# Standard notations for Deep Learning

This document has the purpose of discussing a new standard for deep learning mathematical notations.

## Neural Networks Notations.

#### General comments:

· superscript (i) will denote the  $i^{th}$  training example while superscript [l] will denote the  $l^{th}$  layer

#### Sizes:

 $\cdot m$ : number of examples in the dataset

 $\cdot n_x$ : input size

 $\cdot n_y$ : output size (or number of classes)

 $n_h^{[l]}$ : number of hidden units of the  $l^{th}$  layer

In a for loop, it is possible to denote  $n_x = n_h^{[0]}$  and  $n_y = n_h^{[\text{number of layers } +1]}$ .

 $\cdot L$ : number of layers in the network.

## Objects:

 $X \in \mathbb{R}^{n_x \times m}$  is the input matrix

 $x^{(i)} \in \mathbb{R}^{n_x}$  is the  $i^{th}$  example represented as a column vector

 $Y \in \mathbb{R}^{n_y \times m}$  is the label matrix

 $y^{(i)} \in \mathbb{R}^{n_y}$  is the output label for the  $i^{th}$  example

 $\cdot W^{[l]} \in \mathbb{R}$  number of units in next layer imes number of units in the previous layer weight matrix, superscript [l] indicates the layer

 $b^{[l]} \in \mathbb{R}^{\text{number of units in next layer}}$  is the bias vector in the  $l^{th}$  layer

 $\hat{y} \in \mathbb{R}^{n_y}$  is the predicted output vector. It can also be denoted  $a^{[L]}$  where L is the number of layers in the network.

### Common forward propagation equation examples:

 $a = g^{[l]}(W_x x^{(i)} + b_1) = g^{[l]}(z_1)$  where  $g^{[l]}$  denotes the  $l^{th}$  layer activation function

$$\hat{y}^{(i)} = softmax(W_h h + b_2)$$

• General Activation Formula:  $a_i^{[l]} = g^{[l]}(\sum_k w_{ik}^{[l]} a_k^{[l-1]} + b_i^{[l]}) = g^{[l]}(z_i^{[l]})$ 

· J(x, W, b, y) or  $J(\hat{y}, y)$  denote the cost function.

### Examples of cost function:

Cross-Entropy Loss (classification):

 $\cdot \ J_{CE}(\hat{y},y) = -\sum_{i=0}^m y^{(i)} \log \hat{y}^{(i)} \quad \ \ \text{-1. single class (0/1, sigmoid activation)} \\ \quad \ \ -2. \ \text{multi-class (one-hot encoding, softmax activation)}$ 

 $J_1(\hat{y}, y) = \sum_{i=0}^m |y^{(i)} - \hat{y}^{(i)}|$ 

Mean squared error (regression)

# Deep Learning representations

## For representations:

- · nodes represent inputs, activations or outputs
- · edges represent weights or biases

Here are several examples of Standard deep learning representations

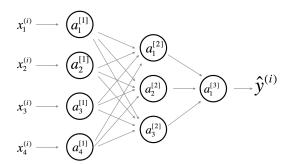
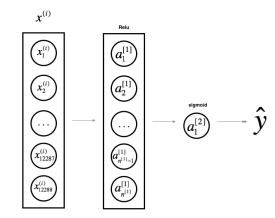


Figure 1: Comprehensive Network: representation commonly used for Neural Figure 2: Simplified Network: a simpler representation of a two layer neural Networks. For better aesthetic, we omitted the details on the parameters  $(w_{ij}^{[l]}$  and  $b_i^{[l]}$  etc...) that should appear on the edges



network, both are equivalent.