

Notes - 19/11/24

(*) Phase and Group Velocity

Consider 2 sinusoidal waves of slightly different wavelengths on a string

$$y_1 = A \sin 2\pi (\kappa_1 x - v_1 t)$$

$$y_2 = A \sin 2\pi (\kappa_2 x - v_2 t)$$

Characteristic speeds are $v = \frac{\omega}{\kappa} = \frac{2\pi v}{\kappa}$

→ Superposition of these 2 waves yields

$$\circ y = A (\sin [2\pi (\kappa_1 x - v_1 t)] + \sin [2\pi (\kappa_2 x - v_2 t)])$$

$$= 2A \cos \pi ((\kappa_1 - \kappa_2)x - (v_1 - v_2)t) \times$$

$$\sin \left(2\pi \left(\frac{\kappa_1 + \kappa_2}{2}x - \frac{v_1 + v_2}{2}t \right) \right)$$

↳ 2 wavelengths - very similar

$$\kappa_1 - \kappa_2 = \Delta \kappa$$

$$v_1 - v_2 = \Delta v$$

$$Y = 2A \cos \pi(x\omega k - t\Delta v) \sin 2\pi(\kappa x - vt)$$

where $\kappa = \frac{\kappa_1 + \kappa_2}{2}$, $v = \frac{v_1 + v_2}{2}$

2 characteristic velocities here:

One - the speed at which a crest belonging to the average wave no. ' κ ' moves along.

This is phase velocity

$$v_p = \frac{\omega}{\kappa} = v\lambda$$

Other - is the velocity at which the modulating envelope moves. This envelope encloses a group of short waves.

Group velocity = $v_g = \frac{\Delta \omega}{\Delta k} = \frac{d\omega}{dk}$

Consider waves in deep water "gravity waves"

These are strongly dispersive - wave speed

for a well-defined λ

(Cle phase velocity)

\propto proportional to $\lambda^{1/2}$

C: constant

$$V_p = C\lambda^{1/2} \sim C' \kappa^{-1/2}$$

but $V_p = \frac{w}{\kappa} \therefore w \sim C \kappa^{1/2}$

$$\frac{dw}{d\kappa} = \frac{1}{2} C \kappa^{-1/2} = V_g$$

i.e
$$V_g = \frac{V_p}{2}$$

component wave crests, seem to pass rapidly through the group first growing in amplitude and disappearing again

NOTE: sound waves in gases (like other elastic vibrations) — are non-dispersive

★ Review of gradient, divergence and curl :

→ If we have a function of one variable $f(n)$ then $\frac{df}{dn}$ tells us how rapidly $f(n)$ varies when we change the argument by a tiny amount dn .

$$df = \left(\frac{df}{dn} \right) dn$$

Geometrical interpretation
— $\frac{df}{dn}$ is the slope of the curve $f(n)$

Gradient :

Now, if we have a function of 3 variables eg. Temperature $T(x, y, z)$ in a room

$$dT = \left(\frac{\partial T}{\partial x} \right) dx + \left(\frac{\partial T}{\partial y} \right) dy + \left(\frac{\partial T}{\partial z} \right) dz$$

— the partial derivatives being along each of the 3 coordinate directions

$$\text{ie } dT = \left(\frac{\partial T}{\partial x} i + \frac{\partial T}{\partial y} j + \frac{\partial T}{\partial z} k \right) \cdot (dx i + dy j + dz k)$$

$$= \vec{\nabla} T \cdot d\vec{r}$$

gradient of
 T

\rightarrow Infinitesimal displacement vector

$$d\Gamma = \vec{\nabla} T \cdot d\vec{r} = |\vec{\nabla} T| |d\vec{r}| \cos \theta$$

\rightarrow if we keeps $|d\vec{r}|$ fixed - i.e find its magnitude and search around in various directions, max change in T occurs when $\theta = 0$.

i.e for a fixed distance $|d\vec{r}|$, dT is greatest when moved in the same direction as $\vec{\nabla} T$
i.e $\vec{\nabla} T$ points in the direction of maximum

increase of the function T .

→ Should gradient vanish

$$\text{i.e } \vec{\nabla}T = 0 \text{ at } (x, y, z)$$

⇒ $dT = 0$ for small points about (x, y, z)

⇒ This is a **stationary point** of the function $T(x, y, z)$

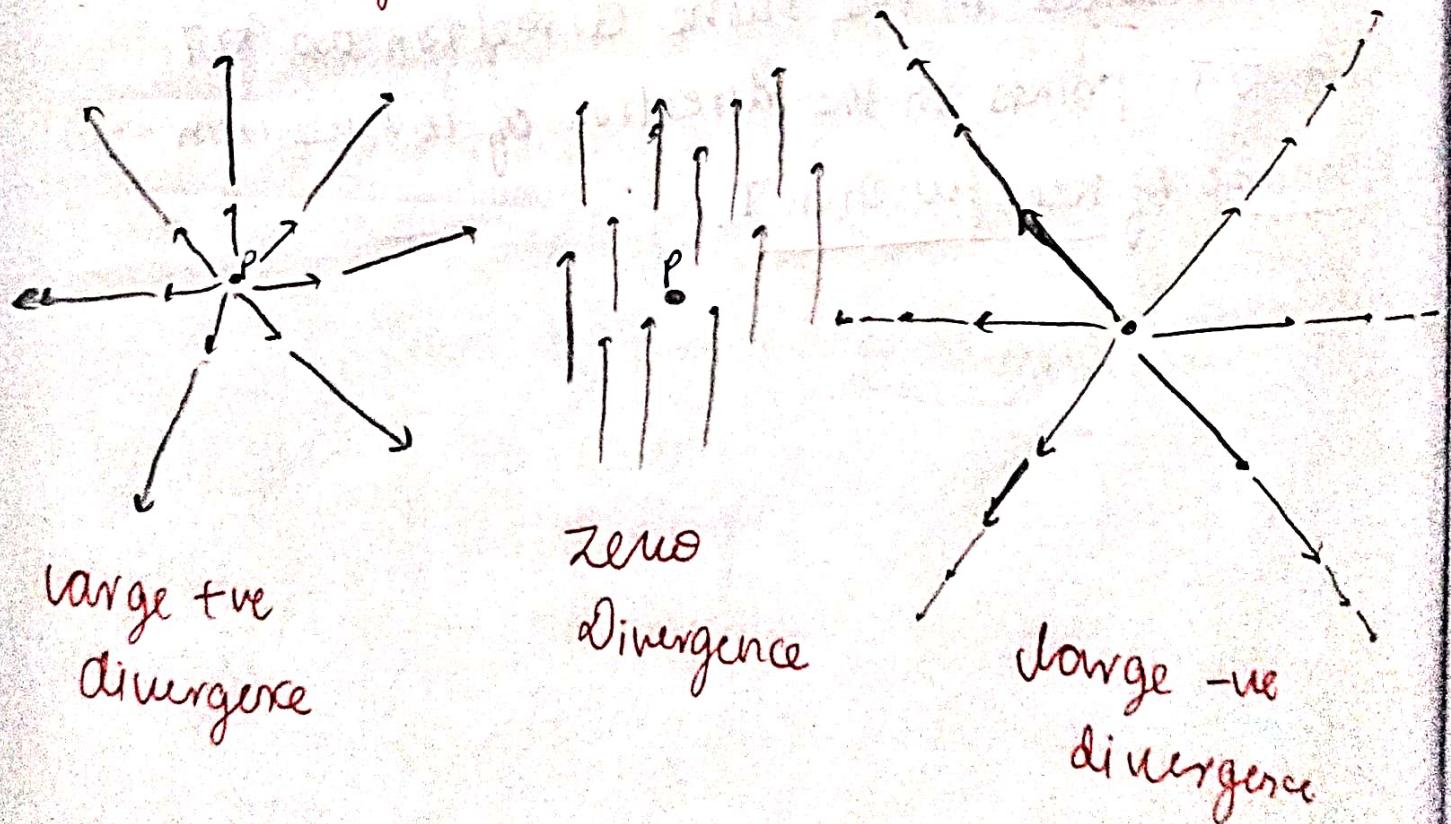
- i.e it could be a maximum (summit)

- or could be a minimum (valley)

- or a saddle point (a pass)

④ Divergence:

- a measure of how much the vector spreads out (diverges) from a point



$$\vec{\nabla} \cdot \vec{A} = \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \cdot (A_x \hat{i} + A_y \hat{j} + A_z \hat{k})$$

Indicative of rotation

and:

$$\vec{\nabla} \times \vec{V} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix}$$



$$\vec{\nabla} \times \vec{V} = \hat{i} \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) - \hat{j} \left(\frac{\partial v_z}{\partial x} - \frac{\partial v_x}{\partial z} \right) + \hat{k} \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right)$$

Divergence:

- If a large +ve divergence - source
- If a large -ve divergence - sink
or a drain

Consider the

Vector \vec{V} - velocity of
surface of
water

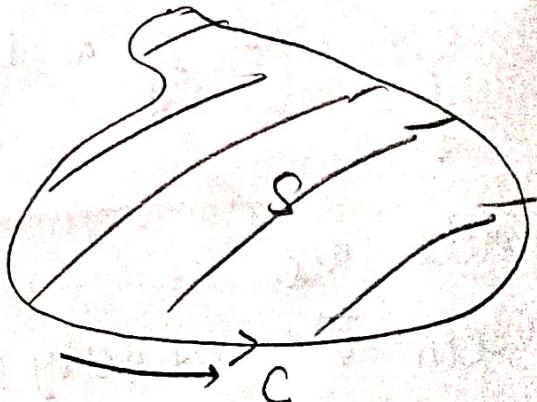
Gauss Theorem or divergence theorem

$$\int_{\text{Vol}} (\vec{\nabla} \cdot \vec{V}) d\tau = \iint_{\text{surface}} \vec{V} \cdot \vec{dA}$$

Stokes theorem: If S is an open 2-sided surface bounded by a closed non-intersecting curve C , then if \vec{A} is continuous

$$\oint_C \vec{A} \cdot d\vec{l} = \iint_S (\vec{\nabla} \times \vec{A}) \cdot \hat{n} ds$$

C is traversed in the true direction



① Green's Theorem in a plane

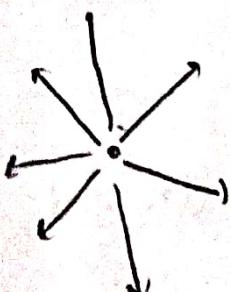
→ If R is a closed region of the xy plane bounded by a simple closed curve C and if M & N are continuous functions of x & y having continuous derivatives in R then

$$\oint_C M dx + N dy = \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx dy$$

→ C being traversed in the +ve counterclockwise direction

② Divergence of $\frac{\vec{r}}{r^2}$:

Consider $\vec{V} = \frac{\vec{r}}{r^2}$



The source of problem is free singularity at $r=0$
 $\vec{\nabla} \cdot \vec{V} = 0$ everywhere except at the origin

→ In spherical coordinates

$$\begin{aligned} \vec{\nabla} \cdot \vec{A} &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta A_\theta) \\ &\quad + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} A_\phi \end{aligned}$$

$$\vec{\nabla} \cdot \vec{J} = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{1}{r^2} \right) = \frac{1}{r^2} \frac{\partial}{\partial r} (1) = 0 \quad [3]$$

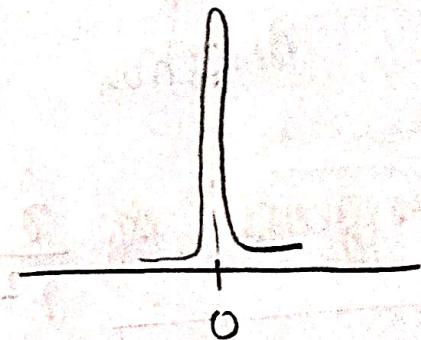
Now

$$\begin{aligned} \int \vec{V} \cdot d\vec{a} &= \int \left(\frac{1}{r^2} \hat{r} \right) \cdot (r^2 \sin\theta d\phi d\theta) \hat{r} \\ \text{But this} &= \int_0^{\pi} \sin\theta d\theta \int_0^{2\pi} d\phi = 2\pi \end{aligned}$$

$\int \vec{\nabla} \cdot \vec{J} da$ (Gauss's theorem)

→ Such a function is the dirac delta fn

$$\delta(x) = \begin{cases} 0 & x \neq 0 \\ \infty & x = 0 \end{cases}$$



$$\int_{-\infty}^{\infty} \delta(x) dx = 1$$

$$\delta(x-a) = \begin{cases} 0 & x \neq a \\ \infty & x = a \end{cases} \quad \int_{-\infty}^{\infty} \delta(x-a) dx = 1$$

In 3.0

$$\delta^3(\vec{r}) = \delta(x) \delta(y) \delta(z) \dots$$

$$\int_{\text{all surface}} \delta^3(r) dx dy dz = 1$$

$$\nabla \cdot \frac{\hat{r}}{r^2} = 4\pi \delta^3(\vec{r})$$