

Experiment description – INS with DMU10 Inertial Measurement Unit and GPS uBlox NEO-6P –

14th May 2016

20160514_INS_DMU10_Flight_01.mat (1538489 x 59) – three flights, without inertial data outages (original file C1.mat, GPS data RB1AA_F.pos, reference data 039782135A0_900.pos). uBlox RTK – FIX = 94,5%; FLOAT = 5,5%. Geodetic RTK – FIX = 90,2%; FLOAT = 9,8%.

20160514_INS_DMU10_Flight_02.mat (394629 x 59) – one flight, without inertial data outages (original file C4.mat, GPS data RB4AA_F.pos, reference data 039782135A2_850.pos). uBlox RTK – FIX = 58,4%; FLOAT = 41,6%. Geodetic RTK – FIX = 85,5%; FLOAT = 14,5%.

20160514_INS_DMU10_Flight_03.mat (384138 x 59) – two flights, without inertial data outages (original file C5.mat, GPS data RB5AA_F.pos, reference data 039782135A2_850.pos). uBlox RTK – FIX = 75,2%; FLOAT = 24,8%. Geodetic RTK – FIX = 85,5%; FLOAT = 14,5%. First part of flight – GPS data are delayed, because of FLOAT status.

20160514_INS_DMU10_Flight_04.mat (425167 x 59) – one flight, without inertial data outages (original file C6.mat, GPS data RB6AA_F.pos, reference data 039782135A2_850.pos). uBlox RTK – FIX = 88,9%; FLOAT = 11,1%. Geodetic RTK – FIX = 85,5%; FLOAT = 14,5%.

20160514_INS_DMU10_Flight_05.mat (204111 x 59) – one flight, without inertial data outages (original file C7.mat, GPS data RB7AA_F.pos, reference data 039782135A2_850.pos). uBlox RTK – FIX = 78,9%; FLOAT = 21,1%. Geodetic RTK – FIX = 85,5%; FLOAT = 14,5%.

sampling freq - IMU - 200 Hz

sampling freq - uBlox GPS - 5 Hz

sampling freq - Geodetical GNSS - 10 Hz – X91+ GNSS receiver (CHC)

Data structure:

Inertial data + temperature:

- 01 - counter
- 02 - time [ms] from start of the program
- 03 - DMU10 acceleration X – (g) – longitudinal
- 04 - DMU10 delta acceleration X – (g)
- 05 - DMU10 acceleration Y – (g) – lateral
- 06 - DMU10 delta acceleration Y – (g)
- 07 - DMU10 acceleration Z – (g) – vertical
- 08 - DMU10 delta acceleration Z – (g)
- 09,10 - Zeros
- 11 - DMU10 rate X – (°/s) - longitudinal
- 12 - DMU10 delta rate X – (°/s)
- 13 - DMU10 rate Y – (°/s) – lateral
- 14 - DMU10 delta rate Y – (°/s)
- 15 - DMU10 rate Z – (°/s) – vertical
- 16 - DMU10 delta rate Z – (°/s)

uBlox GPS data – absolute position, based only on receiver

- 17 - uBlox GPS time (s)
- 18 - uBlox GPS fix & valid (LSB = fix, MSB = valid)
- 19 - uBlox GPS number of satellites (-)
- 20 - uBlox GPS latitude (°)
- 21 - uBlox GPS longitude (°)
- 22 - uBlox GPS altitude (m)
- 23 - uBlox GPS speed over ground (m/s)
- 24 - uBlox GPS VDOP (-)
- 25 - uBlox GPS HDOP (-)



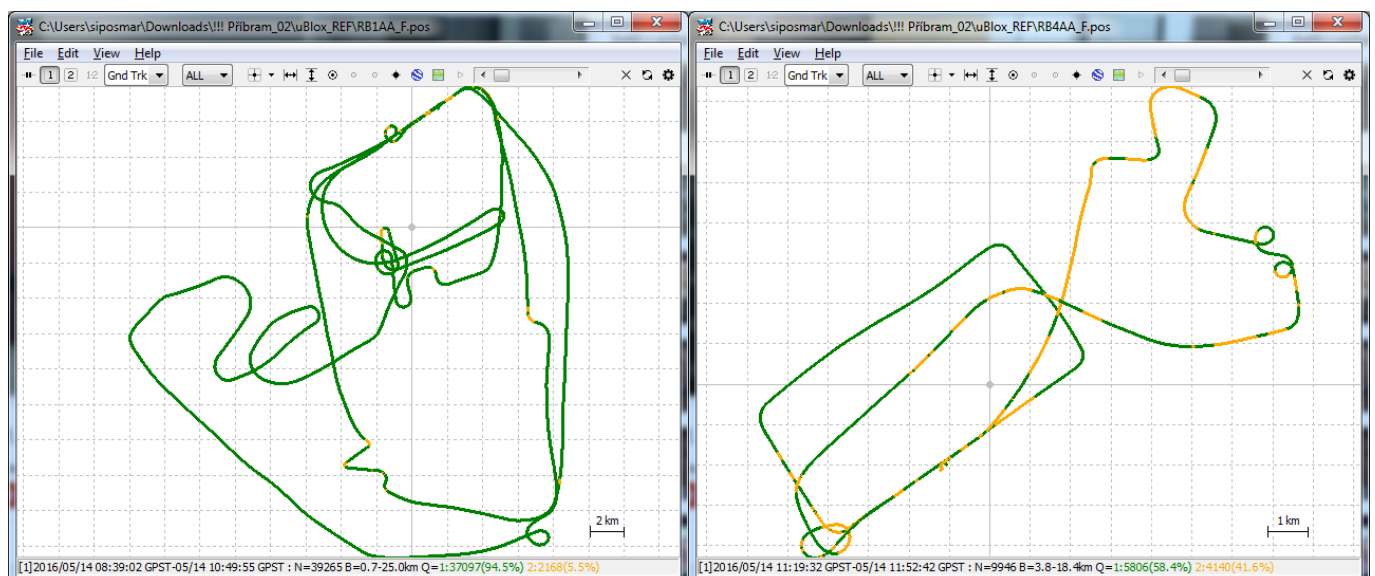
- 26 - uBlox GPS PDOP (-)
- 27 - uBlox GPS NED velocity down (m/s)
- 28 - uBlox GPS NED velocity north (m/s)
- 29 - uBlox GPS NED velocity east (m/s)
- 30 - uBlox GPS heading (°)
- 31 - uBlox GPS date (may be wrong by one day because of SD parser error) (-)

uBlox NEO-6P GPS receiver – (uBlox NEO-6P receiver 2 Base station Pribram)

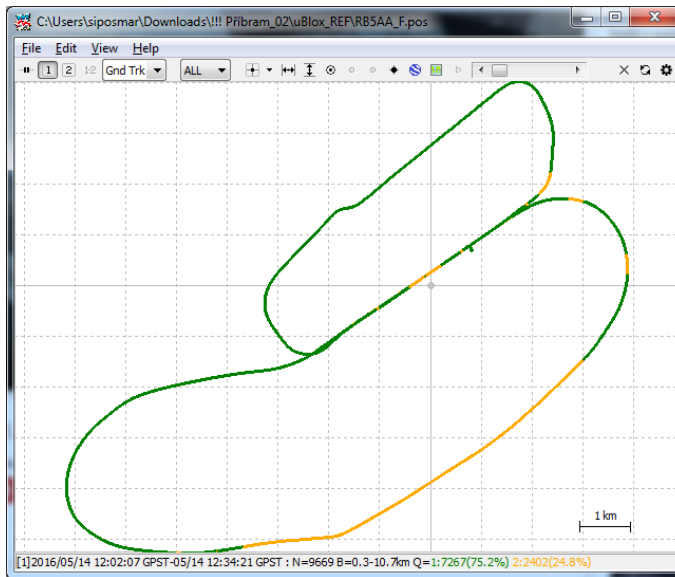
- 32 - uBlox RTK GPS time (s)
- 33 - uBlox RTK GPS latitude (°)
- 34 - uBlox RTK GPS longitude (°)
- 35 - uBlox RTK GPS altitude (m)
- 36 - uBlox RTK GPS fix & valid (5 = single, 2 = float, 1 = fix)
- 37 - uBlox RTK GPS number of satellites (-)
- 38 - uBlox RTK standard deviation - north (m)
- 39 - uBlox RTK standard deviation - east (m)
- 40 - uBlox RTK standard deviation - up (m)
- 41 - uBlox RTK standard deviation – north-east (m)
- 42 - uBlox RTK standard deviation – east-up (m)
- 43 - uBlox RTK standard deviation – up-north (m)
- 44 - uBlox RTK age (s)
- 45 - uBlox RTK ratio (-)

Geodetic X91+ GNSS receiver – Results based on RTKLIB (Geodetic receiver 2 Base station Pribram)

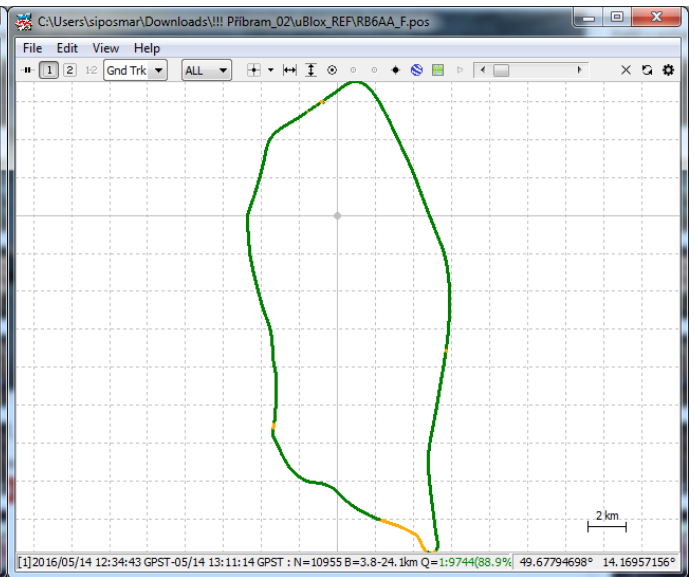
- 46 - Reference RTK GPS time (s)
- 47 - Reference RTK GPS latitude (°)
- 48 - Reference RTK GPS longitude (°)
- 49 - Reference RTK GPS altitude (m)
- 50 - Reference RTK GPS fix & valid (5 = single, 2 = float, 1 = fix)
- 51 - Reference RTK GPS number of satellites (-)
- 52 - Reference RTK standard deviation - north (m)
- 53 - Reference RTK standard deviation - east (m)
- 54 - Reference RTK standard deviation - up (m)
- 55 - Reference RTK standard deviation - north-east (m)
- 56 - Reference RTK standard deviation - east-up (m)
- 57 - Reference RTK standard deviation - up-north (m)
- 58 - Reference RTK age (s)
- 59 - Reference RTK ratio (-)



RTK – uBlox NEO-6P – Flight 1 – RB1AA_F.pos

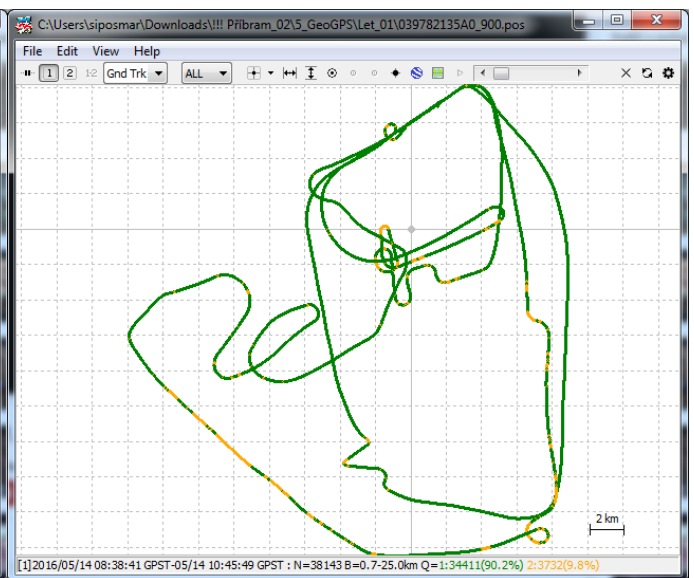
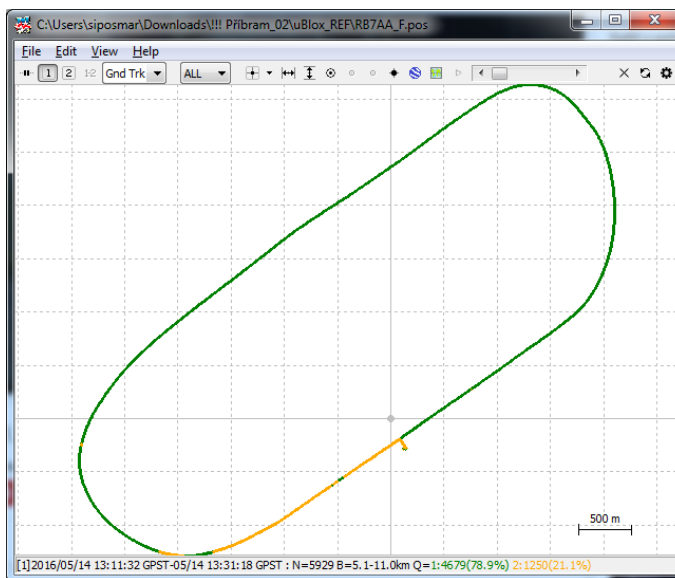


RTK – uBlox NEO-6P – Flight 2 – RB4AA_F.pos



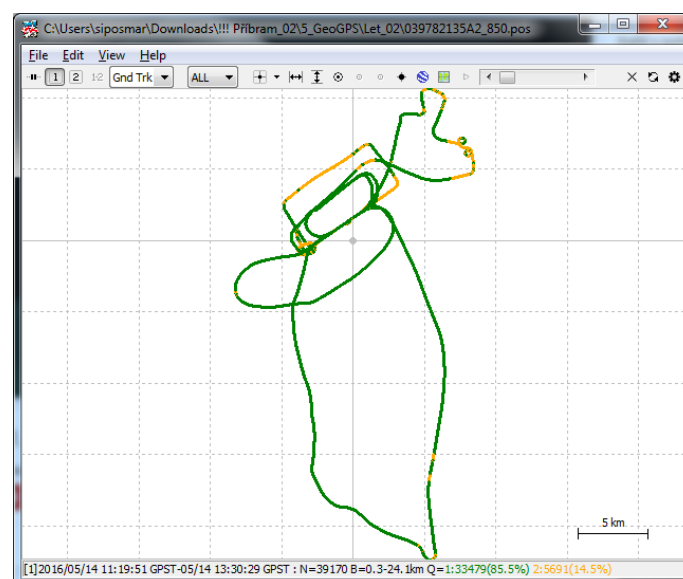
RTK – uBlox NEO-6P – Flight 3 – RB5AA_F.pos

RTK – uBlox NEO-6P – Flight 4 – RB6AA_F.pos



RTK – uBlox NEO-6P – Flight 5 – RB7AA_F.pos

RTK – Geodetic X91 – Flight 1 – 039782135A0_900.pos



RTK – Geodetic X91 – Flights 2-5 – 039782135A2_850.pos