hw9

December 9, 2021

1 Mathematical Foundations on Deep Neural Network

- 1.1 Homework #9
- $1.1.1 \quad 2017-11362$
- 1.2 Problem 1.

$$C = \left\{ (x_{1}, x_{2}) \in \mathbb{R}^{2} : x_{1} = \alpha, 0 \in x_{2} \leq 1 \right\}$$

$$T_{C}(y) = \underset{x \in C}{\operatorname{argmin}} \|x - y\|^{2} = \underset{x_{1} = \alpha}{\operatorname{argmin}} \left\{ (x_{1} - y_{1})^{2} + (x_{2} - y_{2})^{2} \right\}$$

$$\hat{x}_{1} = \underset{x_{1} = \alpha}{\operatorname{argmin}} (x_{1} - y_{1})^{2} = \alpha$$

$$\hat{x}_{2} = \underset{0 \leq x_{2} \leq 1}{\operatorname{argmin}} (x_{2} - y_{2})^{2} = \begin{cases} 1, & y_{2} > 1 \\ y_{2}, & 0 \leq y_{2} \leq 1 \end{cases}$$

$$T_{C}(y) = \begin{bmatrix} \hat{x}_{1} \\ \hat{x}_{2} \end{bmatrix} = \begin{bmatrix} \alpha \\ \min(\max(y_{2}, 0), 1) \end{bmatrix}$$

1.3 Problem 2.

```
[2]: import torch
import torch.nn as nn
import torch.nn.functional as F
import torchvision
from torchvision import datasets, transforms
from torchvision.utils import save_image, make_grid

import numpy as np
import matplotlib.pyplot as plt

batch_size = 128
(full_dim, mid_dim, hidden) = (1 * 28 * 28, 1000, 5)
lr = 1e-3
```

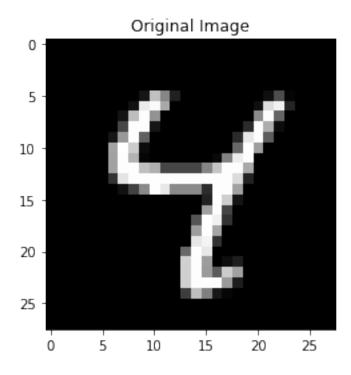
```
epochs = 100
device = torch.device("cpu")
# STEP 1: Define dataset and preprocessing #
class Logistic(torch.distributions.Distribution):
   def __init__(self):
       super(Logistic, self).__init__()
   def log_prob(self, x):
       return -(F.softplus(x) + F.softplus(-x))
   def sample(self, size):
       z = torch.distributions.Uniform(0., 1.).sample(size).to(device)
       return torch.log(z) - torch.log(1. - z)
# STEP 3: Implement Coupling Layer #
class Coupling(nn.Module):
   def __init__(self, in_out_dim, mid_dim, hidden, mask_config):
       super(Coupling, self).__init__()
       self.mask_config = mask_config
       self.in_block = nn.Sequential(nn.Linear(in_out_dim//2, mid_dim), nn.
→ReLU())
       self.mid_block = nn.ModuleList([nn.Sequential(nn.Linear(mid_dim,_
→mid_dim), nn.ReLU())
                                                         for _ in_
→range(hidden - 1)])
       self.out_block = nn.Linear(mid_dim, in_out_dim//2)
   def forward(self, x, reverse=False):
       [B, W] = list(x.size())
      x = x.reshape((B, W//2, 2))
       if self.mask_config:
          on, off = x[:, :, 0], x[:, :, 1]
       else:
          off, on = x[:, :, 0], x[:, :, 1]
      off_ = self.in_block(off)
       for i in range(len(self.mid_block)):
          off_ = self.mid_block[i](off_)
```

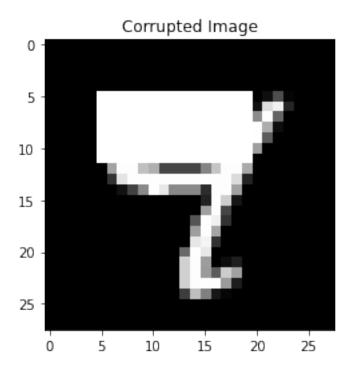
```
shift = self.out_block(off_)
       if reverse:
            on = on - shift
        else:
           on = on + shift
       if self.mask_config:
           x = torch.stack((on, off), dim=2)
       else:
            x = torch.stack((off, on), dim=2)
       return x.reshape((B, W))
class Scaling(nn.Module):
   def __init__(self, dim):
       super(Scaling, self).__init__()
       self.scale = nn.Parameter(torch.zeros((1, dim)), requires_grad=True)
   def forward(self, x, reverse=False):
       log_det_J = torch.sum(self.scale)
       if reverse:
           x = x * torch.exp(-self.scale)
       else:
           x = x * torch.exp(self.scale)
       return x, log_det_J
#############################
# STEP 4: Implement NICE #
class NICE(nn.Module):
   def __init__(self,in out_dim, mid_dim, hidden, mask_config=1.0, coupling=4):
       super(NICE, self).__init__()
       self.prior = Logistic()
       self.in_out_dim = in_out_dim
       self.coupling = nn.ModuleList([
            Coupling(in_out_dim=in_out_dim,
                    mid dim=mid dim,
                    hidden=hidden,
                    mask_config=(mask_config+i)%2) \
           for i in range(coupling)])
       self.scaling = Scaling(in_out_dim)
   def g(self, z):
       x, _ = self.scaling(z, reverse=True)
```

```
for i in reversed(range(len(self.coupling))):
            x = self.coupling[i](x, reverse=True)
        return x
   def f(self, x):
       for i in range(len(self.coupling)):
            x = self.coupling[i](x)
        z, log_det_J = self.scaling(x)
       return z, log_det_J
   def log_prob(self, x):
        z, log_det_J = self.f(x)
        log_ll = torch.sum(self.prior.log_prob(z), dim=1)
       return log_ll + log_det_J
   def sample(self, size):
        z = self.prior.sample((size, self.in_out_dim)).to(device)
       return self.g(z)
   def forward(self, x):
       return self.log_prob(x)
# Load pre-trained NICE model onto CPU
model = NICE(in_out_dim=784, mid_dim=1000, hidden=5).to(device)
model.load_state_dict(torch.load('nice.pt',map_location=torch.device('cpu')))
# Since we do not update model, set requires_grad = False
model.requires_grad_(False)
# Get an MNIST image
testset = torchvision.datasets.MNIST(root='../data/mnist_data', train=False,__
→download=True, transform=torchvision.transforms.ToTensor())
test loader = torch.utils.data.DataLoader(testset, batch size=1, shuffle=False)
pass count = 6
itr = iter(test_loader)
for _ in range(pass_count+1):
   image,_ = itr.next()
plt.figure(figsize = (4,4))
plt.title('Original Image')
plt.imshow(make_grid(image.squeeze().detach()).permute(1,2,0))
plt.show()
# plt.savefig('plt1.png')
# Create mask
```

```
mask = torch.ones_like(image,dtype=torch.bool)
mask[:,:,5:12,5:20] = 0

# Partially corrupt the image
image[mask.logical_not()] = torch.ones_like(image[mask.logical_not()])
plt.figure(figsize = (4,4))
plt.title('Corrupted Image')
plt.imshow(make_grid(image.squeeze()).permute(1,2,0))
plt.show()
# plt.savefig('plt2.png')
```





```
[3]: lr = 1e-3
X = image.clone().requires_grad_(True)

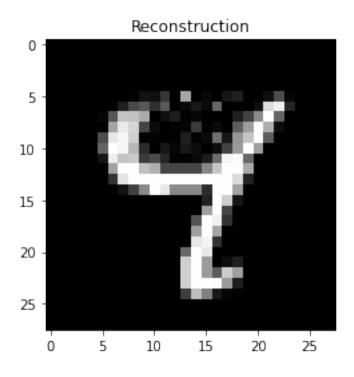
optimizer = torch.optim.SGD([X], lr=lr)

for i in range(3000):
    loss = - model(X.view(1, -1))
    loss.backward()

    optimizer.step()
    optimizer.zero_grad()

    X.data = torch.clamp(image.data * mask + X.data * (~ mask), 0, 1)

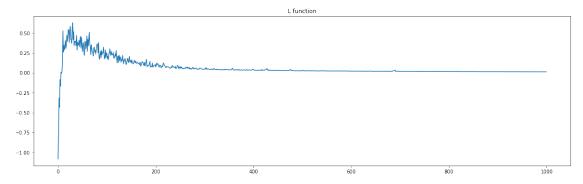
# Plot reconstruction
plt.figure(figsize = (4,4))
plt.title('Reconstruction')
plt.imshow(make_grid(X.squeeze().detach()).permute(1,2,0))
plt.show()
# plt.savefig('plt3.png')
```

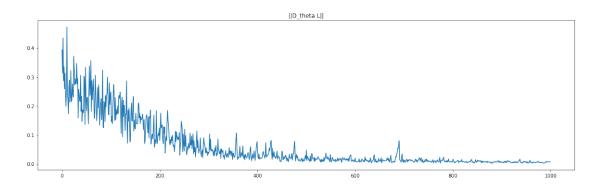


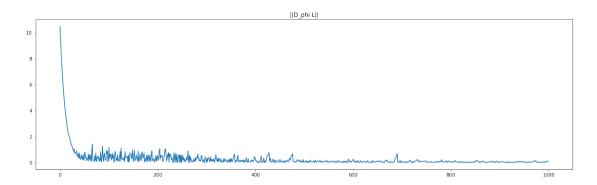
1.4 Problem 3.

1.5 Problem 4.

```
[4]: import numpy as np
     from matplotlib import pyplot as plt
     import math
     N, p = 30, 20
     np.random.seed(0)
     X = np.random.randn(N,p)
     Y = 2*np.random.randint(2, size = N) - 1
     lamda = 30
     theta = 0.1 * np.random.randn(p)
     phi = 0.1 * np.random.randn(p)
     alpha = 3e-1
     beta = 1e-4
     epoch = 1000
     L val = []
     d_phi_val = []
     d_theta_val = []
     for _ in range(epoch):
         for __ in range(N):
             ind = np.random.randint(N)
             Xi, Yi = X[ind, :], Y[ind]
             expo = np.exp(Yi * ((Xi - phi) @ theta))
             grad\_theta = - Yi / (1 + expo) * (Xi - phi)
             grad_phi = Yi / (1 + expo) * theta - lamda * phi
             theta -= alpha * grad_theta
             phi += beta * grad_phi
         L_i = np.average(np.log(1 + np.exp(-Y * ((X - phi.reshape(1,-1))) @_{L}))
      →theta)))) - lamda/2 * np.linalg.norm(phi, axis=0, ord=2) **2
         d phi = np.average(Y / (1 + np.exp(Y * ((X-phi.reshape(1,-1)) @ theta)))) *_{\sqcup}
      →theta - lamda * phi
         d_{theta} = np.average((-Y / (1 + np.exp(Y * ((X-phi.reshape(1,-1))) @_{U}))
      \rightarrowtheta)))).reshape(-1,1)*(X-phi.reshape(1,-1)), axis=0)
         L_val.append(L_i)
         d_phi_val.append(d_phi)
         d_theta_val.append(d_theta)
     fig, ax = plt.subplots(figsize=(20, 20))
     plt.subplots_adjust(left=0.125,
                          bottom=0.1,
                          right=0.9,
                          top=0.9,
```







1.6 Problem 5.

(a) Min max Epa, PB [points of B]

For PA = (a, y, 1-2-y)t, 0 = a, y, x+y = 1, PB = (a, b, 1-a-b)t, 0 = a, b, a+b = 1.

E[pts. of B] = \frac{1}{a} [xb + y(1-a-b) + (1-x-y)a - ya - (1-x-y)b - x(1-a-b)]

$$= \frac{\pi b}{3} - \frac{ya}{3} + \frac{1}{9}(y-x+a-b)$$

$$= \frac{1}{3}(x - \frac{1}{3})(b - \frac{1}{3}) - \frac{1}{3}(y - \frac{1}{3})(a - \frac{1}{3})$$

 $\mathsf{E}_{\mathsf{PA}^{\mathsf{A}},\;\mathsf{PB}} \leq \mathsf{E}_{\mathsf{PA}^{\mathsf{A}},\;\mathsf{Pg}^{\mathsf{A}}} \leq \mathsf{E}_{\mathsf{PA},\;\mathsf{Pg}^{\mathsf{A}}}$

$$(x^{*} - \frac{1}{3})(b - b^{*}) \leq (y^{*} - \frac{1}{3})(a - a^{*})$$
 $\forall a, b s.t o \leq a, b, a+b \leq 1$

i)
$$x^* > \frac{1}{3}$$
, $y^* > \frac{1}{3}$: $0 \Rightarrow b-b^* \le k(a-a^*)$, $k>0 \Rightarrow a^*=0$, $b^*=1$

$$\Leftrightarrow \begin{cases} k < 1: 2x^{*} + y^{*} \leq 2x + y \text{ (contradiction)} \\ \\ k > 1: x^{*} + 2y^{*} \leq x + 2y \text{ (contradiction)} \end{cases}$$

We can similarly derive contradiction at other case except $x^* = y^* = \frac{1}{3}$.

$$x^* = y^* = \frac{1}{3}$$

..
$$P_{A} = \begin{bmatrix} \frac{1}{3} \\ \frac{1}{3} \end{bmatrix}^{\frac{1}{3}} P_{a} = \begin{bmatrix} \frac{1}{3} \\ \frac{1}{3} \end{bmatrix}^{\frac{1}{3}}$$
 is the unique solution of minimax problem.

(b) Arbitrary PA* might satisfy EpA, PB* € EpA, PB*

However, Intinimax problem should satisfy both $E_{PA^*,PB} \leq E_{PA^*,PB^*}$ and $E_{PA^*,PB^*} \leq E_{PA},P_{B^*}$.

Epax, pb < Epax, pbx cannot be satisfied when pax + [3, 3, 3]t.

.. any stretagy is not optimal for A.