

# NUS-ISS

## *Intelligent Sensing and Sense Making*

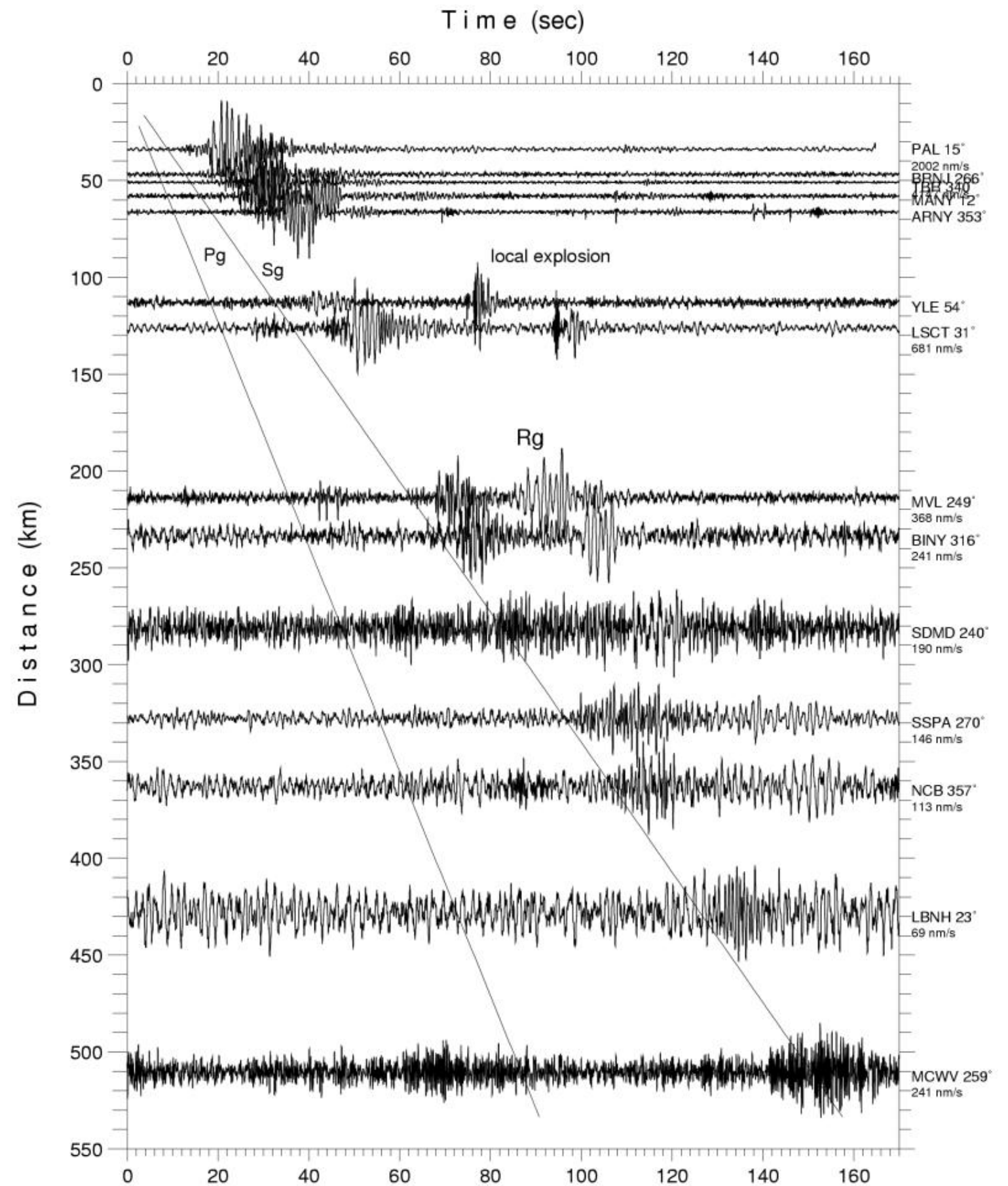


## Introduction to signals

by Dr. Tan Jen Hong

© 2019 National University of Singapore.  
All Rights Reserved.

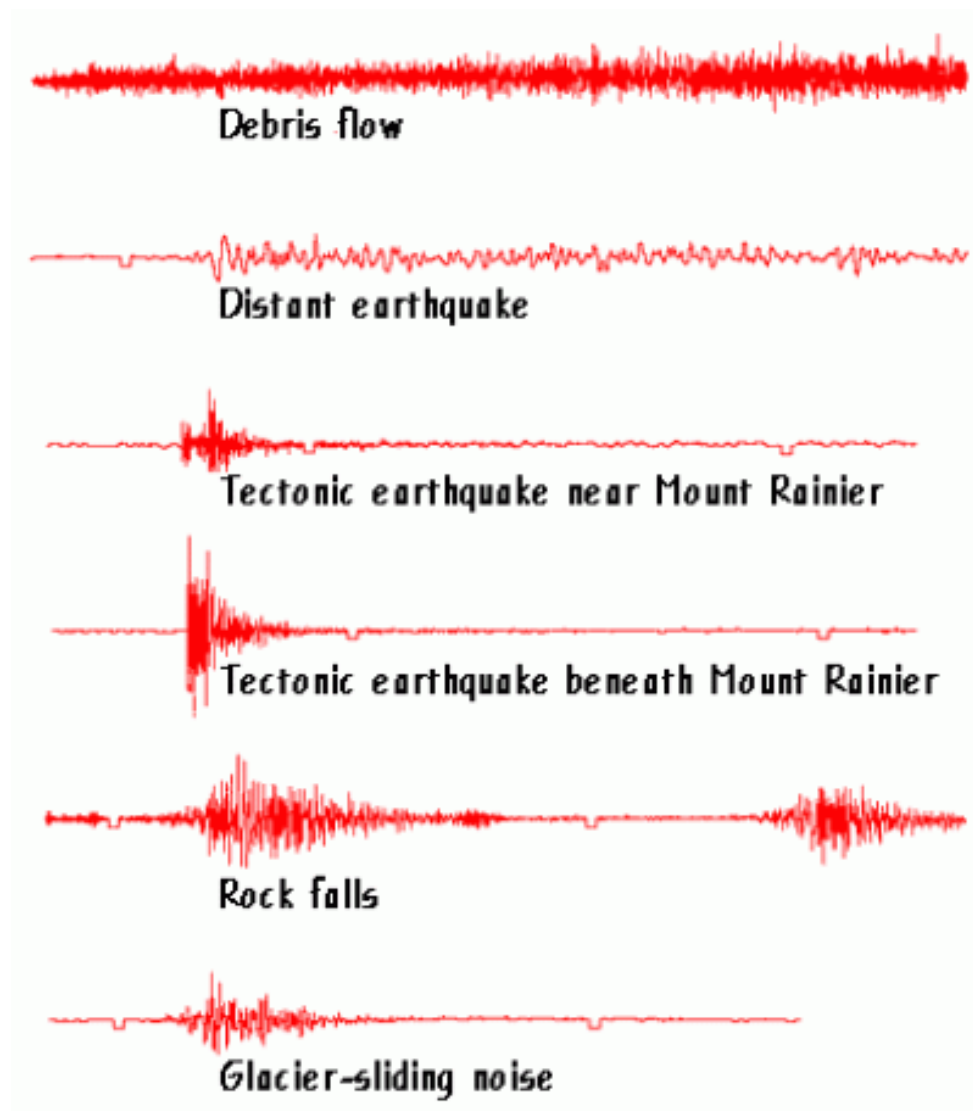
# Signals



Source: [http://911research.wtc7.net/mirrors/guardian2/wtc/seismic/WTC\\_PENT\\_KIM.htm](http://911research.wtc7.net/mirrors/guardian2/wtc/seismic/WTC_PENT_KIM.htm)

# What is signal?

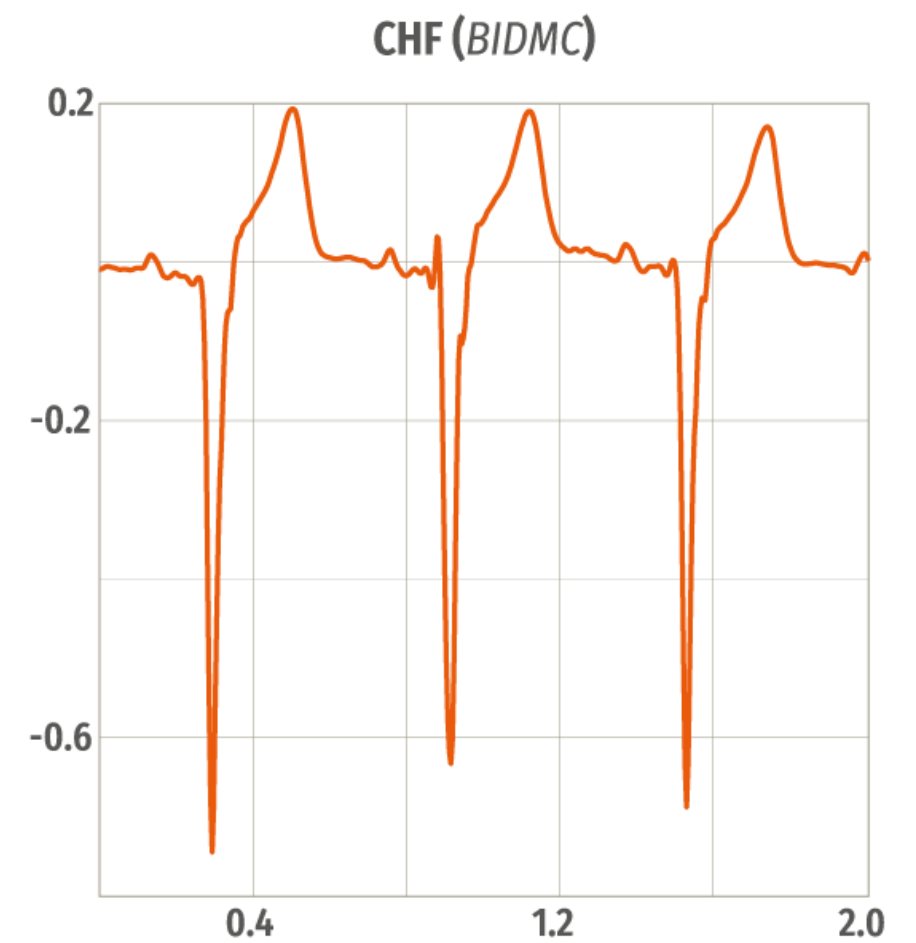
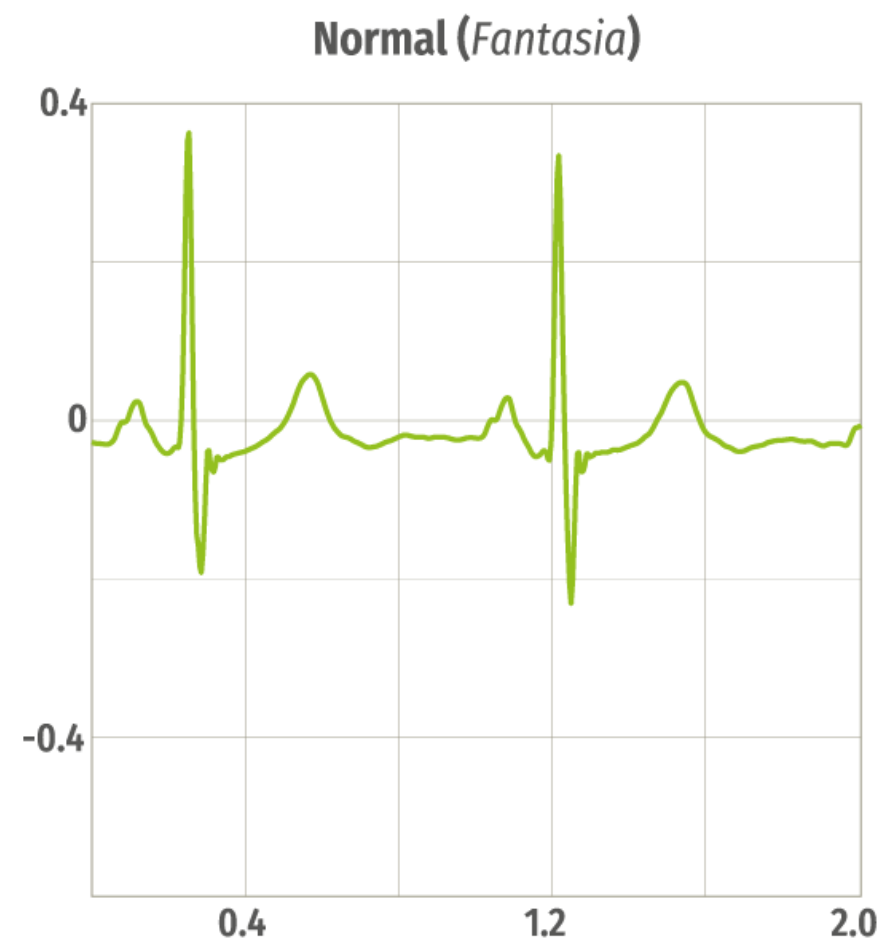
- A set/series of data
- Any kind of physical variable subjected to variations represents a signal
- Independent variable, physical variable can be either scalar or vector
- Independent variable: time (t), position (x,y,z)



Source: [https://volcanoes.usgs.gov/vhp/seismic\\_signals.html](https://volcanoes.usgs.gov/vhp/seismic_signals.html)

# Signals

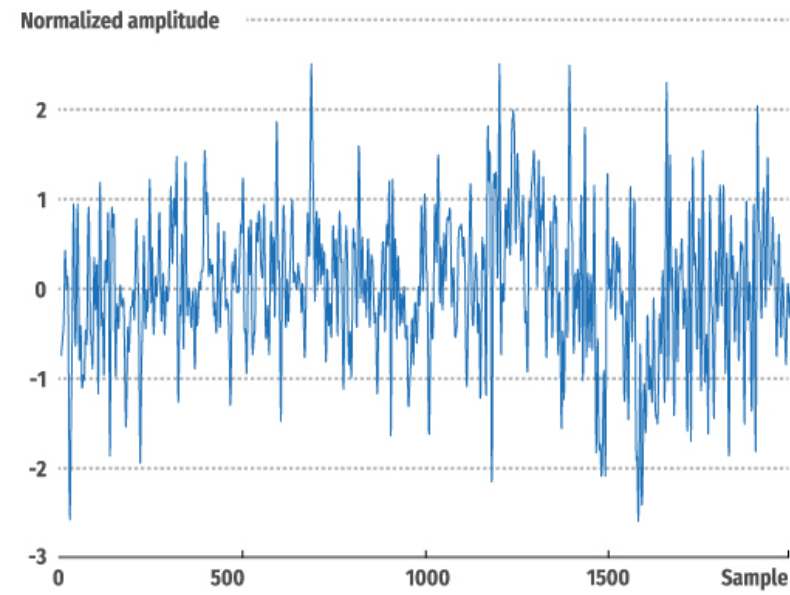
Example: ECG



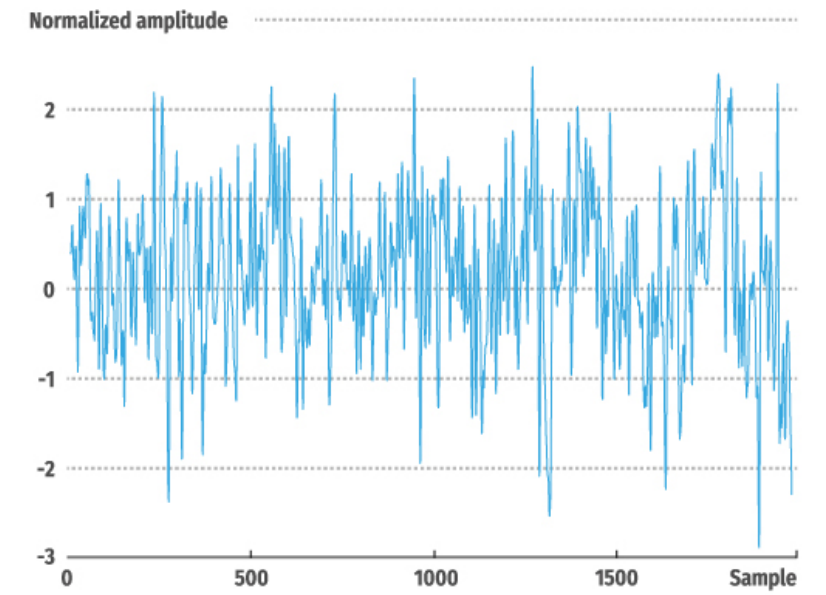
# Signals

## Example: EEG

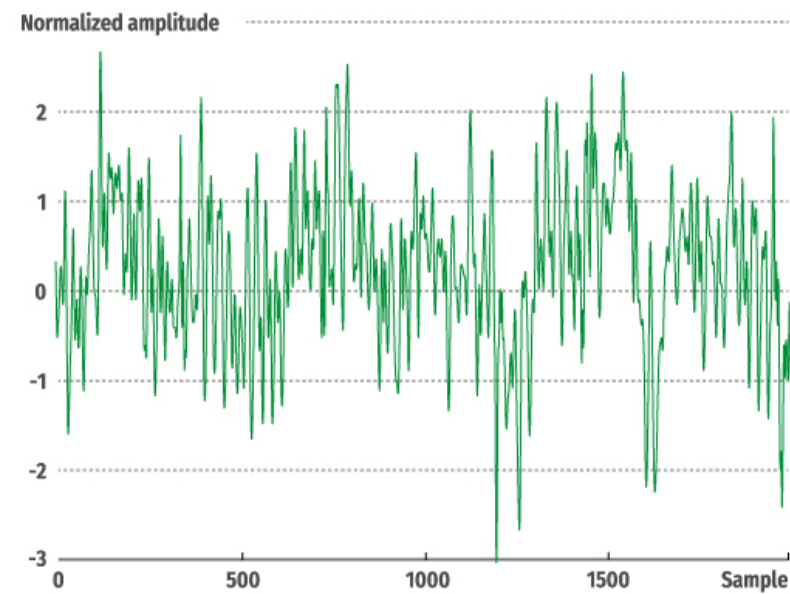
Normal (left, FP1-T3)



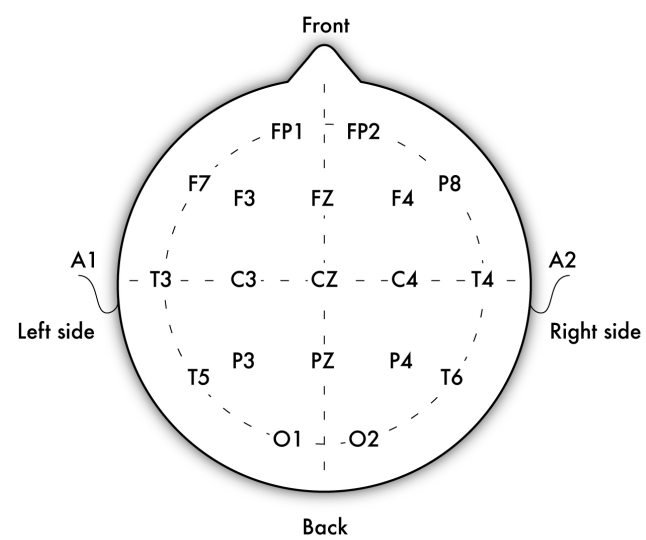
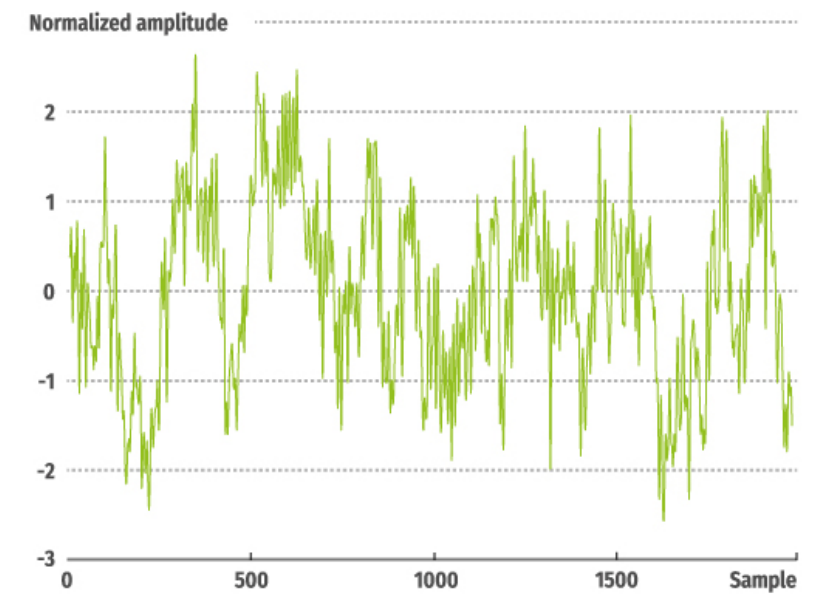
Normal (right, FP2-T4)



Depression (left, FP1-T3)

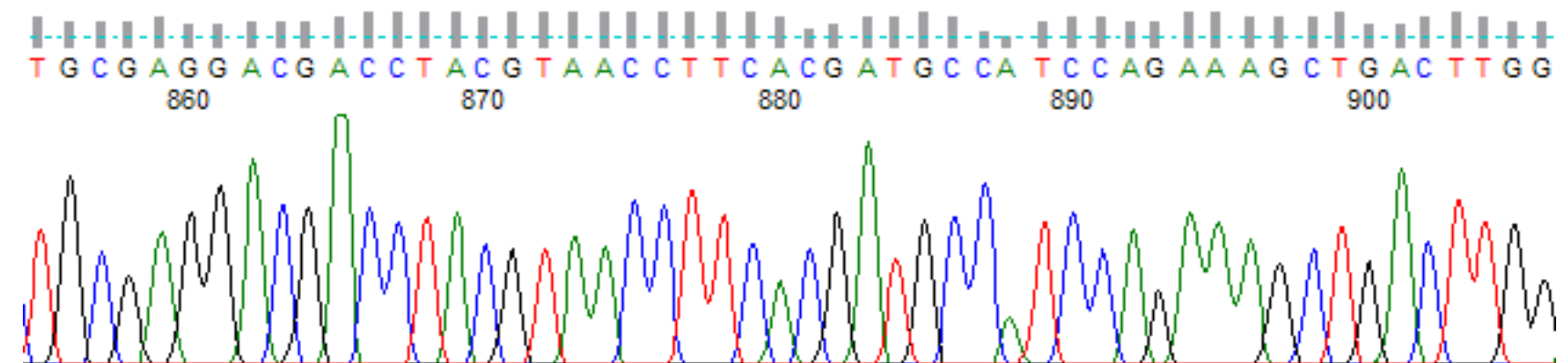
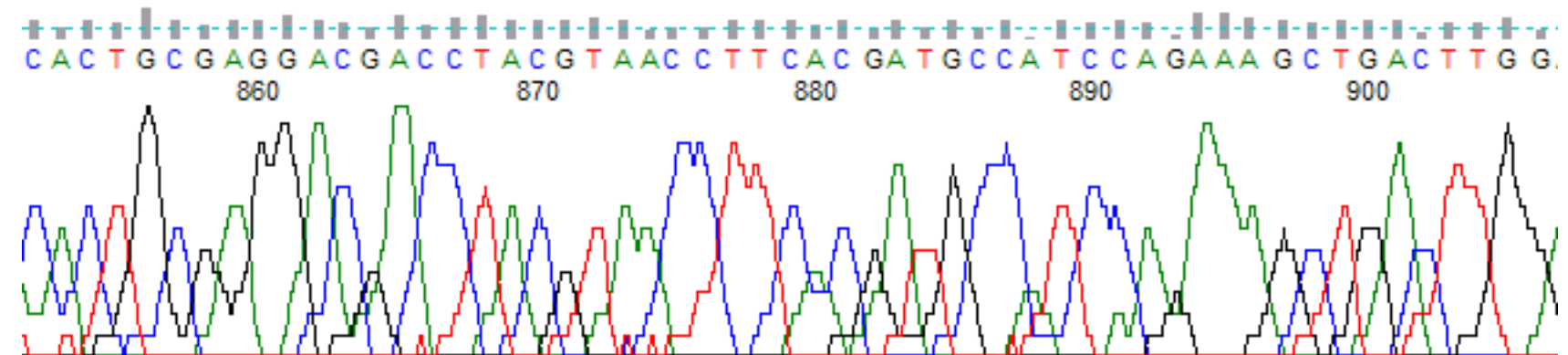


Depression (right, FP2-T4)



# Signals

Example:  
Electropherogram

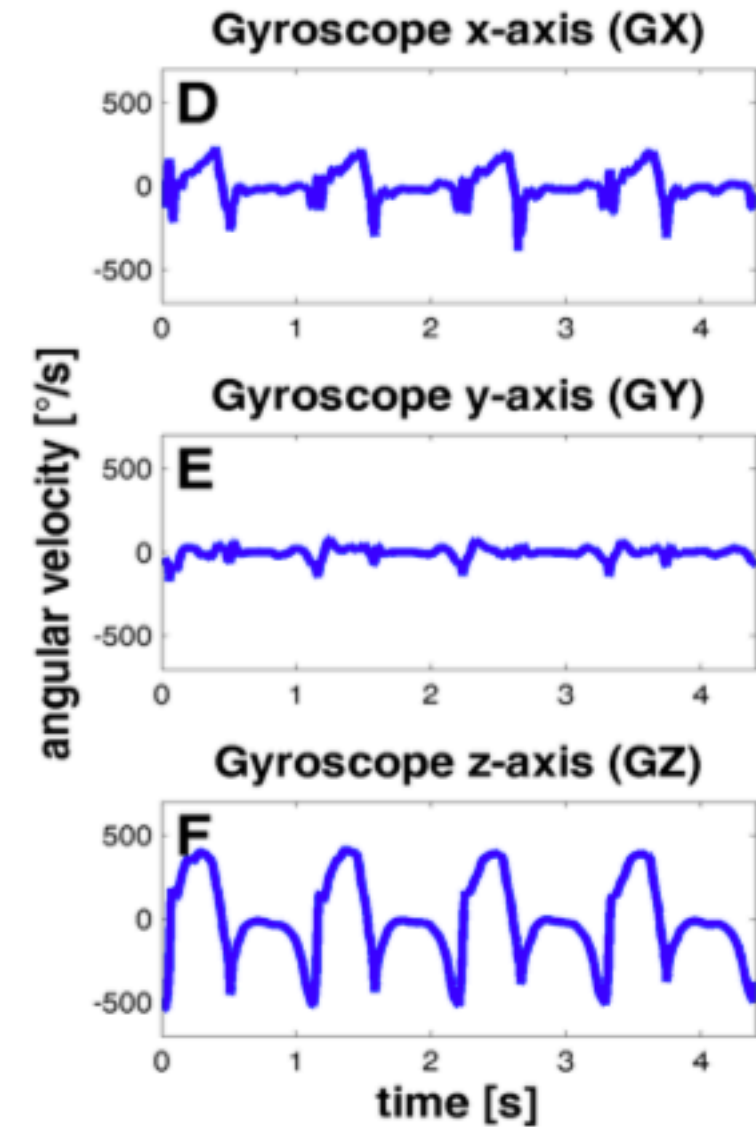
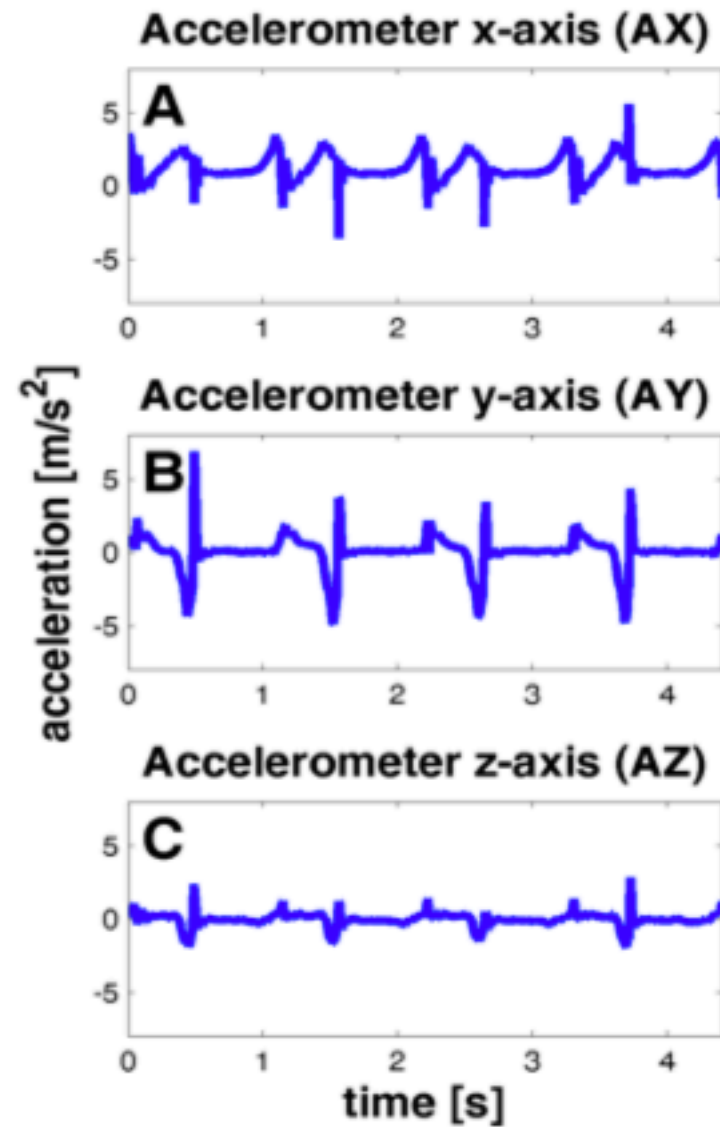
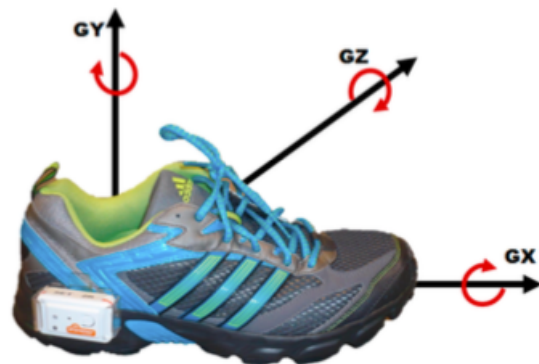


Source: <https://www.nucleics.com/peaktrace/peaktrace-box-overview.html>



# Signals

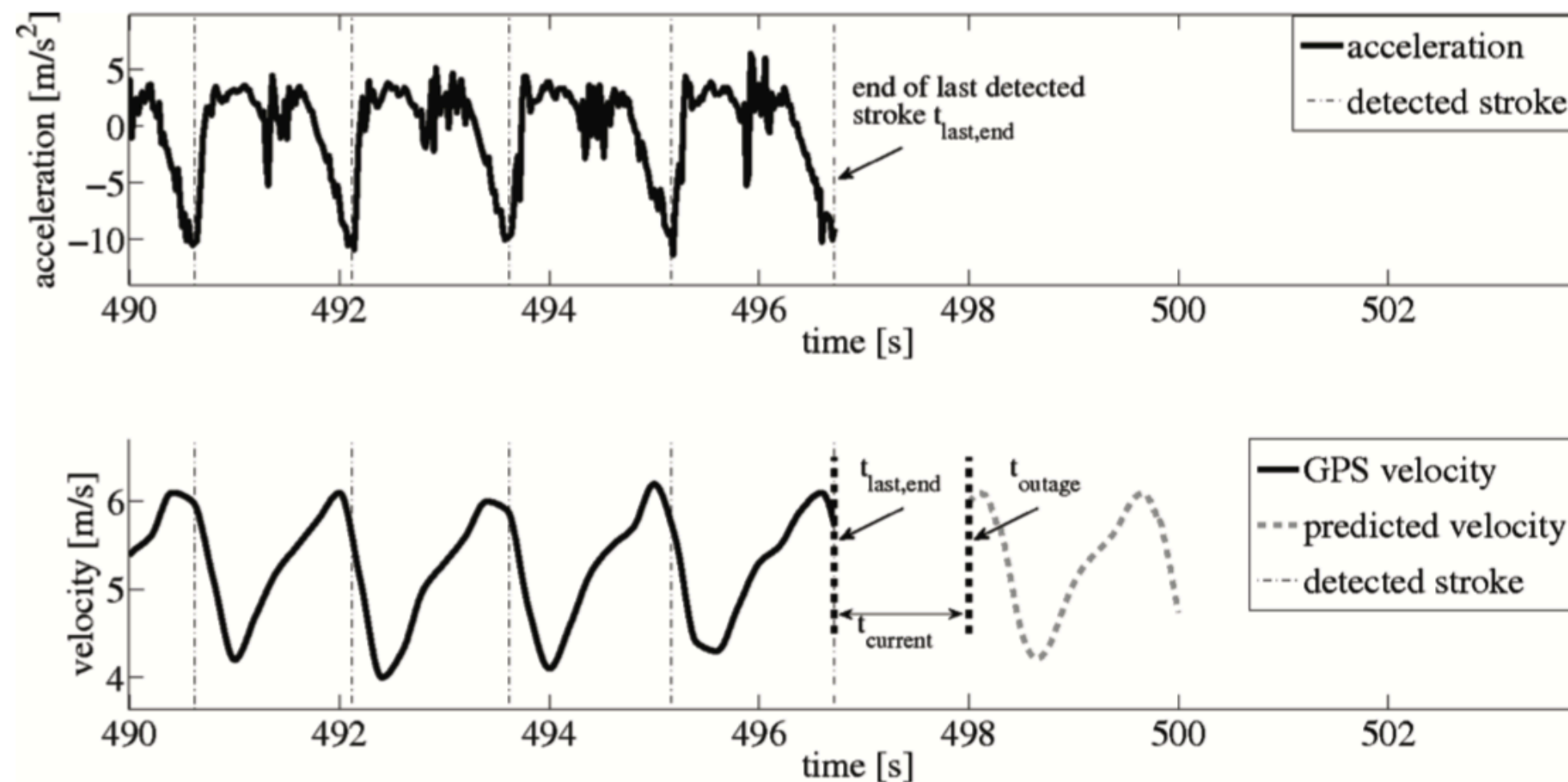
Example: 4 walking strides from an elderly



Source: doi:10.3390/s150306419

# Signals

Example: Movement prediction in rowing based on stroke detection



Source: DOI: 10.1109/ISSNIP.2014.6827684



# Signals

Example: Ultrasound image



Source: <https://www.cliniciansbrief.com/article/liver-ultrasound-guided-fine-needle-aspiration>

# Signal as function

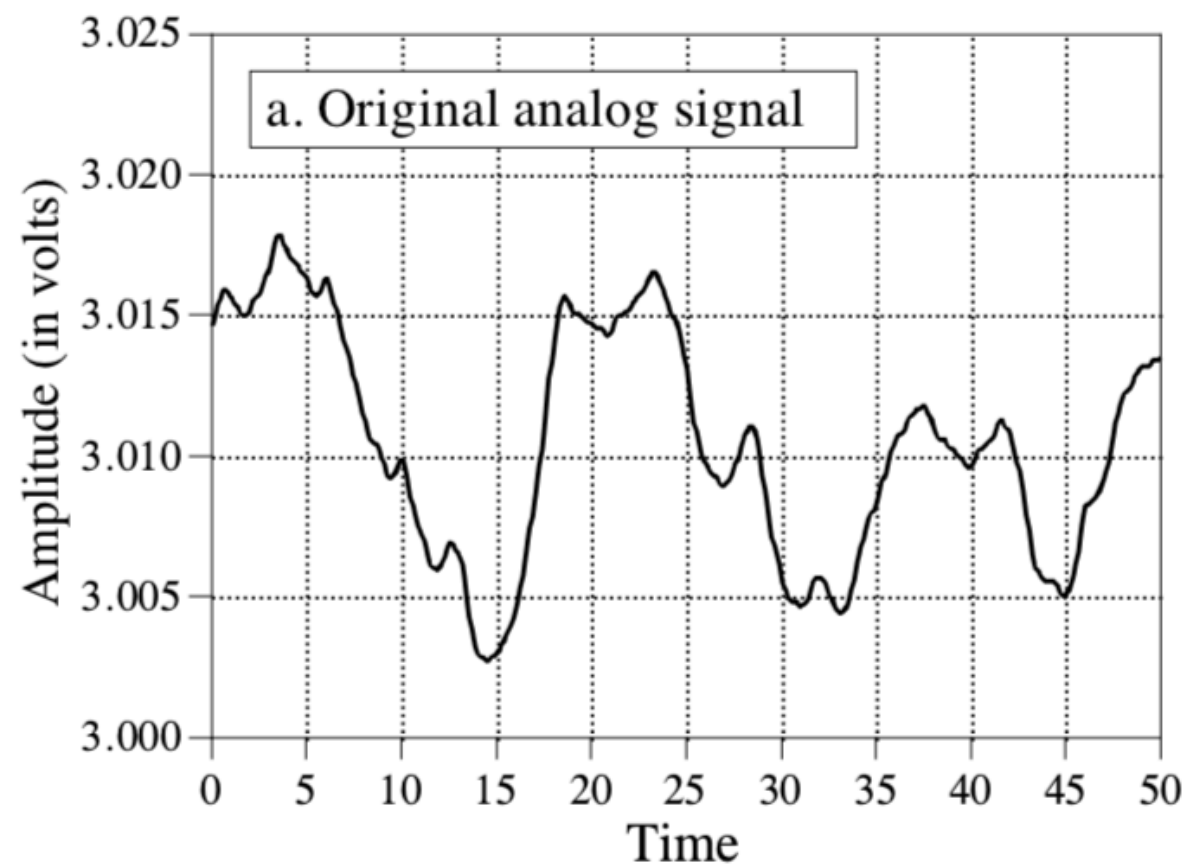
Real - Real

- Continuous function of real independent variables

- 1 dimensional:  $z = f(x)$

- 2 dimensional:  $z = f(x, y)$

$$z, x, y \in R$$



Source: "The scientist and engineer's guide to digital signal processing",  
by Steven W. Smith

# Signal as function

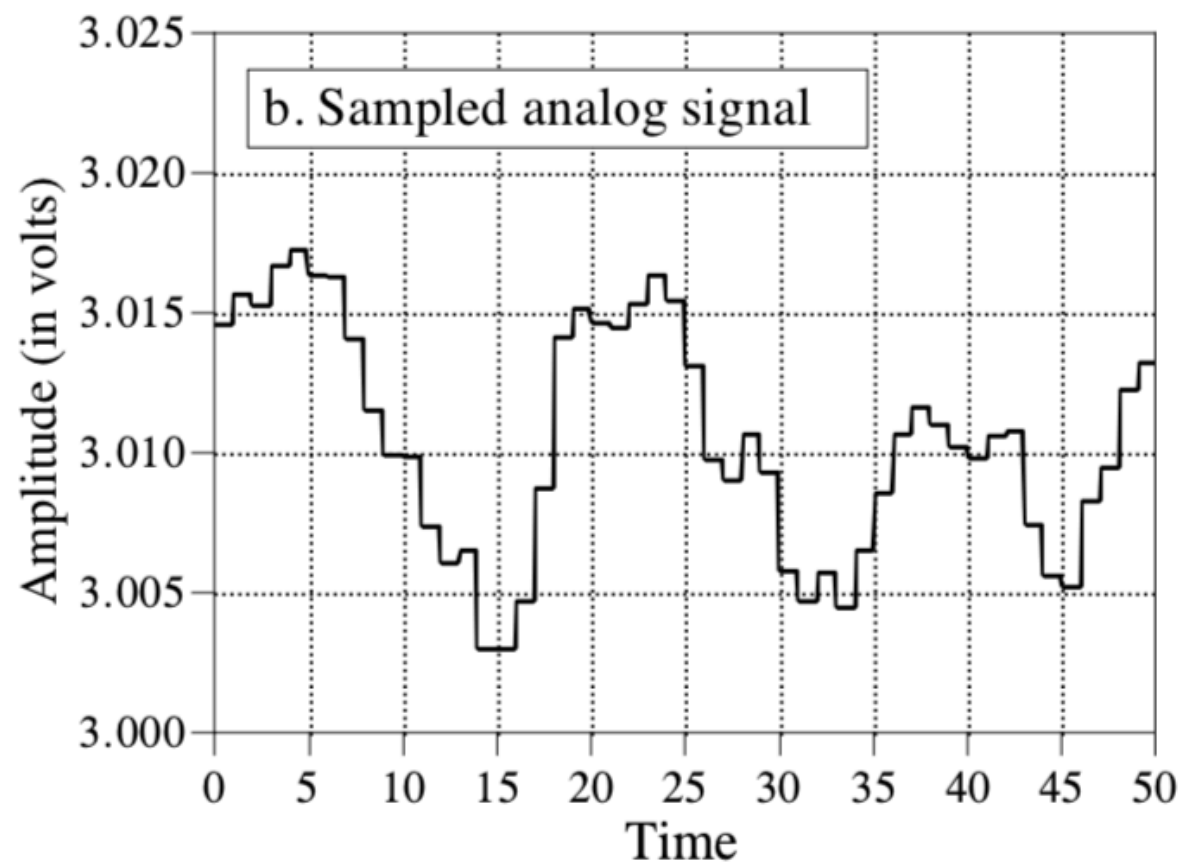
Real - Discrete

- Continuous function of real independent variables

- 1 dimensional:  $z = f[i]$

- 2 dimensional:  $z = f[i, j]$

$$z \in R \quad i, j \in Z^+$$



Source: "The scientist and engineer's guide to digital signal processing",  
by Steven W. Smith

# Signal as function

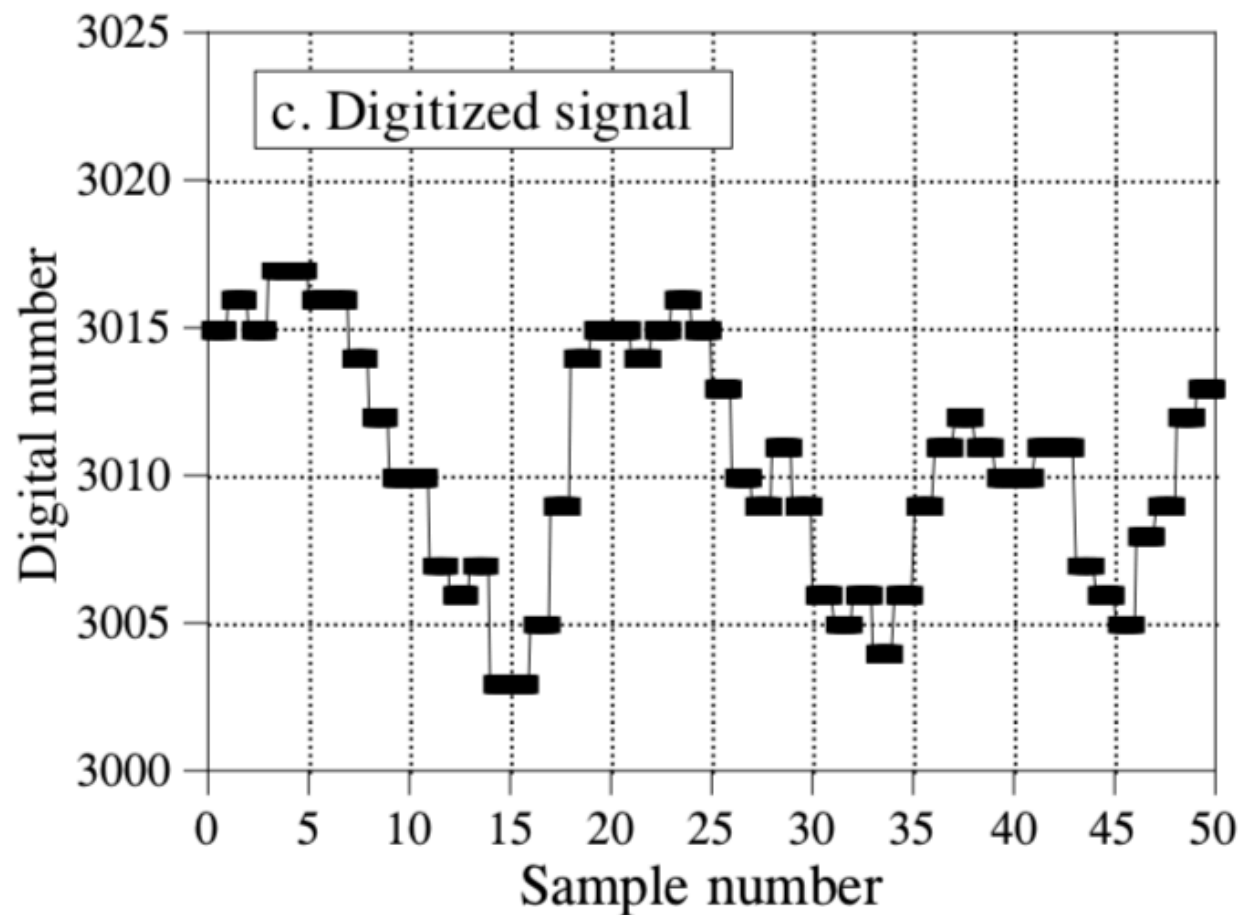
Discrete - Discrete

- Continuous function of real independent variables

- 1 dimensional:  $z = f[i]$

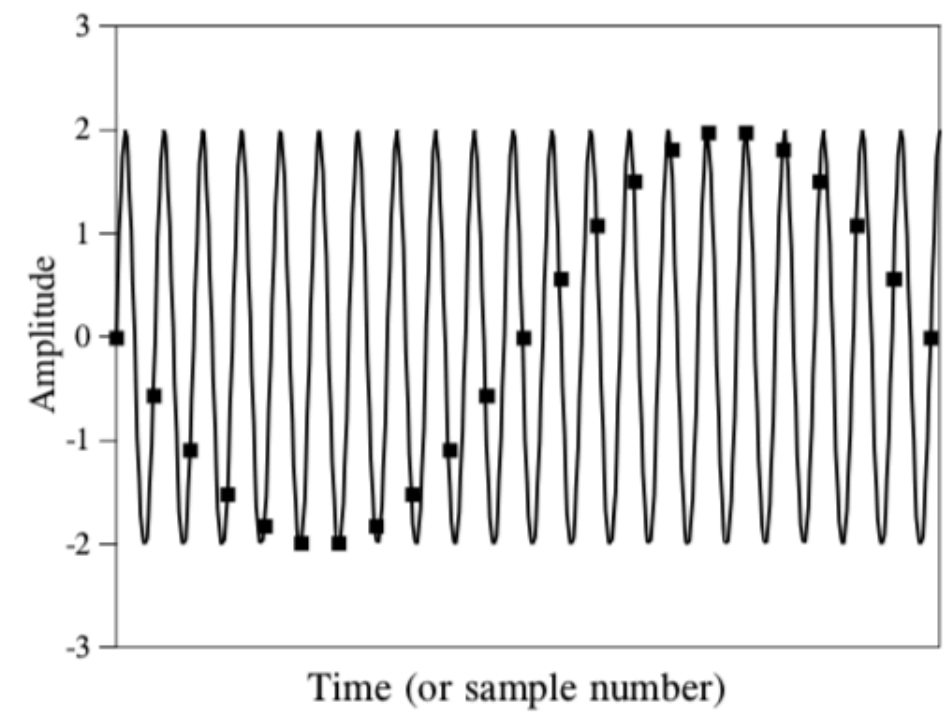
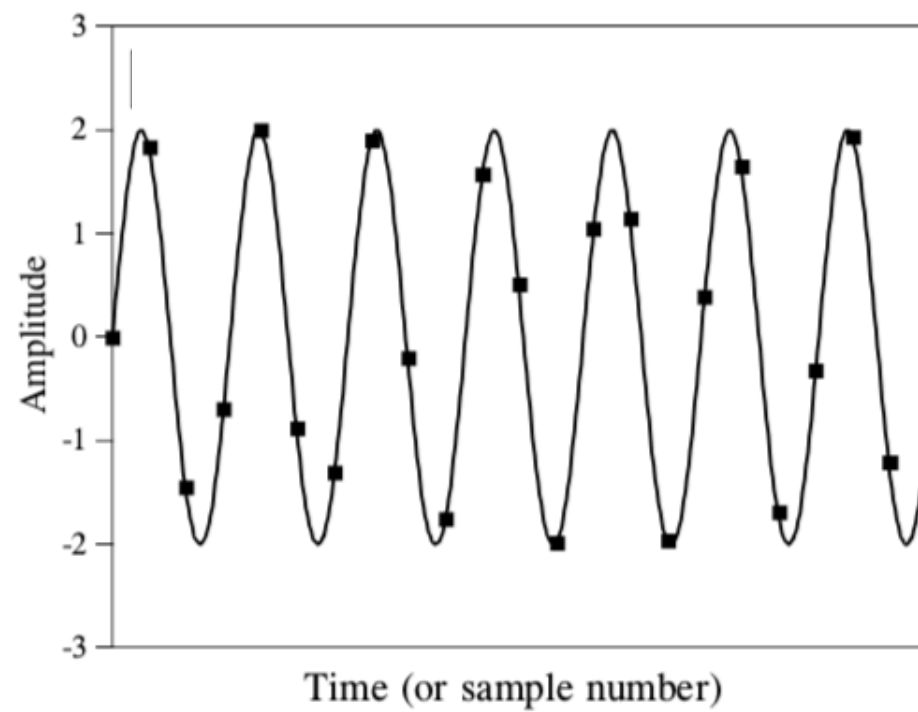
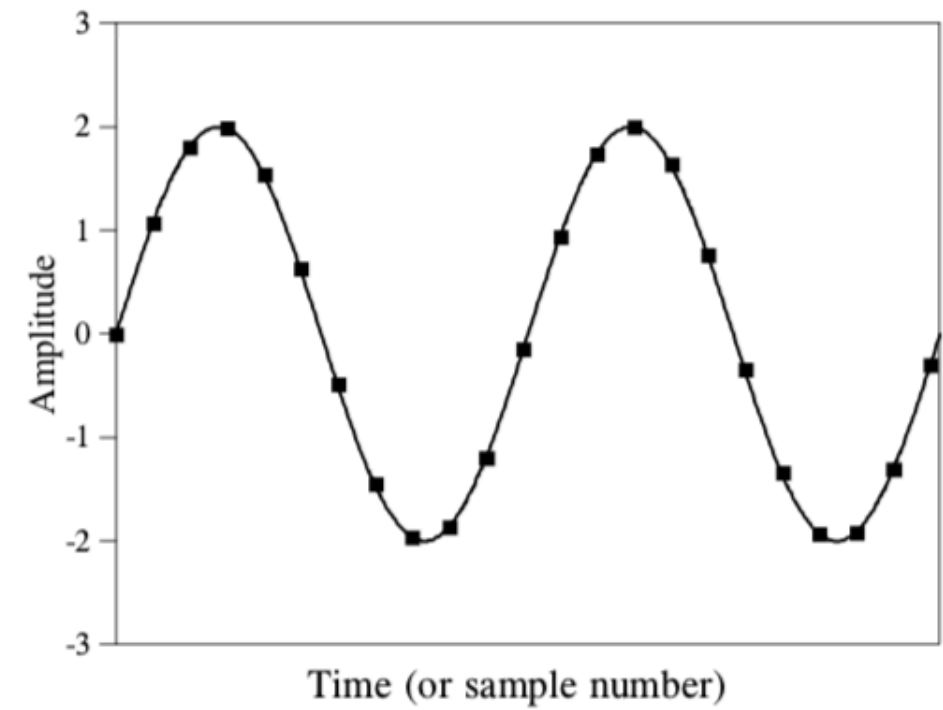
- 2 dimensional:  $z = f[i, j]$

$$z \in Z \quad i, j \in Z^+$$



Source: "The scientist and engineer's guide to digital signal processing",  
by Steven W. Smith

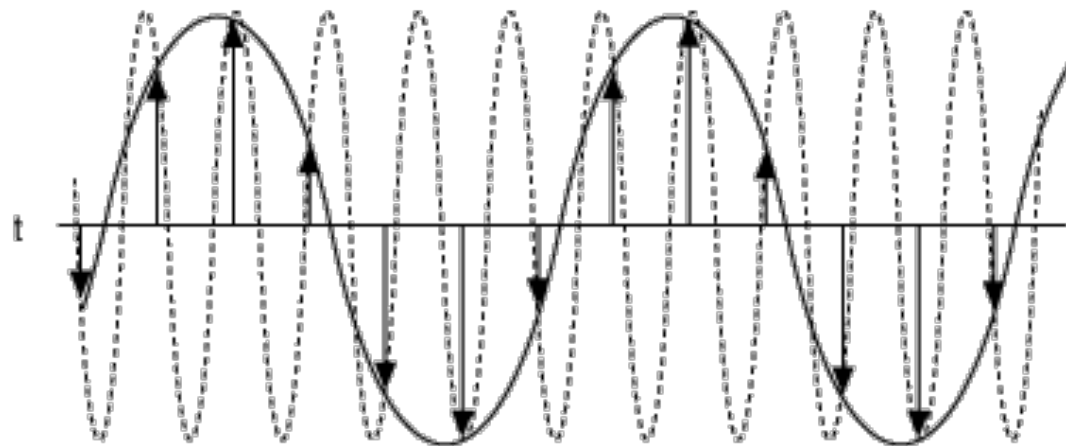
# Sampling



Source: "The scientist and engineer's guide to digital signal processing",  
by Steven W. Smith

# Nyquist-Shannon theorem

- Suppose the highest frequency component, in hertz, for a given analog signal is  $f_{\max}$ .
- According to the Nyquist-Shannon theorem, the sampling rate must be at least  $2f_{\max}$ , or twice the highest analog frequency component.
- If the sampling rate is less than  $2f_{\max}$ , some of the **highest frequency components** in the analog input signal will not be correctly represented in the digitized output



Source: <http://www.writeopinions.com/nyquist-ndash-shannon-sampling-theorem>

Source: <https://whatis.techtarget.com/definition/Nyquist-Theorem>



# Sampling

## Example

- Wheel of a forward-moving car is seemed rotating backward when by right it should rotate forward
- Can be explained by under-sampling. If movie is filmed at 24 frames per second, but wheel rotates more than 12 times per second, under-sampling likely creates the impression of backward rotation



Source: <https://www.howitworksdaily.com/question-of-the-day-why-do-car-wheels-look-like-they-are-spinning-backwards-at-high-speed/>

# Question

- A telephone company digitize voice by assuming a maximum frequency of 4000 Hz
- What should be the sampling rate?

# Question

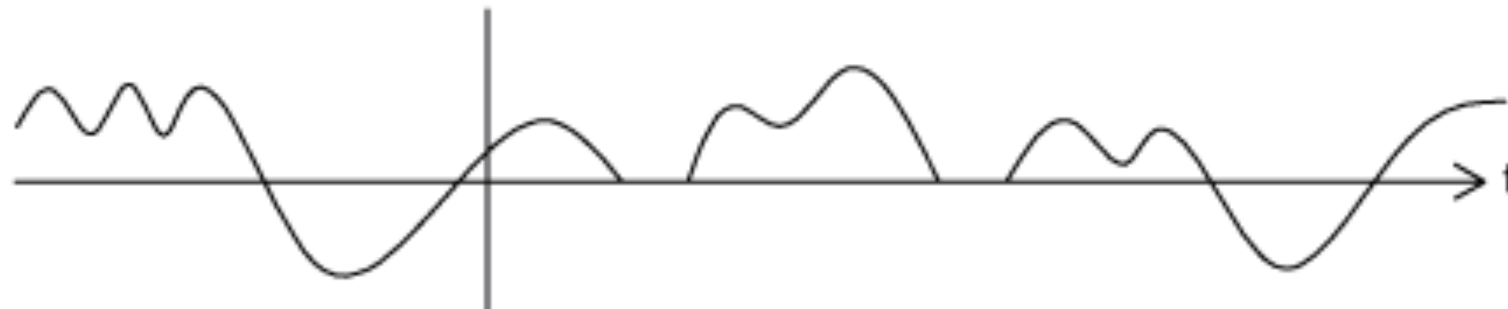
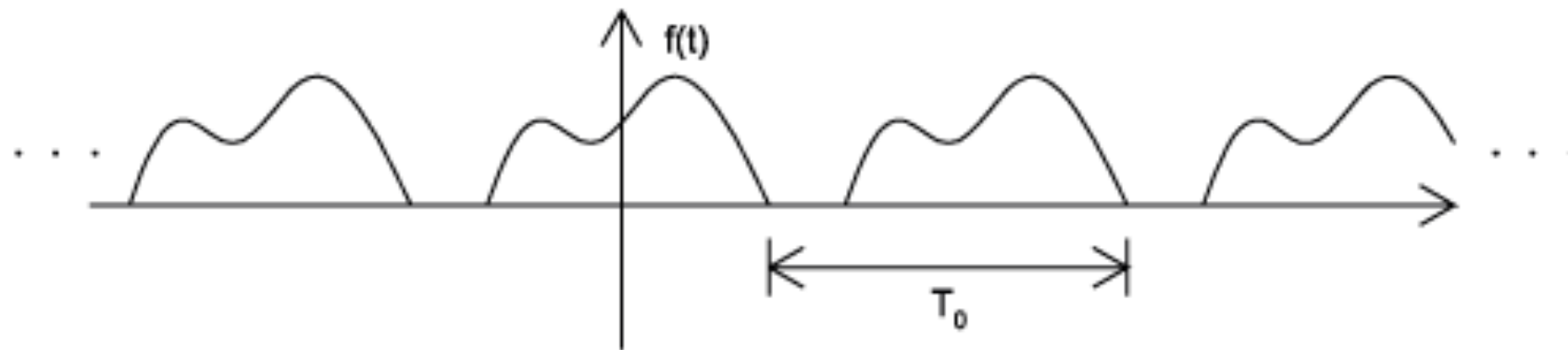
- A complex signal has a bandwidth of 200 kHz.
- What is the minimum sampling rate for this signal?

# Signal types

Periodic | Aperiodic

- A signal is periodic if there exists a positive constant  $T_0$  such that

$$f(t + T_0) = f(t) \quad \forall t$$



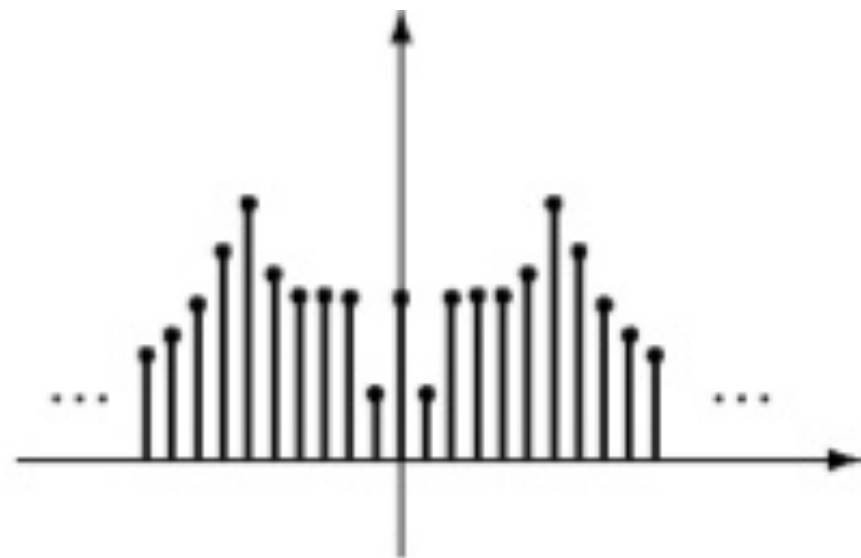
Source: <http://pilot.cnxproject.org/content/collection/col10064/latest/module/m10057/latest>

# Signal types

Even | Odd

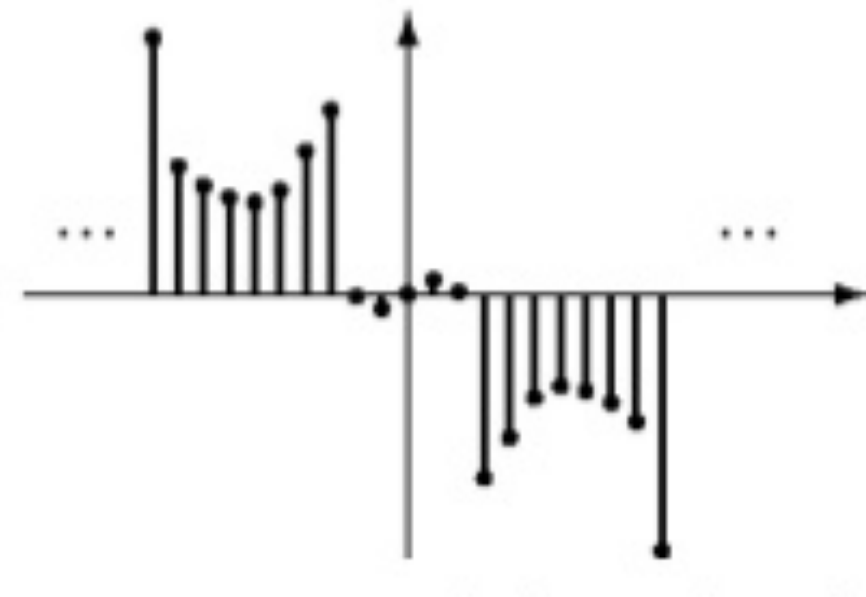
- Even signals can be easily spotted as they are symmetric around vertical axis

$$f(t) = f(-t)$$



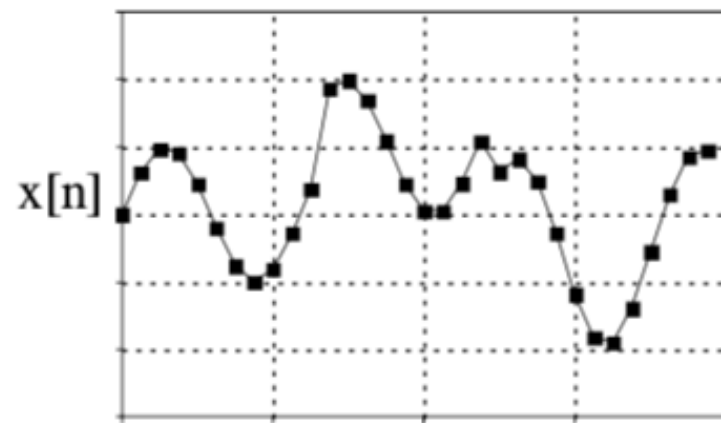
- An odd signal is a signal such that

$$f(t) = -f(-t)$$



Source: <https://www.slideshare.net/mihirkjain/ch1-46505880>

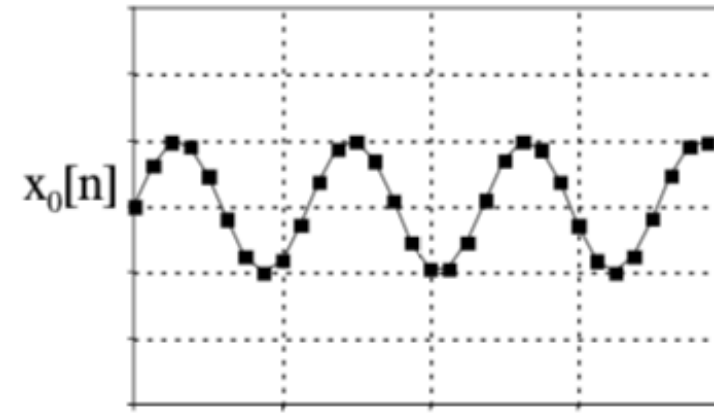
# Superposition, decomposition



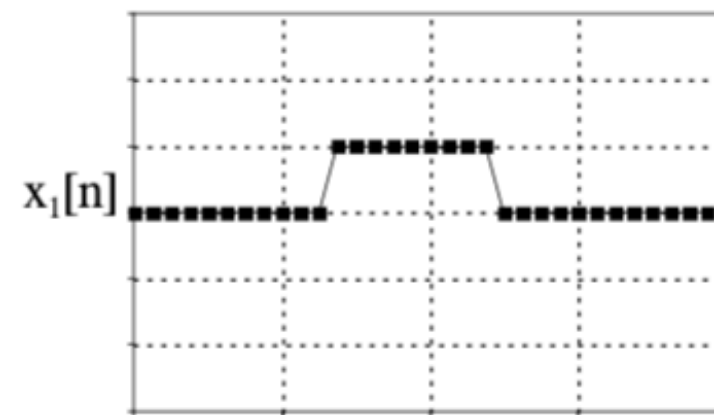
decomposition



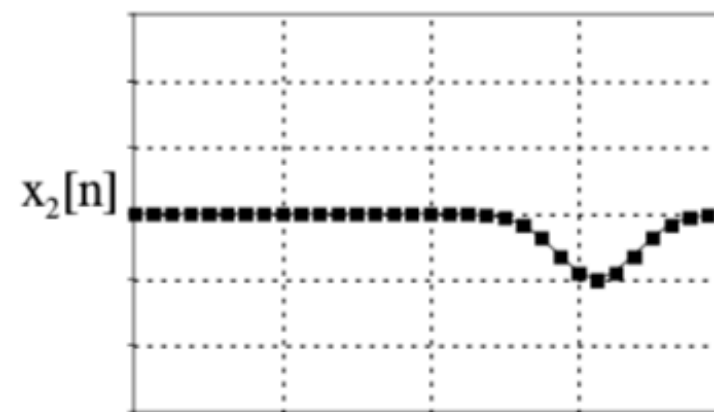
superposition



+



+

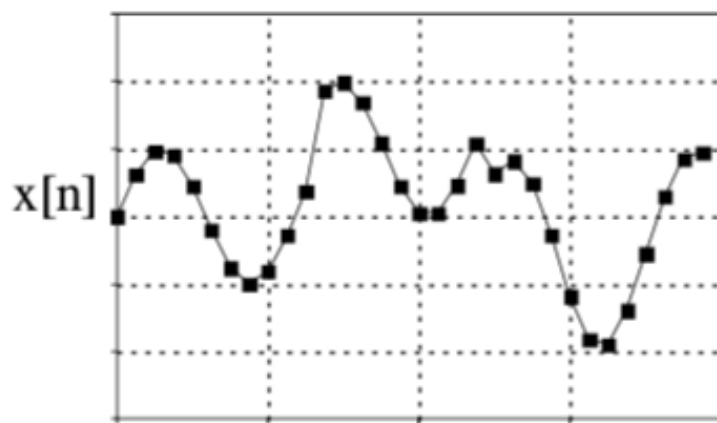


Source: "The scientist and engineer's guide to digital signal processing",  
by Steven W. Smith



# Superposition, decomposition

- When dealing with linear systems, signals can only be combined by scaling and adding, no signal-signal multiplication
- Synthesis: The process of combining signals through scaling and addition
- The beauty of superposition: Instead of trying to understand how complicated signals behave as a whole, we study the individual components, which are simpler signals



Source: "The scientist and engineer's guide to digital signal processing",  
by Steven W. Smith