drive load capacity	8-channel maximum load capacity: <a href="#">DC5V@1.3A</a>
I2C Address	0x25
Product Size	55*24*11.5mm
Package Size	136* 92* 13mm
Product Weight	10.1g
Package Weight	17.6g

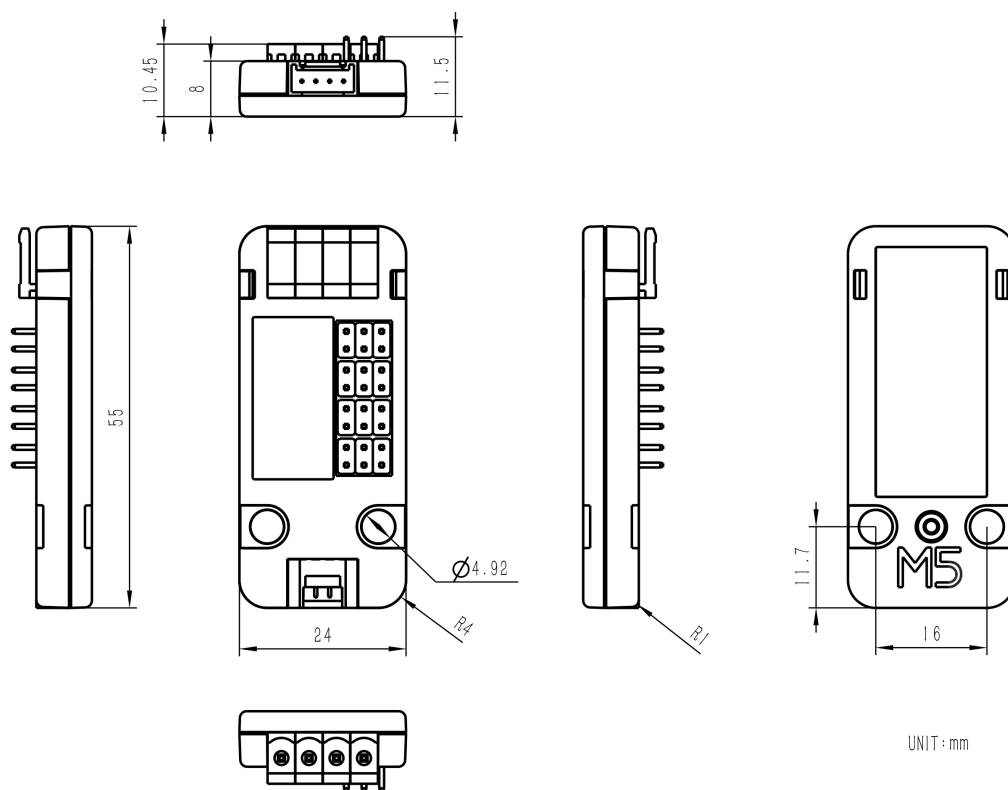


## Related Link

- [INA199A1DCKR](#)

## Schematic





## Protocol

M5Stack Unit 8Servo I2C Protocol																	V1 (FW Version)		
																	2023/3/24		
REG MAP (Addr:0x25)			0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	note
MODE SETTING		0x00 W/R	IO0	IO1	IO2	IO3	IO4	IO5	IO6	IO7								Mode:0~4 <sup>[1]</sup>	
1	OUTPUT CTRL	0x10 W	IO0	IO1	IO2	IO3	IO4	IO5	IO6	IO7								0:LOW ; 1:HIGH	
0	DIGITAL INPUT	0x20 R	IO0	IO1	IO2	IO3	IO4	IO5	IO6	IO7								0:LOW ; 1:HIGH	
2	ANALOG INPUT-8Bits	0x30 R	IO0	IO1	IO2	IO3	IO4	IO5	IO6	IO7								value:0~255	
	ANALOG INPUT-12Bits	0x40 R	IO0-L	IO0-H	IO1-L	IO1-H	IO2-L	IO2-H	IO3-L	IO3-H	IO4-L	IO4-H	IO5-L	IO5-H	IO6-L	IO6-H	IO7-L	IO7-H	value:0~4095
3	SERVO 8Bits	0x50 W/R	IO0	IO1	IO2	IO3	IO4	IO5	IO6	IO7								value:0~180degree	
	SERVO 16Bits	0x60 W/R	IO0-L	IO0-H	IO1-L	IO1-H	IO2-L	IO2-H	IO3-L	IO3-H	IO4-L	IO4-H	IO5-L	IO5-H	IO6-L	IO6-H	IO7-L	IO7-H	value:500~2500us
4	RGB 24Bits	0x70 W/R	IO0-R	IO0-G	IO0-B	IO1-R	IO1-G	IO1-B	IO2-R	IO2-G	IO2-B	IO3-R	IO3-G	IO3-B	IO4-R	IO4-G	IO4-B	IO5-R	R/G/B:0~255
		0x80 W/R	IO5-G	IO5-B	IO6-R	IO6-G	IO6-B	IO7-R	IO7-G	IO7-B									
5	PWM DutyCycle	0x90 W/R	pwm0	pwm1	pwm2	pwm3	pwm4	pwm5	pwm6	pwm7								DutyCycle:0~100 (frequency:1KHz)	
Servo Current		0xA0 R	current-byte0	current-byte1	current-byte2	current-byte3													float
I2C ADDRESS SETTING		0xF0 W/R															Addr	value: 0~127 default:0x25	
Firmware version		0xF0 R														Version		Version: firmware version	

[1] 0: Input, 1: Output, 2: ADC, 3: Servo, 4: NeoPixel, 5: PWM

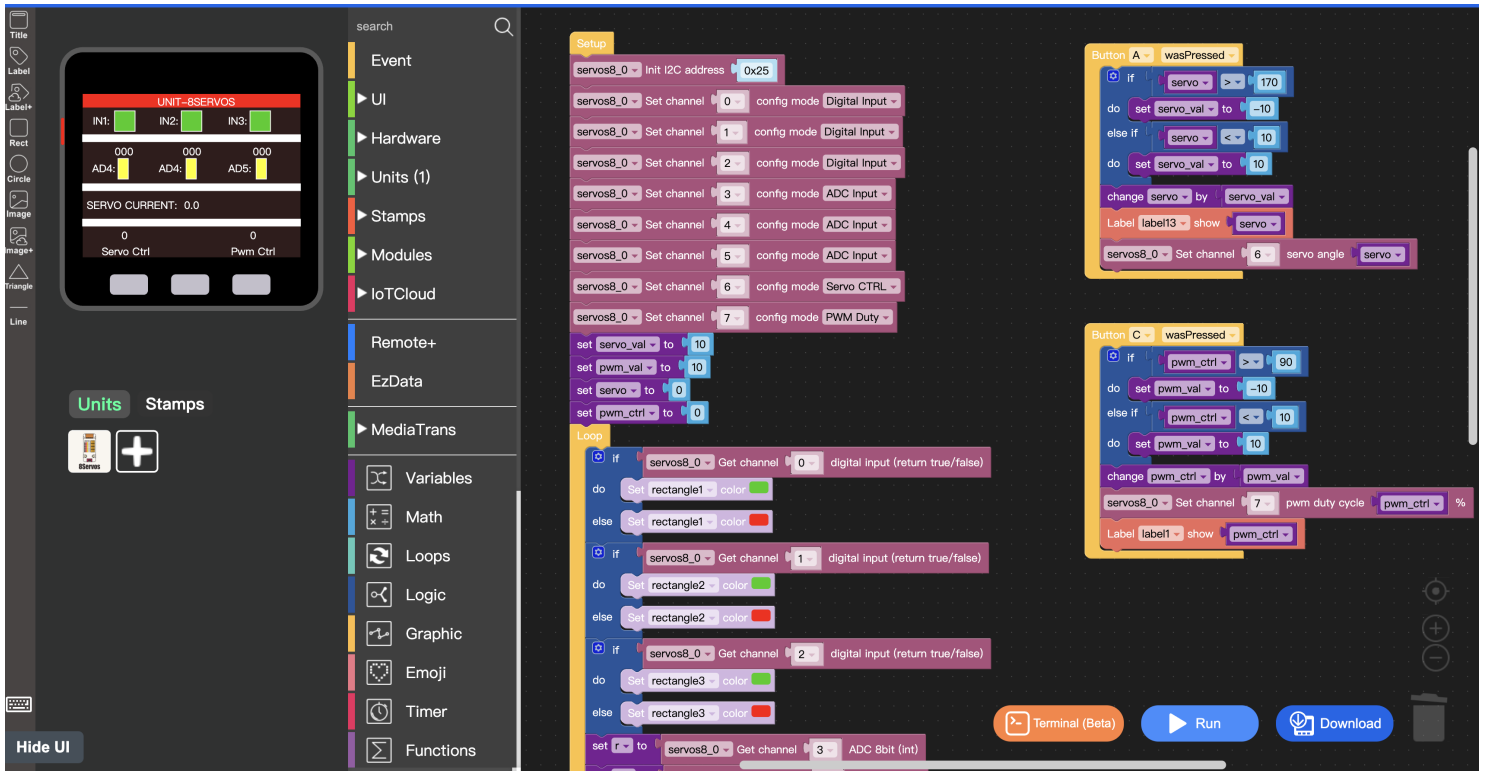
# Examples

## Arduino

- [8Servo Unit Firmware Download](#)
- [8Servo Unit Example](#)

## UIFlow

- [8Servos Unit UIFlow Demo](#)



# UIFlow Blocks

- Init I2C address



- Set config mode



- Get config mode



- Get digital input



- Get ADC 8bit

**servos8\_0** Get channel **0** ADC 8bit (int)

- Get ADC 12bit

**servos8\_0** Get channel **0** ADC 12bit (int)

- Get servo angle

**servos8\_0** Get channel **0** servo angle (int)

- Get servo pulse

**servos8\_0** Get channel **0** servo pulse (int)

- Get RGB LED color

**servos8\_0** Get channel **0** RGB LED color (list)

- Get servo current

**servos8\_0** Get servo current (float)

- Get firmware version

**servos8\_0** Get firmware version

- Set digital output level

**servos8\_0** Set channel **0** digital output level **0**

- Set servo angle

**servos8\_0** Set channel **0** servo angle **0**

- Set servo pulse





- Set pwm duty cycle



- Set RGB LED color



- Set I2C address



## | Video

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- control 8 servos demo

[U165.mp4](#)