

PATTERN RECOGNITION AND MACHINE LEARNING SYSTEMS DAY 5

Dr Zhu Fangming
Institute of Systems Science
National University of Singapore
fangming@nus.edu.sg

Not be reproduced in any form or by any means, without the written permission of ISS, NUS, other than for the purpose for which it has been supplied.

DAY 5 AGENDA

5.1 Ensemble and Hybrid Machine Learning Techniques

5.2 Ensemble Workshop

5.1

Ensemble and Hybrid Machine Learning Techniques

Topics

- Intro to ensemble models
- Random Forest
- Boosting methods
- Hybrid machine learning models

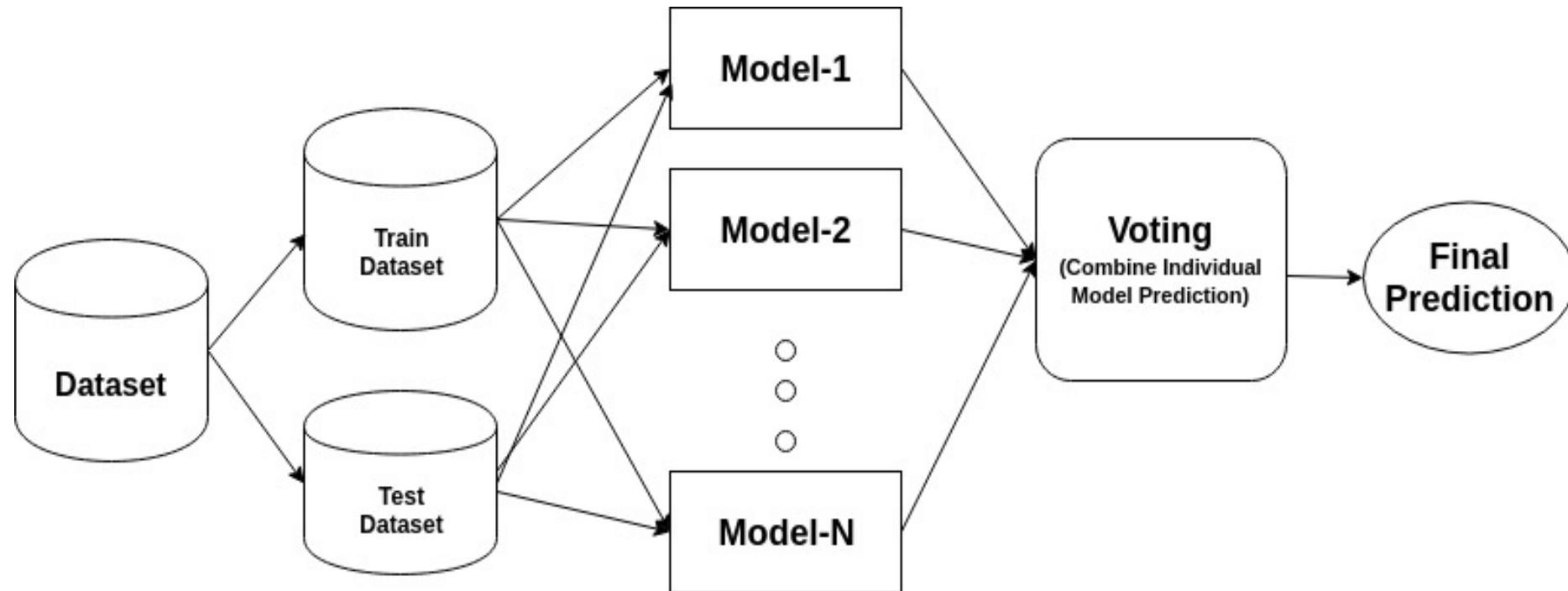
What are Ensembles?

- Ensembles are committees of multiple models
- Each model makes a prediction or “vote”
- Final prediction is average/majority of votes
 - Majority vote for classification (class prediction)
 - Average prediction for regression problems (value prediction)



- What benefits does this bring?
- Why not just train one smart model?

Ensemble



www.datacamp.com

Motivation

- Assume one model and 5 test cases

Truth	1	0	1	1	0	Accuracy
Model 1	1	0	0	1	1	60%

Motivation

- Add another 4 models, each with same accuracy, but with variance (models do not give identical predictions)

Truth	1	0	1	1	0	Accuracy
Model 1	1	0	0	1	1	60%
Model 2	0	1	1	1	0	60%
Model 3	0	0	1	0	0	60%
Model 4	1	1	1	1	1	60%
Model 5	1	0	0	0	0	60%
Vote 1-5	1	0	1	1	0	100%

- No one model is very accurate, learns everything
- Performance of ensemble outperforms individuals
- Usually more reliable/robust than individual models

What makes a good ensemble?

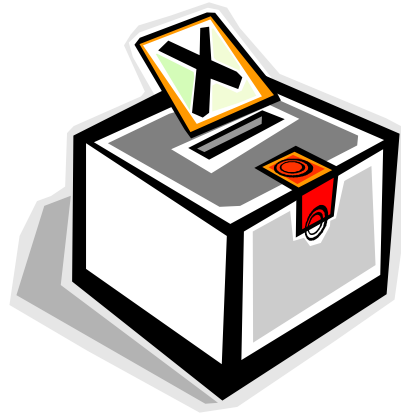
- The term *ensemble* is usually reserved for methods that generate multiple hypotheses using the same base learner

*“A necessary and sufficient condition for an ensemble of classifiers to be more accurate than any of its individual members is if the classifiers are **accurate** and **diverse**”*

-- Tom Dietterich (2000)

How to get suitable diverse models?

- **Ensembles tend to yield better results when there is a significant diversity among the models**
- **Bagging is one way of introducing diversity**
 - Train many models with different random samples
 - Usually applied to decision trees, but can be used with any method

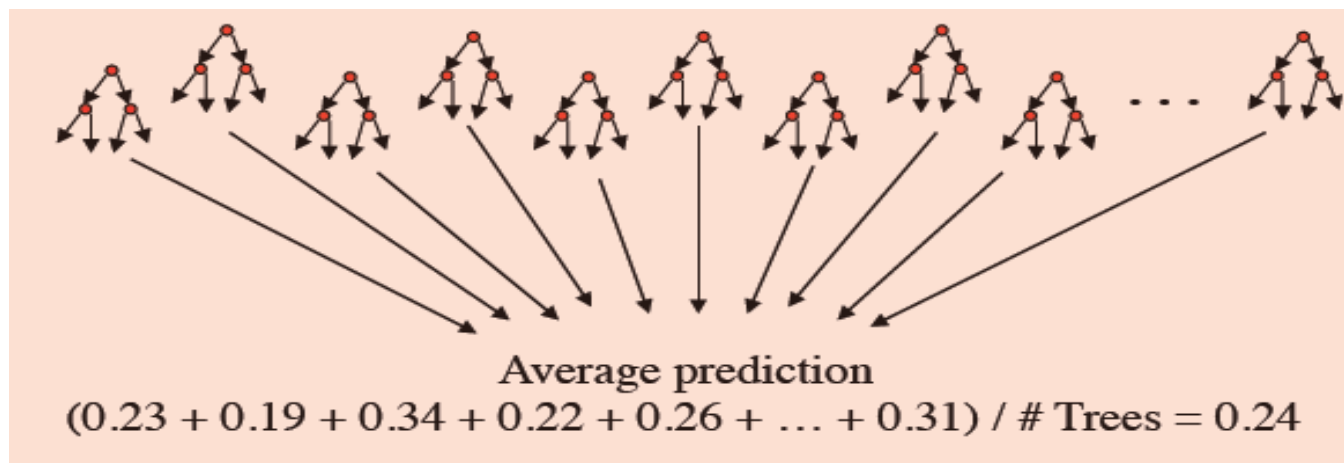


When using bagging, each learned model has a vote of equal value

- **Where do we get many different random samples?**

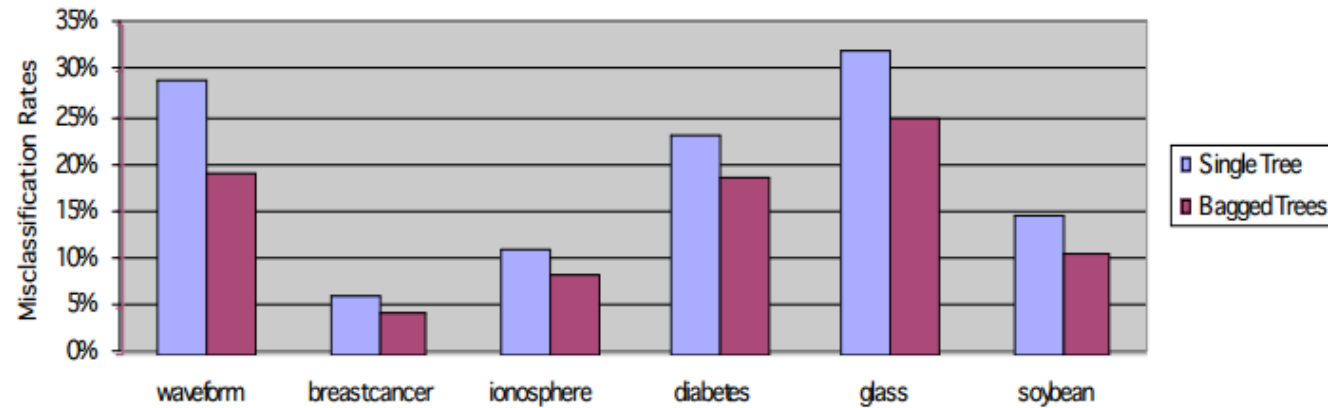
Bagging: Bootstrap Aggregating

- Draw N (say 100) bootstrap samples (sampling with replacement) from the training data, Train models (eg. NN, decision tress) on each sample
- **Algorithm:**
 - Randomly draw 67% (say, two thirds) of the training data
 - Train a model on this sample
 - Repeat this N times to get N models
- **Take the un-weighted average prediction of all models**

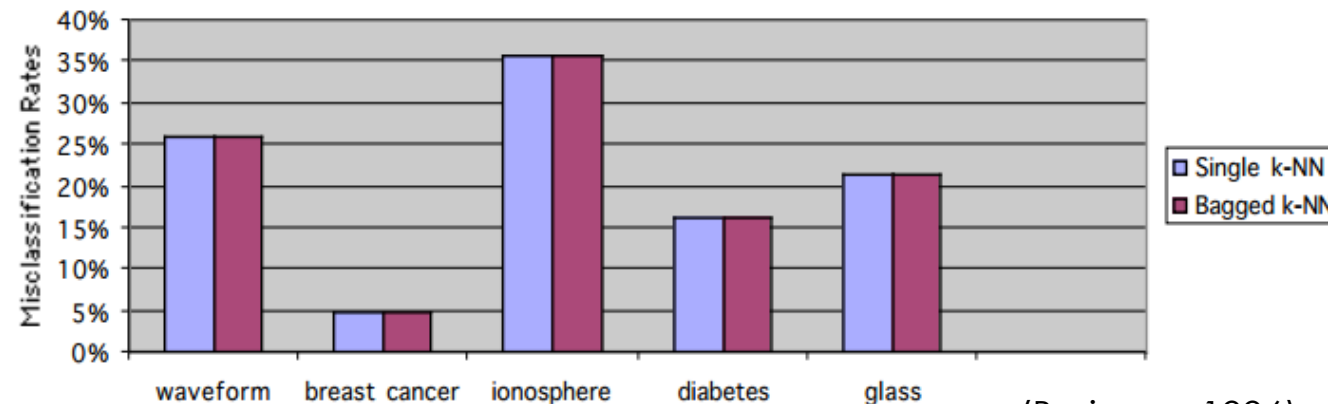


Examples of Bagging

Single and Bagged Decision Trees (50 Bootstrap Replicates)
Test Set Average Misclassification Rates over 100 Runs



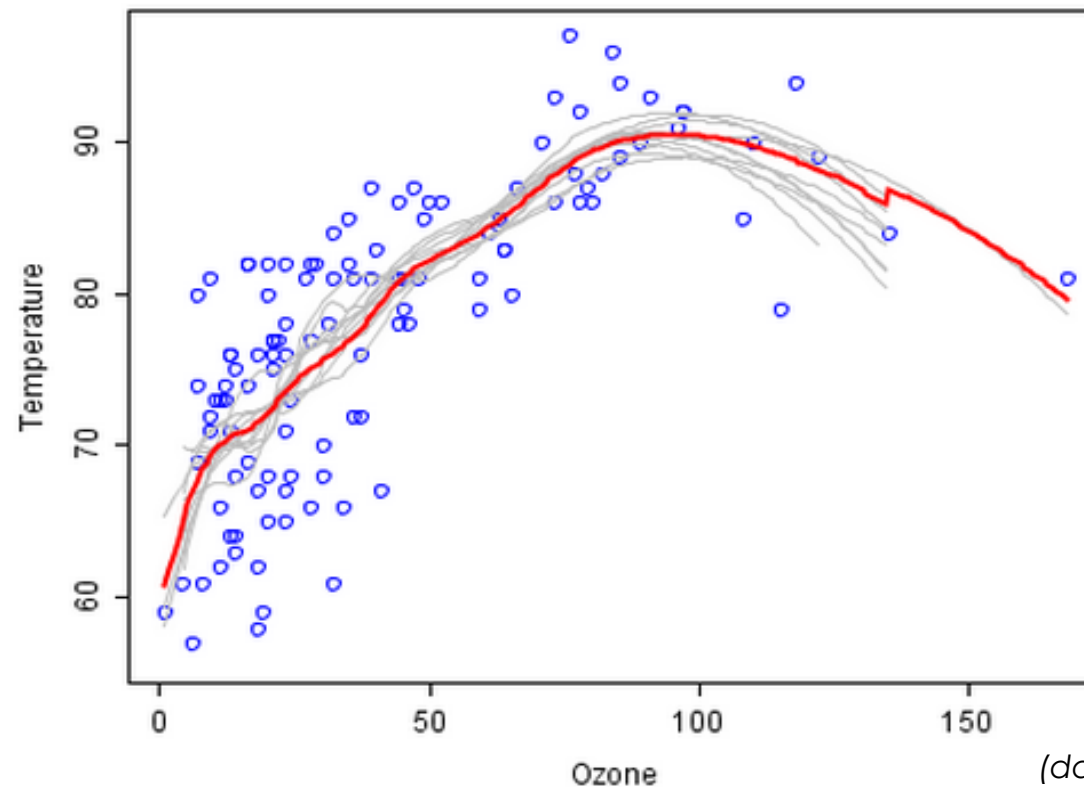
Single and Bagged k-NN (100 Bootstrap Replicates)
Test Set Average Misclassification Rates over 100 Runs



(Breiman, 1996)

Examples of Bagging

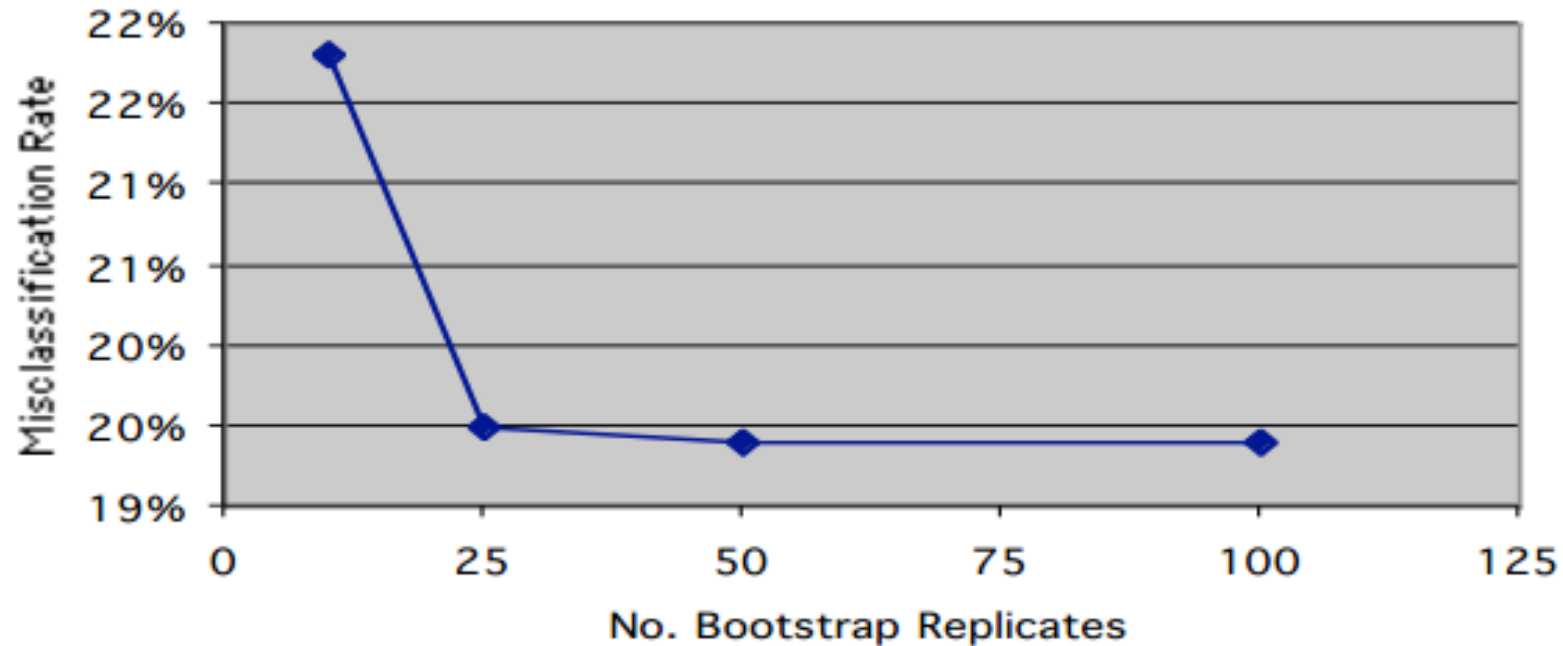
- Ensemble of 10 regression smoothers built from 10 bootstrap samples, each drawing 100 training data.



(data from Rousseeuw and Leroy).

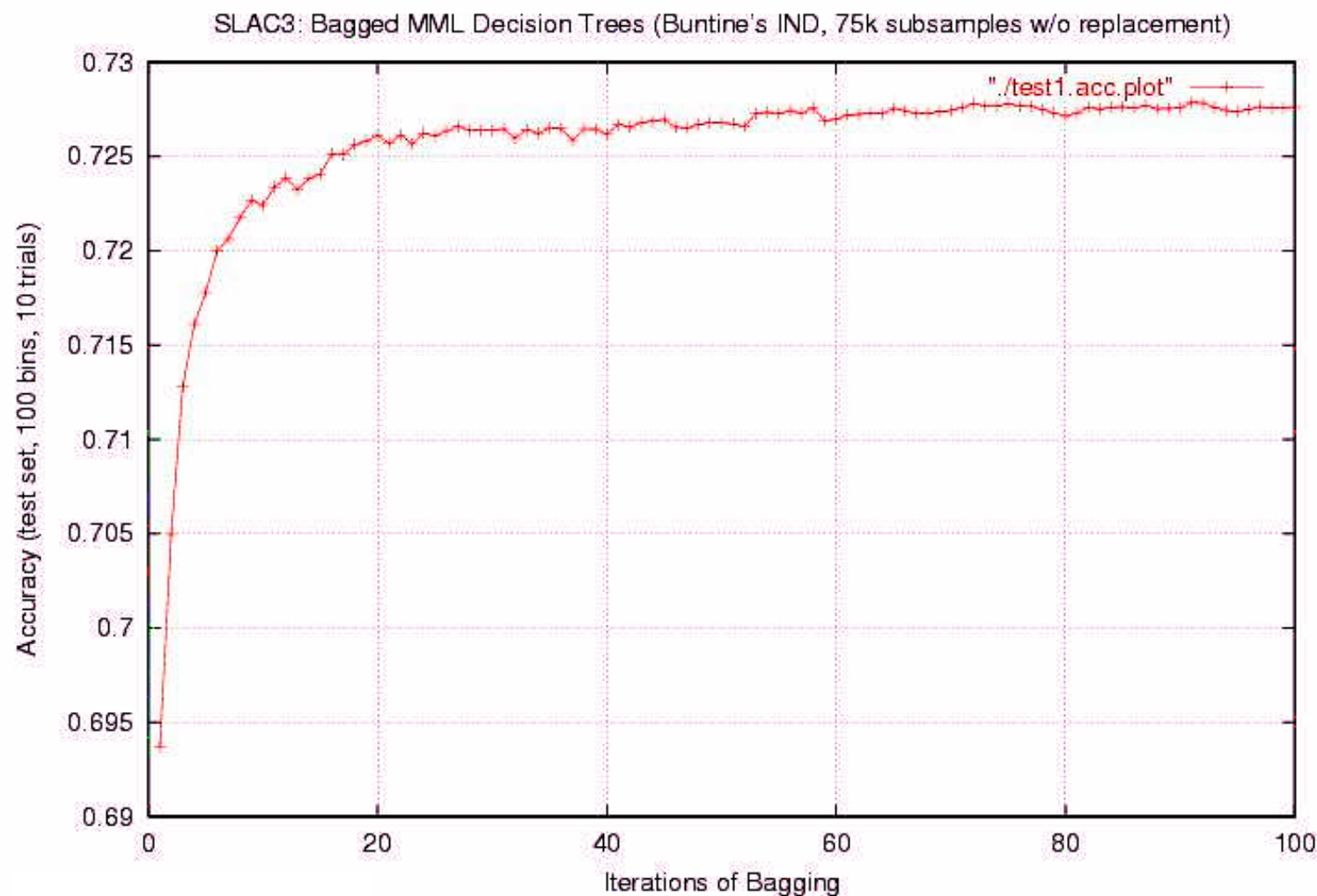
How Many Bagged Models Are Required?

- Example from the soybean data set:



- Depends on data and problem, but generally, < 50 models should work well and often < 25 is adequate

How Many Bagged Models Are Required?



Why does it work? Model Error Reduction

- Assume we build a prediction model $\hat{f}(X)$ to estimate a function $f(X)$ where X is the set of input variables and Y is the variable to be predicted
- Then the expected squared prediction error at point x is:

$$Err(x) = E[(Y - \hat{f}(x))^2]$$

- We can decompose this into 3 components

$$Err(x) = \left(E[\hat{f}(x)] - f(x)\right)^2 + E\left[\left(\hat{f}(x) - E[\hat{f}(x)]\right)^2\right] + \sigma_e^2$$

$$Err(x) = \text{Bias}^2 + \text{Variance} + \text{Irreducible Error}$$

Noise, cannot be
reduced by the
model

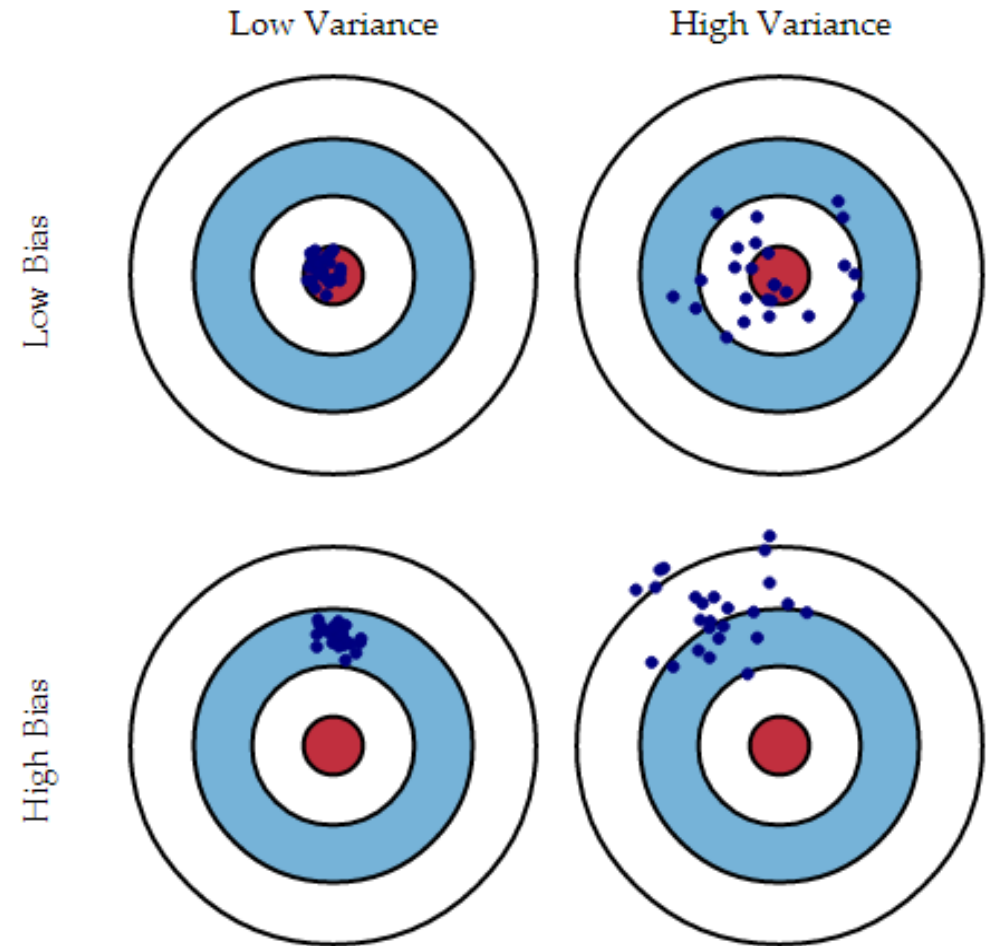
Model Error: Bias versus Variance

- **Error due to Bias:**

- The difference between the expected (or average) prediction of the model and the correct value

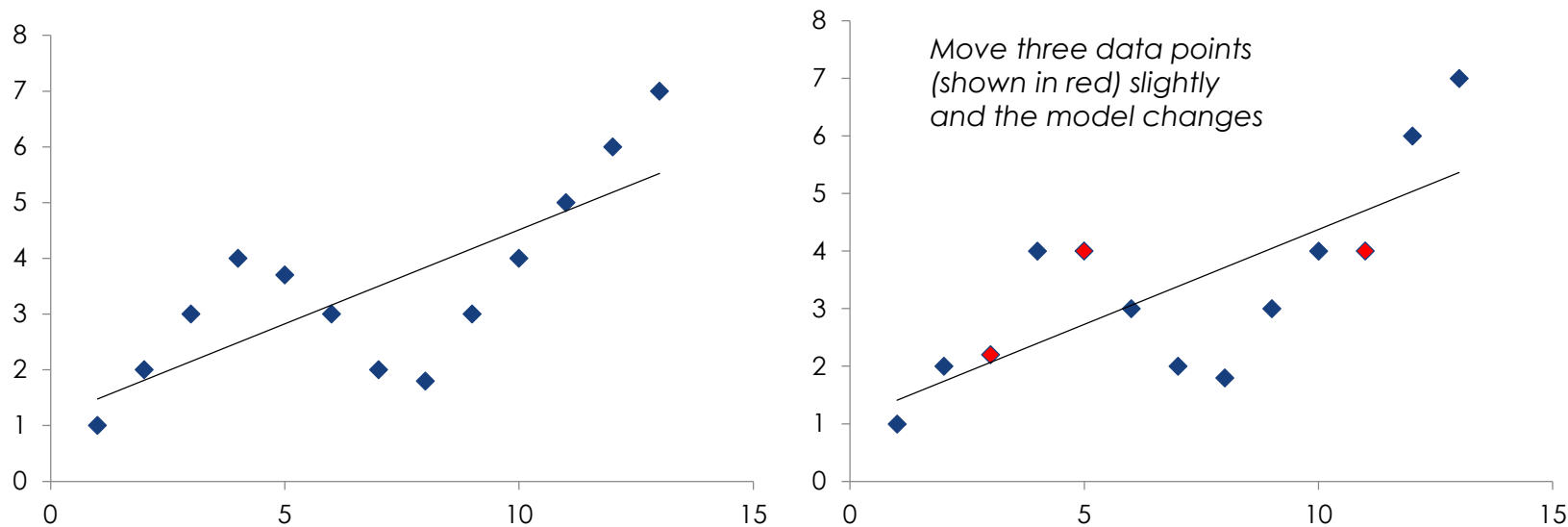
- **Error due to Variance:**

- The variability of the model prediction for a given data point



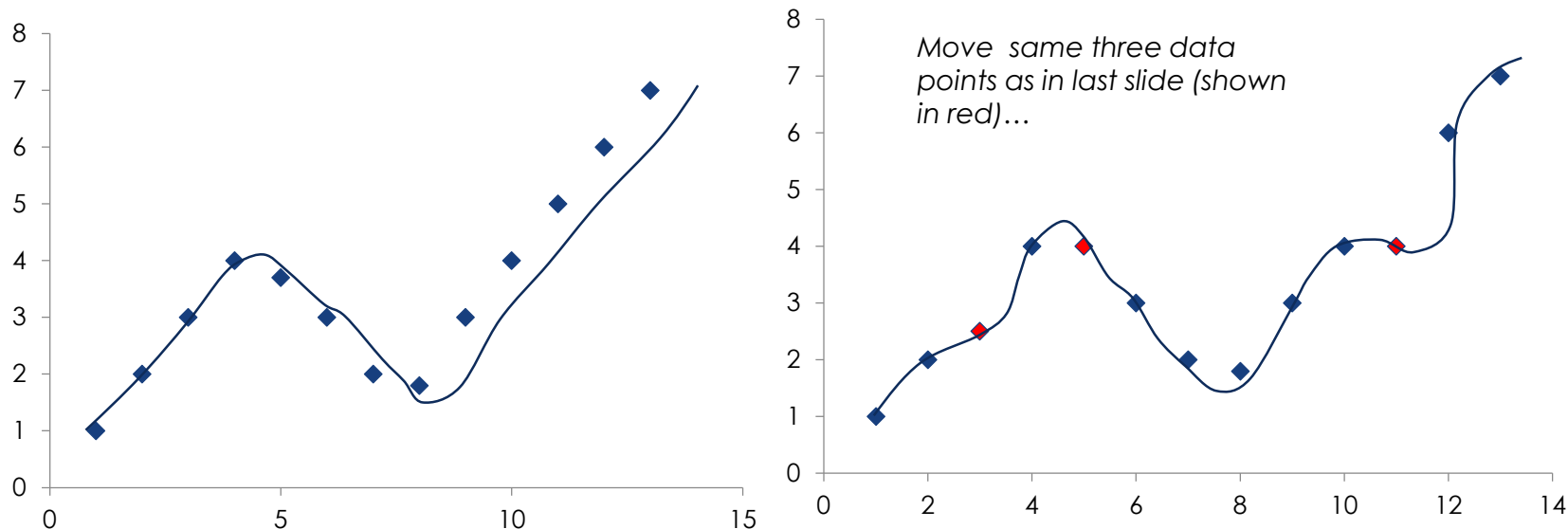
Model Error: Bias versus Variance

- **Models that under-fit the data tend to have:**
 - High bias ~ the model doesn't fit the training data very well
 - Low variance – removing/changing a few training data points won't change the model or predictions much

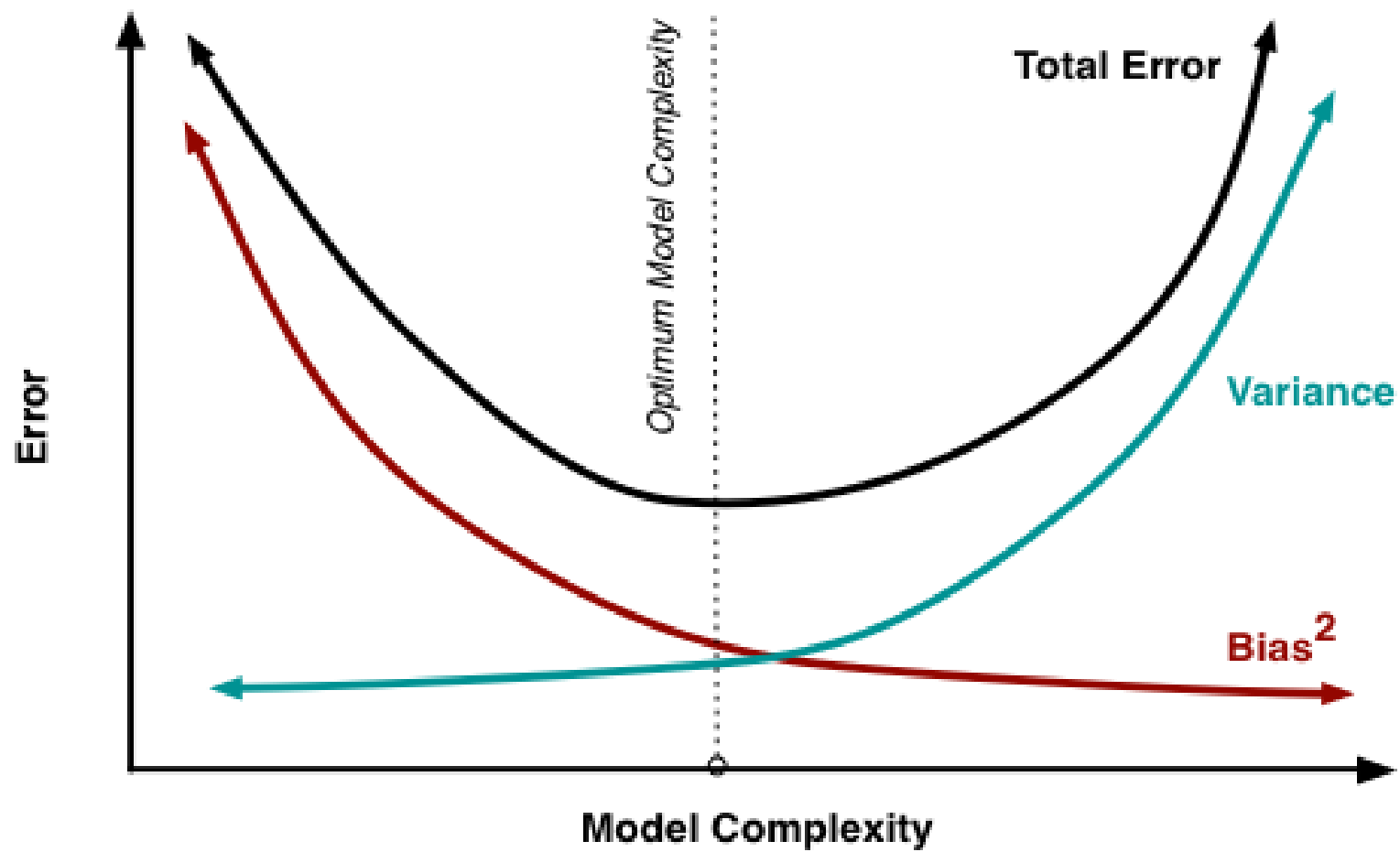


Model Error: Bias versus Variance

- **Models that over-fit the data tend to have:**
 - Low bias ~ the model fits the training data very well
 - High variance – removing/changing a few training data points can change the model and hence the predictions a lot



Tradeoff between Bias and Variance



Tradeoff between Bias and Variance

- Reducing bias & variance is important for prediction accuracy
- Tradeoff:
 - bias vs. variance
 - high complexity models vs. low complexity models
 - most errors due to over-fitting vs. most errors due to under-fitting
 - choice: smart twitchy (sensitive) models vs. less smart but stable models
- Clearly we want smart models, but...
 - Can we reduce variance without increasing bias?
 - Can we reduce over-fitting without under-fitting?

YES!

Reduce Variance Without Increasing Bias

- **Averaging reduces variance:**

$$Var(\bar{X}) = \frac{Var(X)}{N}$$

- **Average models to reduce model variance**
- **For large N, residual model error mainly due to bias!**
- **In practice:**
 - models are correlated, so reduction is smaller than 1/N
 - variance of models trained on fewer training cases is usually larger
 - only works with some learning methods: very stable learning methods have such low variance to begin with, that bagging does not help much.

Can Bagging Hurt?

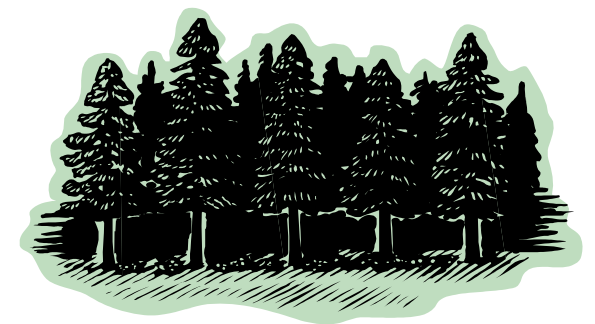
- **Each base classifier is trained on less data**
 - E.g. only about 67% of the data points are in any one bootstrap sample
- **If data is poor, then losing this much data can hurt accuracy**
- **Bagging usually helps, but sometimes not much...**

Ways to create Model Diversity

- **Manipulating the training data (e.g. bagging)**
- **Manipulating the input features**
- **Varying the classifier type, architecture**

Random Forests

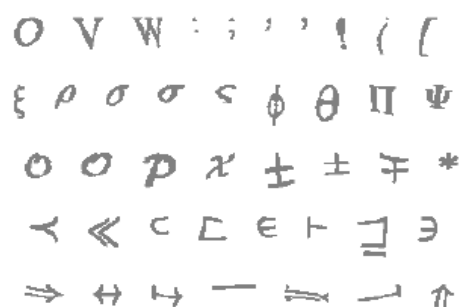
- Draw 1000+ bootstrap samples of data
- Draw random sample of available features at each tree split
 - Randomisation (hence model diversity) now occurs in two places:
Random sampling of *training data* + Random sampling of *feature set*
 - Training speed increases due to less computation at each tree split (less features to evaluate the splitting cost function for)
- Train trees on each sample/attribute set -> 1000+ trees
- Use un-weighted voting to get final prediction (as with bagging)



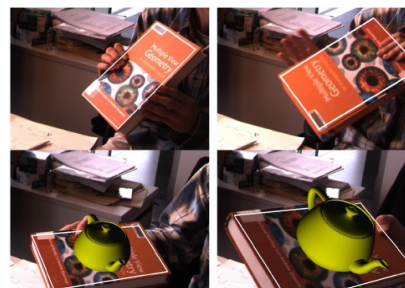
Random Forests

- **Usually works better than bagging**
 - robust to noise, easy to use, surprisingly high accuracy
 - but.. lots of trees means hard to interpret (becomes a black box)
- **Variance of RF trees is higher than Bagged Trees**
 - typically needs 10X as many trees
 - trees should be (generally) unpruned (to encourage diversity)
 - RF needs 100's to 1000's
- **Extra parameter to tune: $p(\text{feat})$**
 - probability of getting to use feature at each split
 - fortunately, usually not too sensitive
 - Breiman suggests $\text{SQRT}(N)$, N : total number of features
- **Unlike Bagging and Boosting, RF is for decision trees only**

Random Forests in Vision



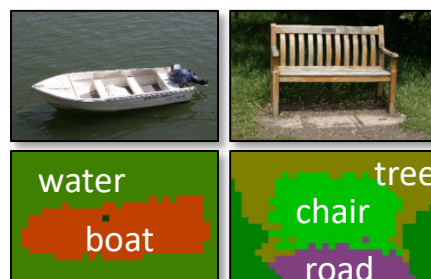
[Amit & Geman, 97]
digit recognition



[Lepetit *et al.*, 06]
keypoint recognition



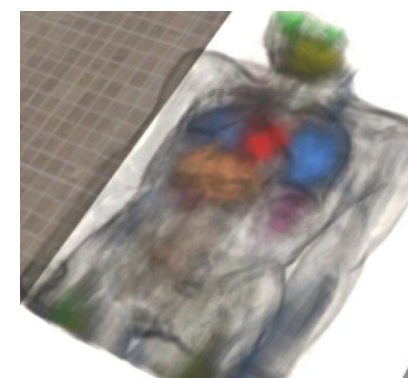
[Moosmann *et al.*, 06]
visual word clustering



[Shotton *et al.*, 08]
object segmentation



[Rogez *et al.*, 08]
pose estimation



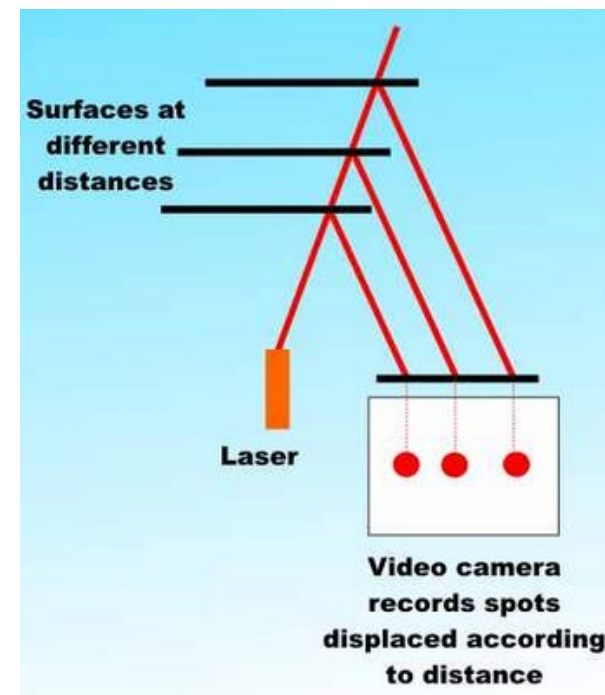
[Criminisi *et al.*, 09]
organ detection

(Among many others...)

Kinect's Decision Forest

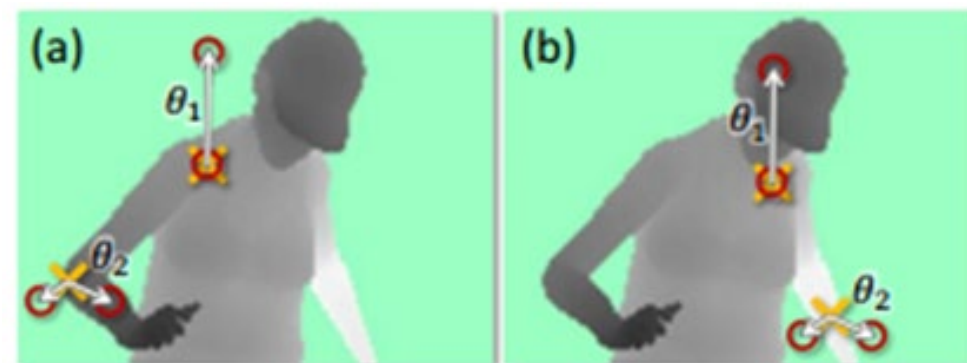
- **Step1: Generate a 3D image**

- Kinect uses "structured light" ~ If you have a light source offset from a detector by a small distance then the projected spot of light is shifted according to the distance it is reflected back from.



- **Step2: Compute Features**

- Compute the difference in depth (z) to two pixels that are close together in (x, y). If difference is small then they likely belong to same object. Repeat many times.



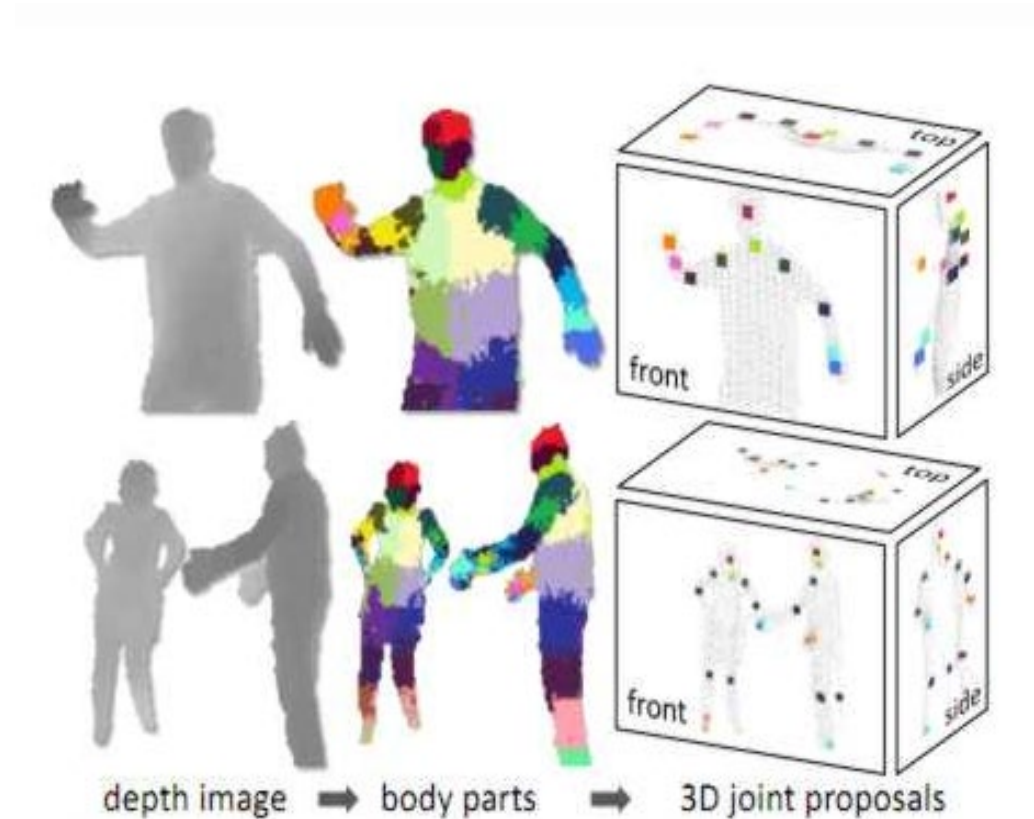
Kinect's Decision Forest

- **Step3: Build Forest**

- Each tree was trained on features that were pre-labeled with the target body parts.
- Training just 3 trees using 1 million test images took a day using a 1000 core cluster.
- The trained classifiers assign a probability of a pixel being in each body part

- **Step4: Execute the Forest**

- Picks areas of maximum probability for each body part type.



<http://www.youtube.com/watch?v=HNkbG3KsY84>

Testing Random Forests

- No need for separate test set

- Method:

- Test each tree against the data left over after the bootstrap sample was taken; this is called the OOB (out-of-bag) data

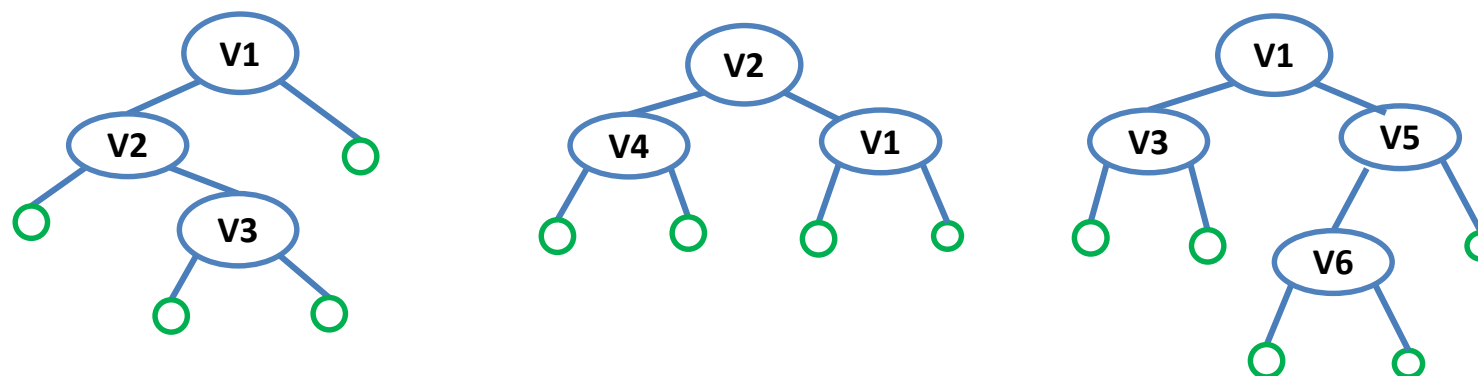


- If each bootstrap sample takes 67% of the training data, then after building T trees every training example will have been OOB (and hence a valid test example) for about $T/3$ times.
- For each training example, take the majority vote of all $T/3$ test predictions to get the forest's prediction* and compare with the actual class value. Output 1 if forest prediction \neq actual, else output 0
- Sum over all training examples to get error estimate for the forest

* For regression problems, average all $T/3$ test predictions to get the forest prediction.
Then compute MSE as $\sum_{\text{training examples}} (\text{prediction} - \text{actual})^2$

Measuring Variable Importance

- For a single tree the order in which the variables occur in the tree is a measure of their relative importance to the prediction



- For a forest?
 - Naïve method: Count the number of times the variable occurs in all of the trees, more occurrences => more important
 - Better method: sum the total reduction in impurity (eg. the decreases in the Gini index) for all nodes that test the variable

Measuring Variable Importance

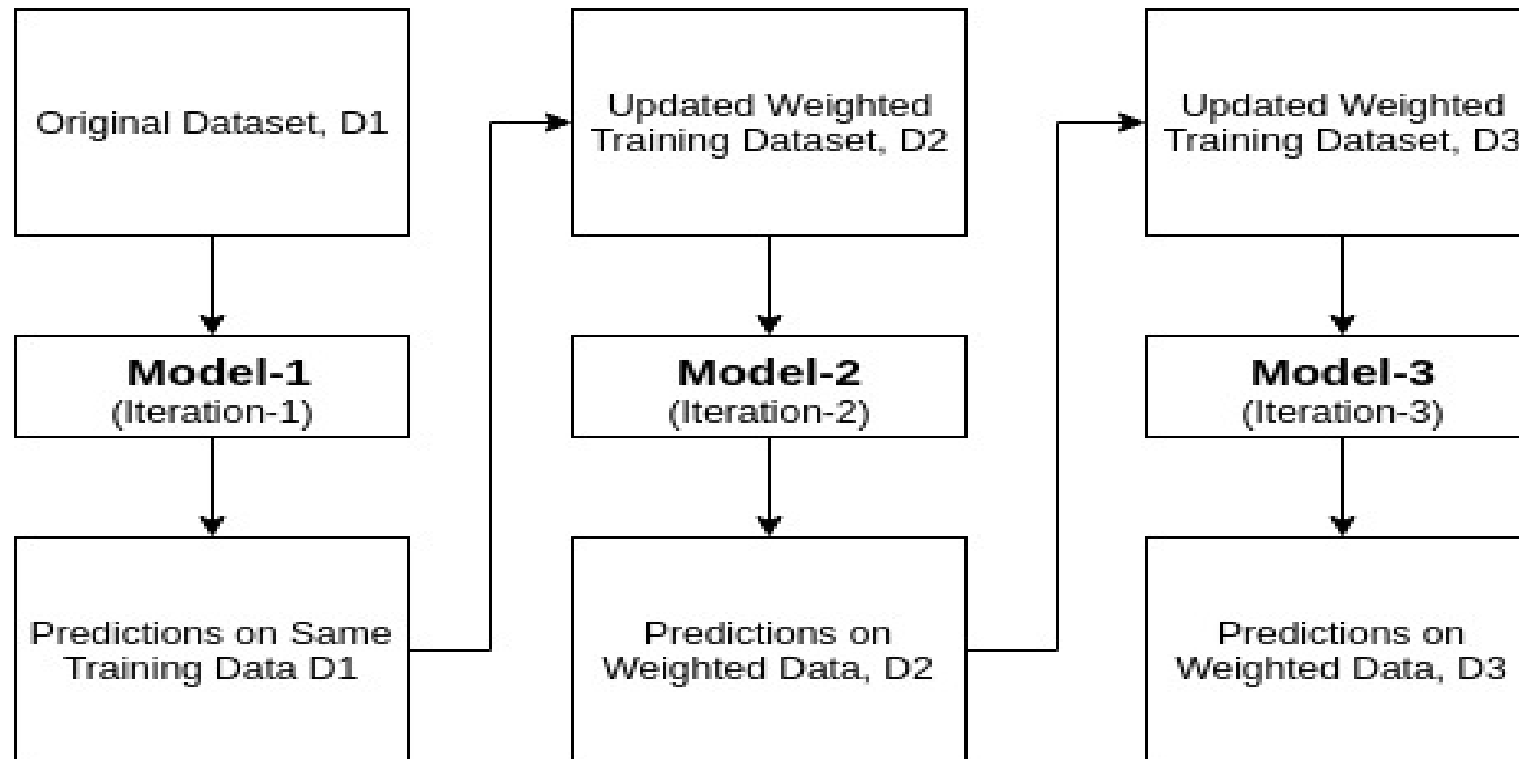
- **Permutation Method**

- Randomly shuffle the values of a given input variable to “break” the bond of the variable to the response. Then the difference of the model accuracy before and after the shuffling is a measure of how important the variable is for predicting the response
- Detailed Steps
 1. Test every tree on its own OOB examples. For each training example \mathbf{e} count the votes for the correct class (call this $\text{NormalCorrectVotes}_{\mathbf{e}}$)
 2. For each input variable \mathbf{v} :
 - For each tree \mathbf{t} :
 - Randomly permute the values for \mathbf{v} in the OOB examples and retest the tree
 - For each training example, count the votes for the correct class
 - $\text{Importance}_{\mathbf{v}} = \text{average} \left[\frac{\text{NormalCorrectVotes}_{\mathbf{e}} - \text{ShuffledCorrectVotes}_{\mathbf{e}}}{\text{TotalVotes}_{\mathbf{e}}} \right]$

- **Can a set of weak learners create a single strong learner?**
 - A weakly learned model is only slightly better than random guessing
 - A strongly learned model is arbitrarily well-correlated with the truth
- **Boosting essentials:**
 - Build a model (but don't 100% over-fit the data!)
 - Increase weights of the training examples the model gets wrong
 - Retrain a new model using the weighted training set
 - Repeat many times...



Boosting



www.datacamp.com

Basic Boosting Algorithm

1. Weight all training samples equally
2. Train model on train set
3. Compute error of model on train set
4. *Increase weights on train cases that the model gets wrong!*
5. Train new model on re-weighted train set
6. Re-compute errors on weighted train set
7. Increase weights more on cases it still gets wrong
8. Repeat until tired (100+ iterations)
9. Final model: *weighted* prediction of each model (aka base models)

AdaBoost* (Adaptive Boosting)

Given: $(x_1, y_1), \dots, (x_m, y_m)$ where $x_i \in \mathcal{X}$, $y_i \in \{-1, +1\}$. ← The training examples

Initialize: $D_1(i) = 1/m$ for $i = 1, \dots, m$. ← The training example weights

For $t = 1, \dots, T$:

- Train weak learner using distribution D_t . ← Train a model (build a classifier)
- Get weak hypothesis $h_t : \mathcal{X} \rightarrow \{-1, +1\}$.
- Aim: select h_t with low weighted error:

$$\epsilon_t = \Pr_{i \sim D_t} [h_t(x_i) \neq y_i].$$

← Goal of classifier is to reduce weighted error relative to D_t

- Choose $\alpha_t = \frac{1}{2} \ln \left(\frac{1 - \epsilon_t}{\epsilon_t} \right)$.
- Update, for $i = 1, \dots, m$:

$$D_{t+1}(i) = \frac{D_t(i) \exp(-\alpha_t y_i h_t(x_i))}{Z_t}$$

← Cases where the prediction does not equal the real class value ← Re-weight the examples

where Z_t is a normalization factor (chosen so that D_{t+1} will be a distribution).

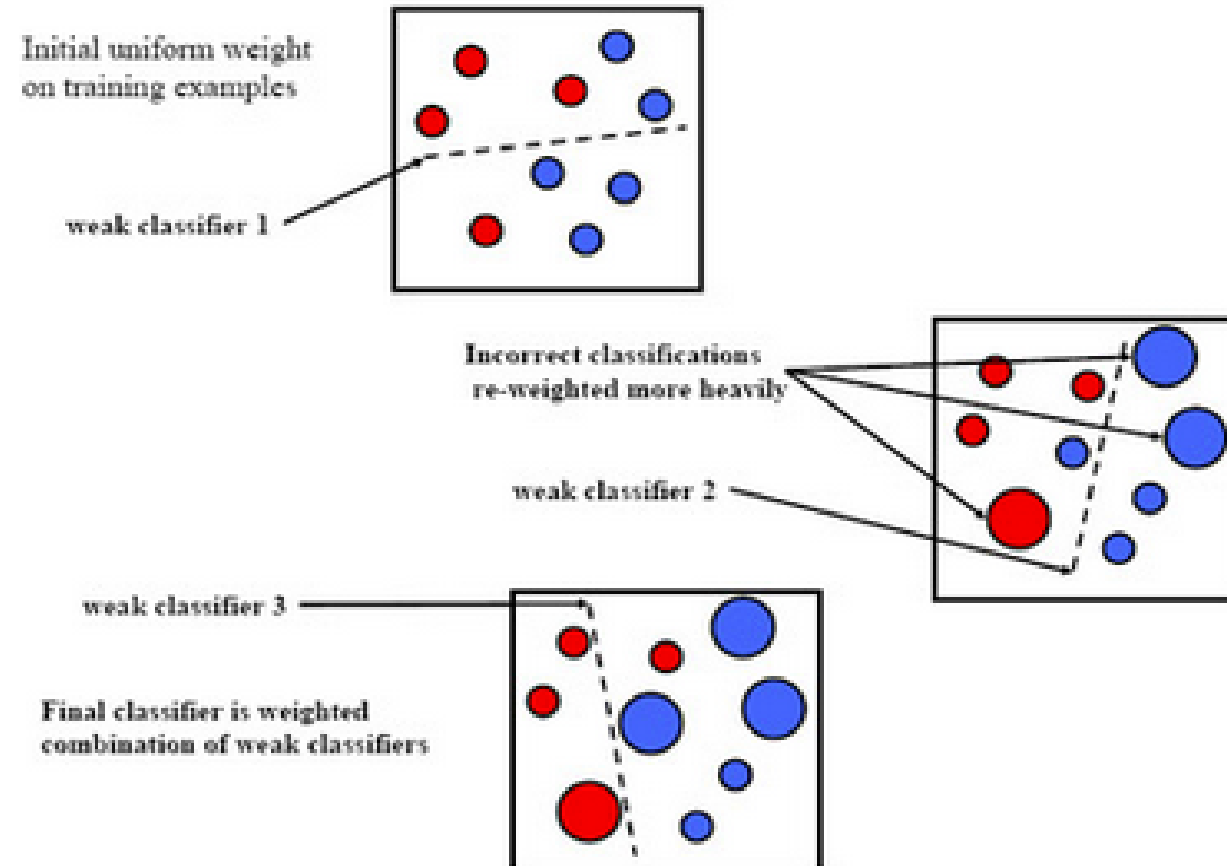
Output the final hypothesis:

$$H(x) = \text{sign} \left(\sum_{t=1}^T \alpha_t h_t(x) \right).$$

← The "final" prediction is the weighted average of all of the weak classifiers

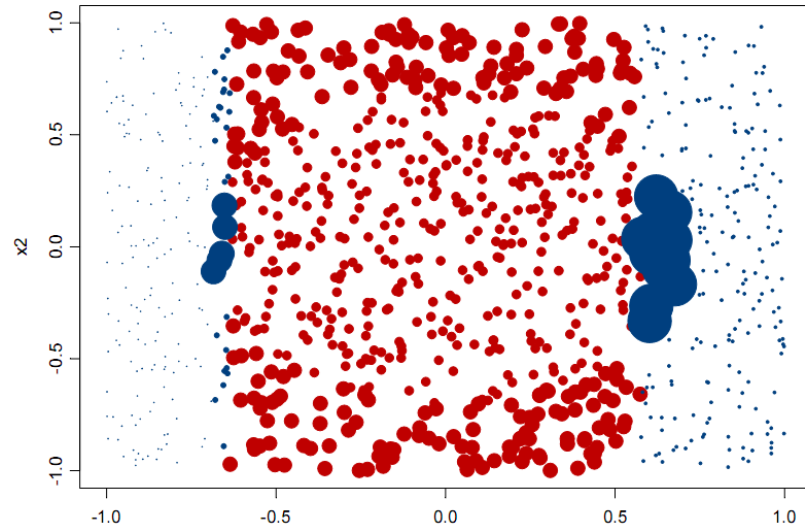
*Freund and Schapire, 94

AdaBoost - Conceptual



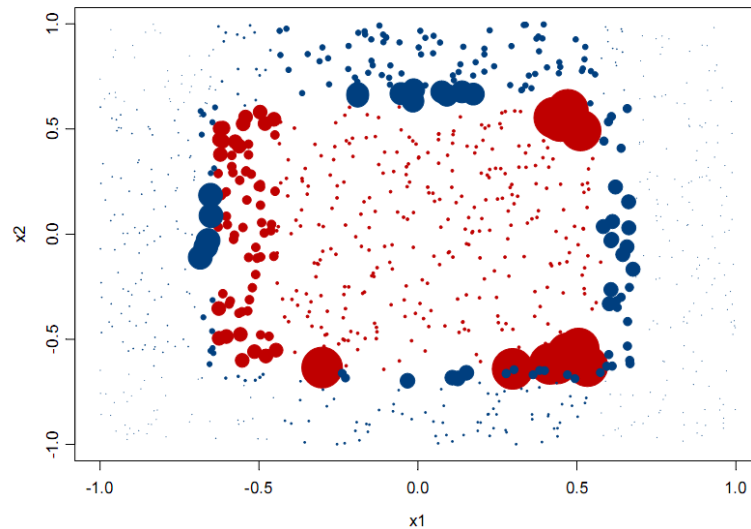
$$H(x) = \text{sign}(\alpha_1 h_1(x) + \alpha_2 h_2(x) + \alpha_3 h_3(x))$$

AdaBoost

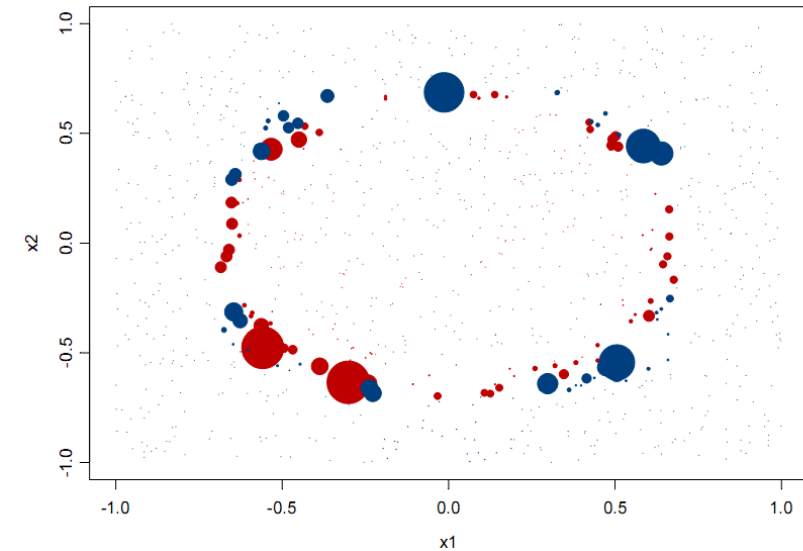


Classifications (colors) and
Weights (size) after *1 iteration*
of AdaBoost

3 iterations



20 iterations

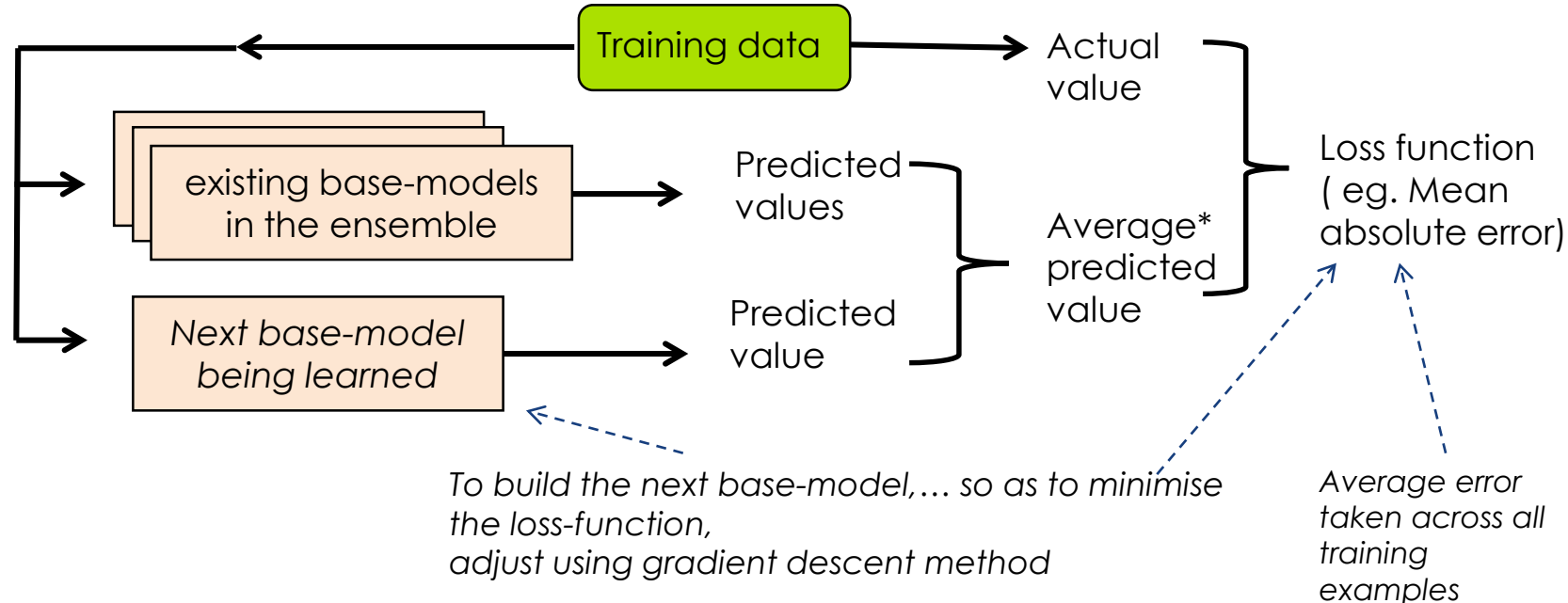


Source: Elder, John. From Trees to Forests and Rule Sets - A Unified Overview of Ensemble Methods. 2007.

- **How might we use the adjusted weights in algorithms?**
 - Neural Networks – Scale learning rate by weight
 - Decision Trees – instance membership is scaled by weight
 - k -NN – node vote is scaled by weight

Gradient Boosting

- Treat learning as Gradient Descent optimisation
- Like Adaboost, models are learned and added to the ensemble sequentially



Gradient Boosting

Input: training set $\{(x_i, y_i)\}_{i=1}^n$, a differentiable loss function $L(y, F(x))$, number of iterations M .

Algorithm:

1. Initialize model with a constant value:

$$F_0(x) = \arg \min_{\gamma} \sum_{i=1}^n L(y_i, \gamma).$$

2. For $m = 1$ to M :

1. Compute so-called *pseudo-residuals*:

$$r_{im} = - \left[\frac{\partial L(y_i, F(x_i))}{\partial F(x_i)} \right]_{F(x)=F_{m-1}(x)} \quad \text{for } i = 1, \dots, n.$$

2. Fit a base learner (e.g. tree) $h_m(x)$ to pseudo-residuals, i.e. train it using the training set $\{(x_i, r_{im})\}_{i=1}^n$.

3. Compute multiplier γ_m by solving the following **one-dimensional optimization** problem:

$$\gamma_m = \arg \min_{\gamma} \sum_{i=1}^n L(y_i, F_{m-1}(x_i) + \gamma h_m(x_i)).$$

4. Update the model:

$$F_m(x) = F_{m-1}(x) + \gamma_m h_m(x).$$

3. Output $F_M(x)$.

Note: Ever since its introduction in 2014, XGBoost has become a widely used and popular tool which implements the gradient boosting algorithm.

Boosting versus Bagging/RF

- **In practice bagging/RF almost always helps**
- **Bagging doesn't work as well with stable models**
 - Boosting and RF might still help.
- **Often, boosting helps more than bagging**
 - Boosting might hurt performance on noisy datasets
 - Bagging/RF don't have this problem.
- **Bagging/RF is easier to parallelize**

- **Ensembles**

- Using multiple models to reduce variance and increase accuracy
- Works best if models don't agree with each other (need model variance)
- Usually refers to multiple models of same type
- Bagging & Boosting are the most popular generic methods
- Random Forest increasingly popular

- **Ensemble Creation Approaches**

- A good goal is to get less correlated errors between models
- Injecting randomness – initial weights, different learning parameters, etc.
- Different Training sets – Bagging, different features, etc.
- Forcing differences – different objective functions, auxiliary tasks

- **Ensemble Combining Approaches**

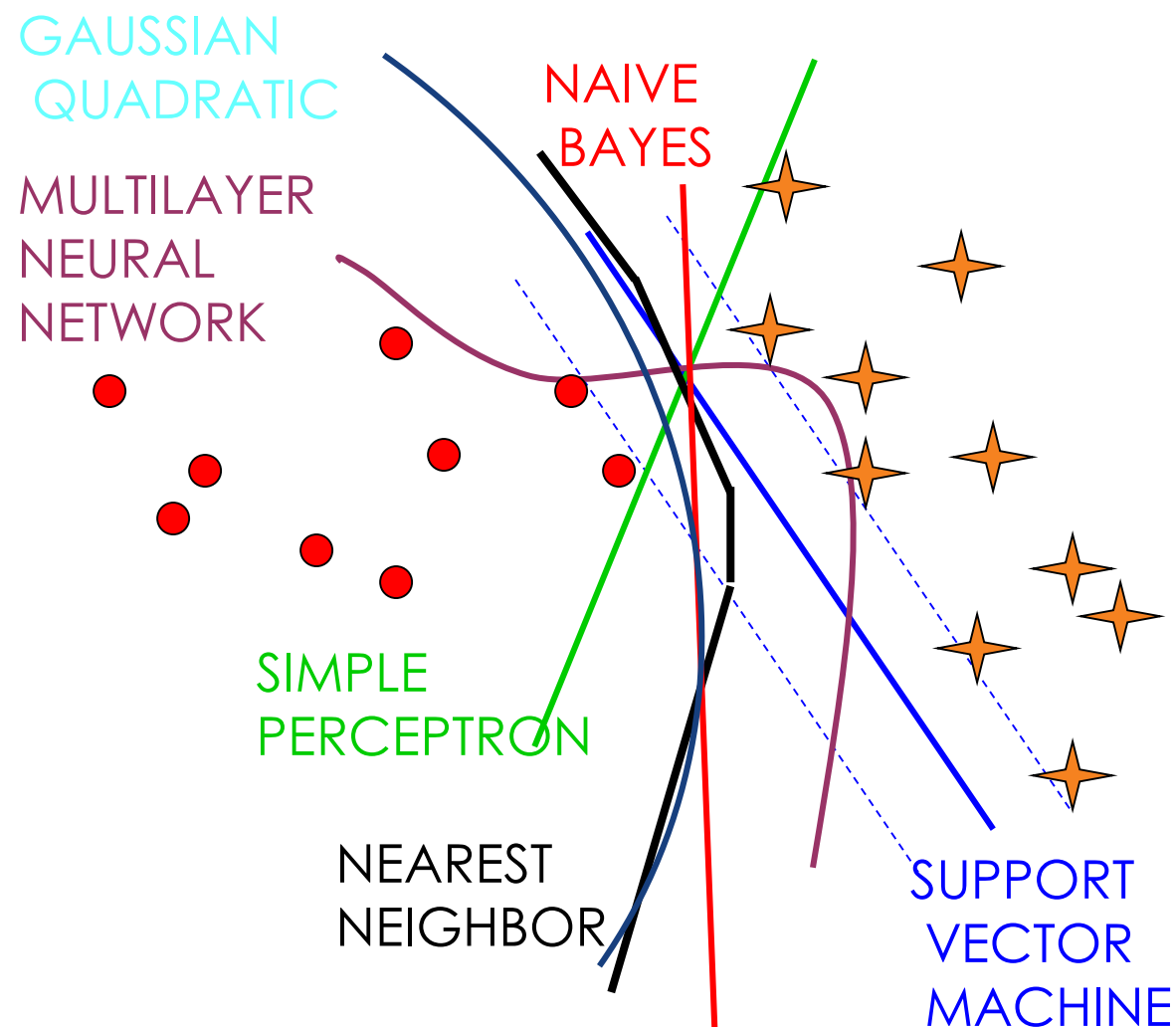
- Unweighted Voting (e.g. Bagging)
- Weighted voting – based on accuracy, heuristics, etc. (e.g. Boosting)
- Stacking - Learn the combination function

Hybrid Machine Learning Models

- Both ensemble models and hybrid models make use of the information fusion concept but in slightly different way.
- Ensemble Models - multiple but homogeneous, weak models are combined
- Hybrid Models combine different, heterogeneous machine learning approaches.
- They both may considerably improve quality of reasoning and boost adaptivity of the entire solutions.
- They both have found applications in numerous real world problems ranging from person recognition, medical diagnosis, bioinformatics, recommender systems and text/music classification to financial forecasting.

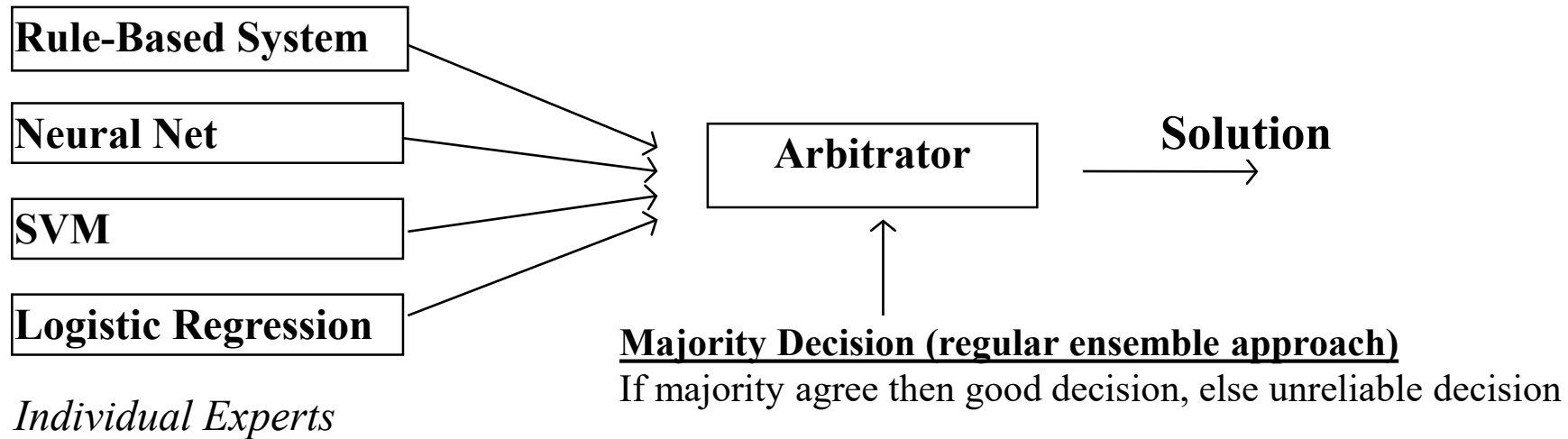
- In “Multiple Classifier Systems” approach, each classifier is expert in certain situations
 - Each model type has different strengths and weaknesses
 - Usually have relatively small number of experts
 - Allows for more model combination methods apart from averaging

Multiple Classifier Systems Example



Multiple Classifier Systems Example

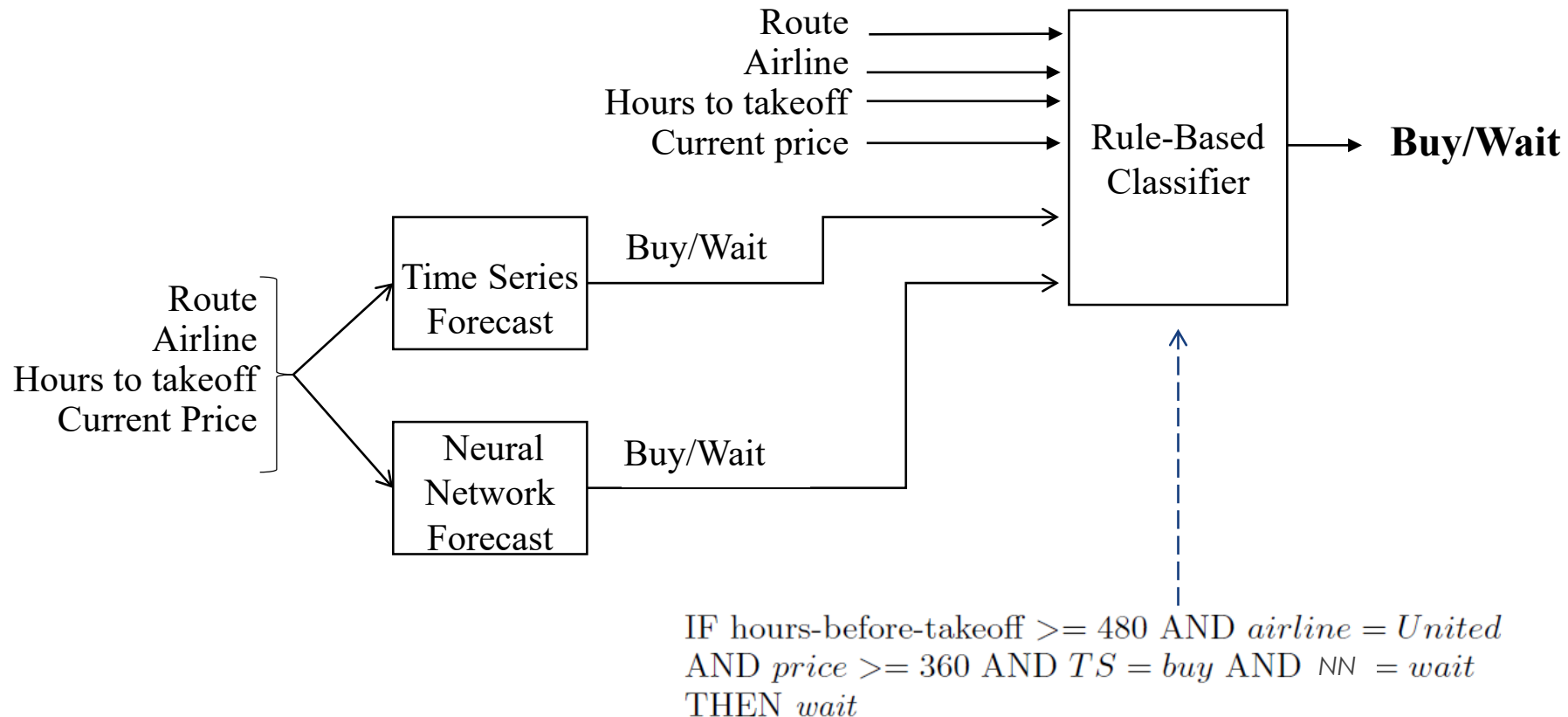
- Different solution strategies (experts) offer alternative solutions. Another process decides which solution to accept or how to combine the solutions, e.g. majority vote algorithm.
- This architecture is also known as stacking*



*Stacking (sometimes called stacked generalization) involves training a learning algorithm to combine the predictions of several other learning algorithms (Wikipedia)

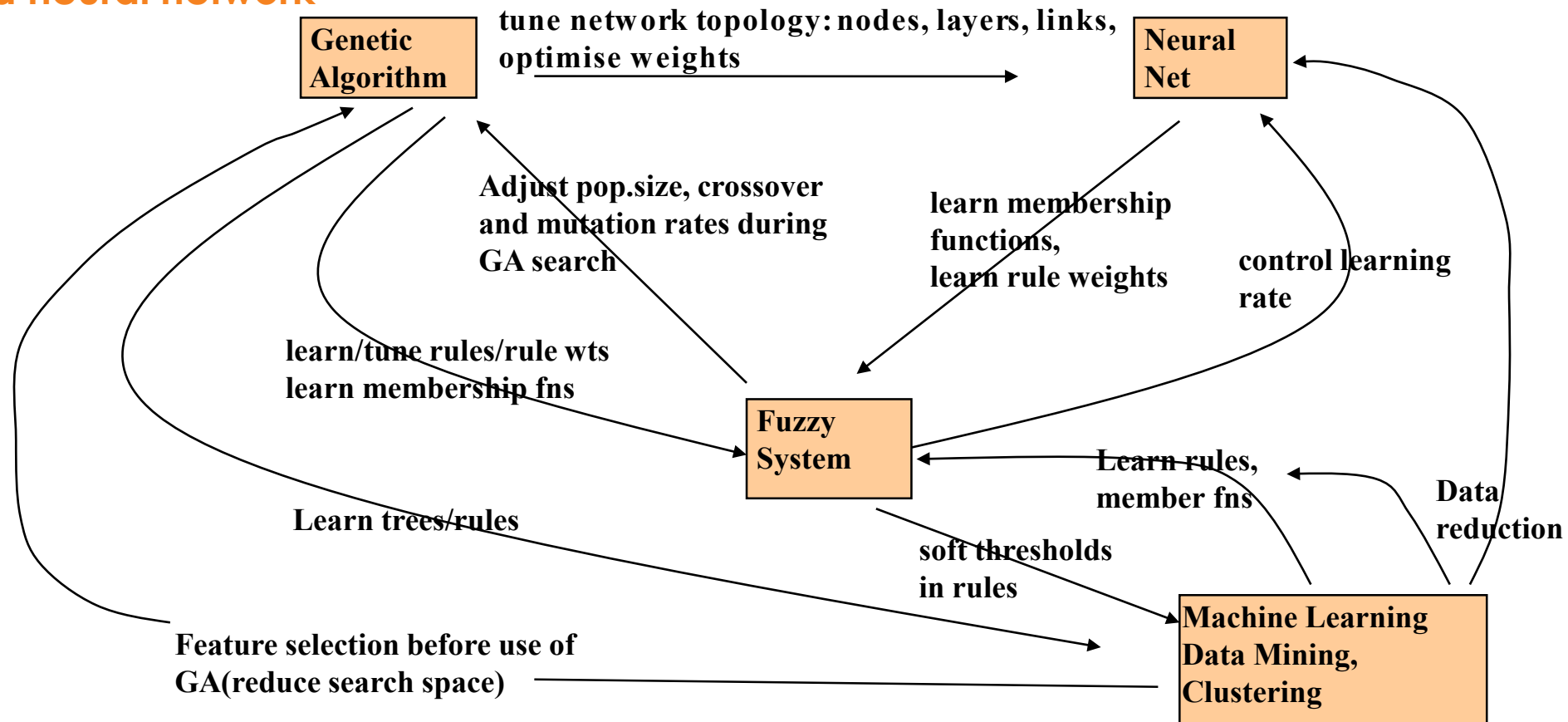
Multiple Classifier Systems Example

- Airfare Price prediction
- The Experts have same skills (Buy/Wait decision) but sometimes one is better than the other! The arbitrator helps decide which to use and when



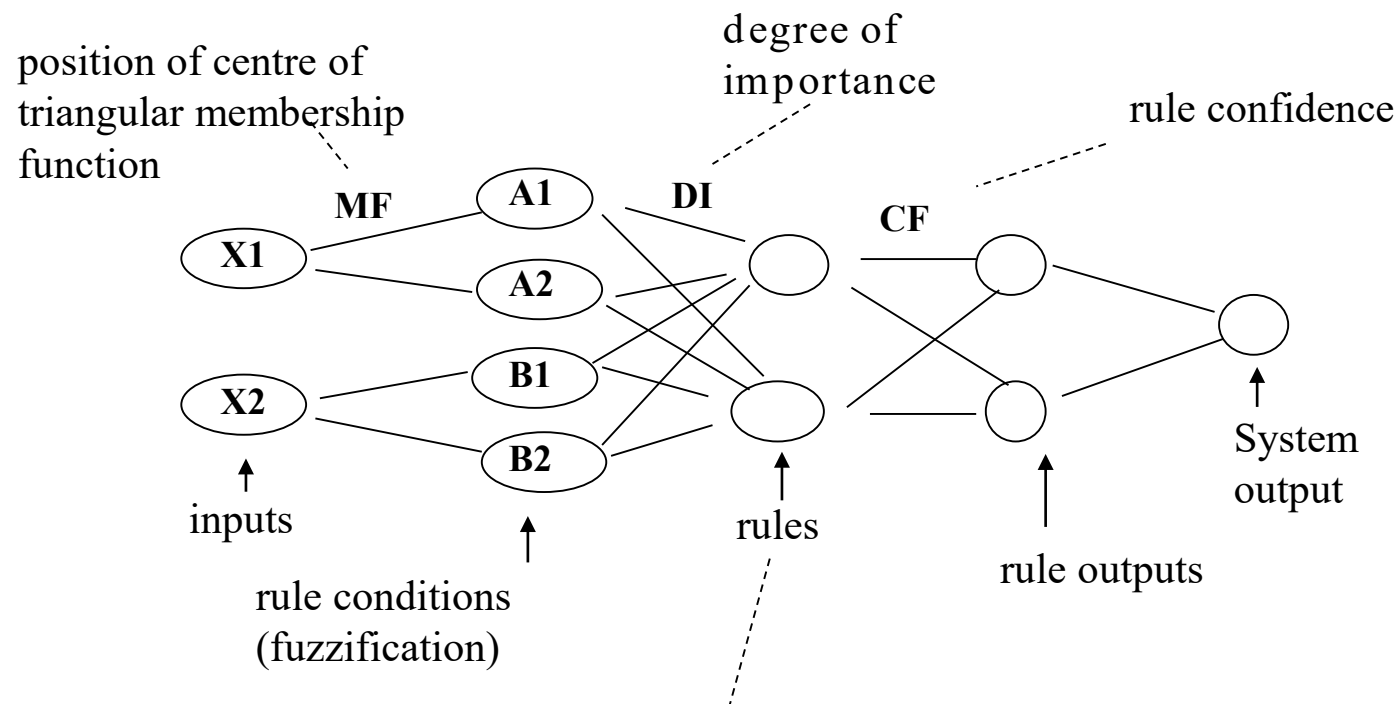
Self-Tuning Systems

- One technique is used to tune or learn the architecture for another, e.g: Neural network is used to learn a Fuzzy System , Genetic algorithm is used to optimise a neural network



Self-Tuning Systems Example: Neuro-Fuzzy Systems

- **Neural Network is used to represent and “learn” a Fuzzy System**
- **Nodes represent rule inputs, conditions, actions etc**
- **Special training algorithm required**



Taking only the strongest connection to each condition element yields rules like (other schemes exist):-

e.g. If X1 is A1 (DI1) And X2 is B1 (DI2) Then output = C (CF1)

Self-Tuning Systems Example: GA-ML

- **Example: learning rules to predict type of object**

- Let F1 and F2 be the input variables with
F1 taking values {small, medium large}
F2 taking values {sphere, cube, brick, tube}
Let Class take values {widgets, gadgets}

- Then the chromosome

F1	F2	Class
110	0001	0

Represents the rule

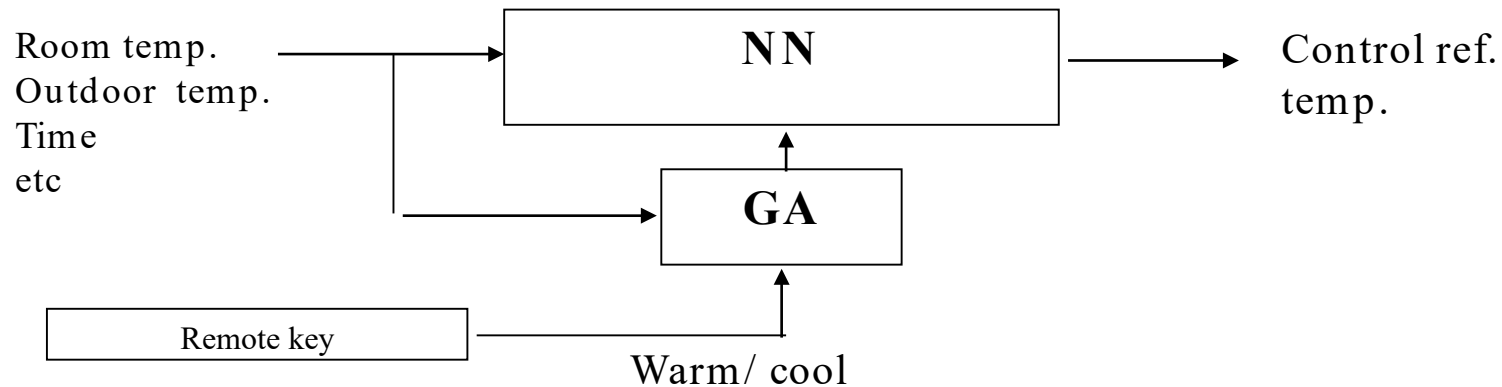
If F1 = small or medium and F2 = tube then widget

Self-Tuning Systems Example: GA-Neural

- **NNs are generated/tuned by GAs**
- **GA chromosome represents NN topology**
 - number of hidden layers, hidden nodes and number of links and/or weights
- **Pros: GA can avoid local minima more than back-prop**
- **Cons: size of chromosome gets prohibitively large if topology is being learned**

Self-Tuning Systems Example: GA-Neural

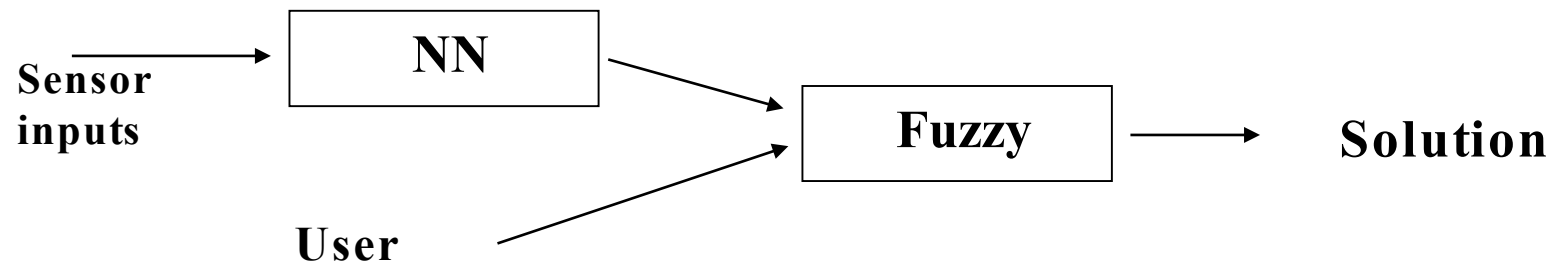
- LG Electric developed an air-con controlled by an NN
- If the user wants the air-con to adapt to their preferences then a GA is used to change the number of neurons and weights



Co-operating Experts

“Pooled Expertise”

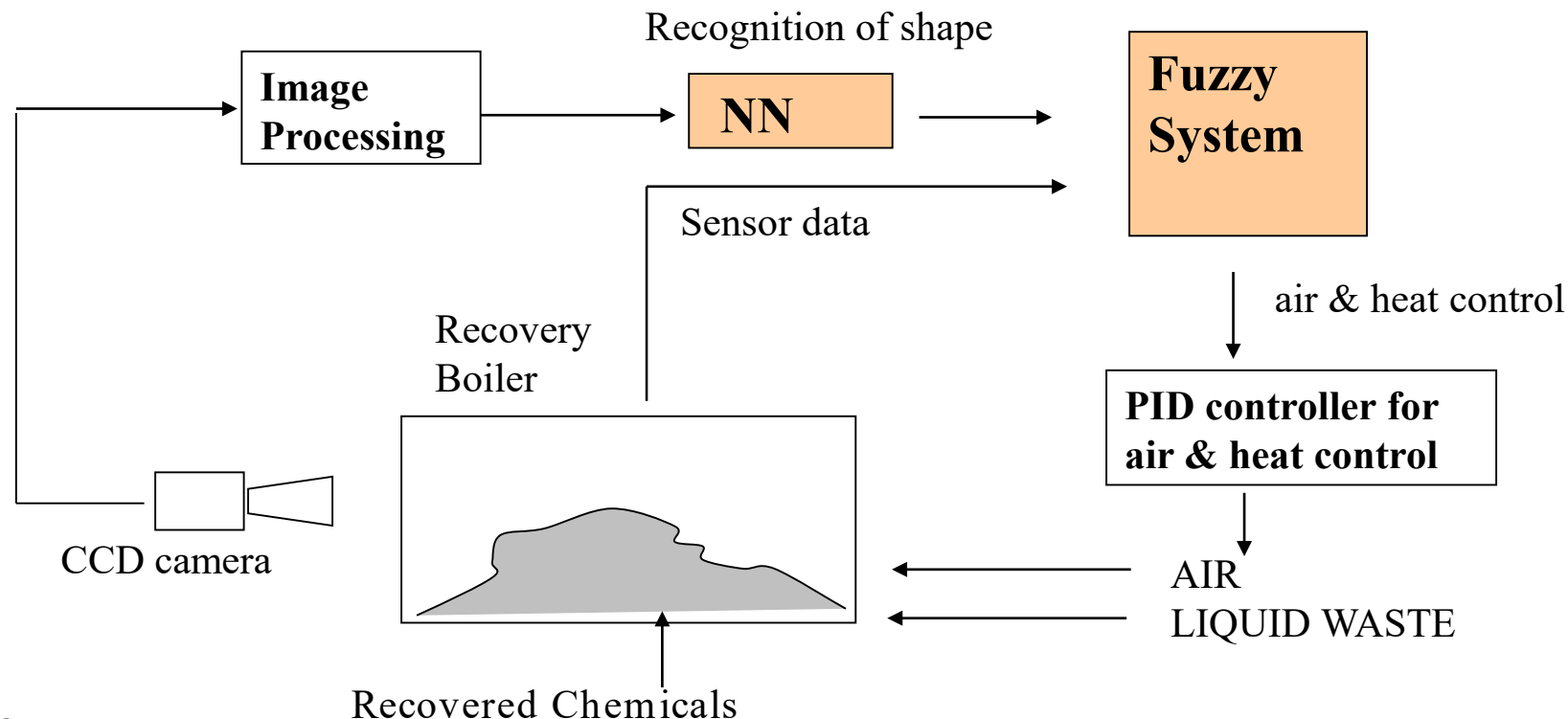
- Different techniques work together as a team to produce a single solution, no single technique/expert is sufficient alone
- E.g, NN provides input to Fuzzy System



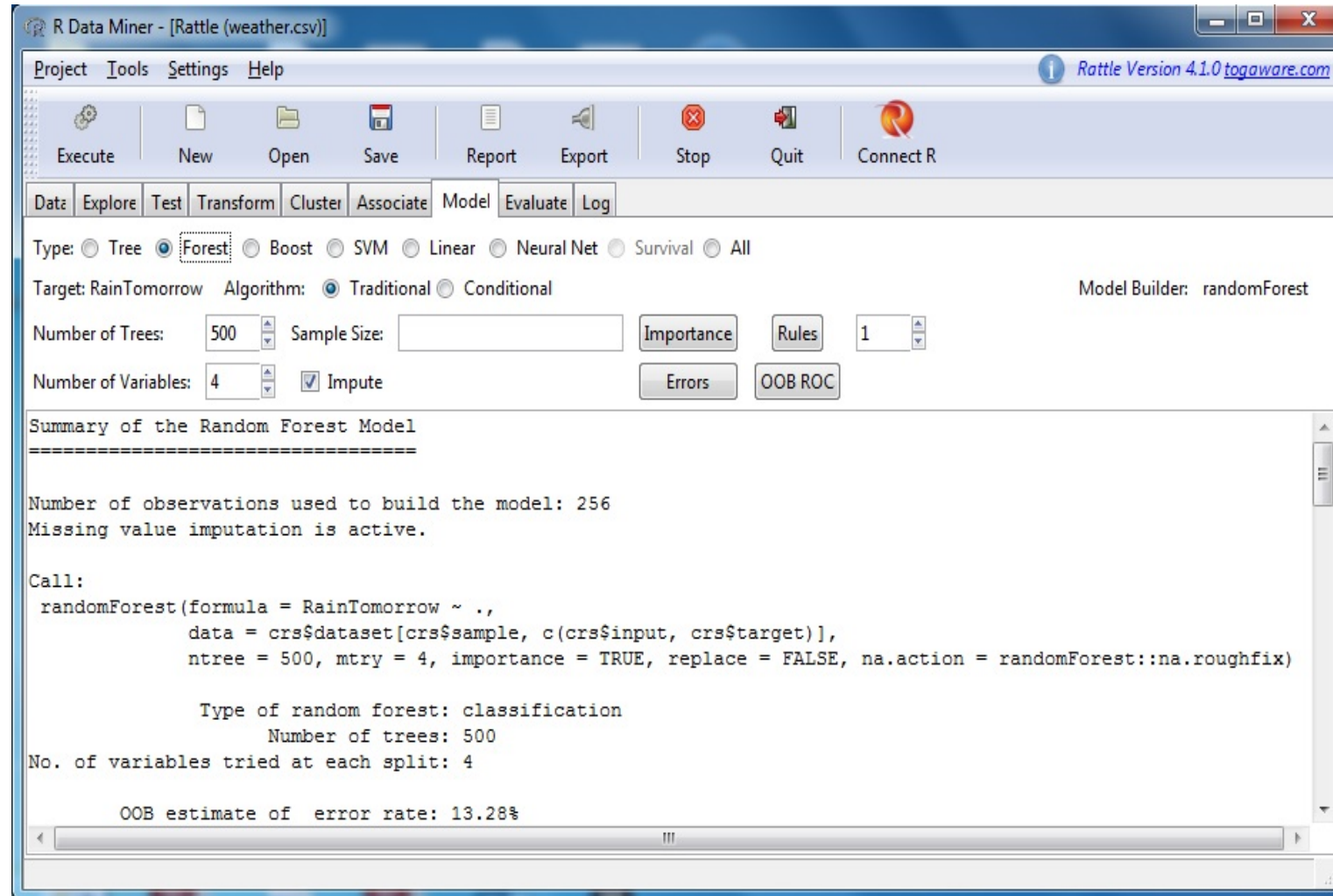
Co-operating Experts Example

- **Recovery of expensive chemicals at a pulp factory**

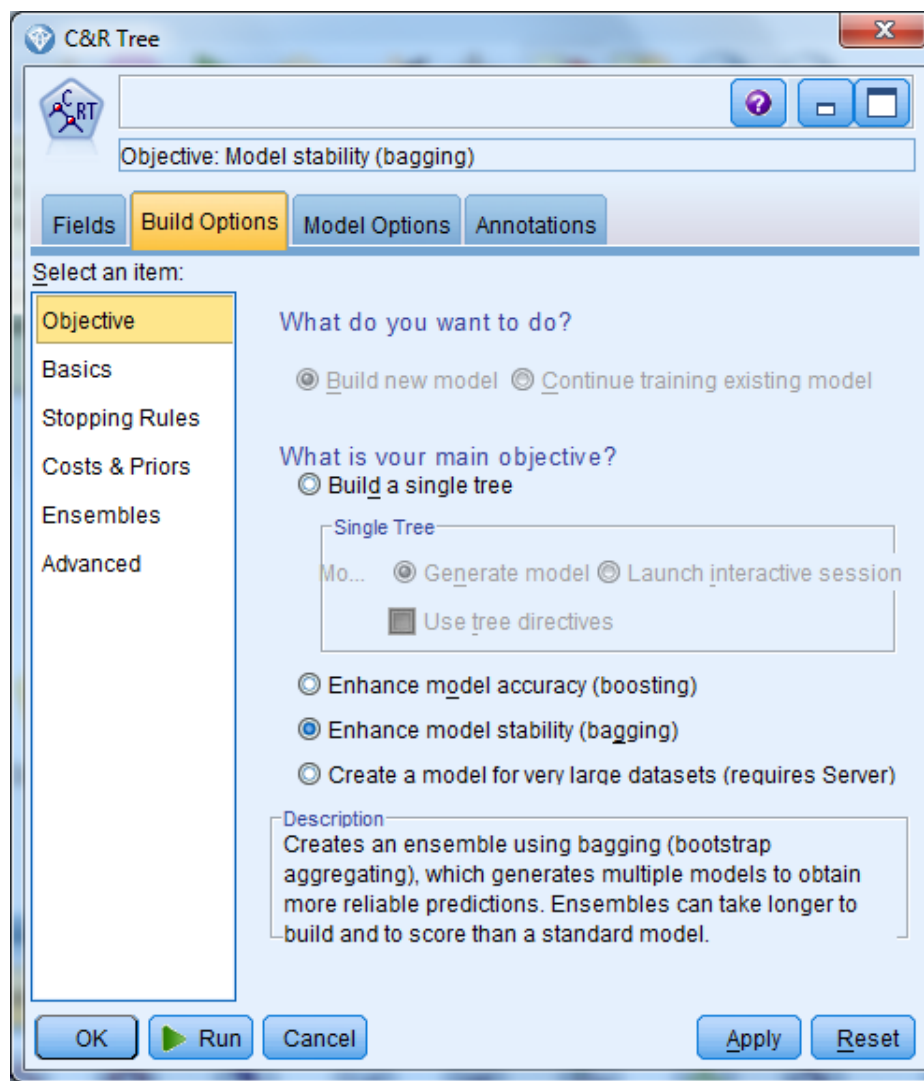
- Fuzzy system controls the temp. of liquid waste and air before input to recovery boiler
- Shape of pile in boiler influences the efficiency of the recovery process (deoxidisation). NN recognises the shape of the pile from (edge) image and passes to the Fuzzy system.



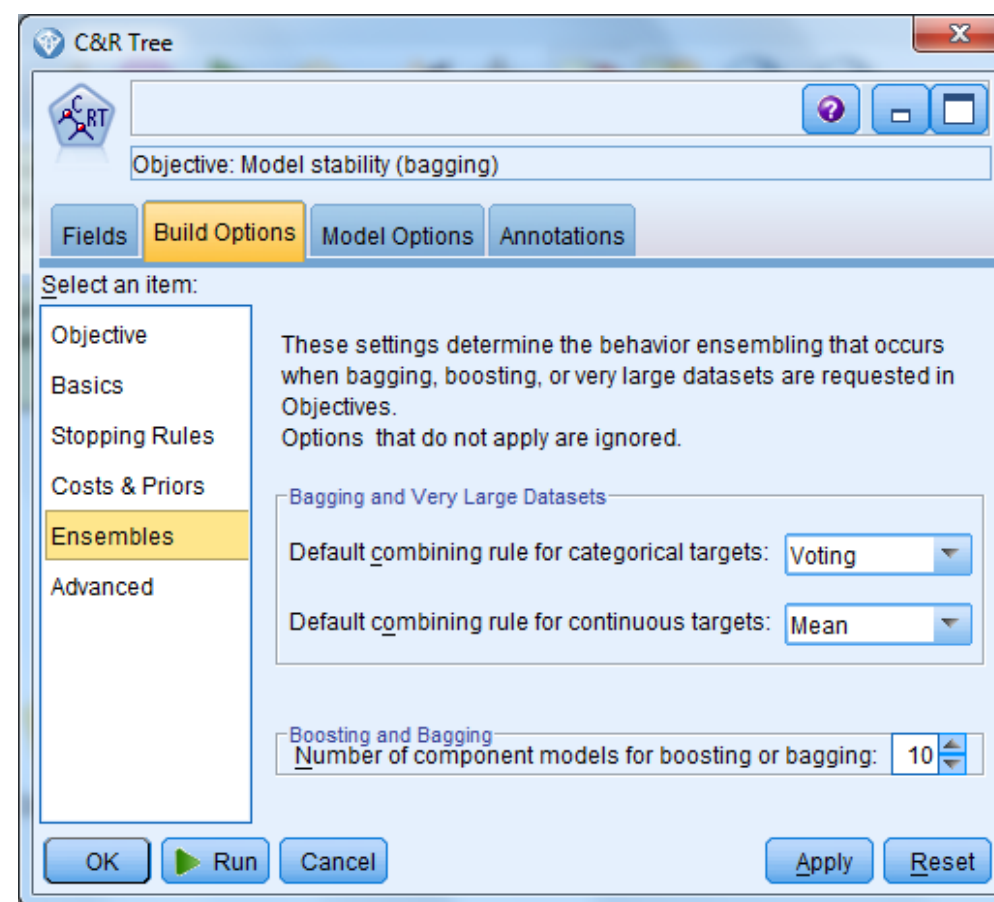
Bagging & Boosting in R & Rattle



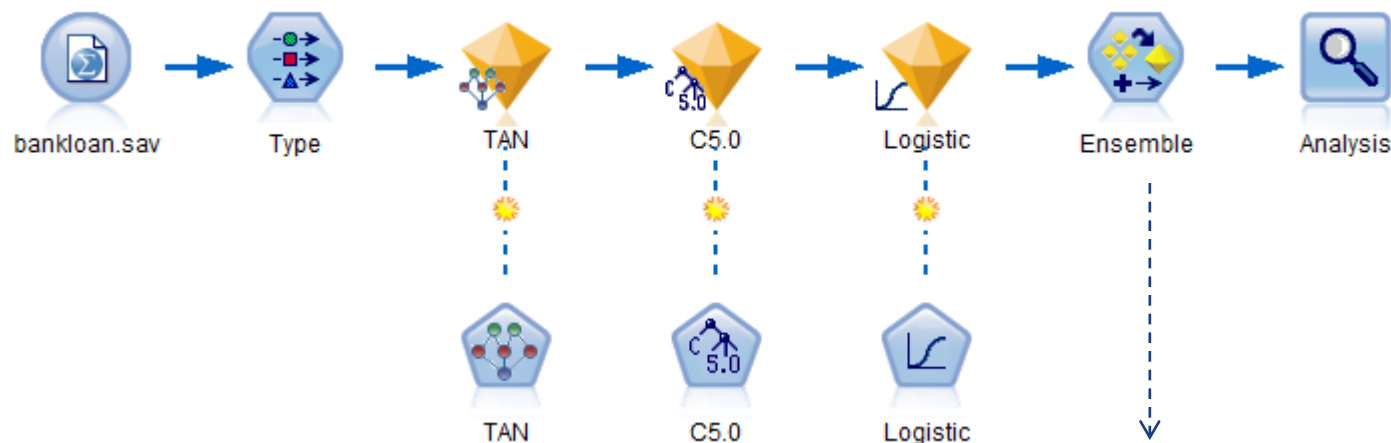
Bagging & Boosting in SPSS Modeler



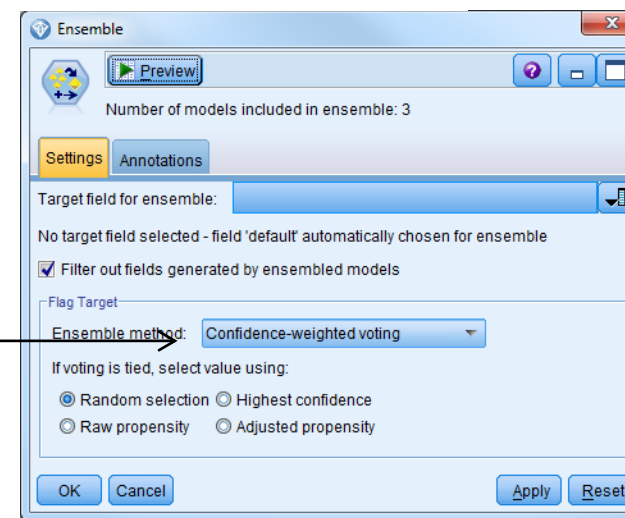
- Some model nodes implement bagging & boosting



Building Ensembles in SPSS Modeler



Ensemble method	Field name
Voting	
Confidence-weighted voting	
Raw-propensity-weighted voting	\$XFC_<field>
Raw-propensity-weighted voting	
Highest confidence wins	
Average raw propensity	\$XFRP_<field>
Average adjusted raw propensity	\$XFAP_<field>



Random Forest using Scikit-Learn

```
from sklearn.model_selection import train_test_split

X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.2, random_state=0)

from sklearn.ensemble import RandomForestClassifier

clf = RandomForestClassifier(n_estimators=200, random_state=0)

clf.fit(X_train, y_train)

y_pred = clf.predict(X_test)


from sklearn.metrics import classification_report, confusion_matrix, accuracy_score

print(confusion_matrix(y_test, y_pred))

print(classification_report(y_test, y_pred))

print(accuracy_score(y_test, y_pred))
```

AdaBoosting Using Scikit-Learn

```
from sklearn.ensemble import AdaBoostClassifier

from sklearn import datasets

from sklearn.model_selection import train_test_split

from sklearn import metrics


# Load data

iris = datasets.load_iris()

X = iris.data

y = iris.target


X_train, X_test, y_train, y_test = train_test_split(X, y, test_size=0.3)

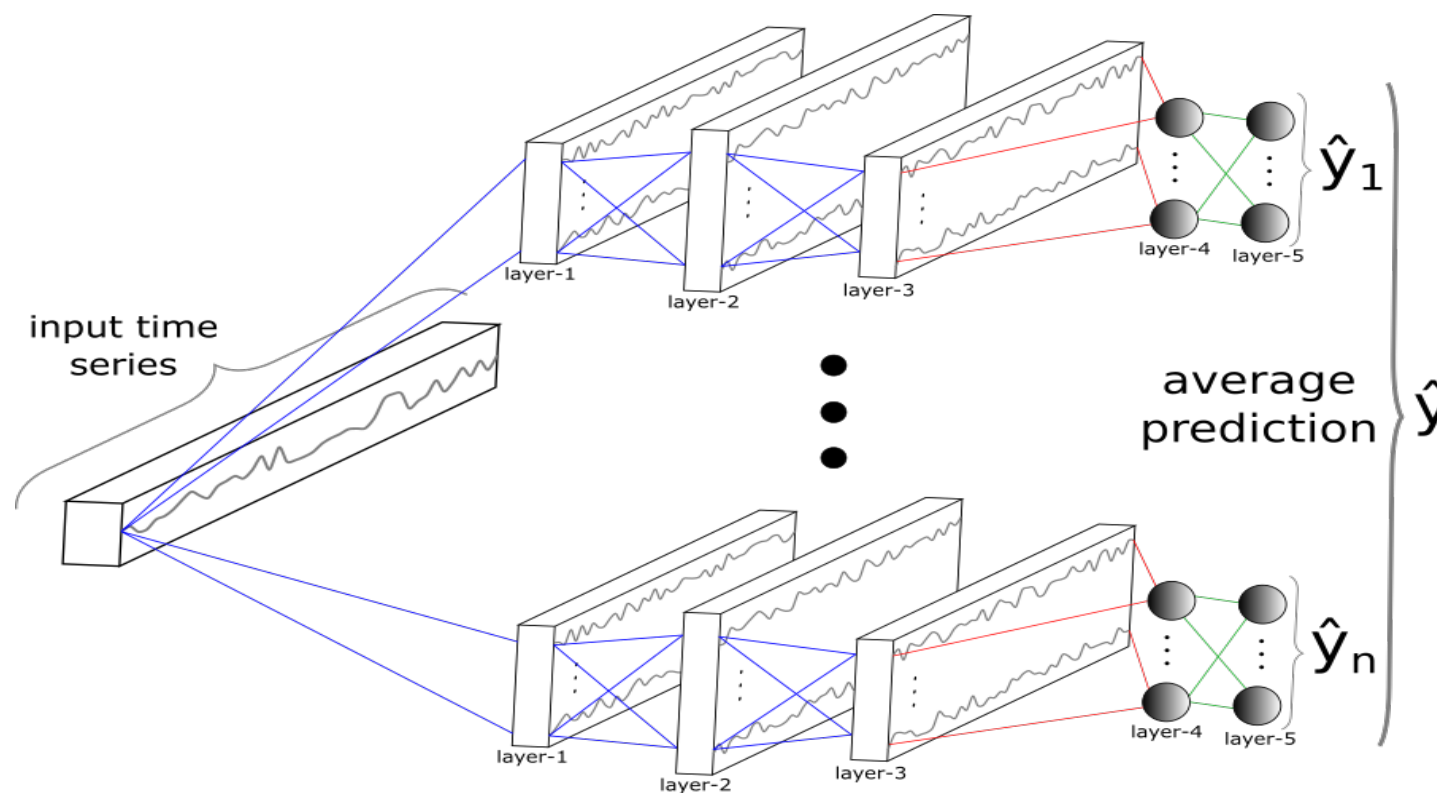

abc = AdaBoostClassifier(n_estimators=50, learning_rate=1)

model = abc.fit(X_train, y_train)

y_pred = model.predict(X_test)
```

Application Examples

- **Deep Neural Network Ensembles for Time Series Classification**



<https://github.com/hfawaz/ijcnn19ensemble>

Application Examples

- An Ensembled Neural Network Classifier for Vehicle Classification
- Artificial Neural Network Ensembles and Their Application in Pooled Flood Frequency Analysis
- Ensembling ConvNets using Keras
<https://towardsdatascience.com/ensembling-convnets-using-keras-237d429157eb>

5.2

Ensemble Workshop

Random Forest and Boosting

- Open the iPython notebooks provided for Random Forest and Boosting.
- As you run through the notebooks, make sure you understand how each **ensemble** method is implemented. (you can save notes as markdown in the notebook).
- Compare the performance of these models.
- Experiment with different parameter settings.

NN Ensembles – Averaging and Stacking

- Open the iPython notebooks provided for the two NN ensembles: AverageNNEnsemble and StackingNNEnsemble.
- As you run through the notebooks, make sure you understand how each **ensemble** method is implemented. (you can save notes as markdown in the notebook).
- Compare the performance of these models.
- Experiment with different parameter settings.
- Save your notebooks with all output as HTML file and upload it to LumiNUS