

1st Homework

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Exercise 1.

(i) $y = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_1 x_2 + x_1^2$

- a. There are 4 parameters $(\theta_0, \theta_1, \theta_2, \theta_3)$
- b. The dependence is Linear.

(ii) $y = \text{sign}(\theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_1 x_2 + \theta_4 x_1^2)$

- a. There are 5 parameters $(\theta_0, \theta_1, \theta_2, \theta_3, \theta_4)$
- b. The dependence is non-Linear.

(iii) $y = 2x_1 + \text{sign}(3 - 7)x_2 + \text{ReLU}(3)x_1 x_2$

- a. There are no parameters, since we only have constants.
- b. The dependence is Non-Linear.

(iv) $y = \theta + \theta x_1 + \theta x_2 + \theta x_1 x_2$

- a. The parameter involved is one: θ
- b. The dependence is linear.

Exercise 2.

1. $y = \theta_0 + \theta_1 x_1 + \theta_2 x_2$

The model is parametric.

2. $y = \min(x_1, x_2)$

The model is non-parametric, since there are no parameters

3. $y = \text{ReLU}(\theta_0 + \theta_1 x_1)$

The model is parametric.

4. $y = \sum_{i=1}^N \theta_i (x_{i1} x_1 - x_{i2} x_2)$

The model is non-parametric since the output depends on the size of \mathbf{x}

Exercise 3.

a) Define the parametric set of the **quadratic** functions $f_\theta : R \rightarrow R$ give two instances of it. What is the dimensionality of θ ?

For a given $\mathbf{x} = [x_1, x_2]^T$ it is:

$$f_\theta(\mathbf{x}) = \theta_0 + \theta_1 x_1 + \theta_2 x_1^2, \quad \theta = [\theta_0, \theta_1, \theta_2]^T$$

and

$$F_{lin} := f_\theta(\cdot) : \theta \in R^3$$

i) If we choose e.g., $\theta = [1, 2, 3]^T$ have the following instance of F_{lin}

$$f_\theta(\mathbf{x}) = 1 + 2x_1 + 3x_1^2$$

ii) If we choose e.g., $\theta = [42, 42, 42]^T$ have the following instance of F_{lin}

$$f_\theta(\mathbf{x}) = 42 + 42x_1 + 42x_1^2$$

b) Define the parametric set of the **3rd degree polynomials** $f_\theta : R^2 \rightarrow R$ give two instances of it. What is the dimensionality of θ ?

For a given $\mathbf{x} = [x_1]^T$ it is:

$$f_\theta(\mathbf{x}) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_1^2 + \theta_4 x_2^2 + \theta_5 x_1 x_2 + \theta_6 x_1^2 x_2 + \theta_7 x_1 x_2^2 + \theta_8 x_1^3 + \theta_9 x_2^3$$

thus,

$$\theta = [\theta_0, \theta_1, \theta_2, \theta_3, \theta_4, \theta_5, \theta_6, \theta_7, \theta_8, \theta_9]^T$$

and

$$F_{lin} := f_\theta(\cdot) : \theta \in R^{10}$$

i) If we choose e.g., $\theta = [10, 1, 2, 3, 4, 5, 6, 7, 8, 9]^T$ have the following instance of F_{lin}

$$f_\theta(\mathbf{x}) = 10 + x_1 + 2x_2 + 3x_1^2 + 4x_2^2 + 5x_1 x_2 + 6x_1^2 x_2 + 7x_1 x_2^2 + 8x_1^3 + 9x_2^3$$

ii) If we choose e.g., $\boldsymbol{\theta} = [42, 42, 42, 42, 42, 42, 42, 42, 42, 42]^T$ have the following instance of F_{lin}

$$f_{\boldsymbol{\theta}}(\mathbf{x}) = 42 + 42x_1 + 42x_2 + 42x_1^2 + 42x_2^2 + 42x_1x_2 + 42x_1^2x_2 + 42x_1x_2^2 + 42x_1^3 + 42x_2^3$$

c) Define the parametric set of the **3rd degree polynomials** $f_{\boldsymbol{\theta}} : R^3 \rightarrow R$ give two instances of it. What is the dimensionality of $\boldsymbol{\theta}$?

For a given $\mathbf{x} = [x_1, x_2, x_3]^T$ it is:

$$\begin{aligned} f_{\boldsymbol{\theta}}(\mathbf{x}) = & \theta_0 + \theta_1x_1 + \theta_2x_2 + \theta_3x_1^2 + \theta_4x_2^2 + \\ & \theta_5x_1x_2 + \theta_6x_1^2x_2 + \theta_7x_1x_2^2 + \theta_8x_1^3 + \theta_9x_2^3 + \\ & \theta_{10}x_3 + \theta_{11}x_3^2 + \theta_{12}x_3^3 + \theta_{13}x_1x_3 + \theta_{14}x_1x_3^2 + \\ & \theta_{15}x_1^2x_3 + \theta_{16}x_2x_3 + \theta_{17}x_2x_3^2 + \theta_{18}x_2^2x_3 + \theta_{19}x_1x_2x_3 \end{aligned}$$

thus,

$$\boldsymbol{\theta} = [\theta_0, \theta_1, \theta_2, \theta_3, \theta_4, \theta_5, \theta_6, \theta_7, \theta_8, \theta_9, \theta_{10}, \theta_{11}, \theta_{12}, \theta_{13}, \theta_{14}, \theta_{15}, \theta_{16}, \theta_{17}, \theta_{18}, \theta_{19}]^T$$

and

$$F_{lin} := f_{\boldsymbol{\theta}}(\cdot) : \boldsymbol{\theta} \in R^{20}$$

i) If we choose e.g., $\boldsymbol{\theta} = [10, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15, 16, 17, 18, 19]^T$ have the following instance of F_{lin}

$$\begin{aligned} f_{\boldsymbol{\theta}}(\mathbf{x}) = & 10 + 1x_1 + 2x_2 + 3x_1^2 + 4x_2^2 + \\ & 5x_1x_2 + 6x_1^2x_2 + 7x_1x_2^2 + 8x_1^3 + 9x_2^3 + \\ & 10x_3 + 11x_3^2 + 12x_3^3 + 13x_1x_3 + 14x_1x_3^2 + \\ & 15x_1^2x_3 + 16x_2x_3 + 17x_2x_3^2 + 18x_2^2x_3 + 19x_1x_2x_3 \end{aligned}$$

ii) If we choose e.g., $\boldsymbol{\theta} = [42, 42, 42, 42, 42, 42, 42, 42, 42, 42, 42, 42, 42, 42, 42, 42, 42, 42, 42, 42]^T$ have the following instance of F_{lin}

$$\begin{aligned} f_{\boldsymbol{\theta}}(\mathbf{x}) = & 42 + 42x_1 + 42x_2 + 42x_1^2 + 42x_2^2 + \\ & 42x_1x_2 + 42x_1^2x_2 + 42x_1x_2^2 + 42x_1^3 + 42x_2^3 + \\ & 42x_3 + 42x_3^2 + 42x_3^3 + 42x_1x_3 + 42x_1x_3^2 + \\ & 42x_1^2x_3 + 42x_2x_3 + 42x_2x_3^2 + 42x_2^2x_3 + 42x_1x_2x_3 \end{aligned}$$

d) Consider the function $f_{\boldsymbol{\theta}}(\mathbf{x}) : R^5 \rightarrow R$, $f_{\boldsymbol{\theta}}(\mathbf{x}) = \frac{1}{1+\exp(-\boldsymbol{\theta}^T \mathbf{x})}$. Define the associated parametric set and give two instances of it. What is the dimensionality of $\boldsymbol{\theta}$?

For a given $\mathbf{x} = [x_1, x_2, x_3, x_4, x_5]^T$ it is:

$$f_{\boldsymbol{\theta}}(\mathbf{x}) = \frac{1}{1 + \exp(-(\theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_3 + \theta_4 x_4 + \theta_5 x_5))}$$

thus,

$$\boldsymbol{\theta} = [\theta_0, \theta_1, \theta_2, \theta_3, \theta_4, \theta_5]^T$$

and

$$F_{lin} := f_{\boldsymbol{\theta}}(\cdot) : \boldsymbol{\theta} \in R^6$$

i) If we choose e.g., $\boldsymbol{\theta} = [0, 1, 2, 3, 4, 5]^T$ have the following instance of F_{lin}

$$f_{\boldsymbol{\theta}}(\mathbf{x}) = \frac{1}{1 + \exp(-(1x_1 + 2x_2 + 3x_3 + 4x_4 + 5x_5))}$$

ii) If we choose e.g., $\boldsymbol{\theta} = [42, 42, 42, 42, 42, 42]^T$ have the following instance of F_{lin}

$$f_{\boldsymbol{\theta}}(\mathbf{x}) = \frac{1}{1 + \exp(-(42 + 42x_1 + 42x_2 + 42x_3 + 42x_4 + 42x_5))}$$

e) In which of the above cases $f_{\boldsymbol{\theta}}$ is linear with respect to $\boldsymbol{\theta}$?

$f_{\boldsymbol{\theta}}$ is linear with respect to $\boldsymbol{\theta}$ in cases a, b, c, while non linear in case d.

Exercise 4.

For the left part of the equation we have:

$$\begin{aligned} (\boldsymbol{\theta}^T \mathbf{x}) \mathbf{x} &= \left([\theta_1, \dots, \theta_l] \begin{bmatrix} x_1 \\ \vdots \\ x_l \end{bmatrix} \right) \mathbf{x} \\ &= \left(\sum_{i=1}^l \theta_i x_i \right) \begin{bmatrix} x_1 \\ \vdots \\ x_l \end{bmatrix} \end{aligned} \tag{3.1}$$

For the right part of the equation we have:

$$\begin{aligned}
 (\mathbf{x}\mathbf{x}^T)\boldsymbol{\theta} &= \left(\begin{bmatrix} x_1 \\ \vdots \\ x_l \end{bmatrix} [x_1, \dots, x_l] \right) \begin{bmatrix} \theta_1 \\ \vdots \\ \theta_l \end{bmatrix} = \begin{bmatrix} x_1 \\ \vdots \\ x_l \end{bmatrix} \left([x_1, \dots, x_l] \begin{bmatrix} \theta_1 \\ \vdots \\ \theta_l \end{bmatrix} \right) \\
 &= \begin{bmatrix} x_1 \\ \vdots \\ x_l \end{bmatrix} \left(\sum_{i=1}^l \theta_i x_i \right) \tag{3.2}
 \end{aligned}$$

The last expression (3.2) can be written exactly as (3.1) since $\sum_{i=1}^l \theta_i x_i$ is a number (vector 1x1) and we know that for a matrix $A : cA = Ac$.

Exercise 5.

a) **Verify the identities.**

i) We have:

$$\begin{aligned}
 X^T X &= \begin{bmatrix} x_{11} & x_{21} & \dots & x_{N1} \\ x_{12} & x_{22} & \dots & x_{N2} \\ \vdots & \vdots & \ddots & \vdots \\ x_{1l} & x_{2l} & \dots & x_{Nl} \end{bmatrix} \begin{bmatrix} x_{11} & x_{12} & \dots & x_{1l} \\ x_{21} & x_{22} & \dots & x_{2l} \\ \vdots & \vdots & \ddots & \vdots \\ x_{N1} & x_{N2} & \dots & x_{Nl} \end{bmatrix} \\
 &= \begin{bmatrix} \mathbf{x}_1 & \mathbf{x}_2 & \dots & \mathbf{x}_N \end{bmatrix} \begin{bmatrix} \mathbf{x}_1^T \\ \mathbf{x}_2^T \\ \vdots \\ \mathbf{x}_N^T \end{bmatrix} \\
 &= \sum_{n=1}^N \mathbf{x}_n \mathbf{x}_n^T
 \end{aligned}$$

ii) Similarly:

$$\begin{aligned}
 X^T \mathbf{y} &= \begin{bmatrix} x_{11} & x_{21} & \dots & x_{N1} \\ x_{12} & x_{22} & \dots & x_{N2} \\ \vdots & \vdots & \ddots & \vdots \\ x_{1l} & x_{2l} & \dots & x_{Nl} \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix} \\
 &= \begin{bmatrix} \mathbf{x}_1 & \mathbf{x}_2 & \dots & \mathbf{x}_N \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix} \\
 &= \sum_{n=1}^N \mathbf{x}_n y_n = \sum_{n=1}^N y_n \mathbf{x}_n \tag{5.1}
 \end{aligned}$$

We are able to interchange y_n in (5.1) since when creating the inner product, each y_i is a single number and again using $A : cA = Ac$ we come to this form.

b) What are the size of the matrices?

1. $X_{N \times l}$
2. $\mathbf{y}_{N \times 1}$
3. For $X^T X$ we have: $X_{l \times N}^T \cdot X_{N \times l} \rightarrow (X^T X)_{l \times l}$
4. For $X^T \mathbf{y}$ we have: $X_{l \times N}^T \cdot \mathbf{y}_{N \times 1} \rightarrow (X^T \mathbf{y})_{l \times 1}$

c) Assume that a column vector of 1's is added in front of the 1st column of X .

i) What will be the changes in the dimensionality of the quantities in (b)?

1. $X_{N \times (l+1)}$
2. $\mathbf{y}_{N \times 1}$
3. For $X^T X$ we have: $X_{(l+1) \times N}^T \cdot X_{N \times (l+1)} \rightarrow (X^T X)_{(l+1) \times (l+1)}$
4. For $X^T \mathbf{y}$ we have: $X_{(l+1) \times N}^T \cdot \mathbf{y}_{N \times 1} \rightarrow (X^T \mathbf{y})_{(l+1) \times 1}$

ii) Do the identities given in (a) still hold? i) We now have:

$$\begin{aligned}
 X^T X &= \begin{bmatrix} 1 & 1 & \dots & 1 \\ x_{11} & x_{21} & \dots & x_{N1} \\ x_{12} & x_{22} & \dots & x_{N2} \\ \vdots & \vdots & \ddots & \vdots \\ x_{1l} & x_{2l} & \dots & x_{Nl} \end{bmatrix} \begin{bmatrix} 1 & x_{11} & x_{12} & \dots & x_{1l} \\ 1 & x_{21} & x_{22} & \dots & x_{2l} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{N1} & x_{N2} & \dots & x_{Nl} \end{bmatrix} \\
 &= \begin{bmatrix} 1 & 1 & \dots & 1 \\ \mathbf{x}_1 & \mathbf{x}_2 & \dots & \mathbf{x}_N \end{bmatrix} \begin{bmatrix} 1 & \mathbf{x}_1^T \\ 1 & \mathbf{x}_2^T \\ \vdots & \vdots \\ 1 & \mathbf{x}_N^T \end{bmatrix} \tag{5.2}
 \end{aligned}$$

We now consider the vectors $\mathbf{x}'_n = [1, x_{n1}, \dots, x_{nl}]^T$. By substituting in (5.2) we have:

$$\begin{aligned}
 X^T X &= [\mathbf{x}'_1 \quad \mathbf{x}'_2 \quad \dots \quad \mathbf{x}'_N] \begin{bmatrix} \mathbf{x}'_1{}^T \\ \mathbf{x}'_2{}^T \\ \vdots \\ \mathbf{x}'_N{}^T \end{bmatrix} \\
 &= \sum_{n=1}^N \mathbf{x}'_n \mathbf{x}'_n{}^T \\
 &\stackrel{\mathbf{x}'_n = \mathbf{x}_n}{=} \sum_{n=1}^N \mathbf{x}_n \mathbf{x}_n{}^T
 \end{aligned}$$

In a similar way we can show that the second identity still holds.

Exercise 6. (No grade)

Exercise 6 was written in paper for practicing purposes.

Exercise 7. A body moves on a straight line and performs a smoothly accelerating motion (we begin to study its motion at the time instance $t = 0$). In the following table is given the velocity at certain time instances

$t(\text{sec})$	1	2	3	4	5
$\nu(\text{m/sec})$	5.1	6.8	9.2	10.9	13.1

(a) Estimate the initial velocity and the acceleration of the body, based on the above measurements, utilizing the least squares error criterion.

We define:

$$T = \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \\ 1 & 4 \\ 1 & 5 \end{bmatrix} \text{ and } v = \begin{bmatrix} 5.1 \\ 6.8 \\ 9.2 \\ 10.9 \\ 13.1 \end{bmatrix}$$

It is: $T^T T = \begin{bmatrix} 5 & 15 \\ 15 & 55 \end{bmatrix}$ and $(T^T T)^{-1} = \begin{bmatrix} 1.1 & -0.3 \\ -0.3 & 0.1 \end{bmatrix}$. Also $T^T v = \begin{bmatrix} 45.1 \\ 155.4 \end{bmatrix}$.

$$\text{Thus } \boldsymbol{\theta} = (T^T T)^{-1} T^T v = \begin{bmatrix} 1.1 & -0.3 \\ -0.3 & 0.1 \end{bmatrix} \begin{bmatrix} 45.1 \\ 155.4 \end{bmatrix} = \begin{bmatrix} 2.99 \\ 2.01 \end{bmatrix}$$

Thus, the Least Squares line is:

$$v = 2.99 + 2.01 \cdot t$$

By setting $t = 0$ we get that the initial velocity is $v_0 = 2.99$.

(b) Write down the equation that expresses the velocity of the body as a function of time t . The function is:

$$v = 2.99 + 2.01 \cdot t \tag{7.1}$$

(c) Estimate the velocity of the body at $t=2.3$. By substituting $t = 2.3$ in (7.1) we get that:

$$v = 2.99 + 2.01 \cdot 2.3 = 7.613$$