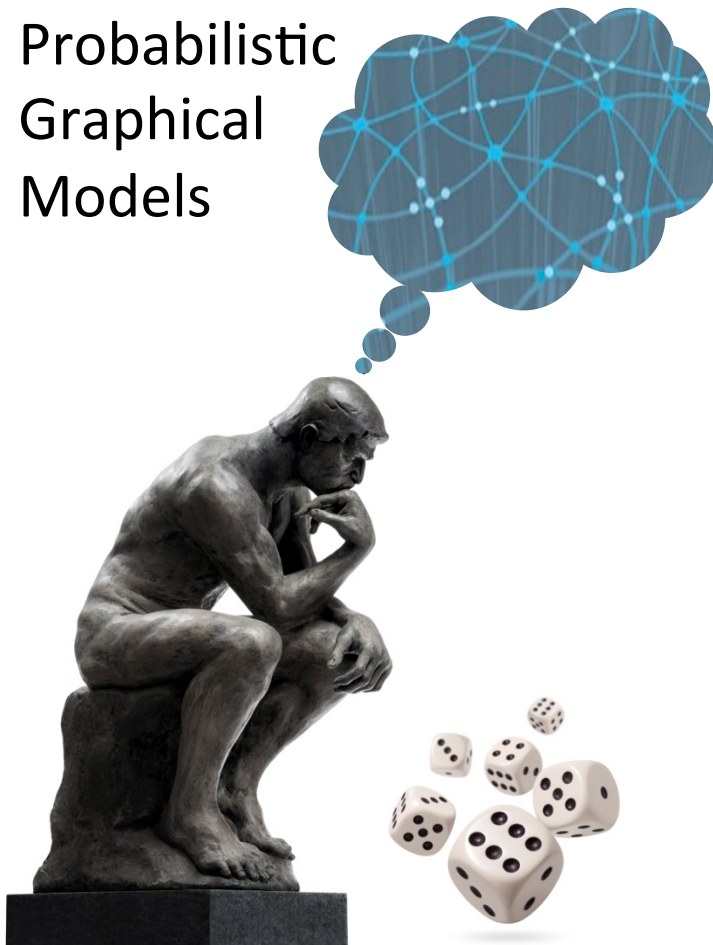


Probabilistic  
Graphical  
Models



Representation

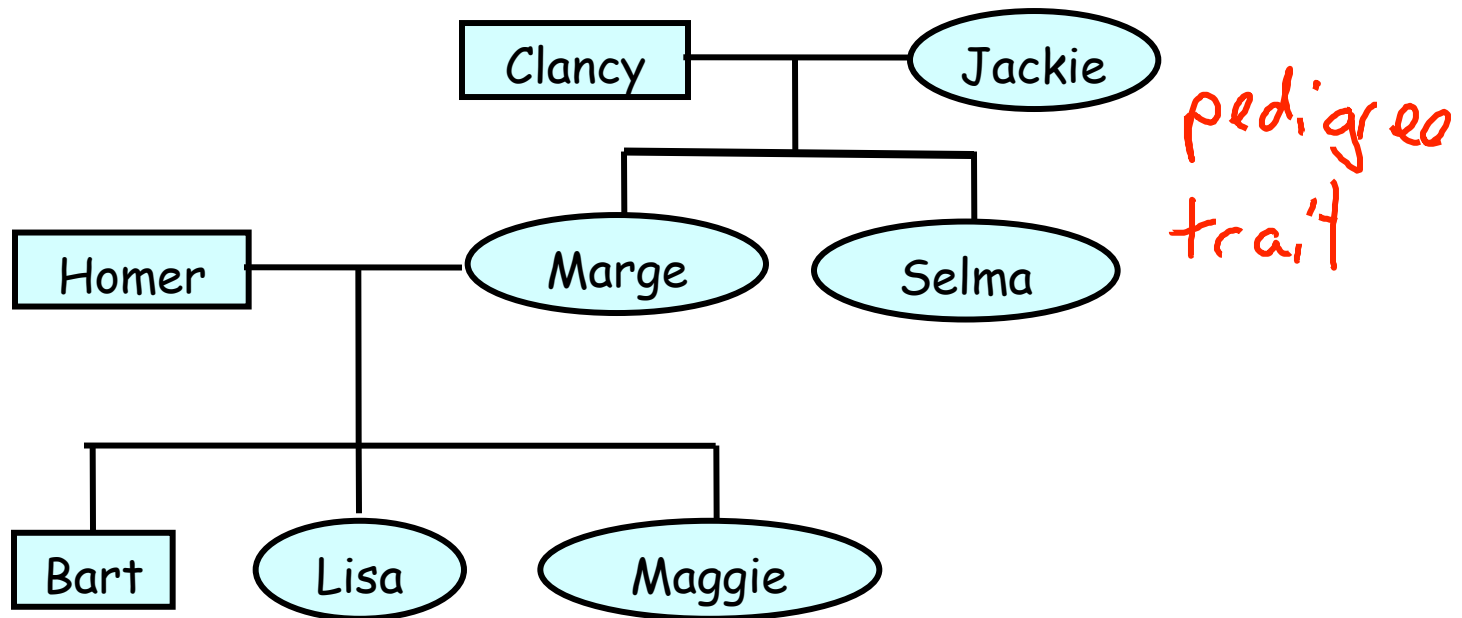
---

Template Models

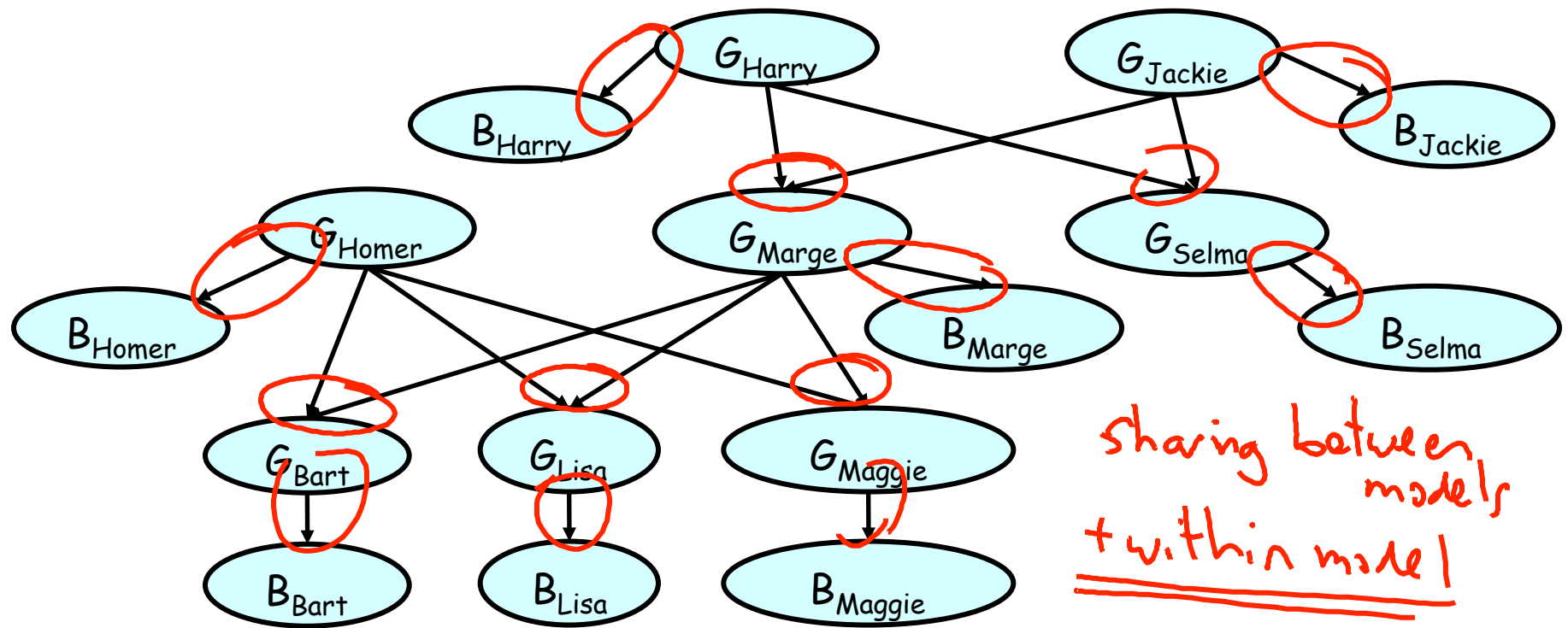
---

# Overview

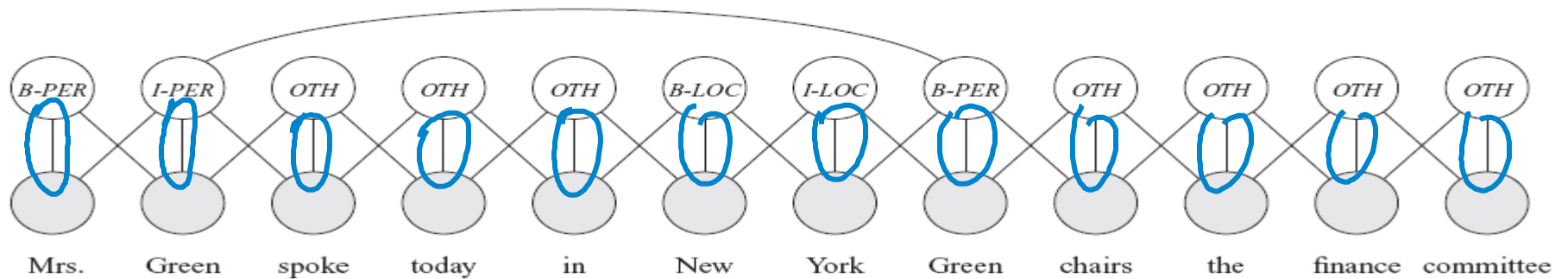
# Genetic Inheritance



# Genetic Inheritance



# NLP Sequence Models



## KEY

<i>B-PER</i>	Begin person name	<i>I-LOC</i>	Within location name
<i>I-PER</i>	Within person name	<i>OTH</i>	Not an entity
<i>B-LOC</i>	Begin location name		

Named entity recognition

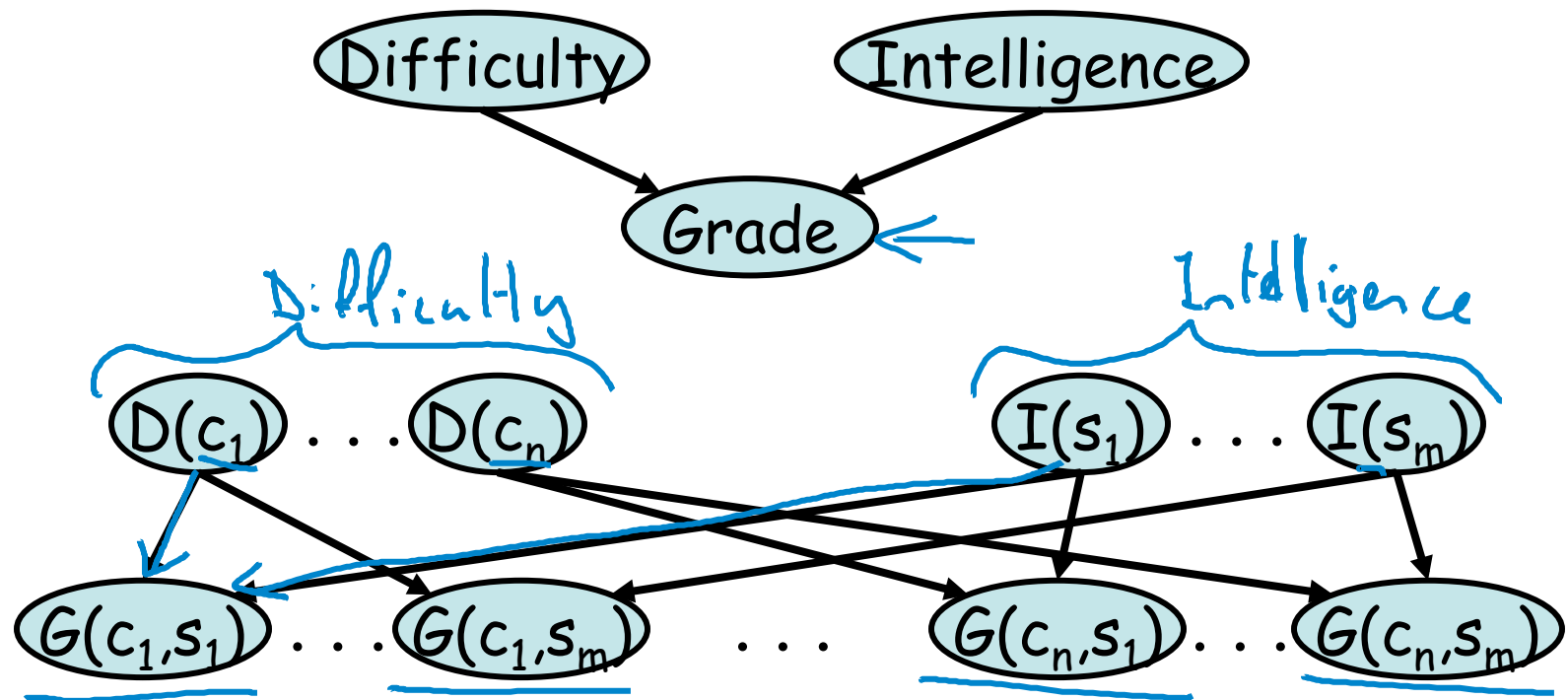
# Image Segmentation

sharing across  
pixel  
and pairs  
of super pixels



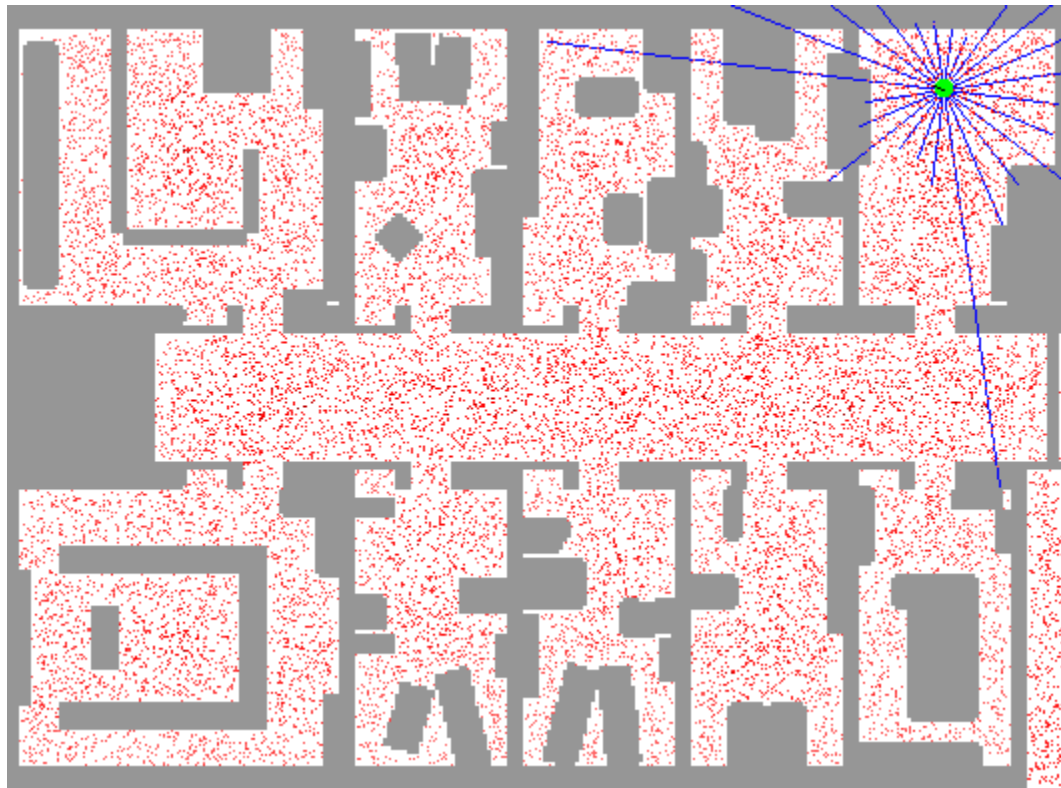
between  
and  
within

# The University Example



# Robot Localization

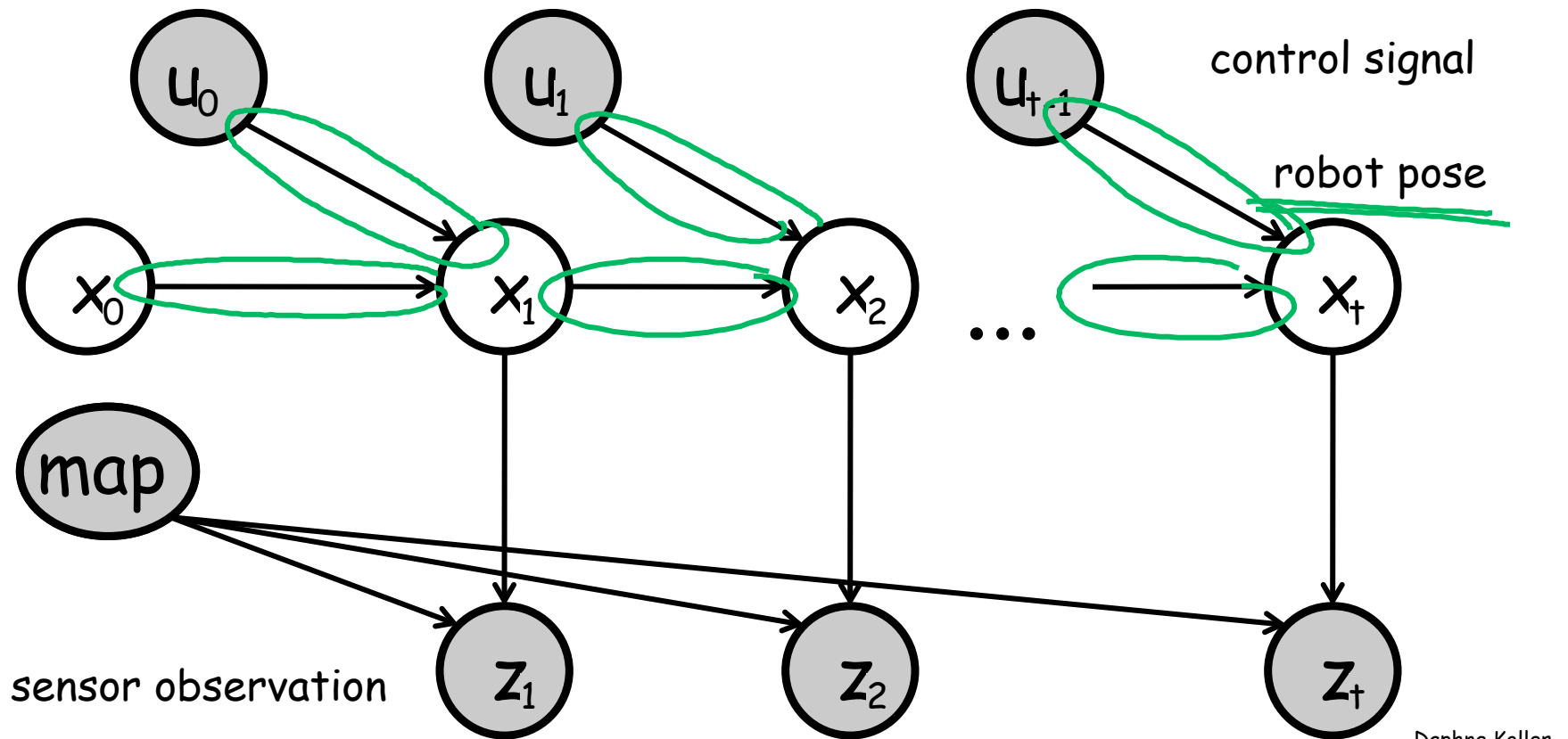
time series  
position at  
time  $t$   
changes over  
time  
robot dynamics  
are fixed



Fox, Burgard, Thrun

Daphne Koller

# Robot Localization





# Template Variables

- Template variable  $X(\underline{U}_1, \dots, \underline{U}_k)$  is instantiated (duplicated) multiple times
  - Location(t), Sonar(t)
  - Genotype(person), Phenotype(person)
  - Label(pixel)
  - Difficulty(course), Intelligence(student), Grade(course, student)

# Template Models

- Languages that specify how <sup>ground</sup> variables inherit dependency model from template
- Dynamic Bayesian networks  $\leftarrow$  <sup>temporal</sup>
- Object-relational models <sup>people, courses, pixels, ...</sup>
  - Directed
    - Plate models
  - Undirected