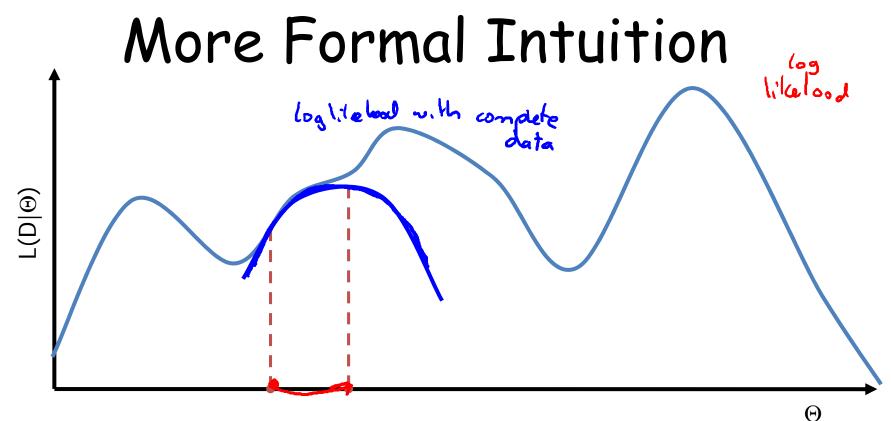


Learning

Incomplete Data

EM Analysis



- Use current point to construct local approximation
- Maximize new function in closed form

Daphne Koller

More Formal Intuition

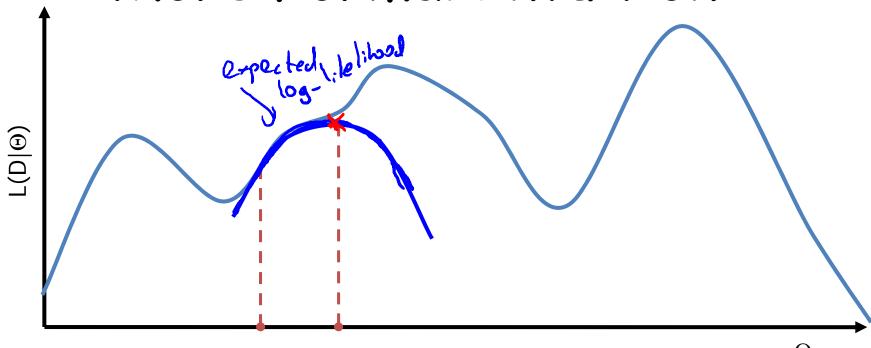
- d: observed data in instance
- H: hidden variables in instance
- Q(H): distribution over hidden variables $\ell(\boldsymbol{\theta}:\langle \boldsymbol{d},\boldsymbol{h}\rangle) = \sum_{\substack{i=1\\n}} \sum_{(x_i,u_i)\in Val(X_i,\mathbf{Pa}_{X_i})} \mathbf{1}_{\langle \boldsymbol{d},\boldsymbol{h}\rangle}[x_i,u_i] \log \theta_{x_i|u_i}$ $E_{Q(H)}[\ell(\boldsymbol{\theta}:\langle \boldsymbol{d},\boldsymbol{H}\rangle)] = \sum_{i=1} \sum_{(x_i,u_i)\in Val(X_i,\mathbf{Pa}_{X_i})} E_{Q(H)}[\mathbf{1}_{\langle \boldsymbol{d},\boldsymbol{H}\rangle}[x_i,u_i]] \log \theta_{x_i|u_i}$ $= \sum_{i=1}^n \sum_{(x_i,u_i)\in Val(X_i,\mathbf{Pa}_{X_i})} Q(x_i,u_i) \log \theta_{x_i|u_i}$

More Formal Intuition

$$\begin{split} \mathbf{E}_{Q(H)}[\ell(\boldsymbol{\theta}:\langle \boldsymbol{d},\boldsymbol{H}\rangle)] &= \sum_{i=1}^{n} \sum_{(x_{i},\boldsymbol{u}_{i})} Q(x_{i},\boldsymbol{u}_{i}) \log \theta_{x_{i}|\boldsymbol{u}_{i}} \\ Q_{m}^{t}(\boldsymbol{H}[m]) &= P(\boldsymbol{H}[m] \mid \boldsymbol{d}[m],\boldsymbol{\theta}^{t}) \\ \sum_{m=1}^{M} \underline{\mathbf{E}_{Q_{m}^{t}(\boldsymbol{H}[m])}[\ell(\boldsymbol{\theta}:\langle \boldsymbol{d}[m],\boldsymbol{H}[m]\rangle)]} \\ &= \sum_{i=1}^{n} \sum_{(x_{i},\boldsymbol{u}_{i})} \sum_{m=1}^{M} P(x_{i},\boldsymbol{u}_{i} \mid \boldsymbol{d}[m],\boldsymbol{\theta}^{t}) \log \theta_{x_{i}|\boldsymbol{u}_{i}} \\ &= \sum_{i=1}^{n} \sum_{(x_{i},\boldsymbol{u}_{i})} \underline{\bar{M}}_{\boldsymbol{\theta}^{t}}[x_{i},\boldsymbol{u}_{i}] \log \theta_{x_{i}|\boldsymbol{u}_{i}} \quad \text{complete data} \\ &= \sum_{i=1}^{n} \sum_{(x_{i},\boldsymbol{u}_{i})} \underline{\bar{M}}_{\boldsymbol{\theta}^{t}}[x_{i},\boldsymbol{u}_{i}] \log \theta_{x_{i}|\boldsymbol{u}_{i}} \quad \text{complete data} \end{split}$$

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EM Guarantees

- $L(D: \theta^{\dagger+1}) \geq L(D: \theta^{\dagger})$
 - Each iteration improves the likelihood

gradient is zero

- If $\theta^{t+1} = \theta^t$, then θ^t is a stationary point of $L(D:\theta)$
 - Usually, this means a local maximum