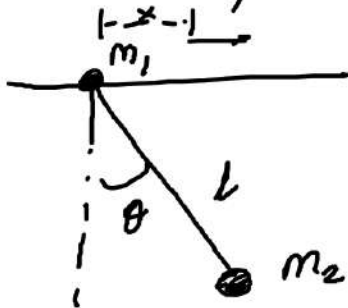


Examples of E-L eqns.



Eqs. of motion ?

$L = ?$

For

$m_1 \rightarrow KE: \frac{1}{2} m_1 \dot{x}^2$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_i} \right) - \frac{\partial L}{\partial q_i} = 0$$

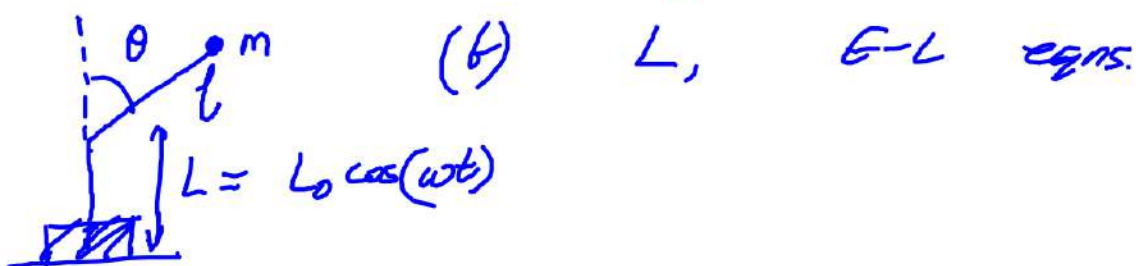
For m_2 — x coord: $x + l \sin \theta$
y coord: $-l \cos \theta$

Find the E-L eqns.

(a) of Assignment.

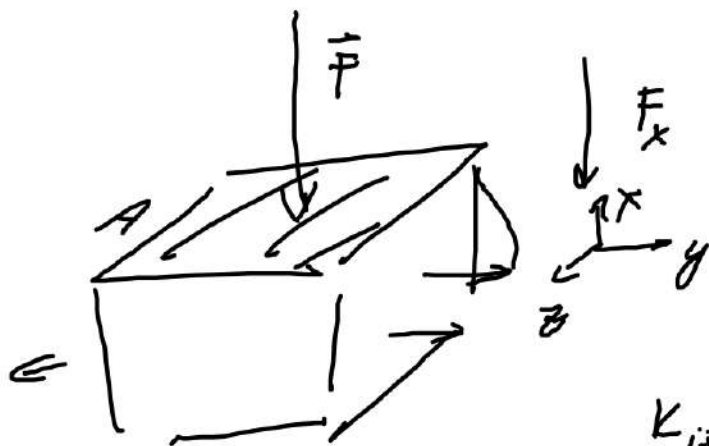
$$L = \frac{1}{2} m_1 \dot{x}^2 + \frac{1}{2} m_2 \left(\dot{x}^2 + l^2 \cos^2 \theta \dot{\theta}^2 + 2 \dot{x} \dot{\theta} l \cos \theta + l^2 \sin^2 \theta \dot{\theta}^2 \right) - (-mg l \cos \theta)$$

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Tensors

A is a no. — a scalar — tensor of rank 0 — no direction
 \vec{A} it is a vector — mag. & direction.
 A_i — 1st rank tensor
 A_{ij} — tensor of rank 2



stress tensor

$$\sigma_{ij}$$

$$\sigma_{xy}$$

$$A_{ij}$$

$$\vec{C} \equiv \vec{A} \times \vec{B} =$$

$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ A_1 & A_2 & A_3 \\ B_1 & B_2 & B_3 \end{vmatrix}$$

$$\vec{P} \equiv (\vec{A} \times (\vec{B} \times \vec{C})) = (\vec{A} \cdot \vec{C}) \vec{B} - (\vec{A} \cdot \vec{B}) \vec{C}.$$

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$$\delta_{ij} = \begin{cases} 0 & \text{if } i \neq j \\ 1 & \text{if } i = j \end{cases}$$

Kronecker delta fn.

$$\vec{A} \cdot \vec{B} = A_1 B_1 + A_2 B_2 + A_3 B_3 \quad (3D)$$

$$A_i B_i \quad \text{Einstein summation convention} = A_i B_j \delta_{ij} = A_i B_i$$

If an index is repeated it implies summation.

$$\vec{A} \cdot \vec{B} \quad \left(A_i B_i = \sum_{i=1}^3 A_i B_i = A_1 B_1 + A_2 B_2 + A_3 B_3 \right)$$

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$\vec{C} = \vec{A} \times \vec{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ A_1 & A_2 & A_3 \\ B_1 & B_2 & B_3 \end{vmatrix} \epsilon_{ijk} = \begin{cases} 1 & \text{if } i,j,k \text{ are symmetric cyclic} \\ -1 & \text{if } i,j,k \text{ are anti-symmetric} \\ 0 & \text{if any 2 indices are repeated} \end{cases}$

$\begin{matrix} X \rightarrow Y \rightarrow Z \\ 1 \rightarrow 2 \rightarrow 3 \end{matrix} \quad \begin{matrix} C_1 = A_2 B_3 - A_3 B_2 \\ C_2 = A_3 B_1 - A_1 B_3 \\ C_3 = A_1 B_2 - A_2 B_1 \end{matrix}$

$\epsilon_{123} = 1$
 $\epsilon_{213} = -1$

$C_i = \epsilon_{ijk} A_j B_k$ (circled in red)

$C_1 = \epsilon_{1jk} A_j B_k = \sum_{j,k} \epsilon_{1jk} A_j B_k$ (repeated)

$C_1 = \cancel{\epsilon_{11k} A_1 B_k} + \epsilon_{12k} A_2 B_k + \epsilon_{13k} A_3 B_k$
 $= \cancel{\epsilon_{121} A_2 B_1} + \epsilon_{122} A_2 B_2 + \epsilon_{123} A_2 B_3 + \cancel{\epsilon_{131} A_3 B_1} + \epsilon_{132} A_3 B_2 + \epsilon_{133} A_3 B_3$

$\rightarrow \epsilon_{ijk} \epsilon_{klm} = \delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}$
 Any index that is summed up — is a "dummy variable"

$$\delta_{ij}, \epsilon_{ijk}, \vec{D} = \vec{A} \times (\vec{B} \times \vec{C}), \vec{G}$$

$$D_i = \epsilon_{ijk} A_j \epsilon_{klm} B_l C_m \quad \vec{D} = \vec{A} \times \vec{G} = \epsilon_{ijk} A_j G_k$$

$$\vec{U} \equiv \vec{V} \times \vec{W}$$

$$U_p = \epsilon_{plm} V_l W_m$$

$$\vec{B} = \vec{A} \times (\vec{B} \times \vec{C})$$

$$G_k = \epsilon_{klm} B_l C_m$$

$$D_i = \epsilon_{ijk} A_j \epsilon_{klm} B_l C_m$$

$$= \epsilon_{ijk} \epsilon_{klm} A_j B_l C_m$$

$$= (\delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}) A_j B_l C_m$$

$$= A_m B_i C_m - A_j B_j C_i$$

$$\vec{D} = (\vec{A} \cdot \vec{C}) \vec{B} - (\vec{A} \cdot \vec{B}) \vec{C}$$

$$D_{jkl} \equiv A_{ij} B_{kli}$$

$$ds^2 = dx^2 + dy^2 + dz^2$$

$$ds = \sqrt{(\quad)}$$

$$ds^2 = g_{ij} dx^i dx^j$$

metric tensor

$$dx_i dx_j$$

$$\underline{g} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\underline{\underline{A}} \quad \underline{\underline{A}}$$

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$$\begin{aligned}
 \vec{E} &= (\vec{A} \times (\vec{B} \times \vec{C})) \times \vec{D} & \vec{F} &= \vec{A} \times (\vec{B} \times \vec{C}) \\
 E_i &= \epsilon_{ijk} [\epsilon_{jlm} A_l \epsilon_{mpq} B_p C_q] D_k & \vec{E} &= \vec{F} \times \vec{D} \\
 & & E_i &= \epsilon_{ijk} F_j D_k \\
 &= \epsilon_{ijk} \epsilon_{jlm} A_l \epsilon_{mpq} B_p C_q D_k & & \\
 &= \epsilon_{ijk} \epsilon_{jlm} \epsilon_{mpq} A_l B_p C_q D_k & & \\
 F_j &= (\vec{A} \times (\vec{B} \times \vec{C}))_j \\
 &= \epsilon_{jlm} A_l \epsilon_{mpq} B_p C_q \\
 &= \epsilon_{ijk} \epsilon_{jlm} \epsilon_{mpq} A_l B_p C_q D_k
 \end{aligned}$$

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$$\begin{aligned}
E_i &= \epsilon_{ijk} \epsilon_{jlm} \epsilon_{mpq} A_l B_p C_q D_k \\
&= (\epsilon_{kij} \epsilon_{jlm}) \epsilon_{mpq} A_l B_p C_q D_k \\
&= (\delta_{kl} \delta_{im} - \delta_{km} \delta_{il}) \epsilon_{mpq} A_l B_p C_q D_k \\
&= \epsilon_{ipq} A_k B_p C_q D_k - \epsilon_{kpq} A_i B_p C_q D_k \\
&= (\epsilon_{ipq} B_p C_q) A_k D_k - (\epsilon_{kpq} B_p C_q) D_k A_i \\
&= (\vec{B} \times \vec{C}) (\vec{A} \cdot \vec{D}) - ((\vec{B} \times \vec{C}) \cdot \vec{D}) \vec{A}
\end{aligned}$$

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29	Oct	Tue	Quiz 1
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19	Nov	Tue.	Quiz 2
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Assignment : due next week