



Software Defined Networking

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In this course, you will learn about software defined networking and how it is changing the way communications networks are managed, maintained, and secured.

Lesson Overview

- Overview of different SDN Controllers
- Basic understanding of each controller
 - Concepts
 - Architecture
 - Programming Model
- Pros and cons of each controller
- Ideal situations for each controller

Many Different SDN Controllers

- ◎ NOX/POX
- ◎ Ryu
- ◎ Floodlight
- ◎ OpenDaylight
- ◎ Pyretic
- ◎ Frenetic
- ◎ Procera
- ◎ RouteFlow
- ◎ Trema

Project
Floodlight



Trema

Full-Stack OpenFlow



Many Considerations

- ⦿ Programming Language (can affect performance)
- ⦿ Learning curve
- ⦿ User base and community support
- ⦿ Focus
 - Southbound API
 - Northbound API / “Policy Layer”
 - Support for OpenStack
 - Education, Research, or Production?

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NOX: Overview

- ⊙ First-generation OpenFlow controller
 - Open source, stable, widely used
- ⊙ Two “flavors” of NOX
 - **NOX-Classic:** C++/Python. No longer supported.
 - **NOX (the “new NOX”)**
 - C++ only
 - Fast, clean codebase
 - Well maintained and supported

NOX: Characteristics

- ◎ Users implement control in C++
- ◎ Supports OpenFlow v.1.0
 - A fork (CPqD) supports 1.1, 1.2, and 1.3
- ◎ Programming model
 - Controller registers for events
 - Programmer writes event handler

When to Use NOX

- ⦿ You know C++
- ⦿ You are willing to use low-level facilities and semantics of OpenFlow
- ⦿ You need good performance

POX: Overview

- ◎ NOX in Python
 - Supports OpenFlow v. 1.0 only
- ◎ **Advantages**
 - Widely used, maintained, supported
 - Relatively easy to read and write code
- ◎ **Disadvantages:** Performance

When to Use POX

- ⦿ If you know (or can learn) Python and are not concerned about controller performance
- ⦿ Rapid prototyping and experimentation
 - Research, experimentation, demonstrations
 - Learning concepts

Ryu

- ◎ Open source Python controller
 - Supports OpenFlow 1.0, 1.2, 1.3, 1.4, Nicira extensions
 - Works with OpenStack
- ◎ Aims to be an “Operating System” for SDN
- ◎ **Advantages**
 - OpenStack integration, OpenFlow 1.2, 1.3, 1.4
- ◎ **Disadvantages:** Performance

Floodlight

- ◎ Open-source Java controller
 - Supports OpenFlow v. 1.0
 - Fork from the Beacon Java OpenFlow controller
 - Maintained by Big Switch Networks
- ◎ **Advantages**
 - Good documentation
 - Integration with REST API
 - Production-level, OpenStack/Multi-Tenant Clouds
- ◎ **Disadvantages:** Steep learning curve

Evolving Existing Controllers: LoxiGen

- ⦿ Generates OF language-specific bindings
 - Input: Wire-protocol descriptions
 - Output: Protocol-specific bindings
 - <http://github.com/floodlight/loxigen>
- ⦿ Generates OpenFlow v1.0-v1.3.1+ bindings
 - C: for Indigo
 - Java: for Floodlight
 - Python: for OFTest
 - Wireshark/Lua

When to Use Floodlight

- ⦿ You know Java
- ⦿ You need production-level performance and support
- ⦿ You will use the REST API to interact with the controller

OpenDaylight

- ◎ **Goal:** Common industry supported platform
 - Robust, extensible open source codebase
 - Common abstractions for northbound capabilities
- ◎ **Advantages:** Industry acceptance, integration with OpenStack, cloud applications, etc.
- ◎ **Disadvantages:** Complex, steep learning curve

Also: HP VAN

When to Use OpenDaylight

- ⦿ You know Java
- ⦿ You need production-level performance and support
- ⦿ You need support with cloud applications, OpenStack, etc.
- ⦿ You need modular functions
- ⦿ You need apps already supported by vendors

Summary

	NOX	POX	Ryu	Floodlight	ODL
Language	C++	Python	Python	Java	Java
Performance	Fast	Slow	Slow	Fast	Fast
Distributed	No	No	Yes	Yes	Yes
OpenFlow	1.0 (CPqD: 1.1, 1.2, 1.3)	1.0	1.0, 1.1, 1.3, 1.4	1.0	1.0, 1.3
Multi-tenant Clouds	No	No	Yes	Yes	Yes
Learning Curve	Moderate	Easy	Moderate	Steep	Steep

- Choice of controller depends on needs, language, etc.
- So far:** Southbound API implementations
Later: “Northbound” APIs