Models in genomics and biodiversity analysis

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Common mathematical tools in biology

Parameterization

Stochasticity

Discrete: Markov Chain

Continuous: Diffusion Process

Complexity:

Confounding factors: Regression

Estimation

- Maximum likelihood
- Bayesian Inference

Markov Chain: A chain of events with Markov property

Random variable X_n

A substitution event can leads to a state of {A,T,C,G}

The probability of the nth substitution event that leads to A: $P(X_n = A)$

$$X_n = [P(X_n = A), P(X_n = T), P(X_n = C), P(X_n = G)]$$

Markov Chain

A sequence of random variables with Markov Property:

$$P(X_{n+1} = A | X_n = T, X_{n-1} = C, ...) = P(X_{n+1} = A | X_n = T)$$

Discrete Time Markov Chain

A sequence of random variables with Markov Property:

$$P(X_{n+1} = A | X_n = T, X_{n-1} = C, ...) = P(X_{n+1} = A | X_n = T)$$

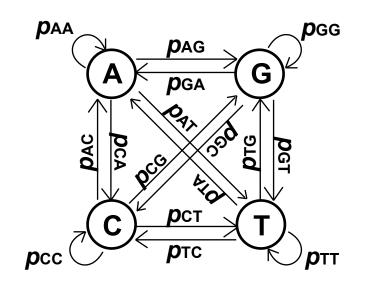
Discrete Time Markov Chain

A sequence of random variables with Markov Property:

$$P(X_{n+1} = A | X_n = T, X_{n-1} = C, ...) = P(X_{n+1} = A | X_n = T)$$

Transition matrix:

$$P = \begin{bmatrix} p_{AA} & p_{AT} & p_{AC} & p_{AG} \\ p_{TA} & p_{TT} & p_{TC} & p_{AG} \\ p_{CA} & p_{CT} & p_{CC} & p_{CG} \\ p_{GA} & p_{GT} & p_{GC} & p_{GG} \end{bmatrix} \quad p_{CC}$$



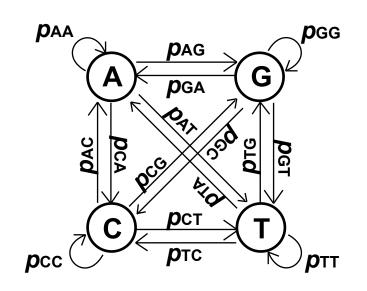
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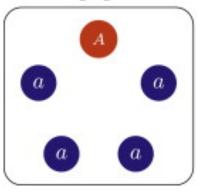


$$X_n = [P(X_{n-1} = A), P(X_{n-1} = T), P(X_{n-1} = C), P(X_{n-1} = G)]P$$

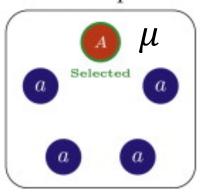
= $X_{n-1}P = X_{n-2}P^2 = \dots = X_0P^n$

DTMC – Moran Model

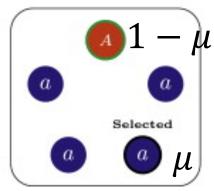
Initial population



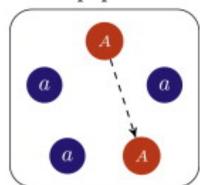
Select for replication



Select for dead



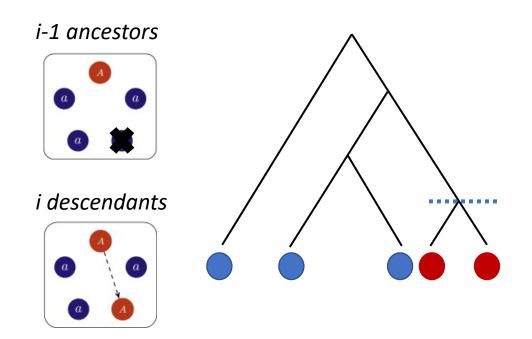
Replace & final population



For red individual, states = $\{1,2,...N\}$, $\mu=1/N$

$$P(X_{n+1} = j | X_n = i) = \begin{cases} \mu (1 - \mu) & \text{if } j = i + 1\\ (1 - \mu)\mu & \text{if } j = i - 1\\ \mu^2 + (1 - \mu)^2 & \text{if } j = i\\ 0 & \text{otherwise} \end{cases}$$

From Moran model to Coalescence



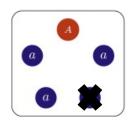
Parent A does not die

$$P(i \text{ lineages from } i-1 \text{ ancestors}) = \left(1 - \frac{1}{N}\right) \left(\frac{i}{N} \frac{i-1}{N-1}\right) = {i \choose 2} \frac{2}{N^2}$$

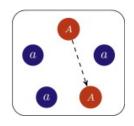
Both parent and offspring \triangle are in the *i* lineages

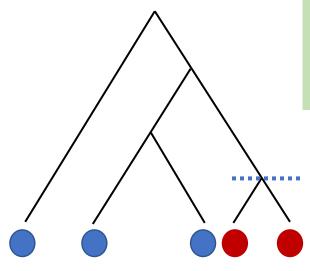
From Moran model to Coalescence





i descendants





If
$$t = \frac{2}{N^2}$$

as $N \to \infty$, $t \to 0$, $P \to {i \choose 2}$

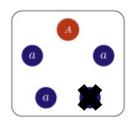
Parent (A) does not die

$$P(i \text{ lineages from } i-1 \text{ ancestors}) = \left(1 - \frac{1}{N}\right) \left(\frac{i}{N} \frac{i-1}{N-1}\right) = {i \choose 2} \frac{2}{N^2}$$

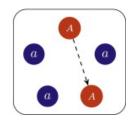
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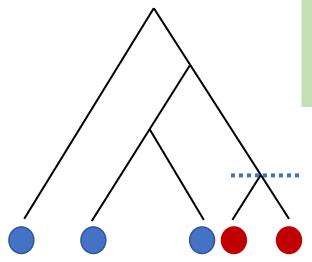
From Moran model to Coalescence





i descendants





If
$$t = \frac{2}{N^2}$$

as $N \to \infty$, $t \to 0$, $P \to {i \choose 2}$

$$f(T=t) = {i \choose 2} e^{-{i \choose 2}t}$$

$$p(\text{no coel in } t) = e^{-\binom{i}{2}t}$$

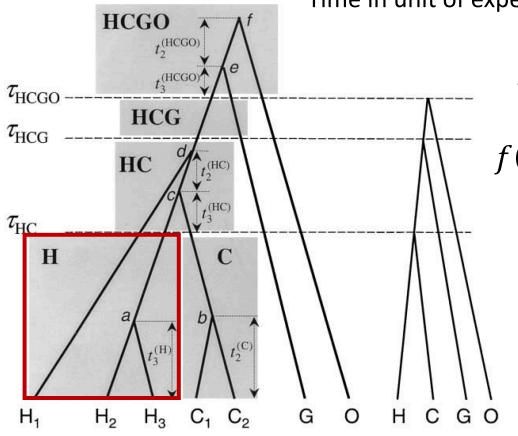
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Both parent and offspring \triangle are in the *i* lineages

Multi-Species Coalescence

Time in unit of expected number of mutations per site



Rannala and Yang 2003 Genetics

$$f(T=t) = {i \choose 2} \frac{2}{\theta} e^{-{i \choose 2} \frac{2}{\theta} t}$$

$$f(H) = {3 \choose 2}^{-1}$$

A coal event happens

$$\times {3 \choose 2} \frac{2}{\theta_H} e^{-{3 \choose 2} \frac{2}{\theta_H} t_3^{(H)}}$$

And the event happens at $t_3^{(H)}$

$$\times e^{-\binom{2}{1}\frac{2}{\theta_H}(\tau_{HC}-t_3^{(H)})}$$

And no coal event between au_{HC} and $t_3^{(H)}$

$$P(X_{n+1} = A | X_n = T) = p_{TA}$$

$$P(X_{t+dt} = A | X_t = T) = q_{TA}, dt \rightarrow 0$$

$$P(X_{n+1} = A | X_n = T) = p_{TA}$$

$$P(X_{t+dt} = A | X_t = T) = q_{TA}, dt \rightarrow 0 \longrightarrow Q$$

Transition rate matrix

$$P(X_{t+\Delta t} = A | X_t = T) = p_{TA}(t; t + \Delta t) \rightarrow P$$

$$P(X_{n+1} = A | X_n = T) = p_{TA}$$

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Transition rate matrix

$$P(X_{t+\Delta t} = A | X_t = T) = p_{TA}(t; t + \Delta t) \rightarrow P$$

Forward equation:

$$p'_{TA}(t; t + \Delta t) = \sum_{i \in \{A, T, C, G\}} p_{Ti}(t; t + \Delta t) q_{iA}$$

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$$P(X_{t+dt} = A | X_t = T) = q_{TA}, dt \rightarrow 0 \longrightarrow Q$$

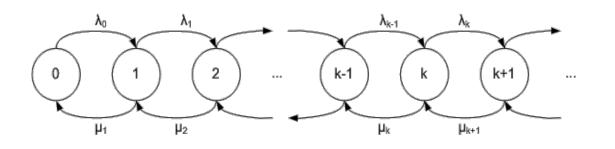
Transition rate matrix

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Forward equation:

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$$P'(t) = P(t)Q, P(0) = I \longrightarrow P(\Delta t) = e^{Q\Delta t}$$

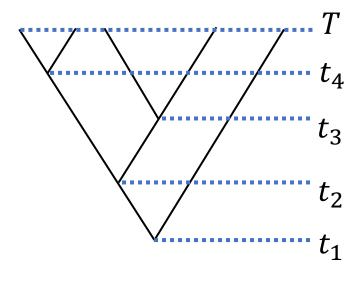


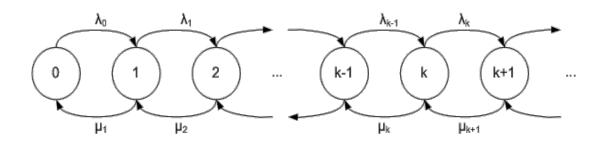
States =
$$\{0,1,2,...,N\}$$

$$q_{k,k+1} = \lambda$$

$$q_{k,k-1} = \mu$$

$$p'_{kk}(0;t) = p_{k,k-1}\lambda + p_{k,k+1}\mu + p_{k,k}(-\lambda - \mu)$$



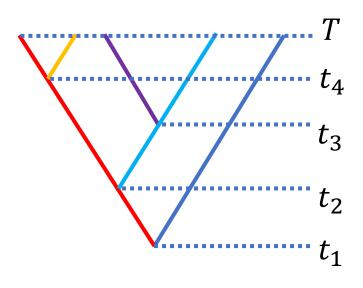


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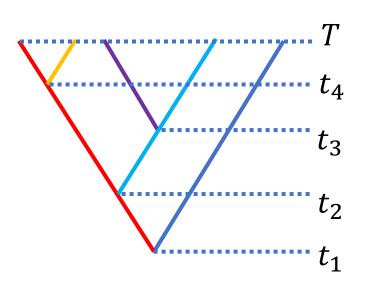
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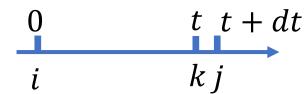
$$f(t_{1,...}t_{4}) = \prod_{i=1}^{5} i \times \lambda(t_{i}) \times p_{11}(T; T - t_{i})$$

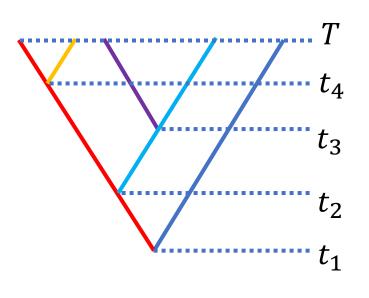


...
$$T$$
 $f(t_{1,...}t_4) = \prod_{i=1}^{5} i \times \lambda(t_i) \times p_{11}(T; T - t_i)$

Forward equation:

$$p'_{ij}(0;t) = \sum p_{ik}(0;t)q_{kj}$$



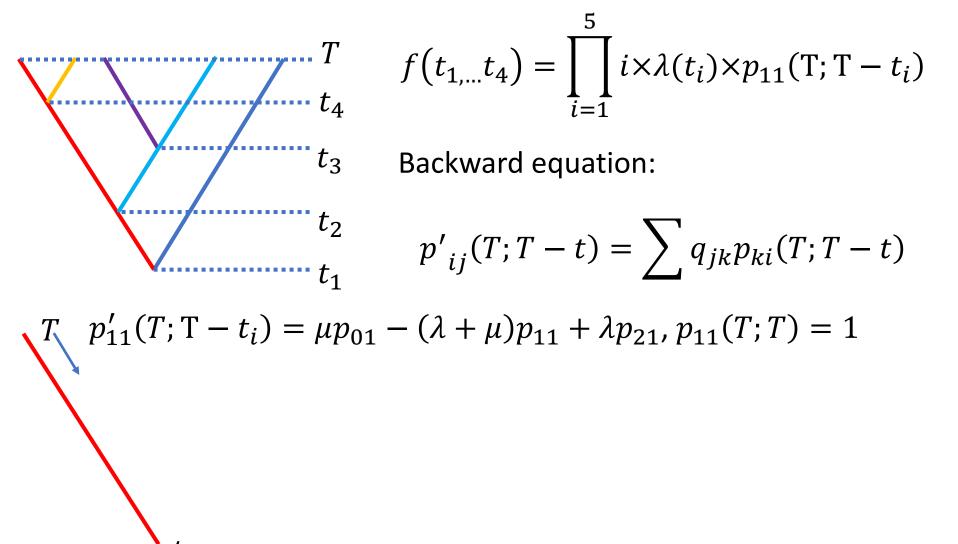


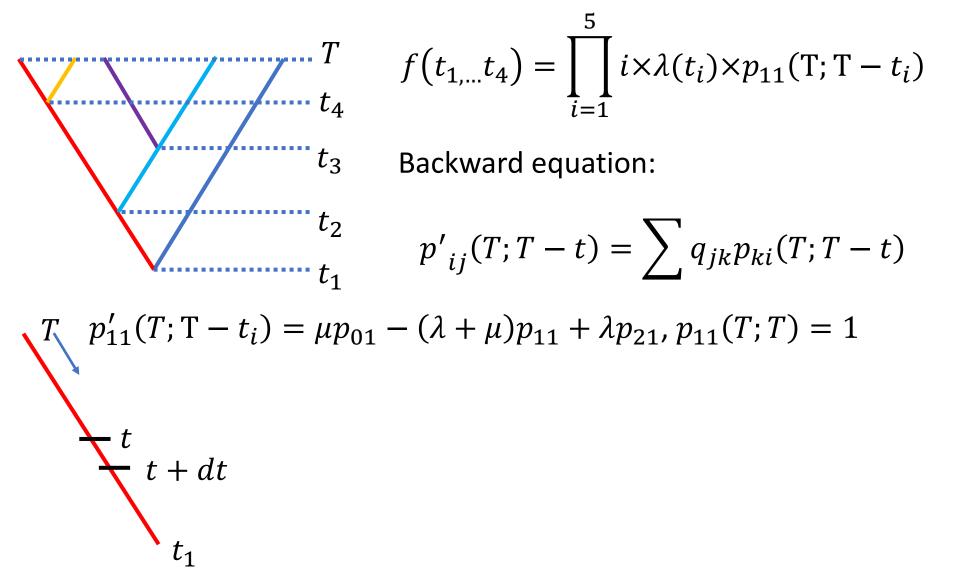
$$T f(t_{1,...}t_4) = \prod_{i=1}^{5} i \times \lambda(t_i) \times p_{11}(T; T - t_i)$$

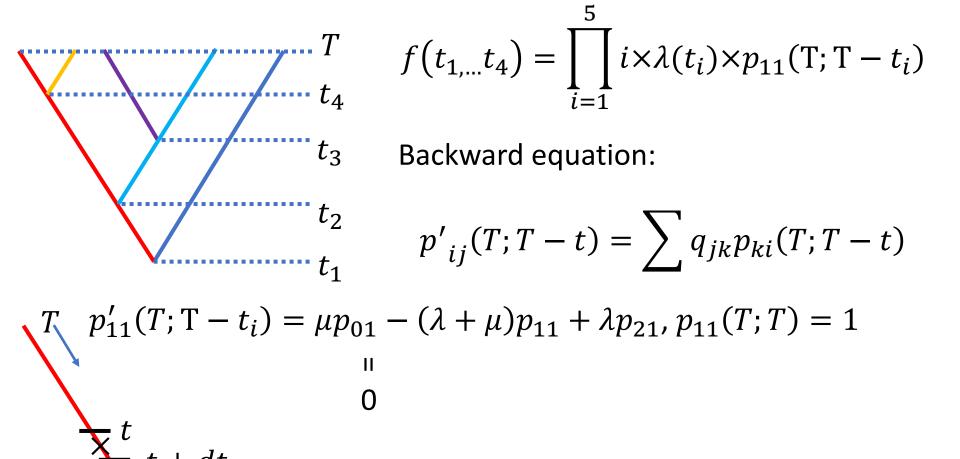
Backward equation:

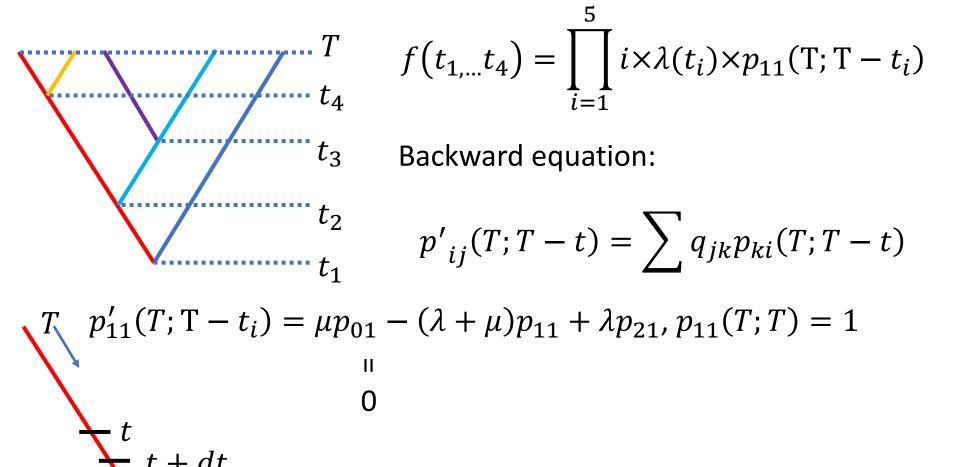
$$p'_{ij}(T;T-t) = \sum q_{jk} p_{ki}(T;T-t)$$

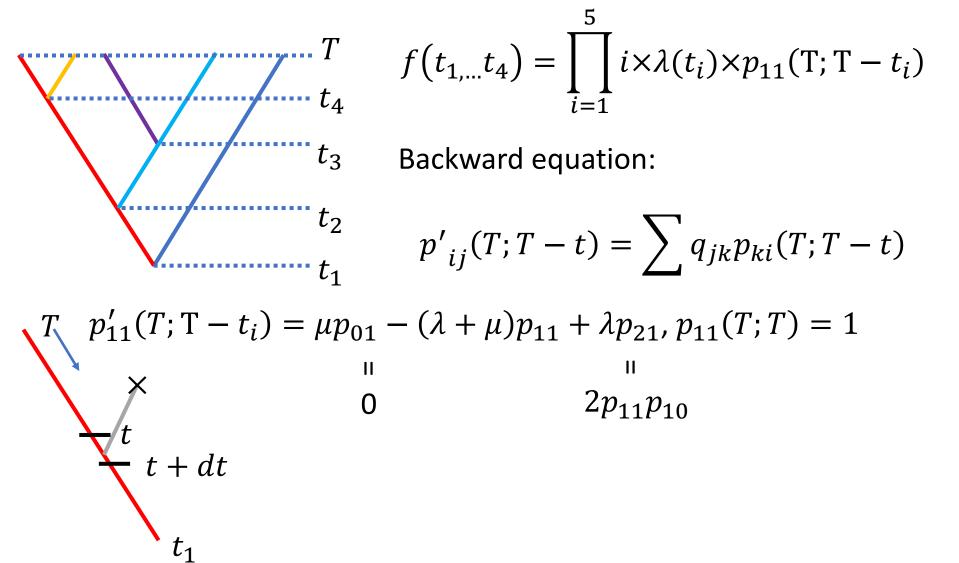
$$T-t$$
 $T-dtT$
 j ki

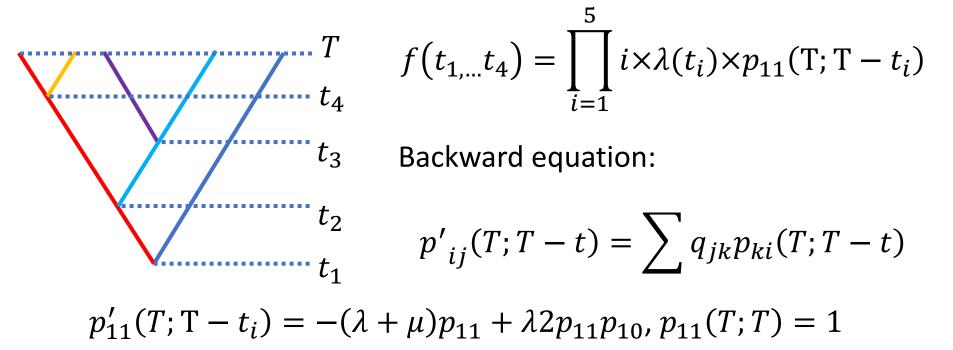


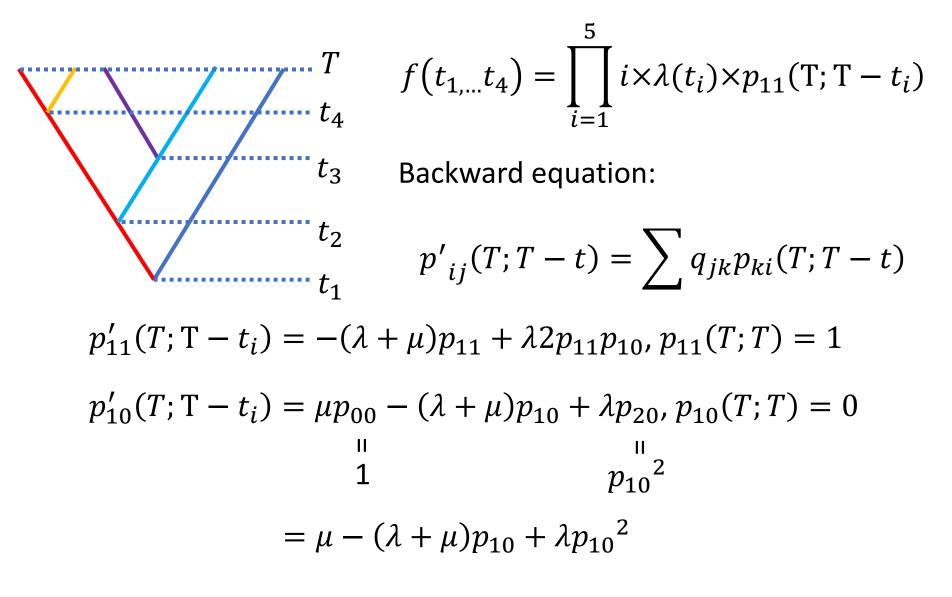












Diffusion Process

$$P(X_{t+dt} = A | X_t = T) = q_{TA}, dt \rightarrow 0$$

$$P(X_{t+dt} = x + dx | X_t = x) = q_x, dt \to 0, dx \to 0$$

Diffusion Process

$$P(X_{t+dt} = A | X_t = T) = q_{TA}, dt \rightarrow 0$$

$$P(X_{t+dt} = x + dx | X_t = x) = q_x, dt \to 0, dx \to 0$$

$$P(X_{t+\Delta t} = x + \Delta x | X_t = x) = p(x, t)$$

Diffusion Process

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$$P(X_{t+\Delta t} = x + \Delta x | X_t = x) = p(x, t)$$

Forward equation: $\frac{d}{dt}P = P(t)Q$

$$\frac{\partial}{\partial t}p(x,t) = -\frac{\partial}{\partial x} \left[\mu(x,t)p(x,t)\right] + \frac{\partial^2}{\partial x^2} \left[\frac{1}{2}D(x,t)p(x,t)\right]$$

Change in mean of x in dt Change in variance of x in dt

Diffusion Process – Trait evolution

	$\mu(x,t)$	D(x,t)
Brownian Motion	0	σ^2
BM with trend	b	σ^2
Ac/Decelerating	0	$\sigma^2 e^{rt}$
Ornstein-Uhlenbeck	$b(\mu-x)$	σ^2
Peak shift	$b(\mu_t - x)$	σ^2

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Continuous: Diffusion Process

Complexity:

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Estimation

- Maximum likelihood
- Bayesian Inference

Regression Models

$$Y_i = f(X_i, \beta) + e_i$$

General Linear Model

$$Y_i = X_i \beta + e_i, e_i \sim N(0, \Omega)$$

Autoregressive Model

$$Y_t = X_t \beta + \sum_{j=1}^p Y_{t-j} + e_t, e_t \sim N(0, \sigma^2)$$

Linear Mixed Model

$$Y_i = X_i \beta + Zu + e_i u \sim N(0, \Omega), e_i \sim N(0, \sigma^2)$$

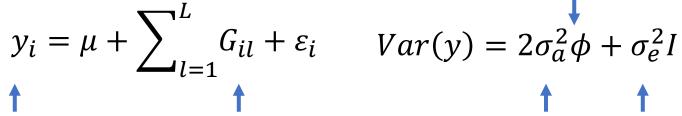
Generalized Linear Model

$$g(Y_i) = X_i\beta + e_i, e_i \sim N(0, \Omega)$$

Genome-Wide Association Studies

Fisher's polygenic model:

Kinship Coefficient Matrix



Phenotype of Genotype of individual i locus l of individual i

Additive Environmental genetic variance variance

Linear mixed model:

Accounting for genetic relatedness

Population admixture:
$$E(G_{i,j}) = 2\sum_{k=1}^{K} \phi_{i,k} P_{k,j}$$

Most restricted: $\sum_{k=1}^{K} \phi_{i,k} = 1$, $\phi_{i,k} \ge 0$

Admixture proportion

Principle component analysis: $E(G_{i,j}) = (\phi F)_{ij}$

$$E(G_{i,j}) = (\phi F)_{i,j}$$

No restriction

loadings factors

Accounting for genetic relatedness

Population admixture:
$$E(G_{i,j}) = 2 \sum_{k=1}^{K} \phi_{i,k} P_{k,j}$$

Most restricted: $\sum_{k=1}^{K} \phi_{i,k} = 1$, $\phi_{i,k} \ge 0$

Admixture proportion

Sparse factor analysis:

$$E(G_{i,j}) = (\phi F)_{ij}$$

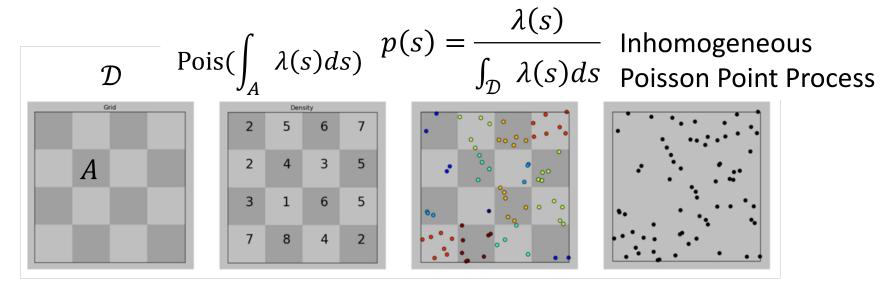
Encouraging sparsity in ϕ by giving prior $\phi_{i,k} \sim N(0, \sigma_{i,k}^2)$

Principle component analysis:

No restriction

$$E(G_{i,j}) = (\phi F)_{ij}$$
loadings factors

Species distribution modeling



$$\ln \lambda(s) = \alpha + X(s)\beta$$

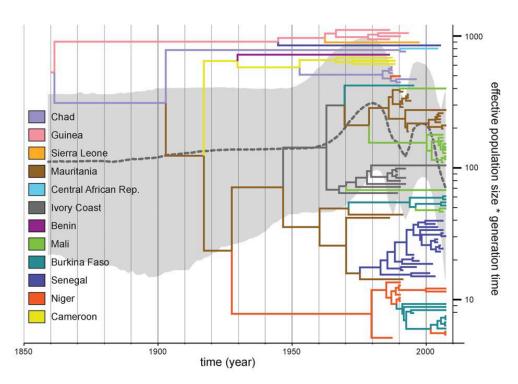
Presence-absence in quadrat $A: N_A \approx \text{Pois}(\lambda(s)A)$

Absence: $P(N_A = 0) = e^{-Ae^{\alpha + X(s)\beta}}$

Presence: $P(N_A > 0) = 1 - e^{-Ae^{\alpha + X(s)\beta}} \approx Ae^{\alpha + X(s)\beta}$

Presence-only at s: $\ln p(S) = \alpha + X(s)\beta - \sum_{i \in BG} \frac{\mathcal{D}}{n_{BG}} e^{\alpha + X(i)\beta}$

Pathogen Phylodynamics



Lemey et al. 2009 PLoS Computational Biology

States: {Chad, Guinea,...}

$$P(T) = e^{Qt}$$

$$\log Q_{ij} = \sum_{k} \delta_k \beta_k X_{ijk}$$

 X_{ijk} : value of predictor k between location i and j

 β_k : effective size of predictor k

 δ_k : (0,1)-indicator of the inclusion of predictor k

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Likelihood: P(Data|Parameter)

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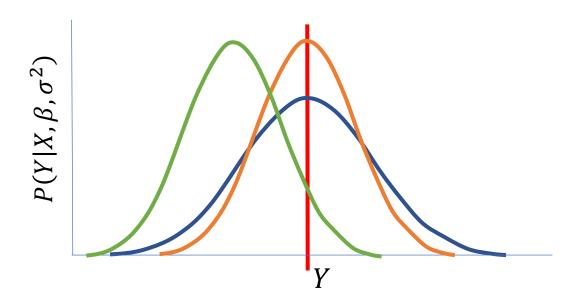
E.g.,
$$Y_i = X_i \beta + e_i, e_i \sim N(0, \sigma^2)$$

$$P(Y|X,\beta,\sigma^2) = N(X\beta,\sigma^2)$$

Likelihood: P(Data|Parameter)

E.g.,
$$Y_i = X_i \beta + e_i, e_i \sim N(0, \sigma^2)$$

$$P(Y|X,\beta,\sigma^2) = N(X\beta,\sigma^2)$$



$$L = \prod_{i=1}^{n} (2\pi\sigma^{2})^{-\frac{1}{2}} e^{-\frac{(Y_{i} - X_{i}\beta)^{2}}{2\sigma^{2}}}$$
$$-lnL = \sum_{i=1}^{n} \frac{1}{2} ln(2\pi\sigma^{2}) + \frac{(Y_{i} - X_{i}\beta)^{2}}{2\sigma^{2}}$$

```
f <- function (p, X, Y) {
    beta <- p[1]
    sigma <- exp(p[2])
    n <- length(Y)
    nll <- n/2*log(2*pi*sigma) + sum((Y-X*beta)^2)/2/sigma
    nll
}
mle <- optim(x0=c(0,0),fun=f)</pre>
```

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

$$P(\text{Parameter}|\text{Data}) = \frac{P(\text{Data}|\text{Parameter})P(\text{Parameter})}{P(\text{data})}$$

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Posterior Probability

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

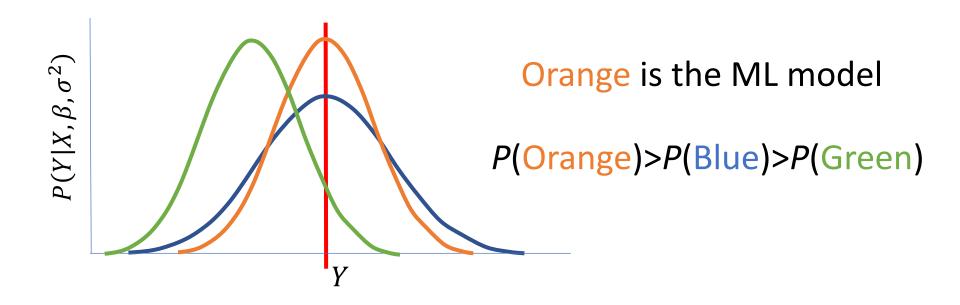
 $P(\text{Parameter}|\text{Data}) = \frac{P(\text{Data}|\text{Parameter})P(\text{Parameter})}{P(\text{data})}$

Posterior Probability

 $\propto P(\text{Data}|\text{Parameter})P(\text{Parameter})$

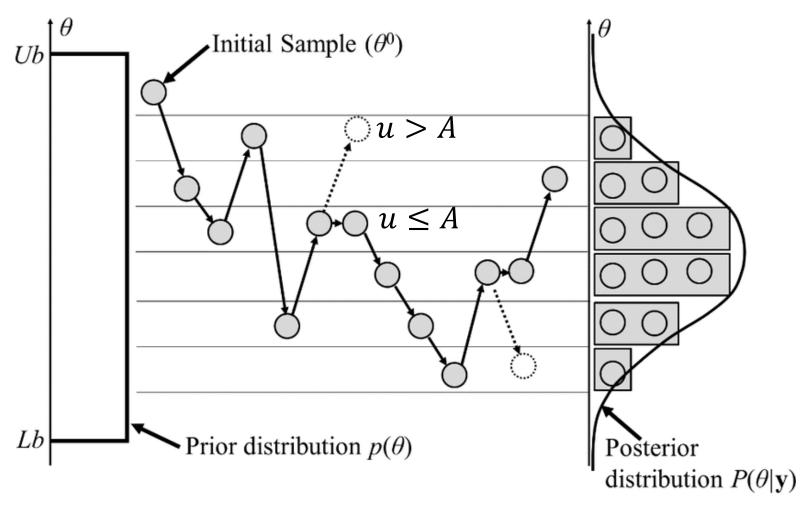
Likelihood: $P(Y|X,\beta,\sigma^2) = N(X\beta,\sigma^2)$

Posterior: $P(\beta, \sigma^2 | Y, X) \propto N(X\beta, \sigma^2) P(\beta, \sigma^2)$



MCMC: Metropolis-Hastings algorithm

$$R = \min\left(1, \frac{L(x') P(x')}{L(x)P(x)} \frac{g(x|x')}{g(x'|x)}\right)$$

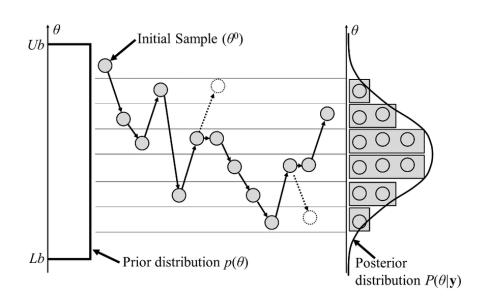


Metropolis—Hastings algorithm

$$L = \prod_{i=1}^{n} (2\pi\sigma^2)^{-\frac{1}{2}} e^{-\frac{(Y_i - X_i\beta)^2}{2\sigma^2}}, \quad \beta \sim N(0,10), \quad \sigma^2 \sim Gamma(0.1,0.1)$$

Initialization:

```
pr <- function (beta,sigma) {</pre>
     dnorm(beta, 0, sqrt(10), log=T)+dgamma(sigma, 0.1, 0.1, log=T)
beta <- rnorm(1, 0, sqrt(10))
sigma <- rgamma(1, 0.1, 0.1)
Il <- -f(c(beta,sigma),X,Y)</pre>
lp <- pr(beta,sigma)</pre>
beta up <- 1
sigma up <- 1
```



Metropolis-Hastings algorithm

```
Start MCMC:
                                           updating sigma:
    updating beta:
                                               u <- runif(1, 0, 1)
niter <- 5000
                                               sigma new <- sigma*
for (i in 1:niter) {
                                                             exp(sigma up*(u-0.5))
    beta new <- beta+
                                               Il new <- -f(c(beta,sigma_new),X,Y)</pre>
             runif(1,-beta up,beta up)
    Il_new <- -f(c(beta_new,sigma),X,Y)</pre>
                                               lp new <- pr(beta,sigma new)</pre>
                                               R \leftarrow II_new + Ip_new - II - Ip
    lp_new <- pr(beta_new,sigma)</pre>
                                               R <- R*exp(sigma_up*(u-0.5))
    R \leftarrow II \text{ new} + Ip \text{ new} - II - Ip
                                               if (R > runif(1,0,1)) {
    if (R > runif(1,0,1)) {
                                                    sigma <- sigma new
         beta <- beta new
         II <- II new
                                                    ll <- ll new
                                                    lp <- lp_new</pre>
         lp <- lp new
```