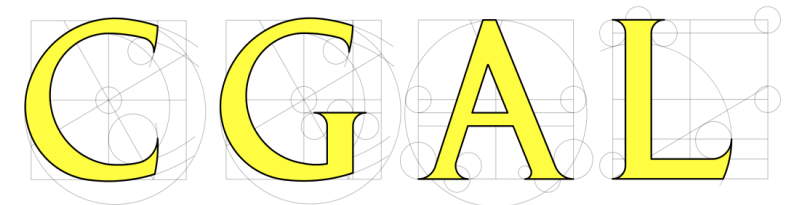
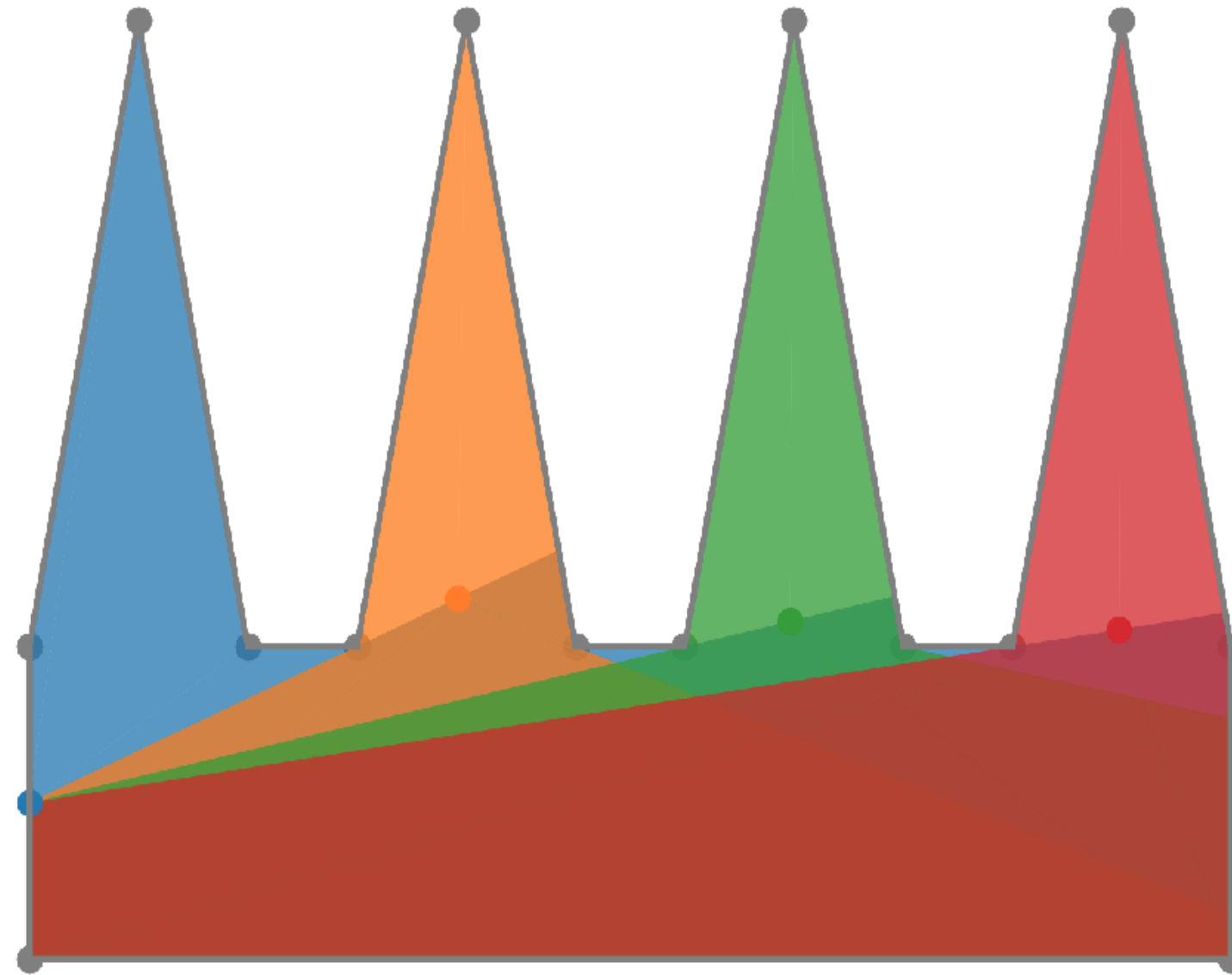
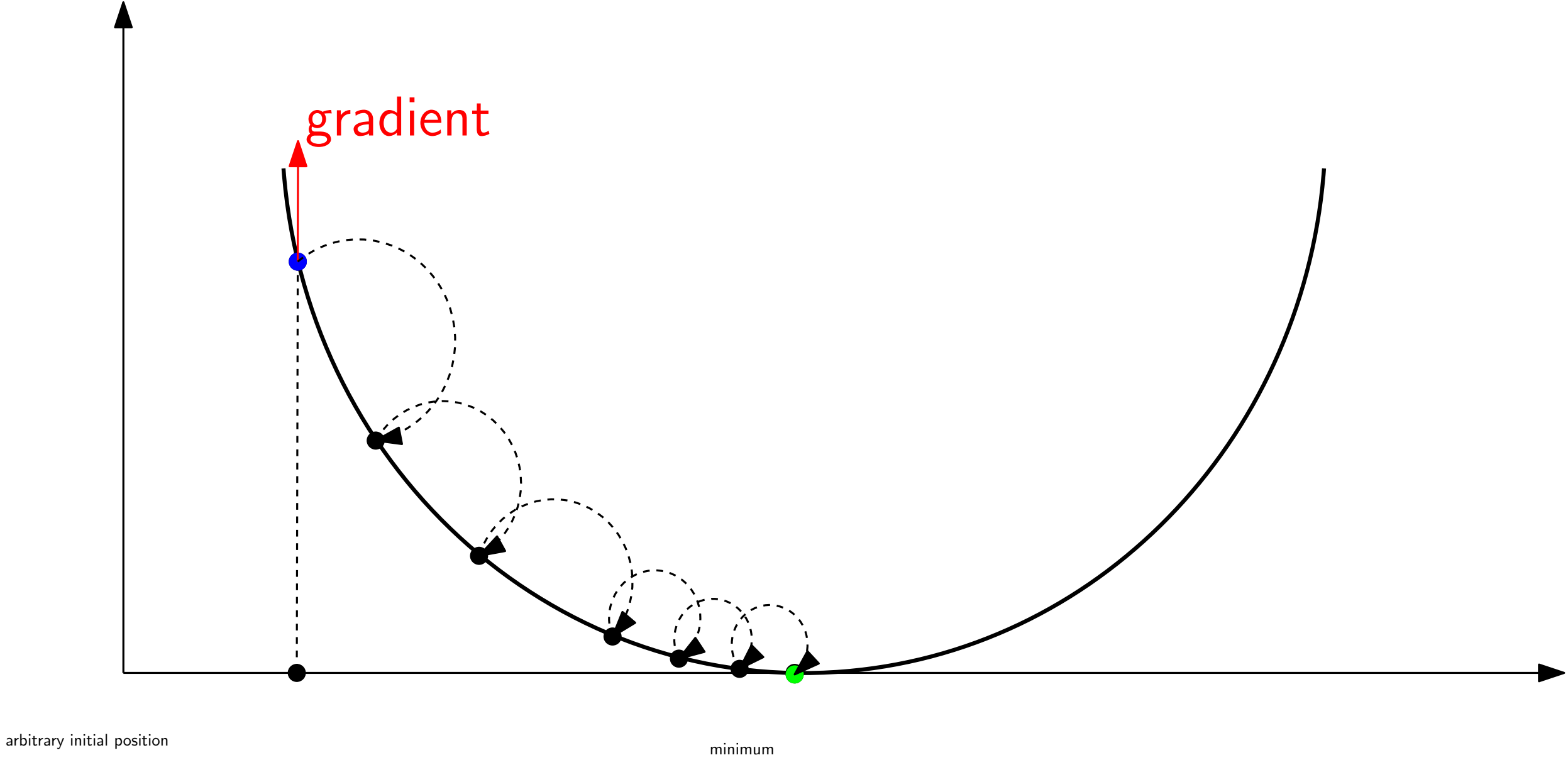


# Solving the Art Gallery Problem Using Gradient Descent

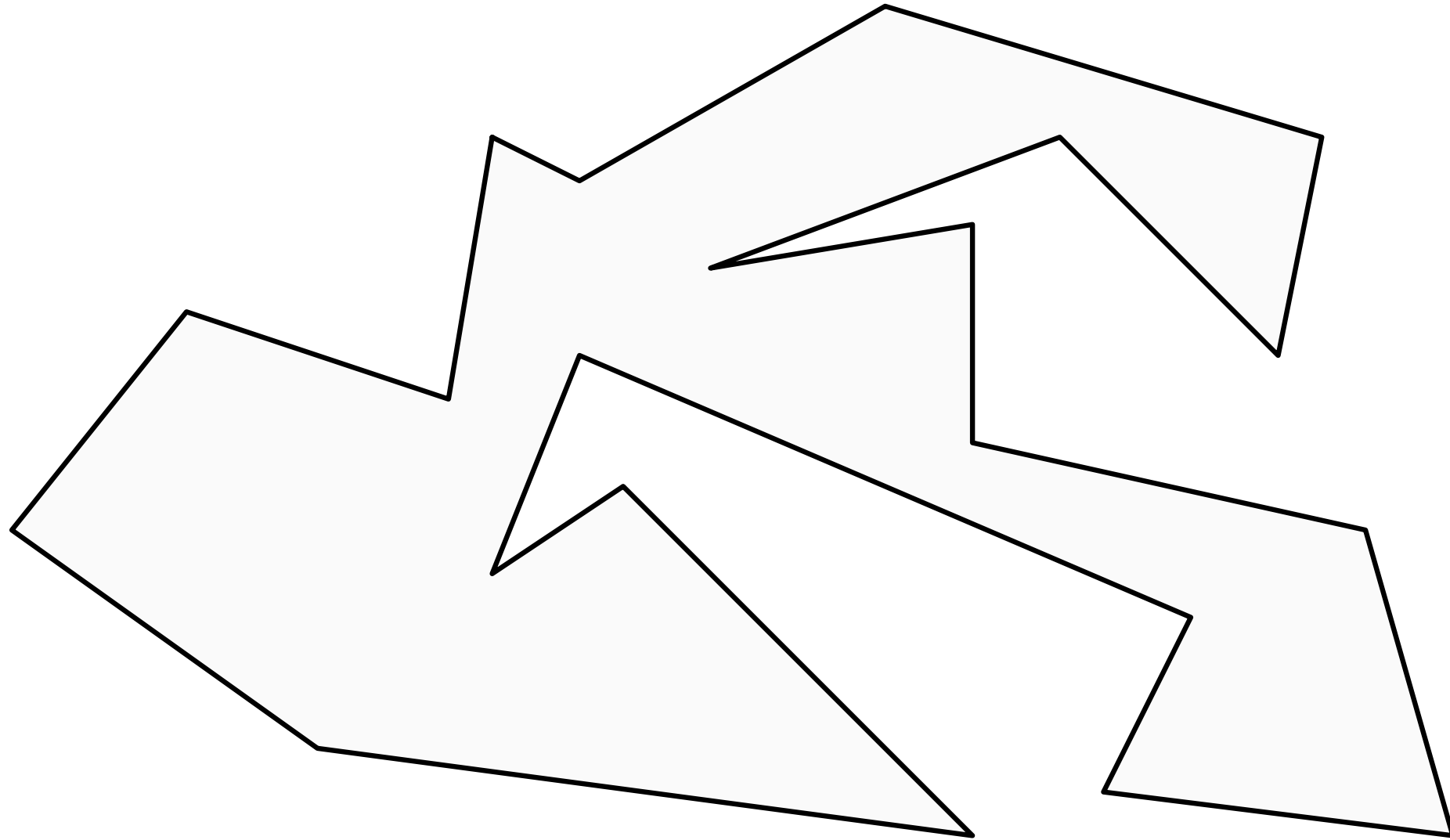
Geo Juglan



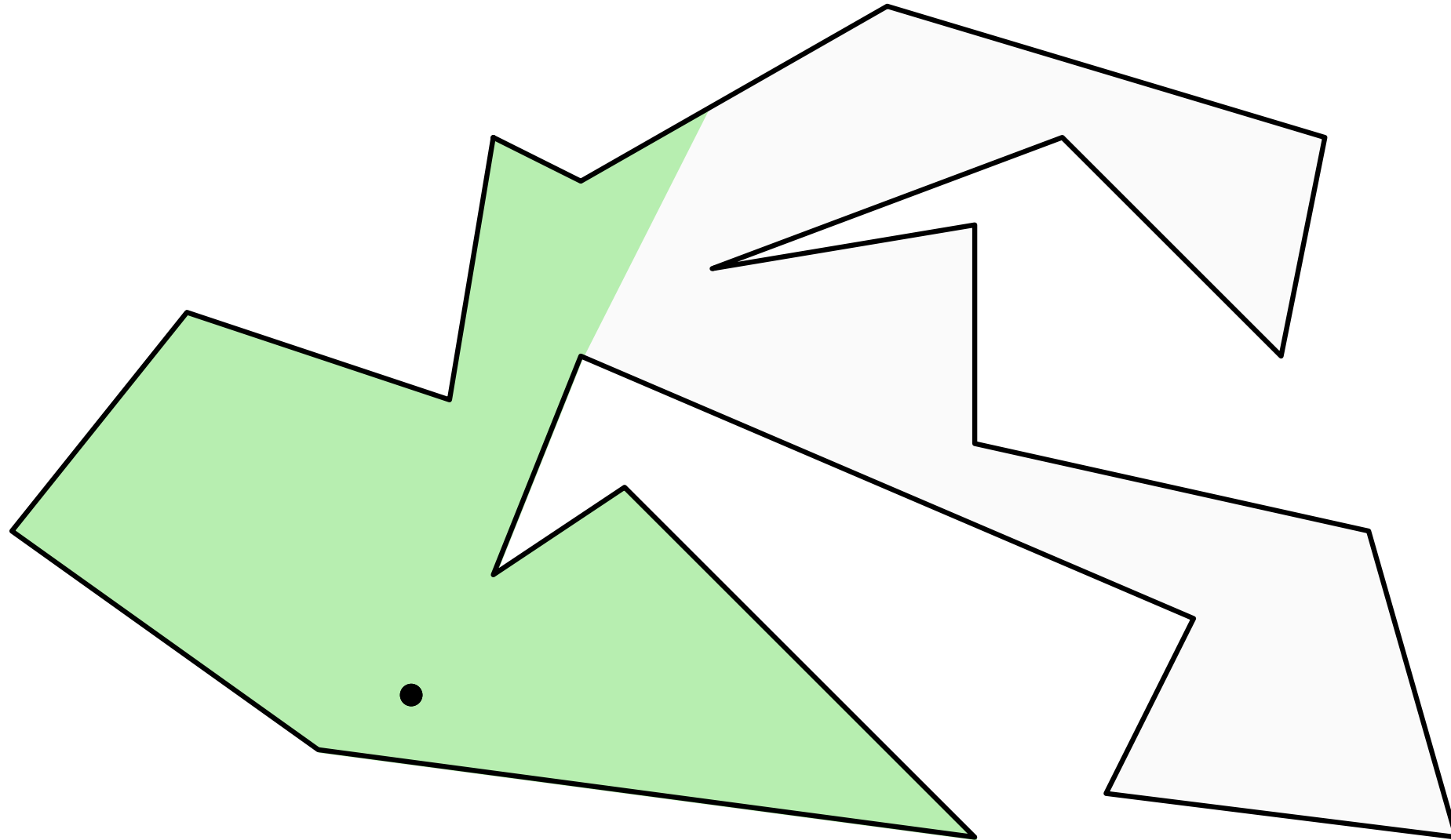
# Gradient Descent



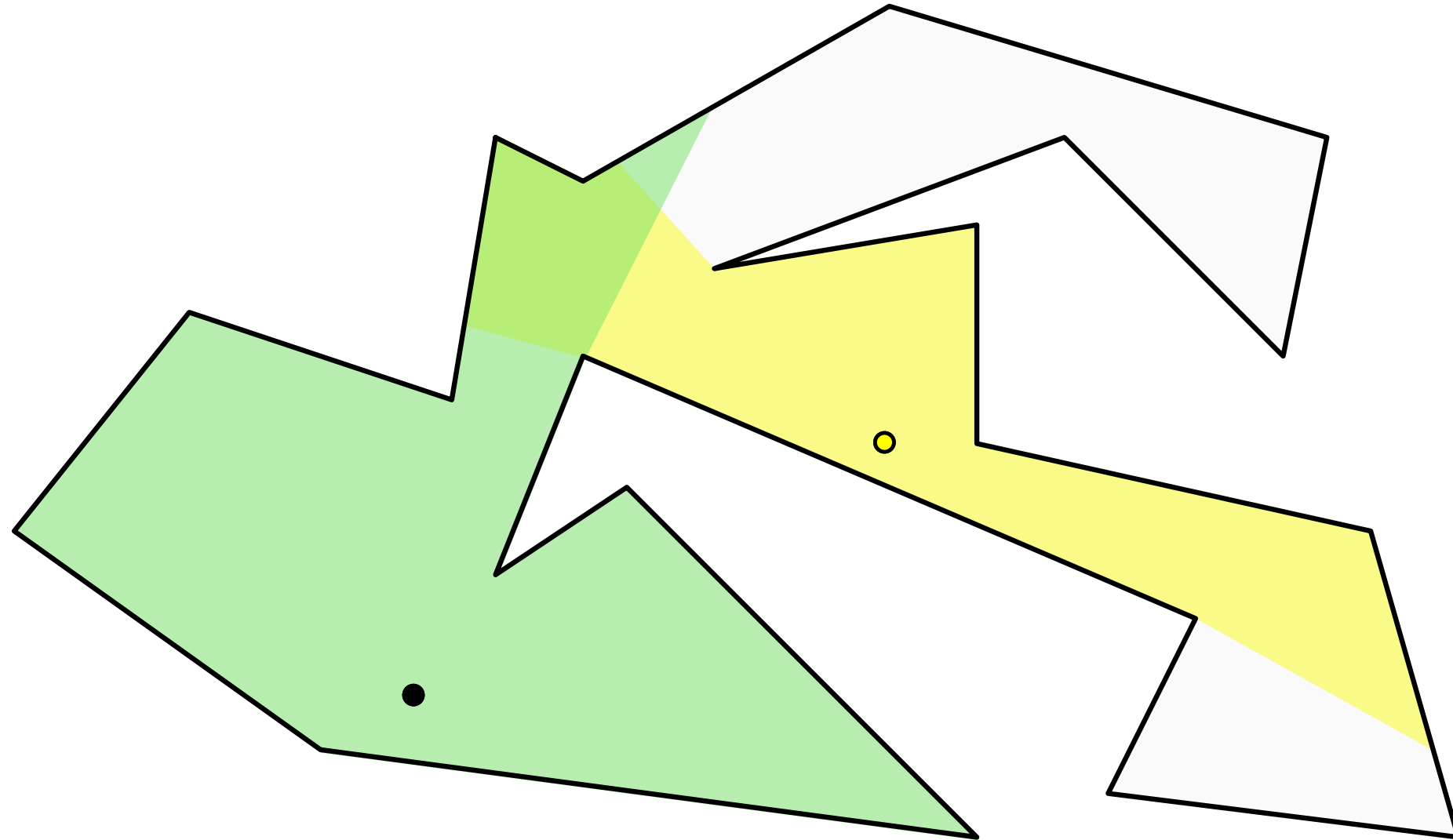
# The Art Gallery Problem



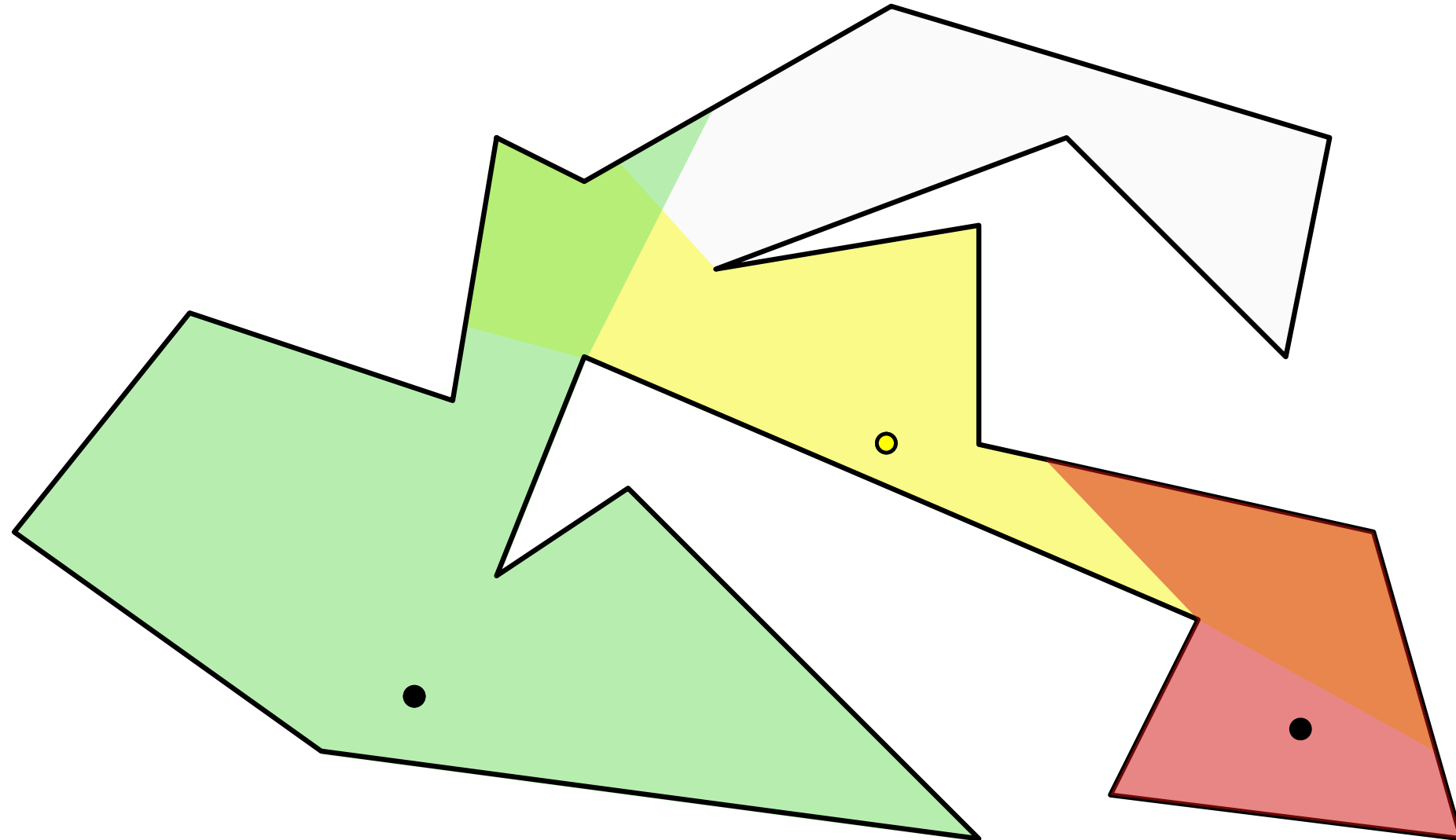
# The Art Gallery Problem



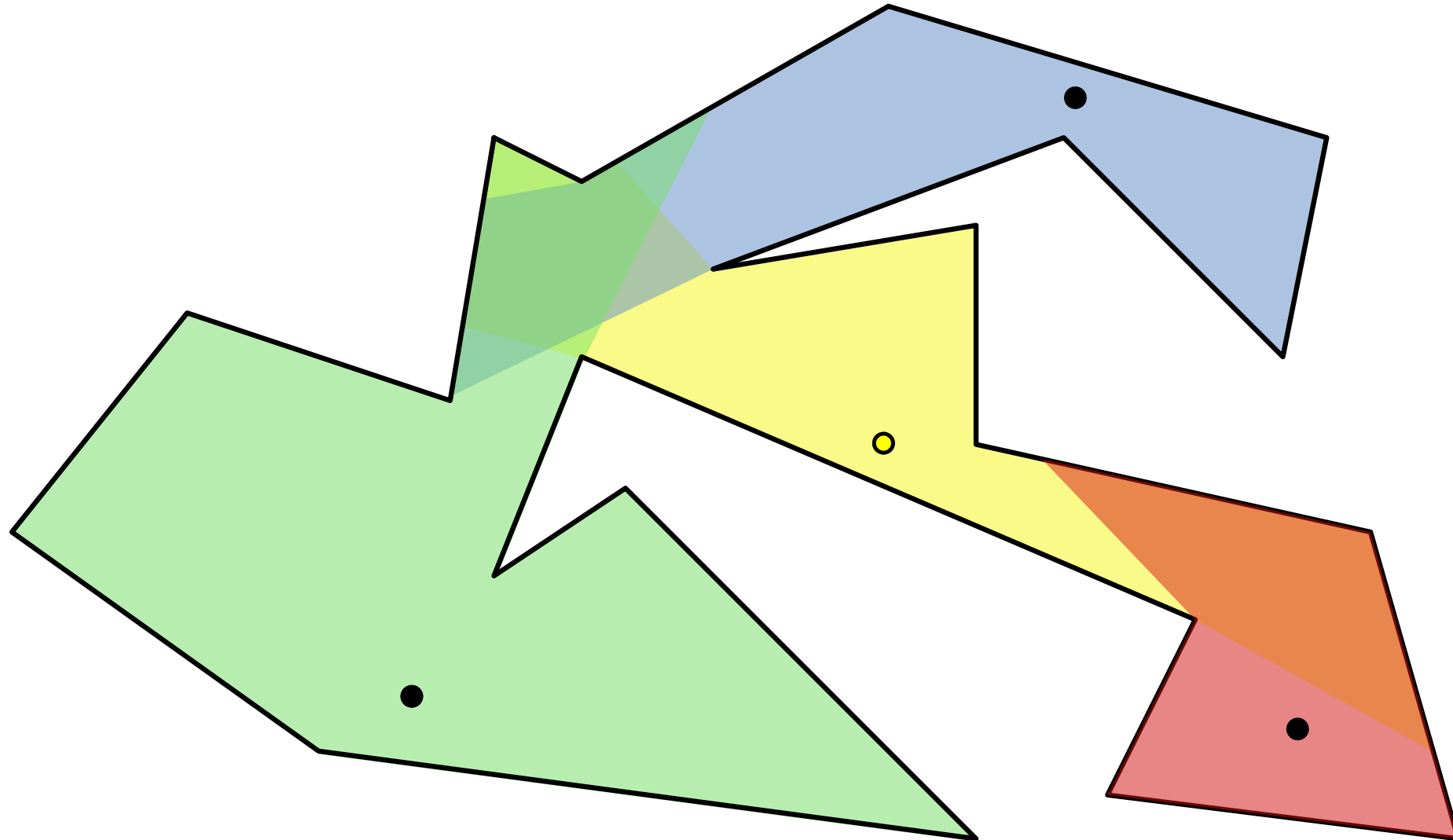
# The Art Gallery Problem



# The Art Gallery Problem

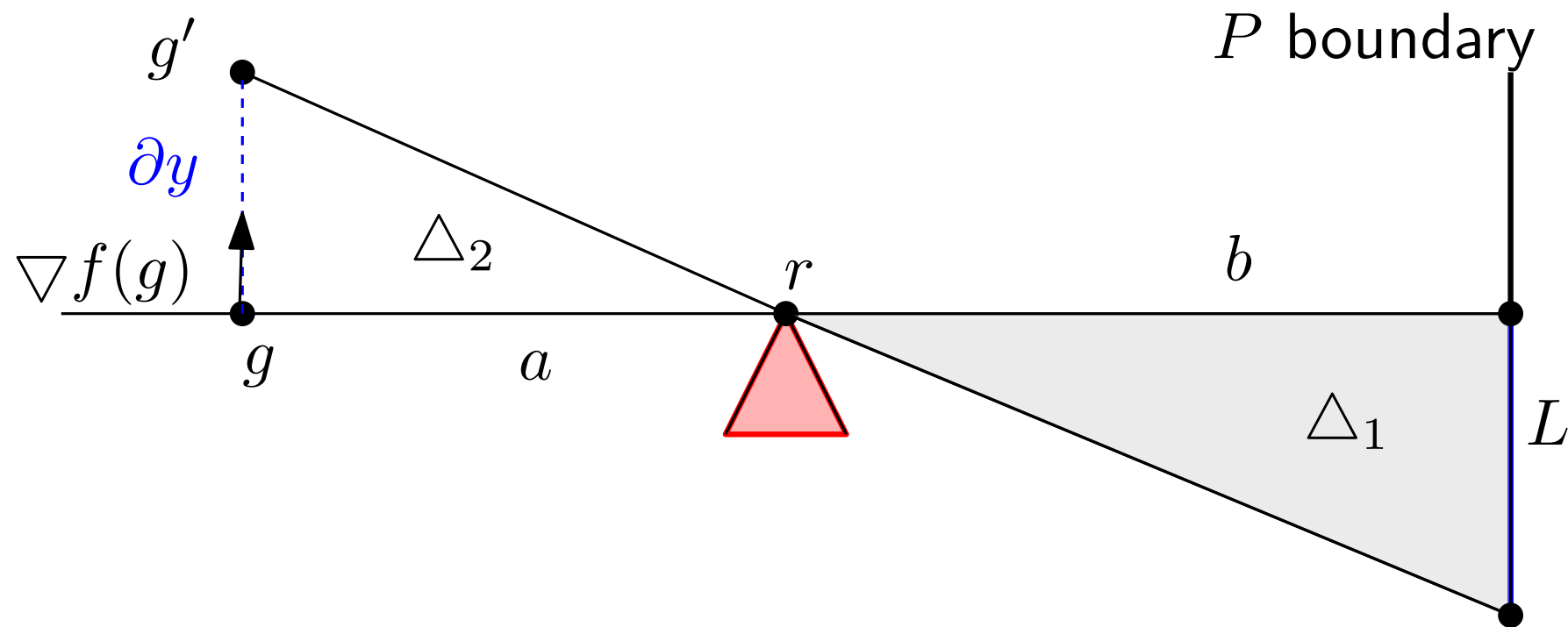


# The Art Gallery Problem



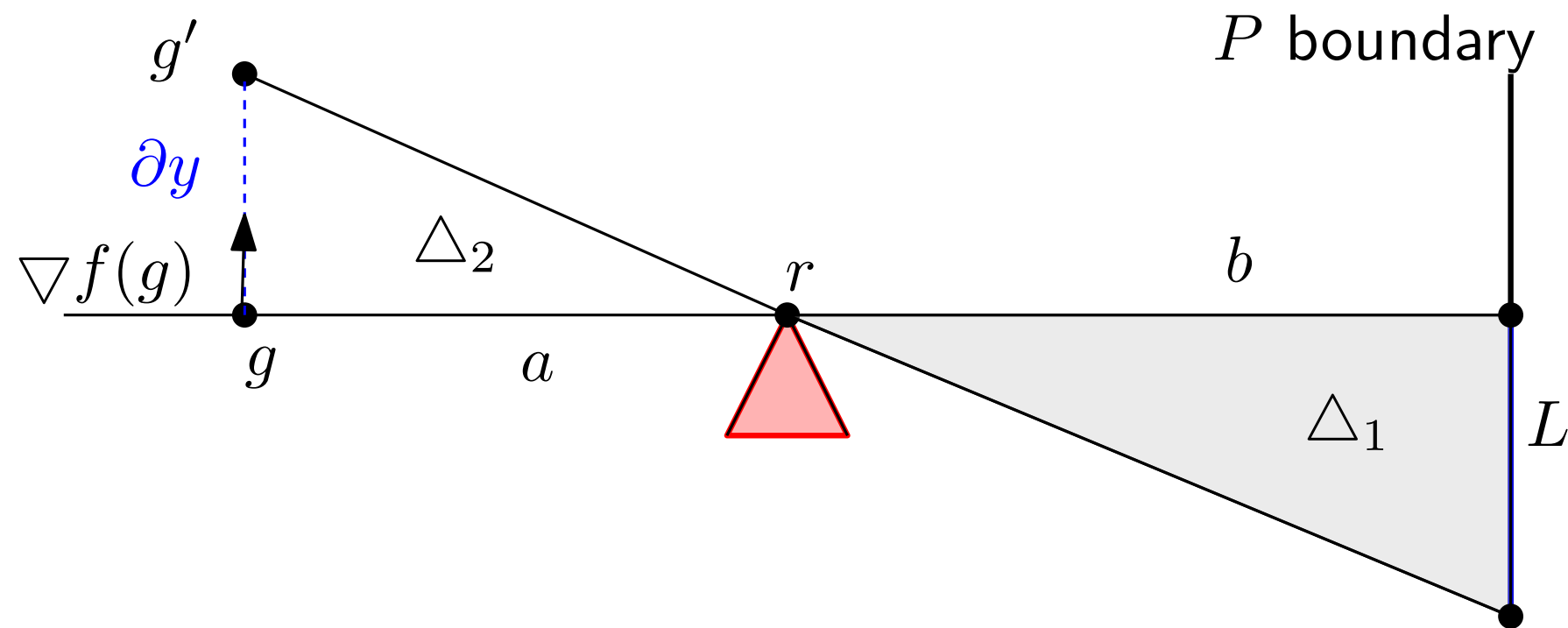
# Computing the gradient for one guard

$$\nabla f(g) = \nabla \text{Area}_{\triangle_1}(g)$$
$$\nabla f(g) = \left( \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right)^\top$$





# Computing the gradient for one guard

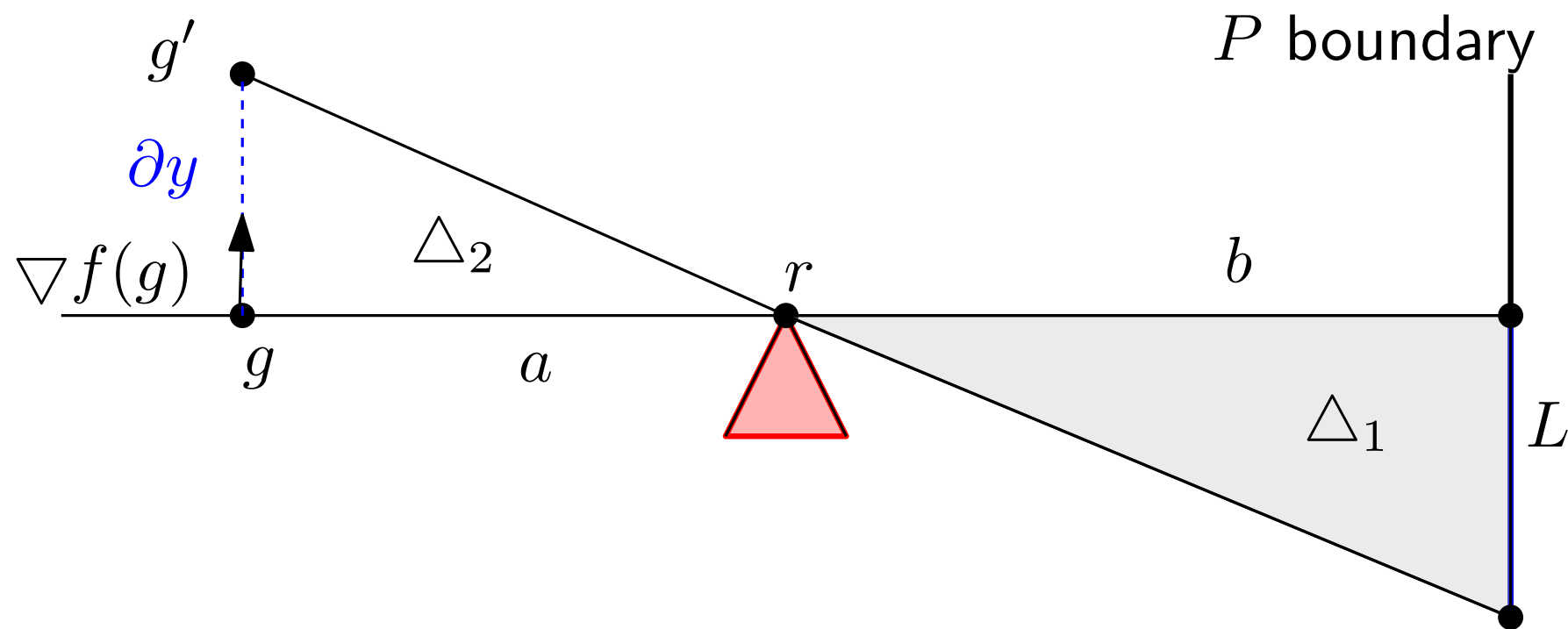


$$\nabla f(g) = \nabla \text{Area}_{\triangle_1}(g)$$

$$\nabla f(g) = \left( \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right)^\top$$

$$\nabla f(g) = \left( 0, \frac{b^2}{2a} \right)^\top$$

# Computing the gradient for one guard



$$\nabla f(g) = \nabla \text{Area}_{\triangle_1}(g)$$

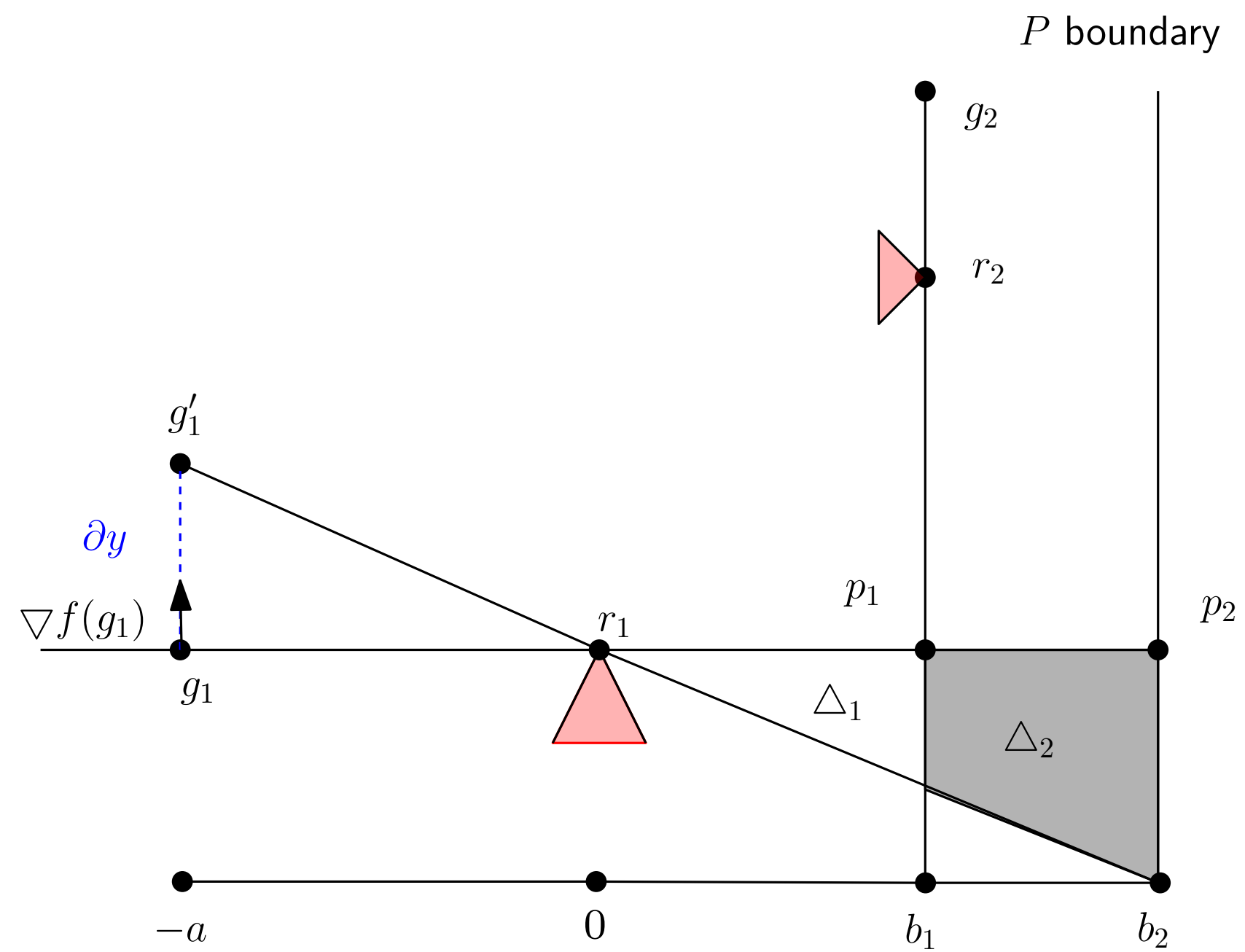
$$\nabla f(g) = \left( \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right)^\top$$

$$\nabla f(g) = \left( 0, \frac{b^2}{2a} \right)^\top$$

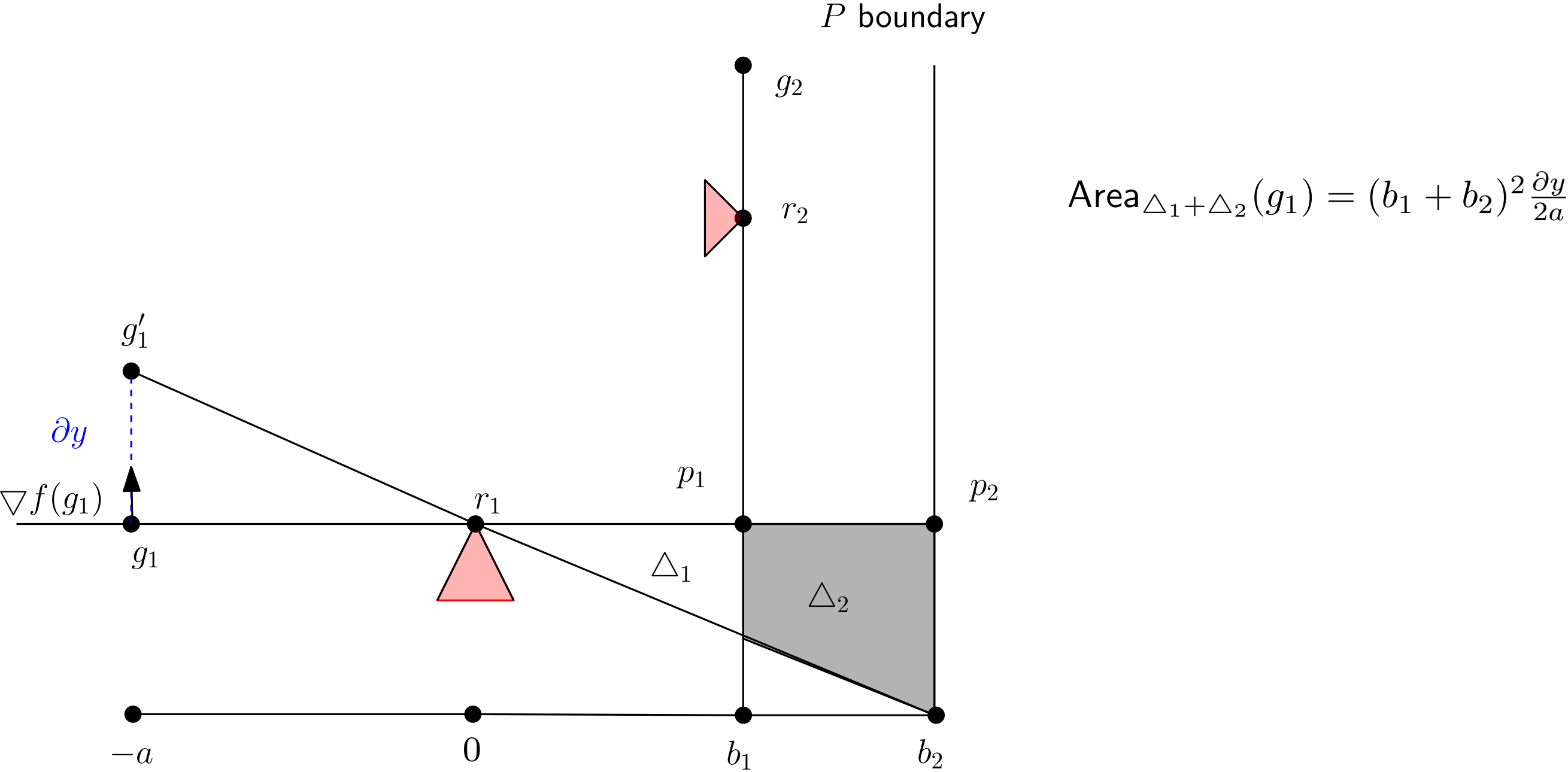
$$g' = g + \alpha \nabla f(g)$$

$\alpha$  - learning rate

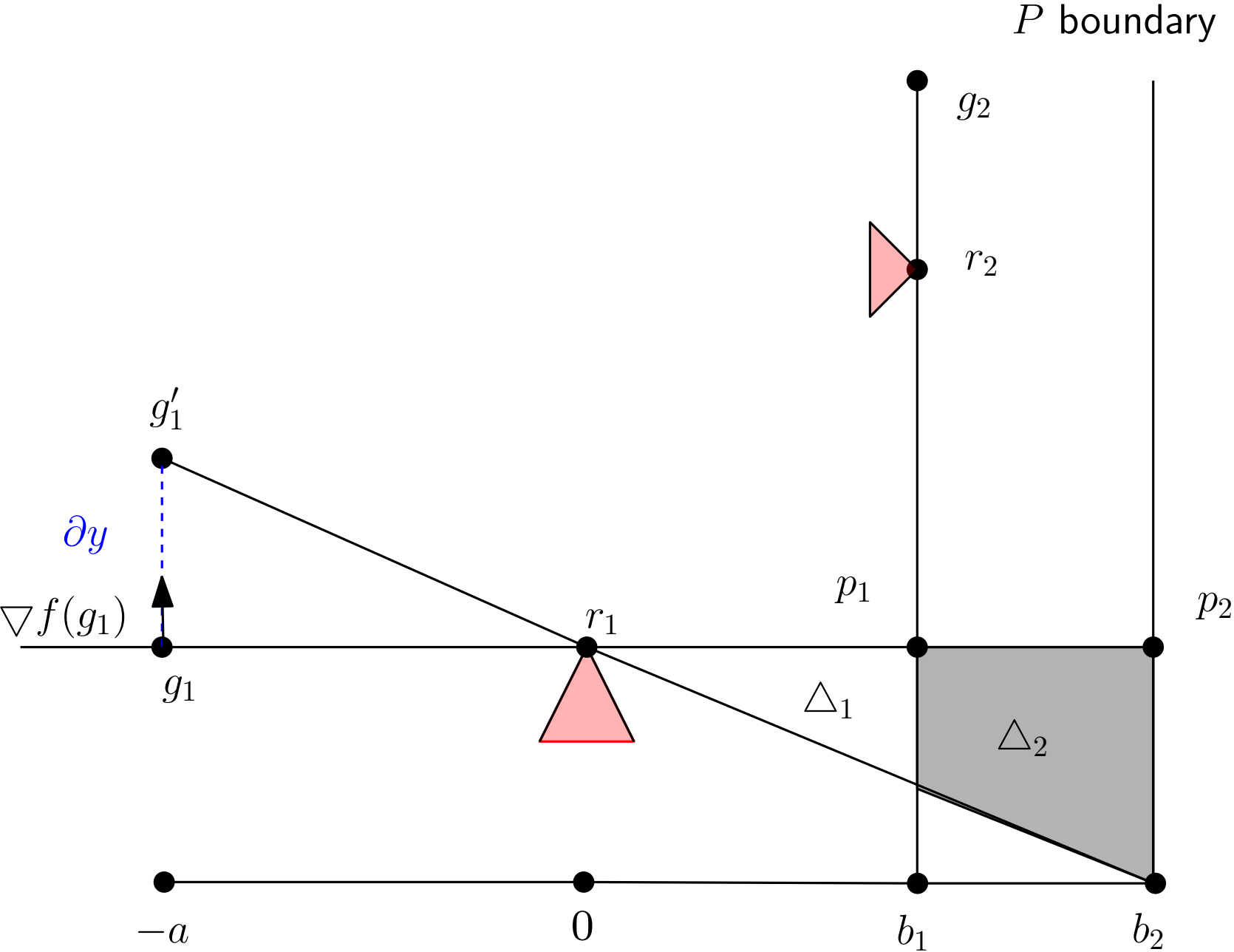
# Computing the gradient for multiple guards



# Computing the gradient for multiple guards



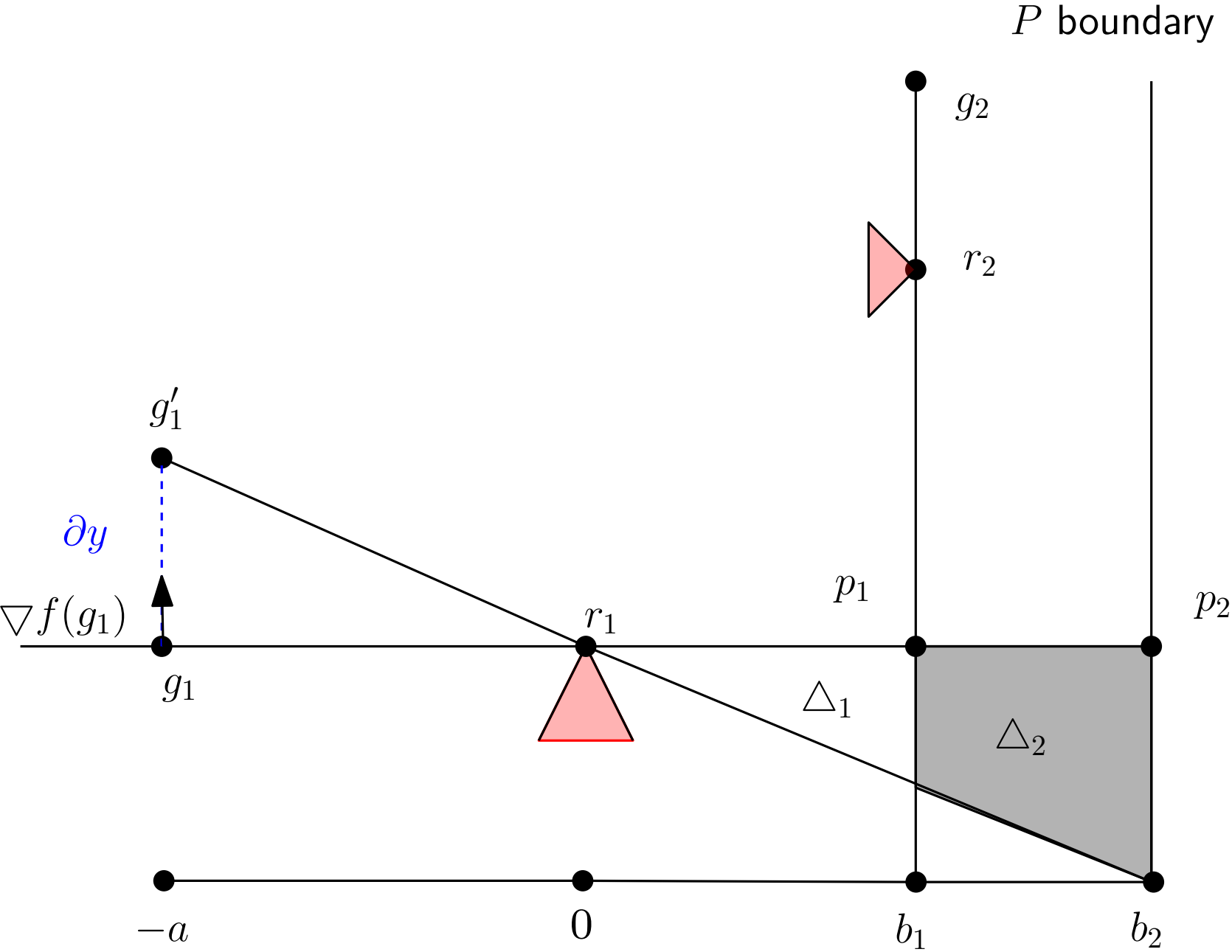
# Computing the gradient for multiple guards



$$\text{Area}_{\Delta_1 + \Delta_2}(g_1) = (b_1 + b_2)^2 \frac{\partial y}{2a}$$

$$\text{Area}_{\Delta_1}(g_1) = b_1^2 \frac{\partial y}{2a}$$

# Computing the gradient for multiple guards

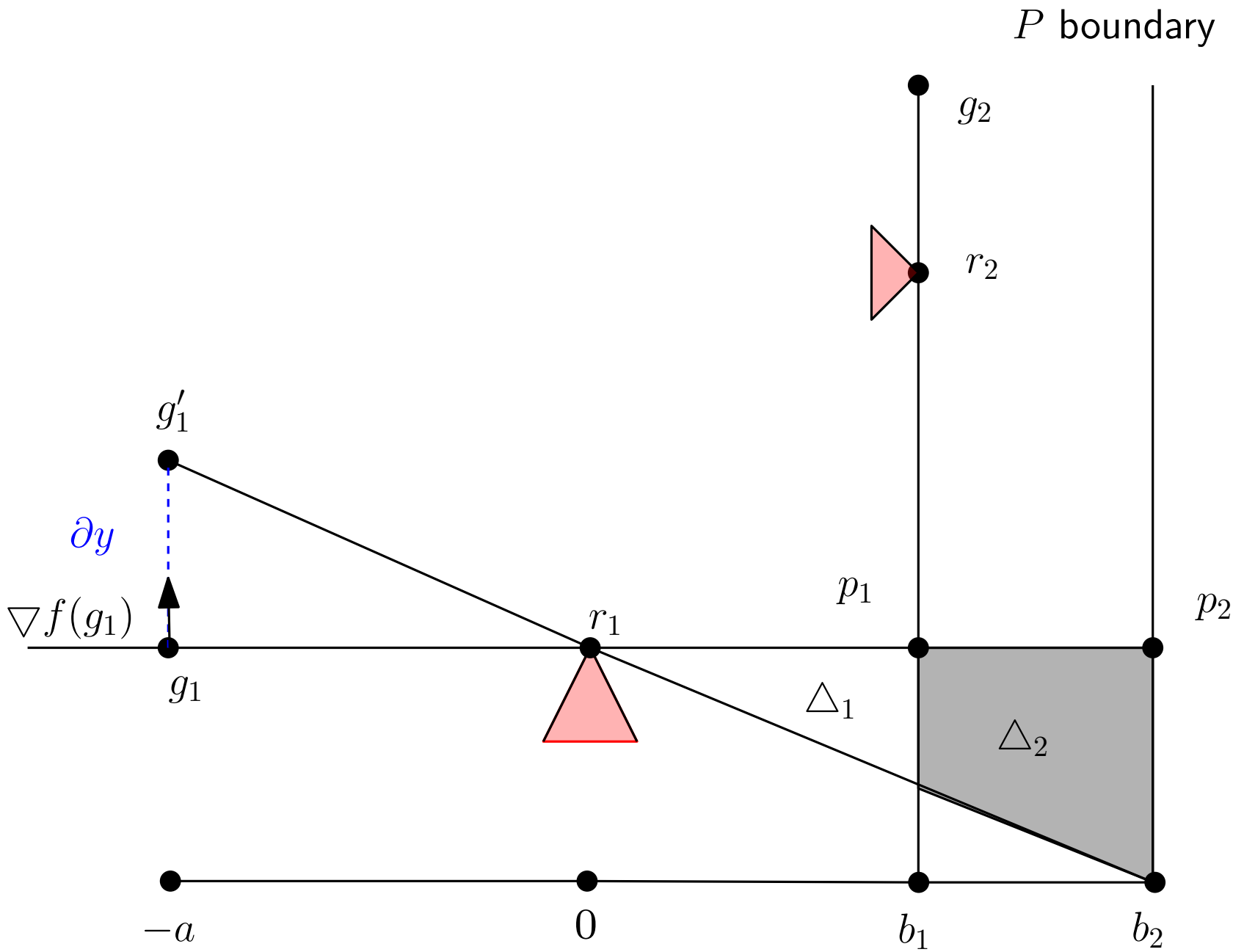


$$\text{Area}_{\triangle_1 + \triangle_2}(g_1) = (b_1 + b_2)^2 \frac{\partial y}{2a}$$

$$\text{Area}_{\triangle_1}(g_1) = b_1^2 \frac{\partial y}{2a}$$

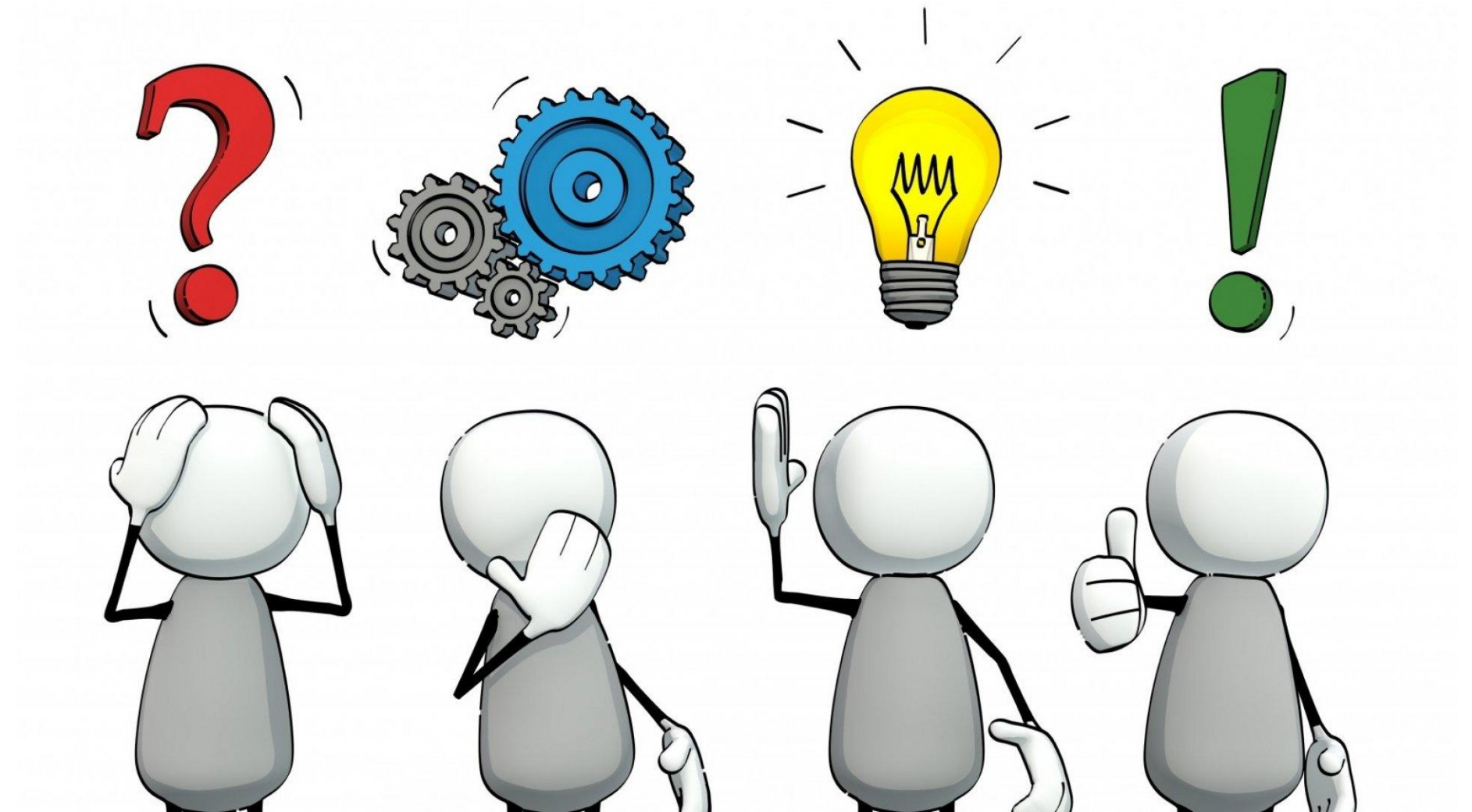
$$\text{Area}_{\triangle_2}(g_1) = \text{Area}_{\triangle_1 + \triangle_2}(g_1) - \text{Area}_{\triangle_1}(g_1)$$

# Computing the gradient for multiple guards



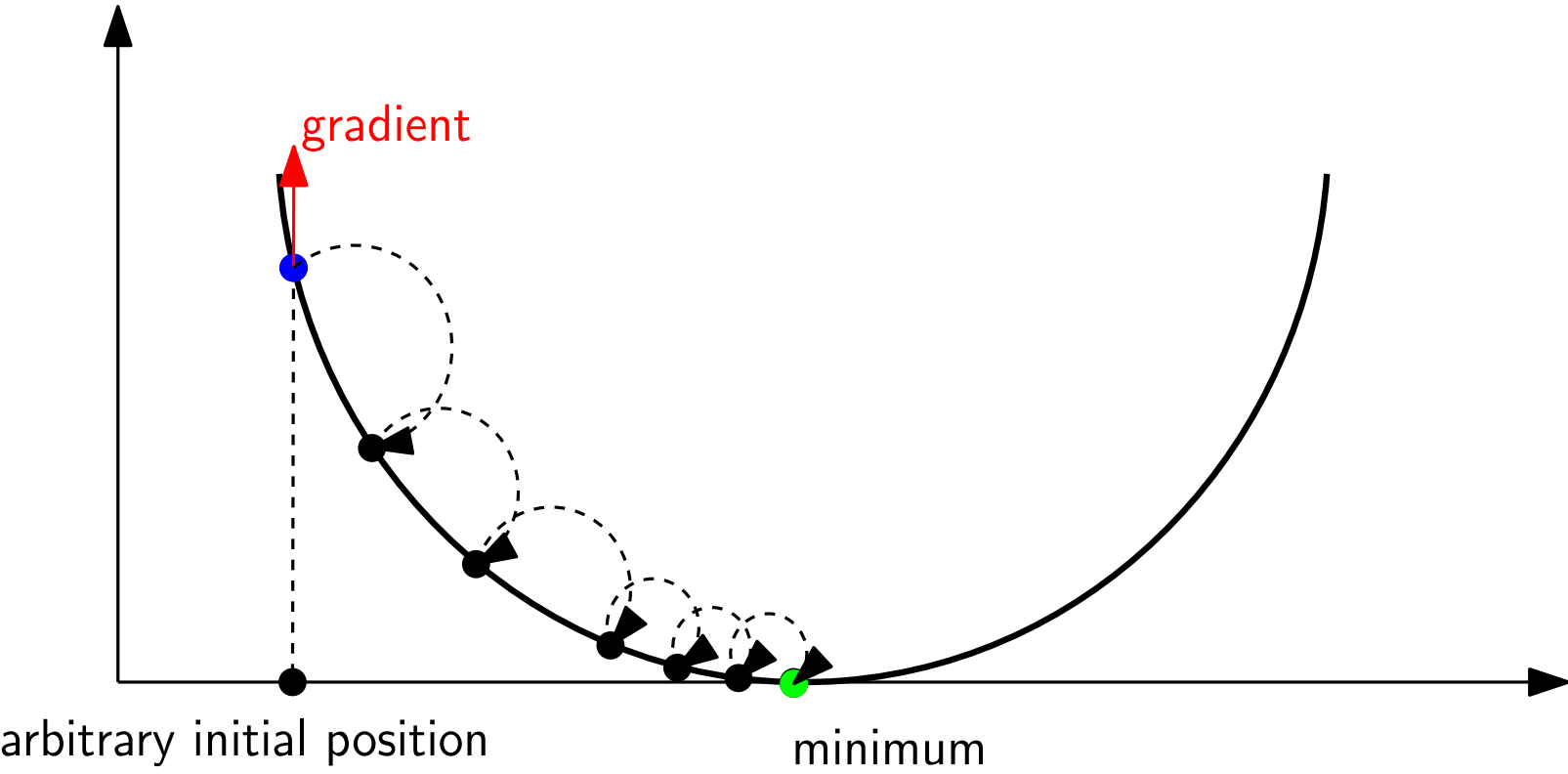
$$\begin{aligned} \text{Area}_{\Delta_1+\Delta_2}(g_1) &= (b_1 + b_2)^2 \frac{\partial y}{2a} \\ \text{Area}_{\Delta_1}(g_1) &= b_1^2 \frac{\partial y}{2a} \\ \text{Area}_{\Delta_2}(g_1) &= \text{Area}_{\Delta_1+\Delta_2}(g_1) - \text{Area}_{\Delta_1}(g_1) \\ &= [(b_1 + b_2)^2 - b_1^2] \frac{\partial y}{2a} \end{aligned}$$

# Heuristics



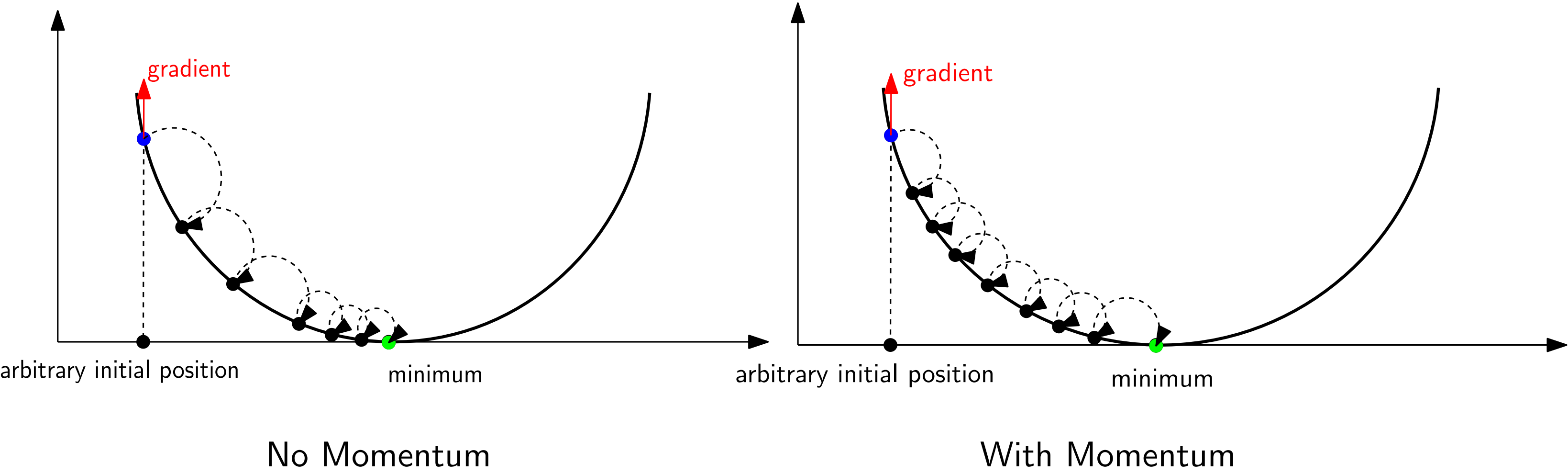


# Heuristics: Momentum



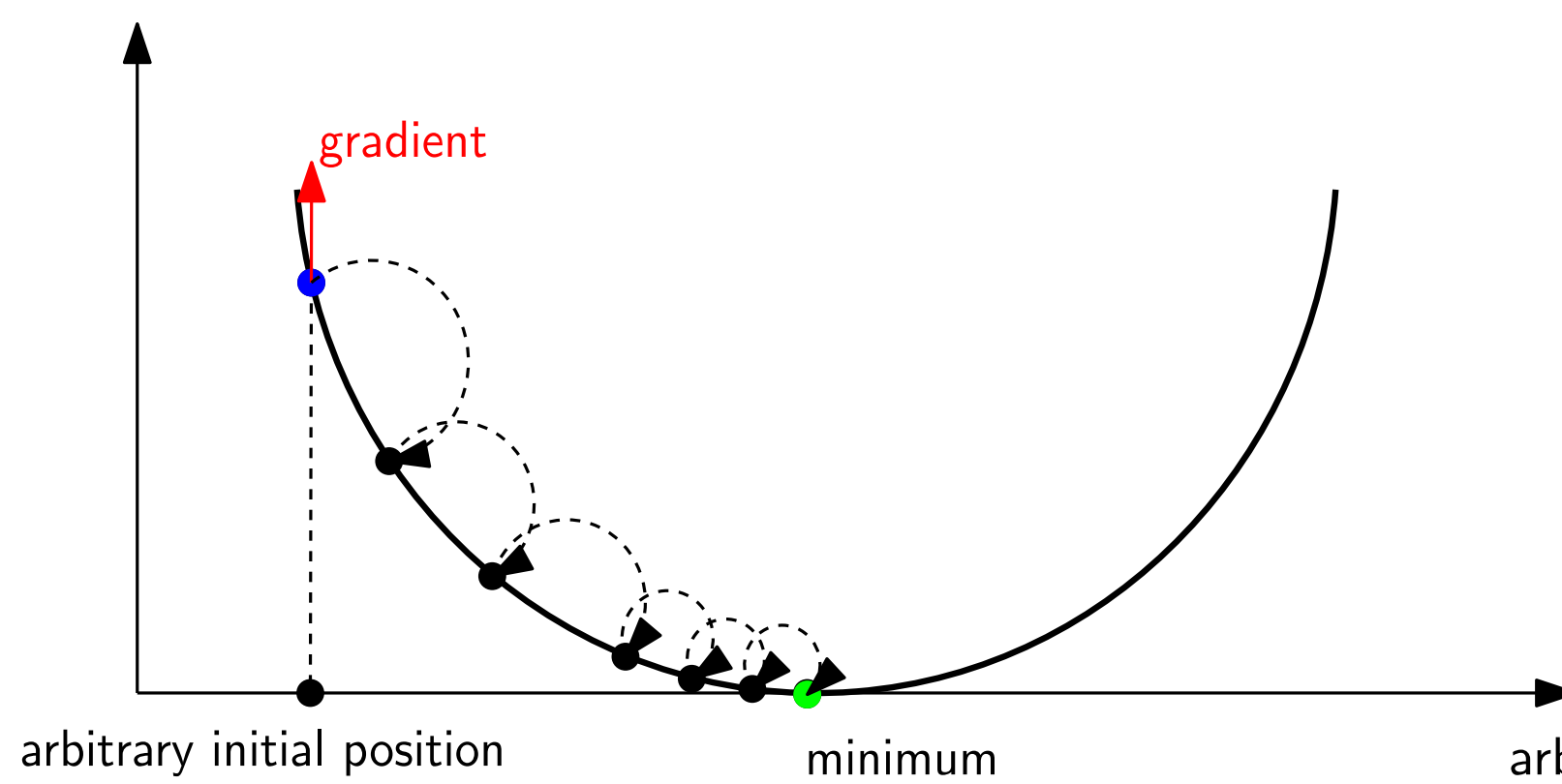
No Momentum

# Heuristics: Momentum

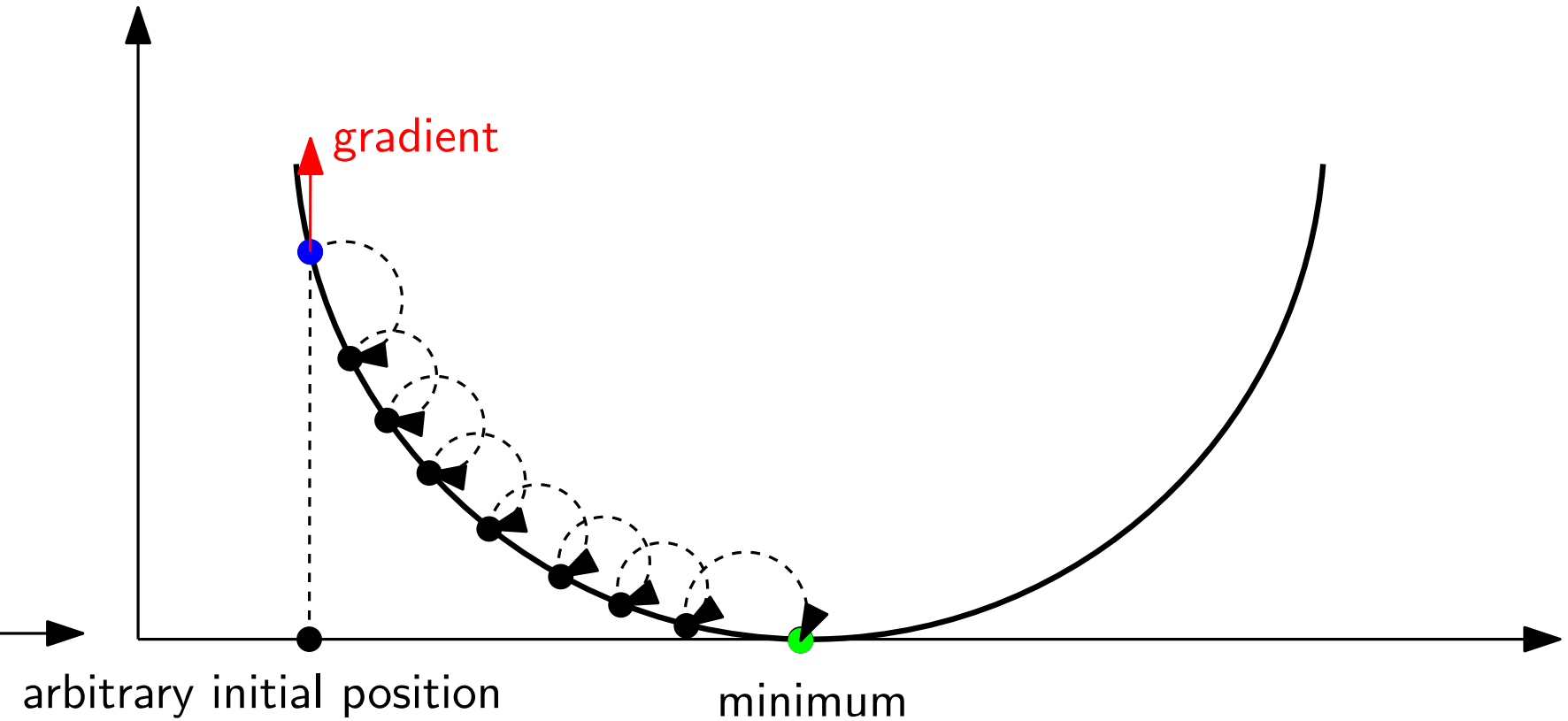


# Heuristics: Momentum

$$M_i(g_i) = \gamma M_{i-1}(g_{i-1}) + (1 - \gamma) \nabla f_i(g_i)$$



No Momentum

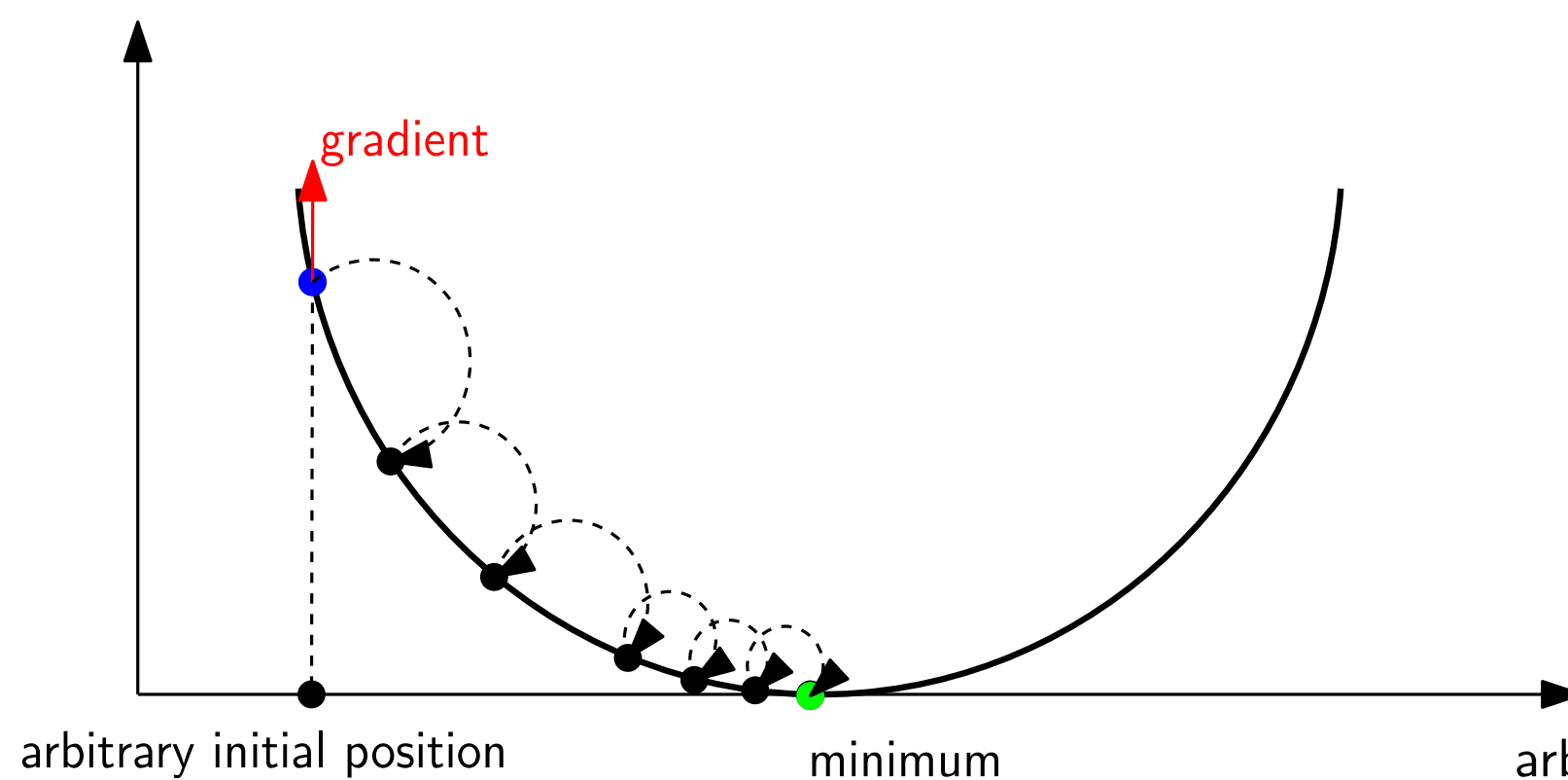


With Momentum

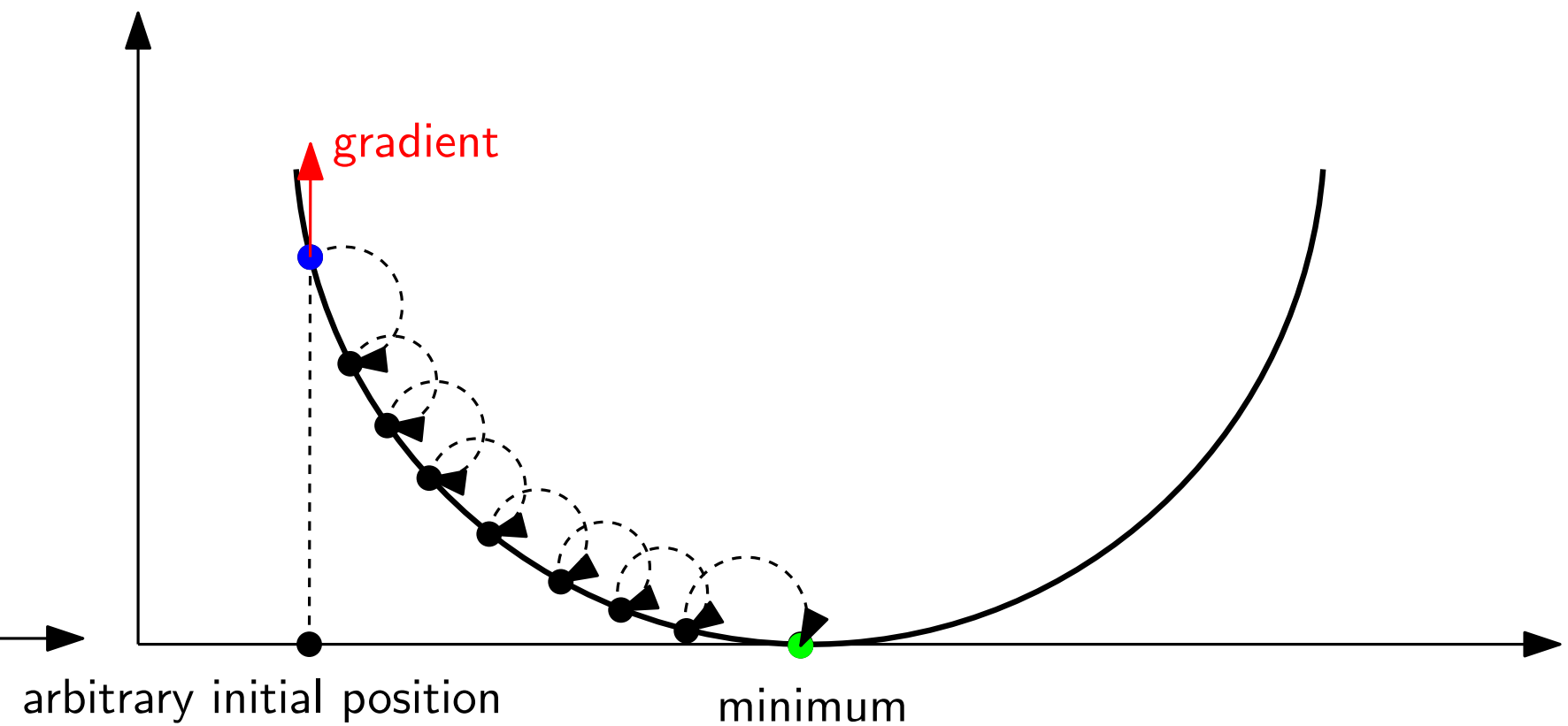
# Heuristics: Momentum

$$g_i = g_{i-1} + \alpha \nabla f_i(g_i)$$

$$M_i(g_i) = \gamma M_{i-1}(g_{i-1}) + (1 - \gamma) \nabla f_i(g_i)$$
$$g_i = g_{i-1} + \alpha M_i(g_{i-1})$$

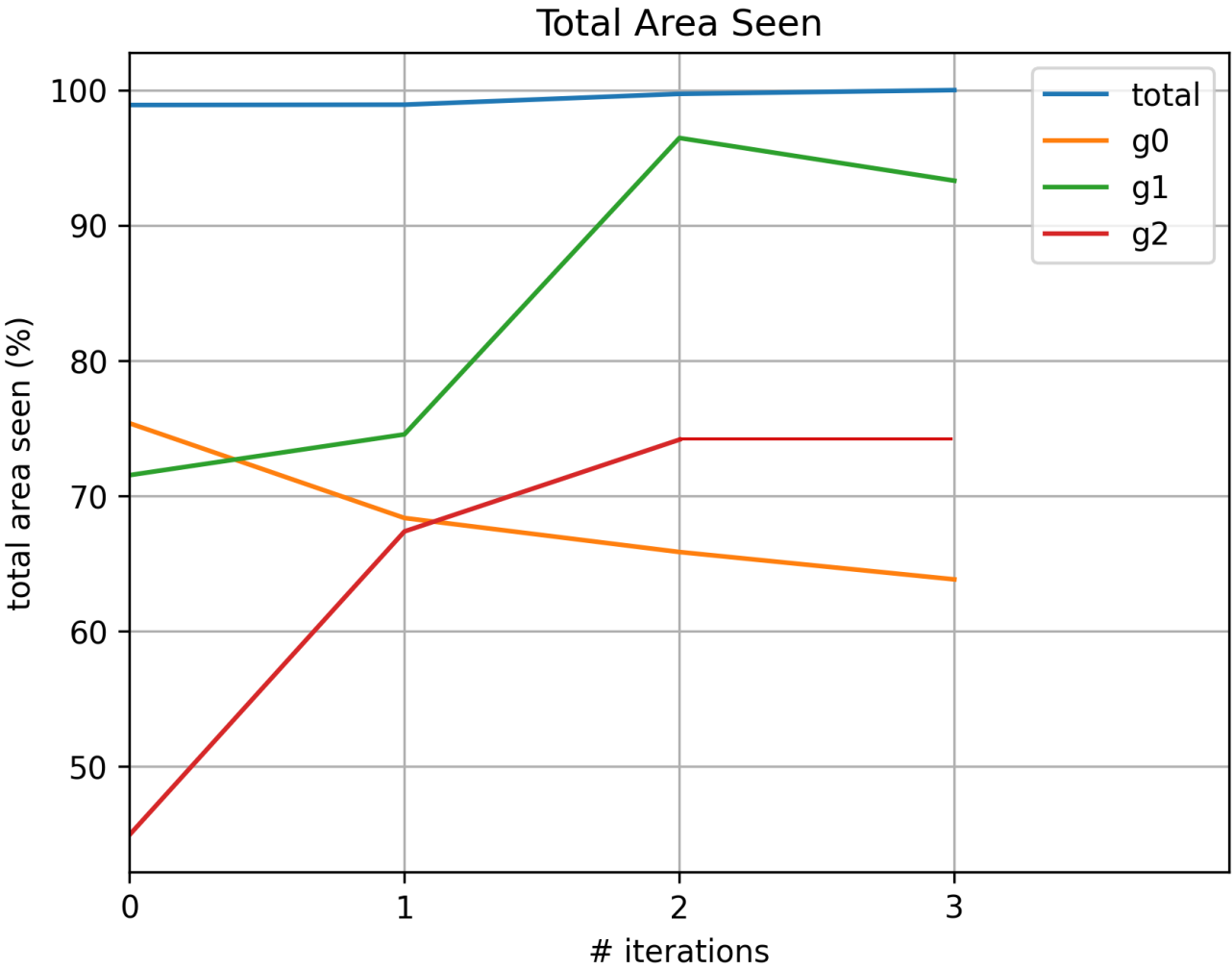
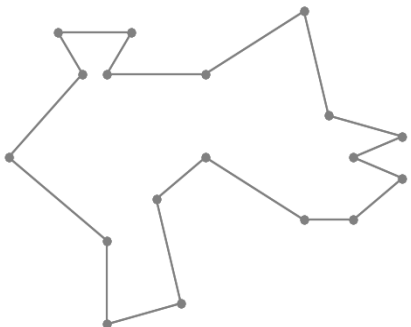


No Momentum

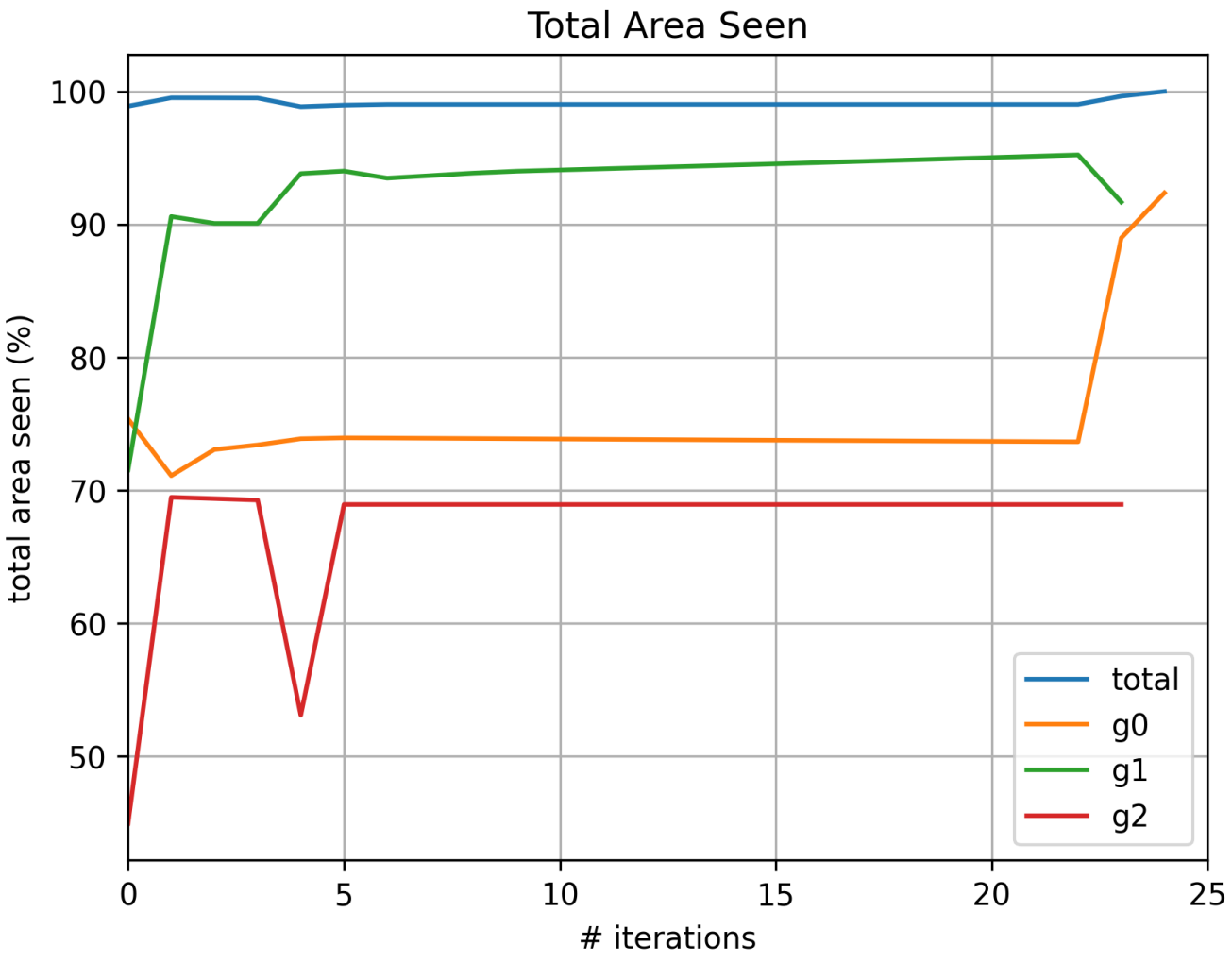


With Momentum

# Heuristics: Momentum

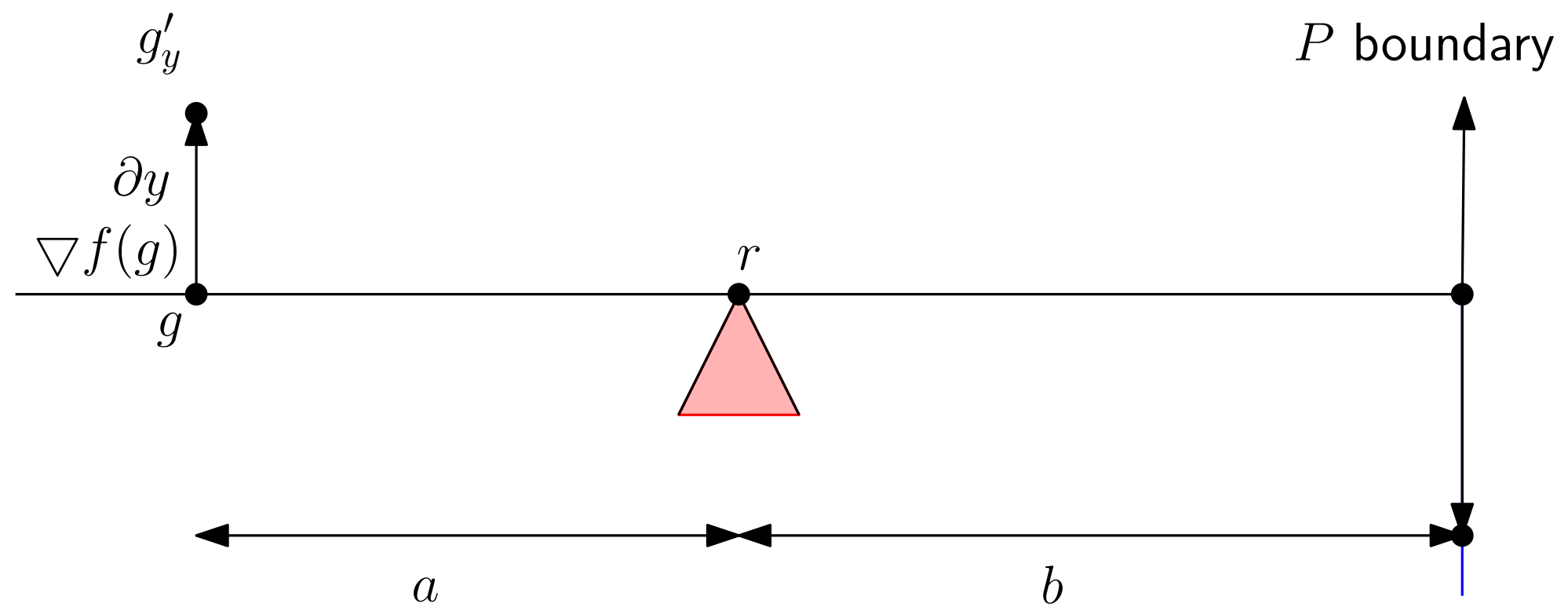


All heuristics

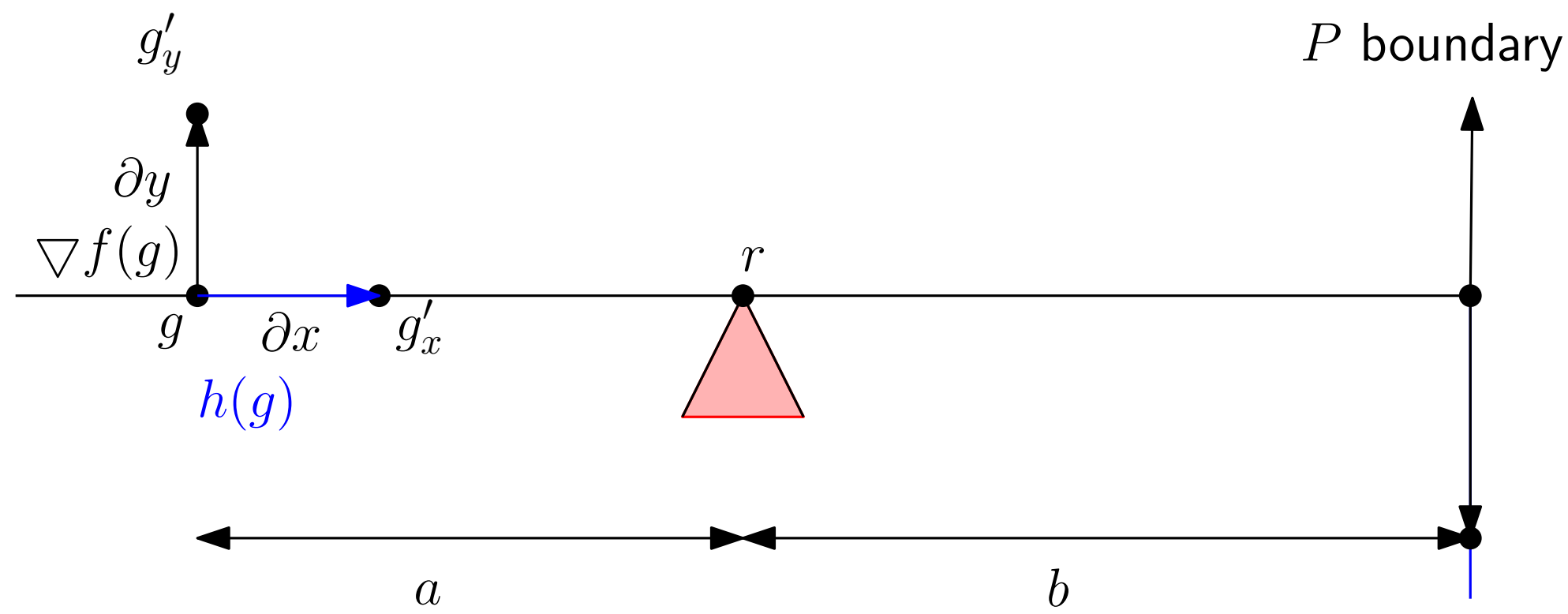


No momentum

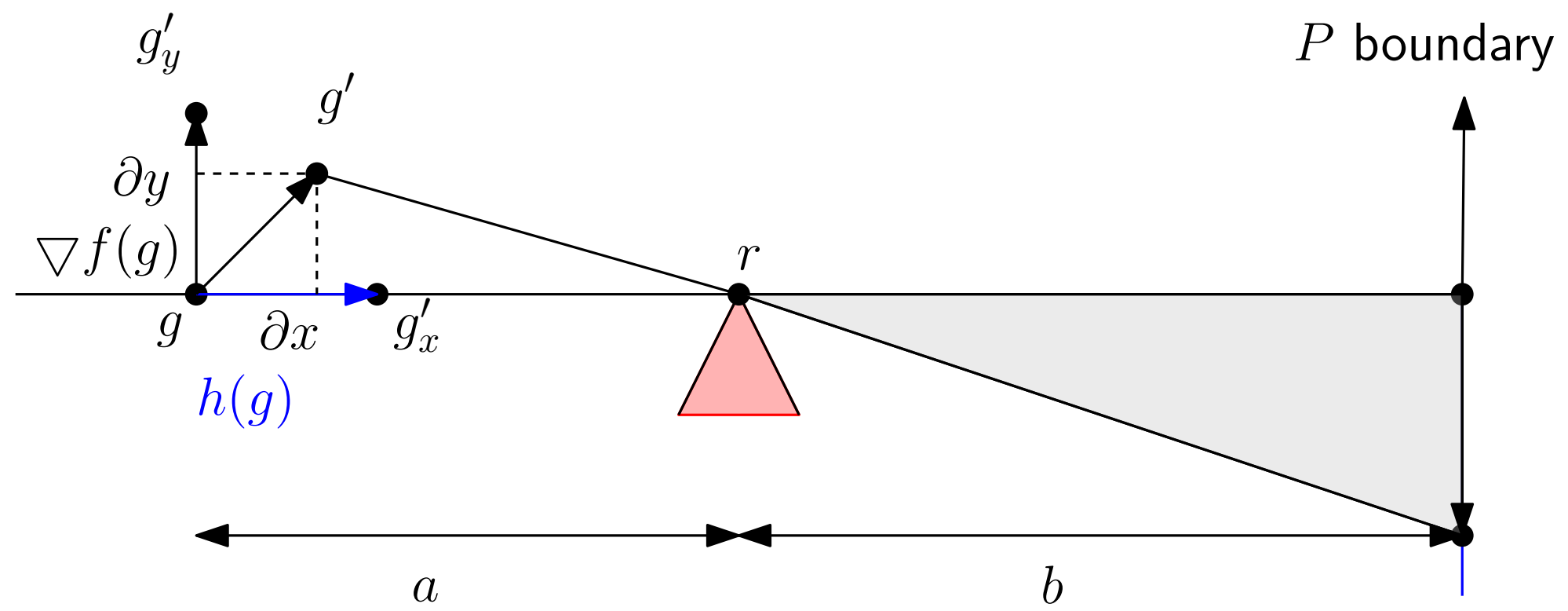
# Heuristics: Pull towards reflex vertex



# Heuristics: Pull towards reflex vertex



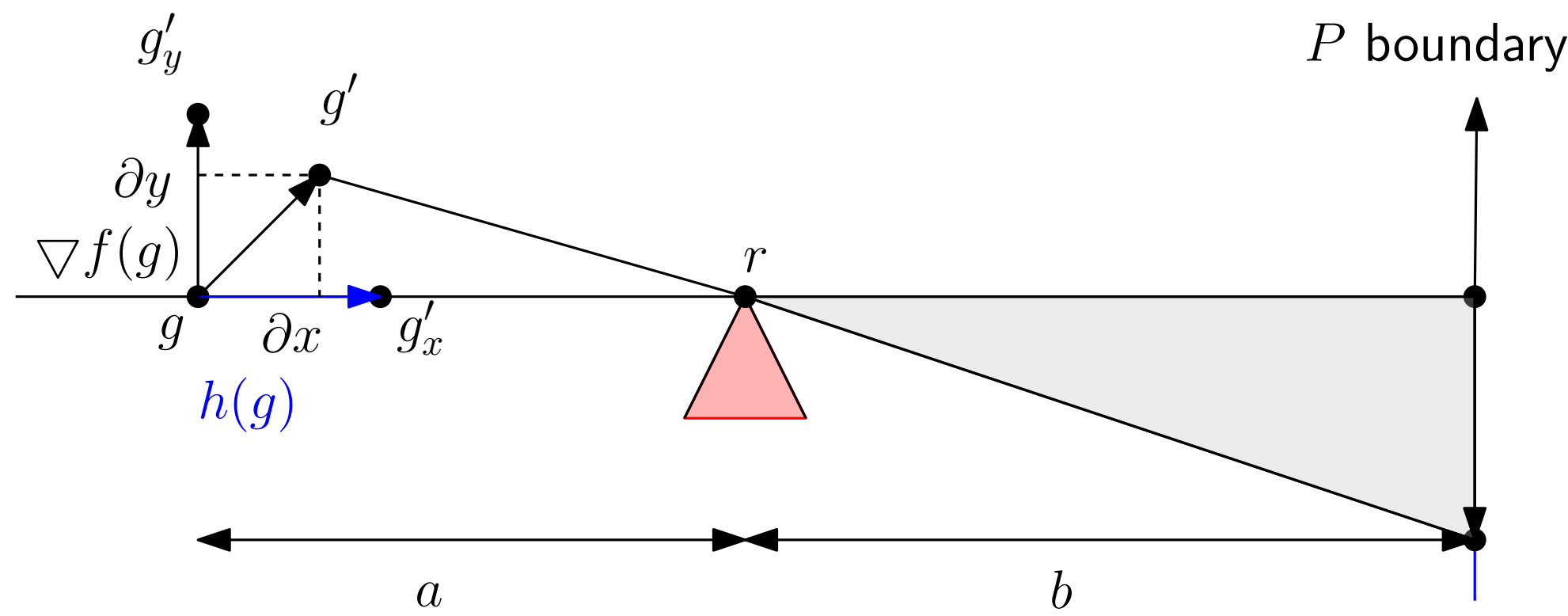
# Heuristics: Pull towards reflex vertex



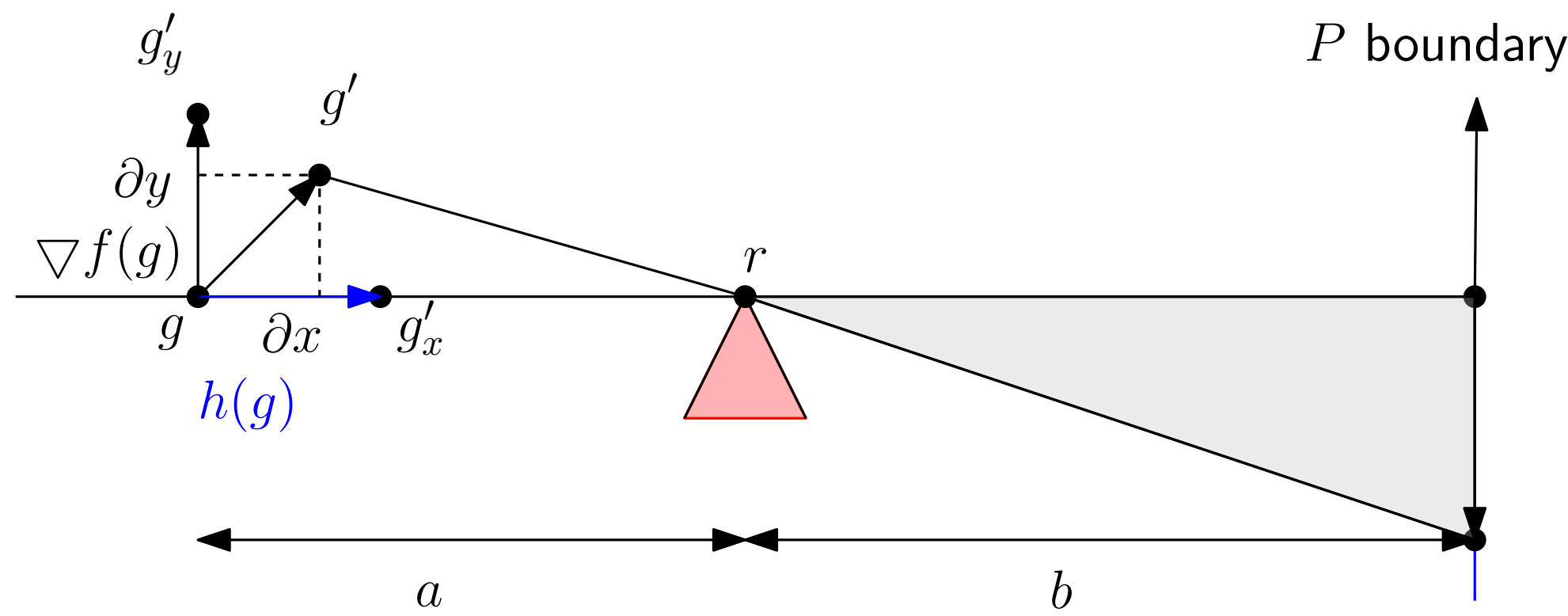


# Heuristics: Pull towards reflex vertex

$$h(g) = \nabla || \nabla f(g) ||$$

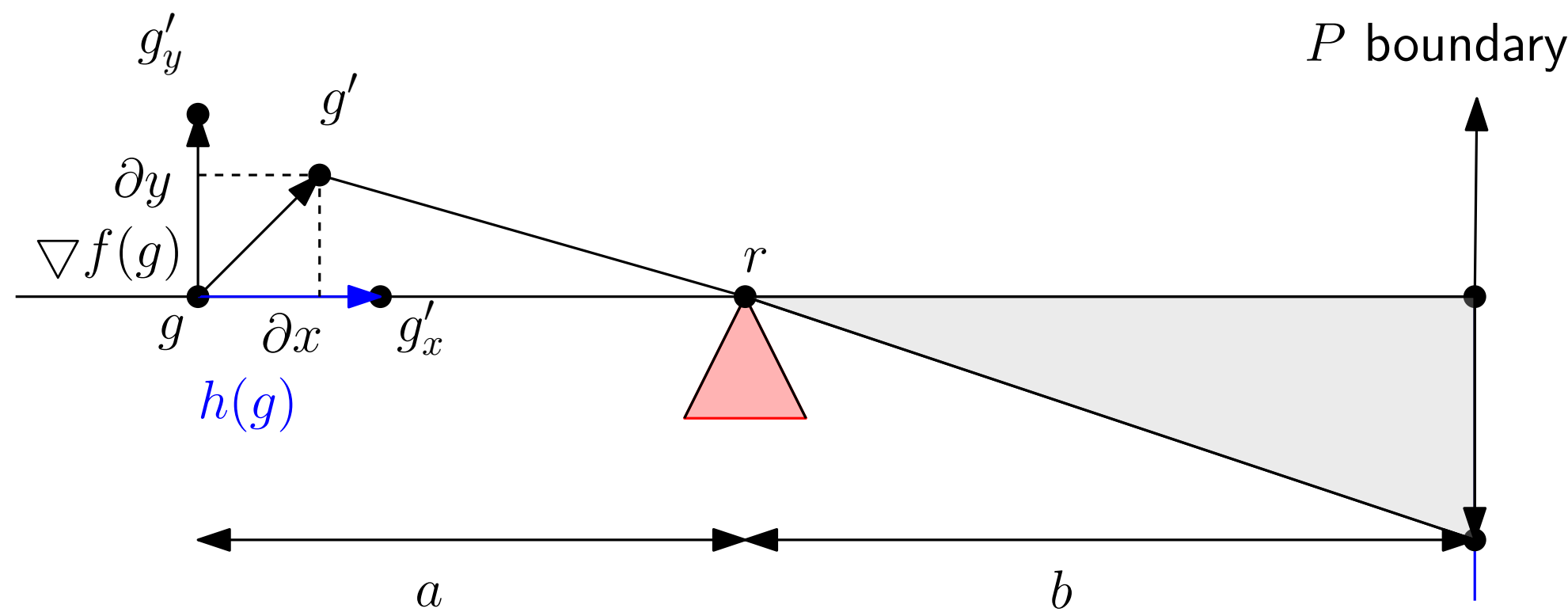


# Heuristics: Pull towards reflex vertex



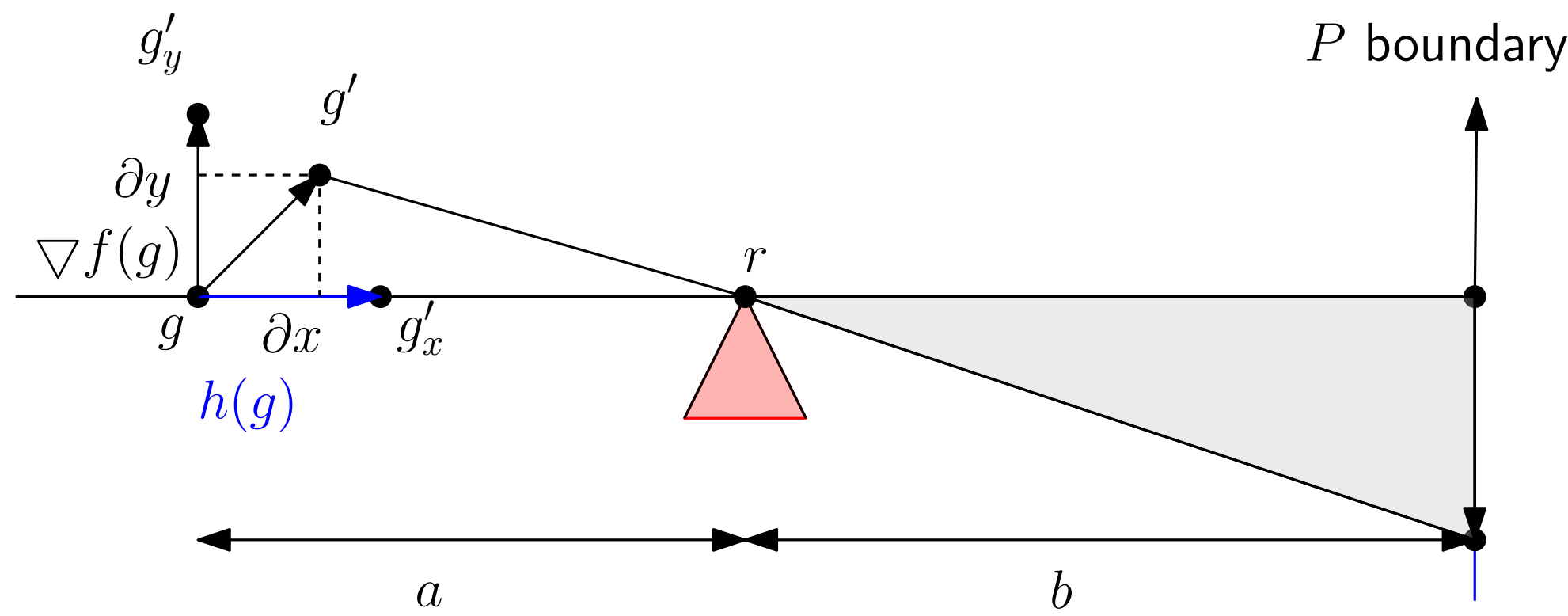
$$h(g) = \nabla || \nabla f(g) ||$$
$$h(g) = \left( \frac{\partial \nabla f(g)}{\partial x}, \frac{\partial \nabla f(g)}{\partial y} \right)^T$$

# Heuristics: Pull towards reflex vertex



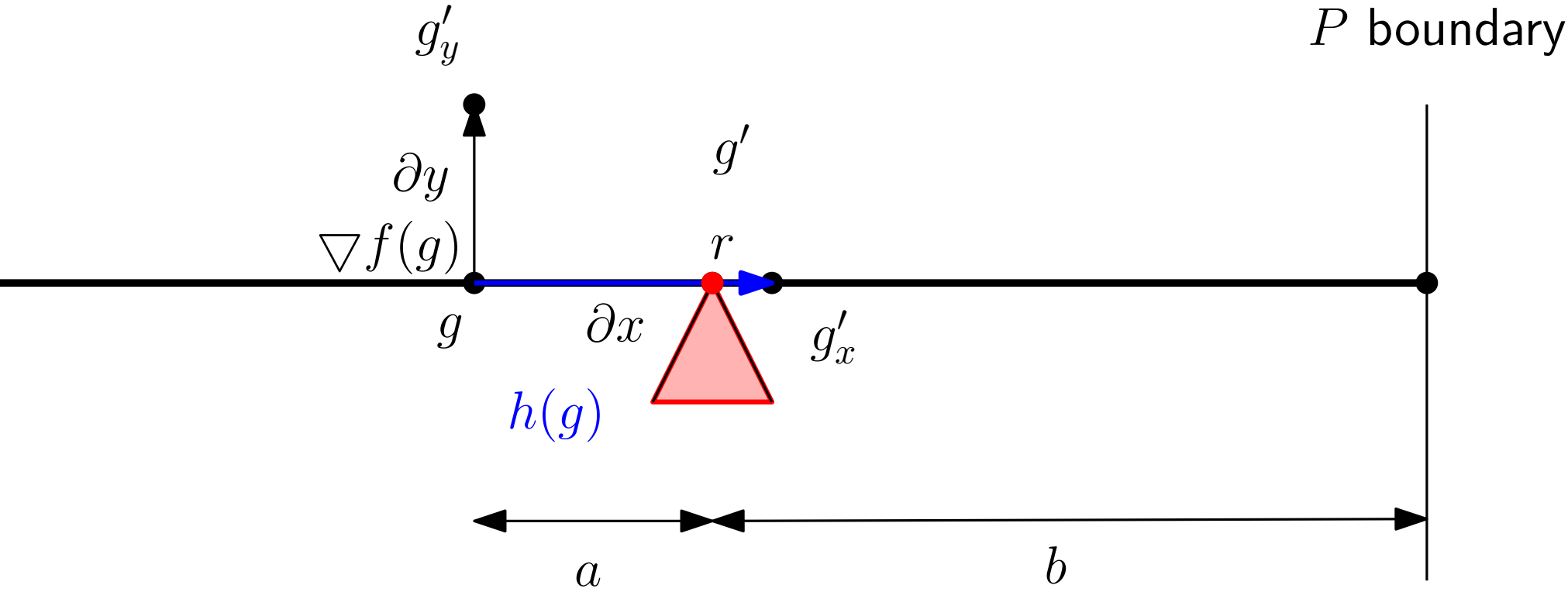
$$h(g) = \nabla || \nabla f(g) ||$$
$$h(g) = \left( \frac{\partial \nabla f(g)}{\partial x}, \frac{\partial \nabla f(g)}{\partial y} \right)^{\top}$$
$$h(g) = \left( \frac{-b^2}{2a^3}, 0 \right)^{\top}$$

# Heuristics: Pull towards reflex vertex



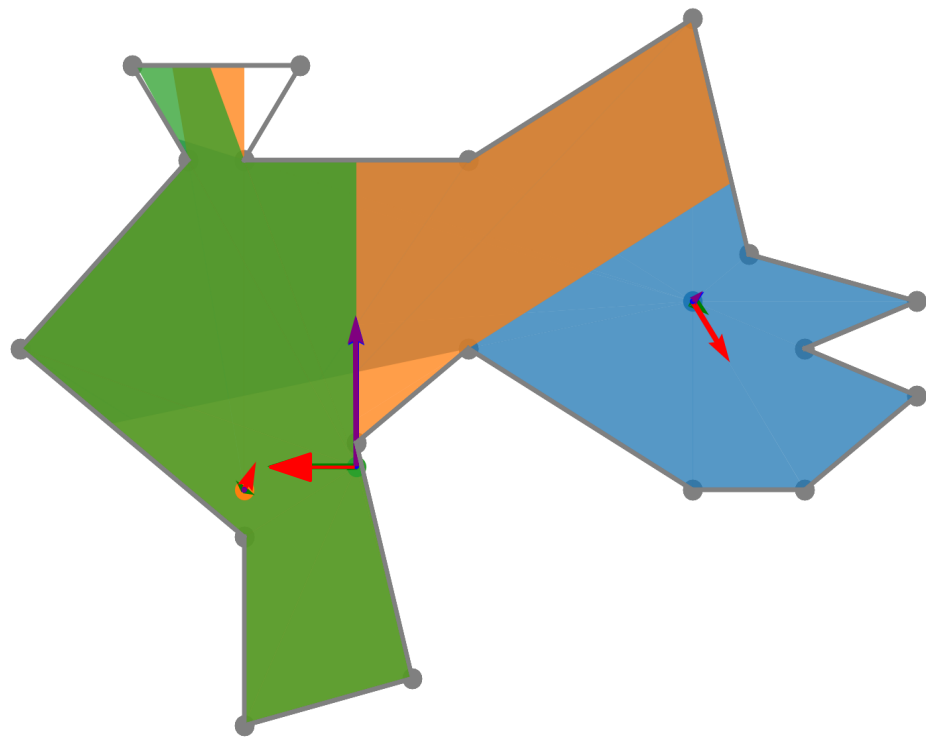
$$h(g) = \nabla || \nabla f(g) ||$$
$$h(g) = \left( \frac{\partial \nabla f(g)}{\partial x}, \frac{\partial \nabla f(g)}{\partial y} \right)^{\top}$$
$$h(g) = \left( \frac{-b^2}{2a^3}, 0 \right)^{\top}$$
$$g' = g + \alpha(\nabla f(g) + h(g))$$

# Heuristics: Pull towards reflex vertex

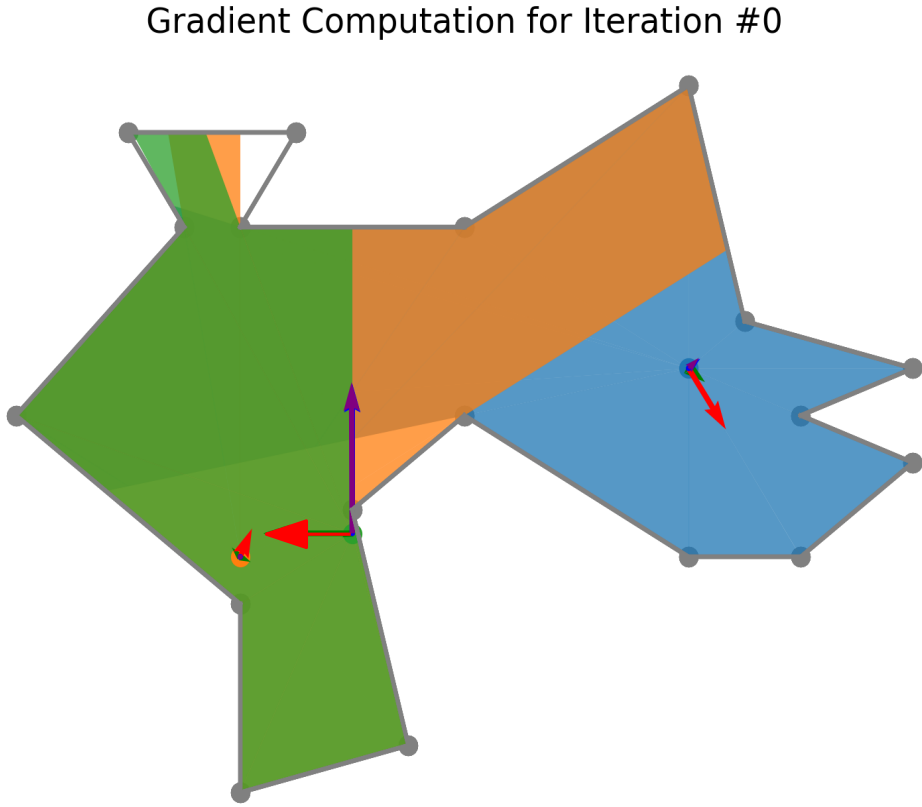


# Heuristics: Pull towards reflex vertex

Gradient Computation for Iteration #0

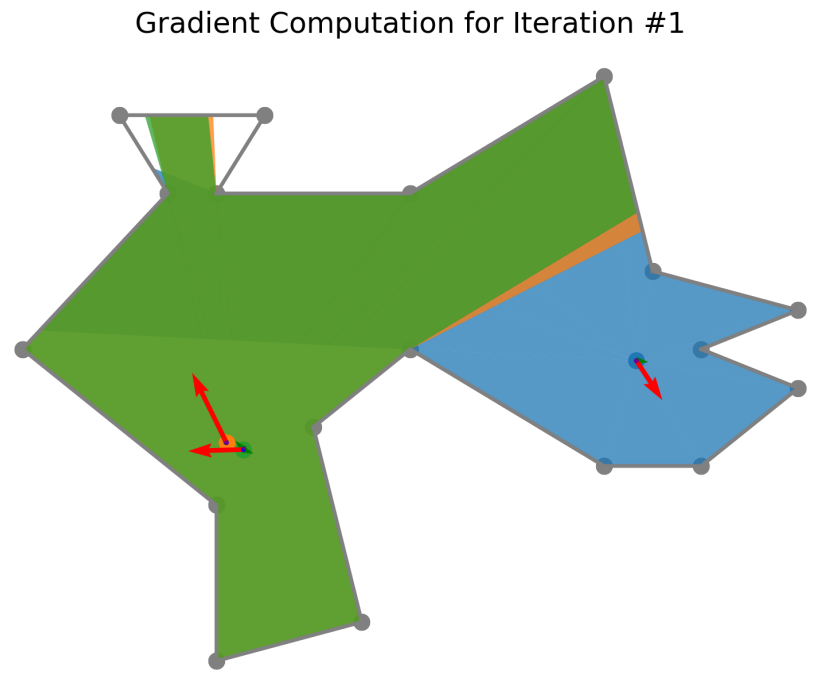
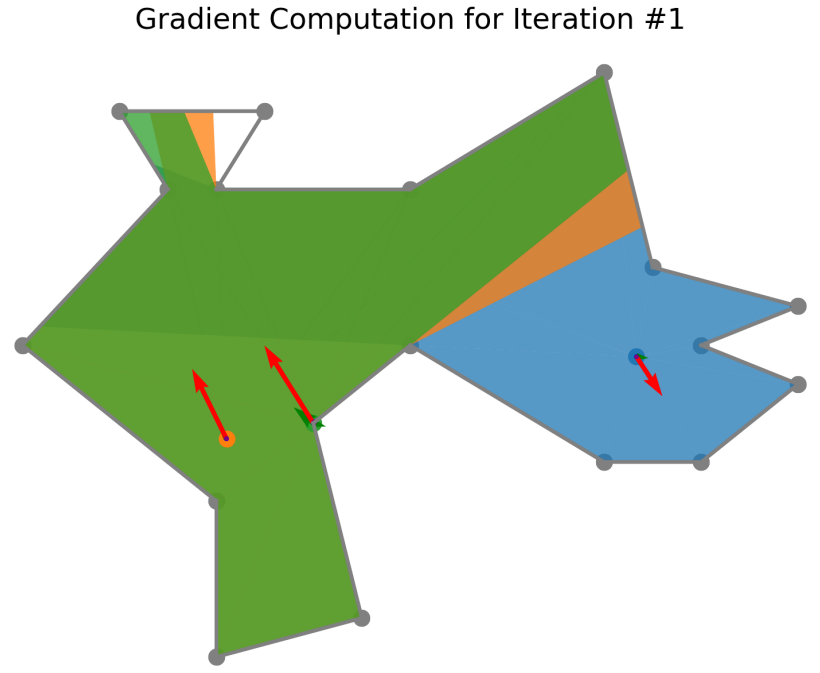


# Heuristics: Pull towards reflex vertex

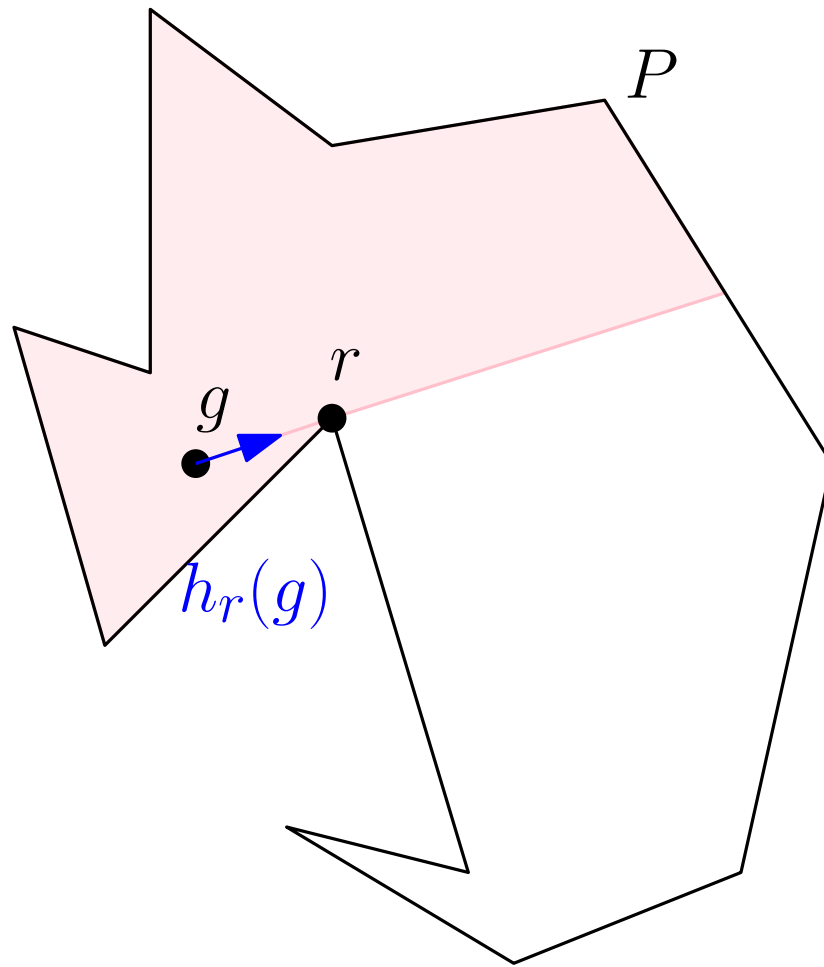


with pull

without pull

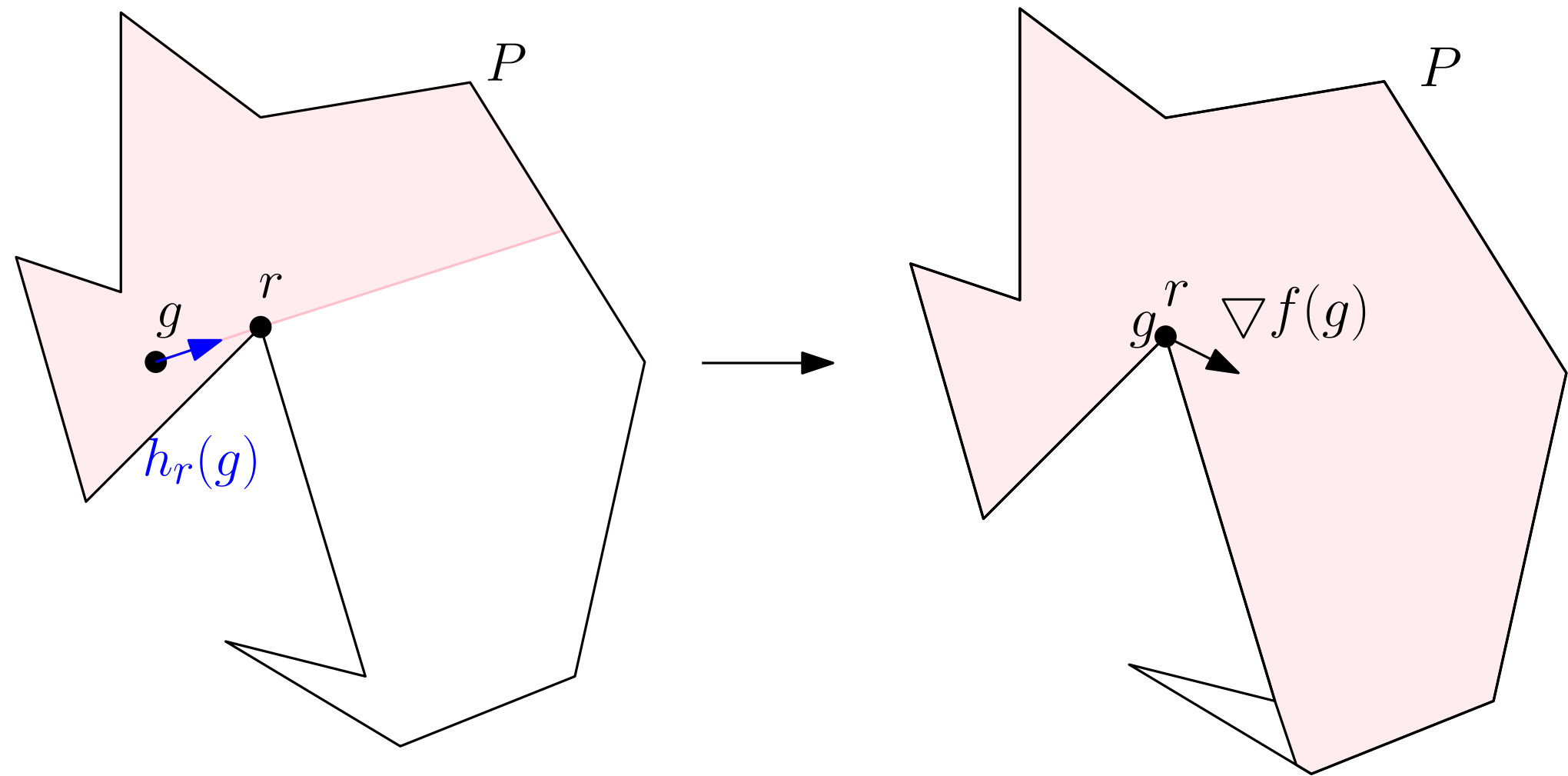


# Heuristics: Reflex area

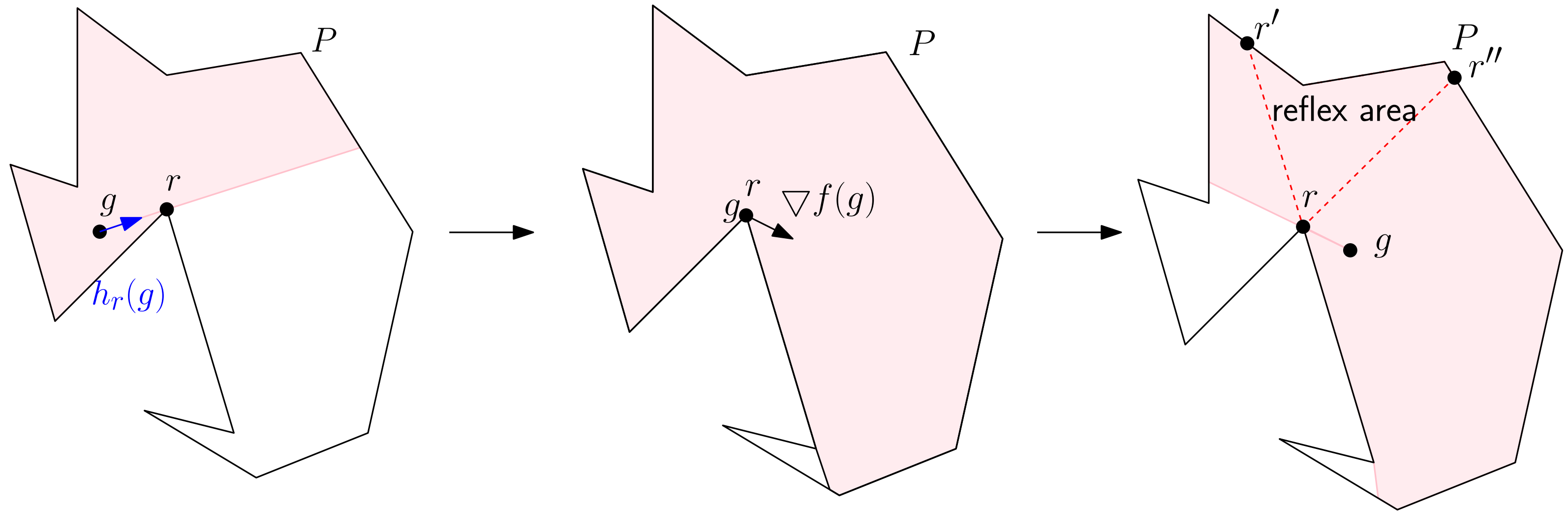




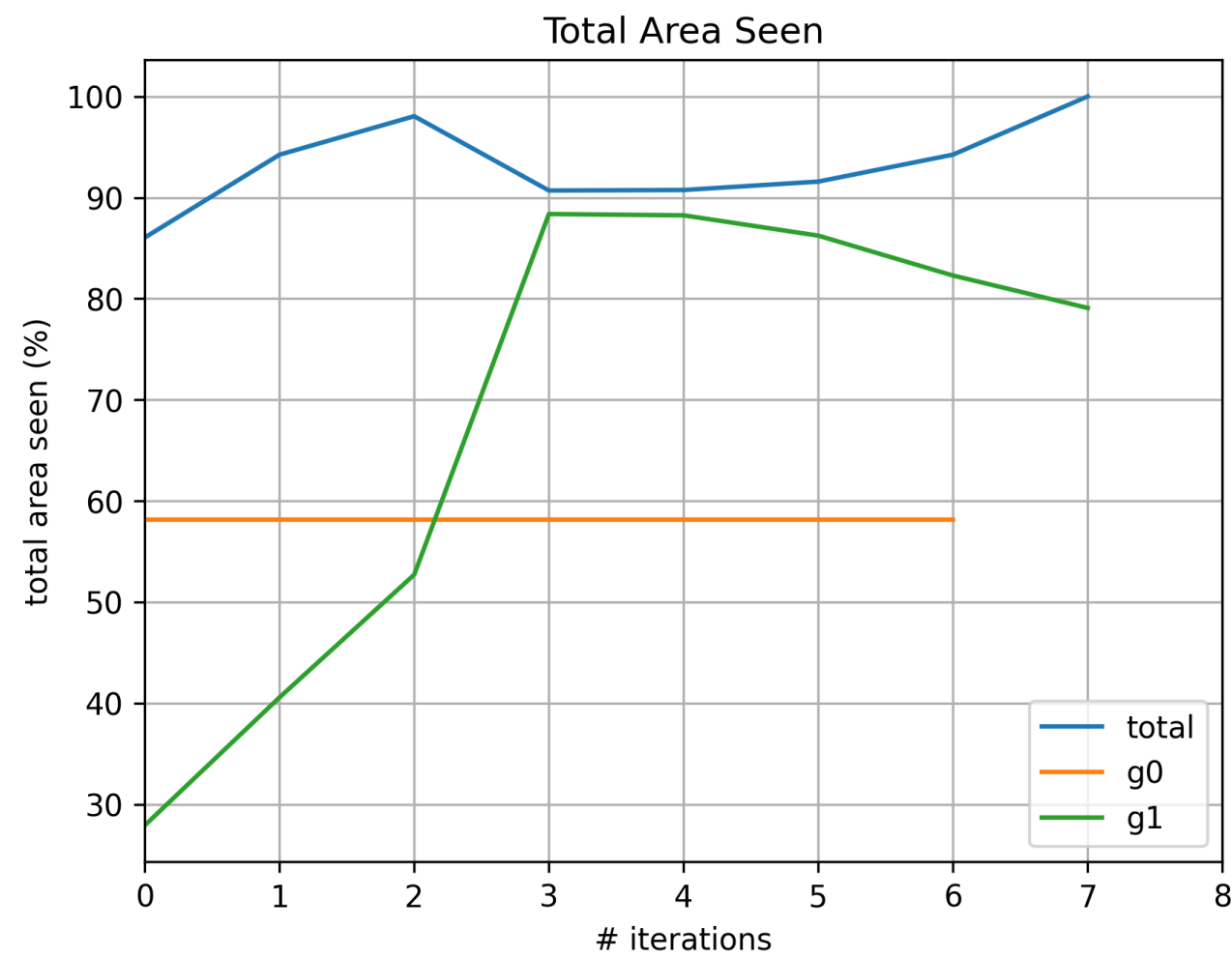
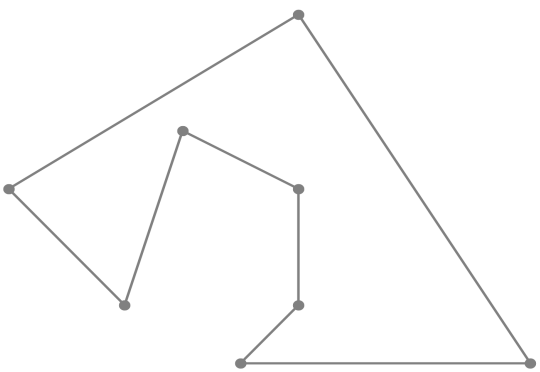
# Heuristics: Reflex area



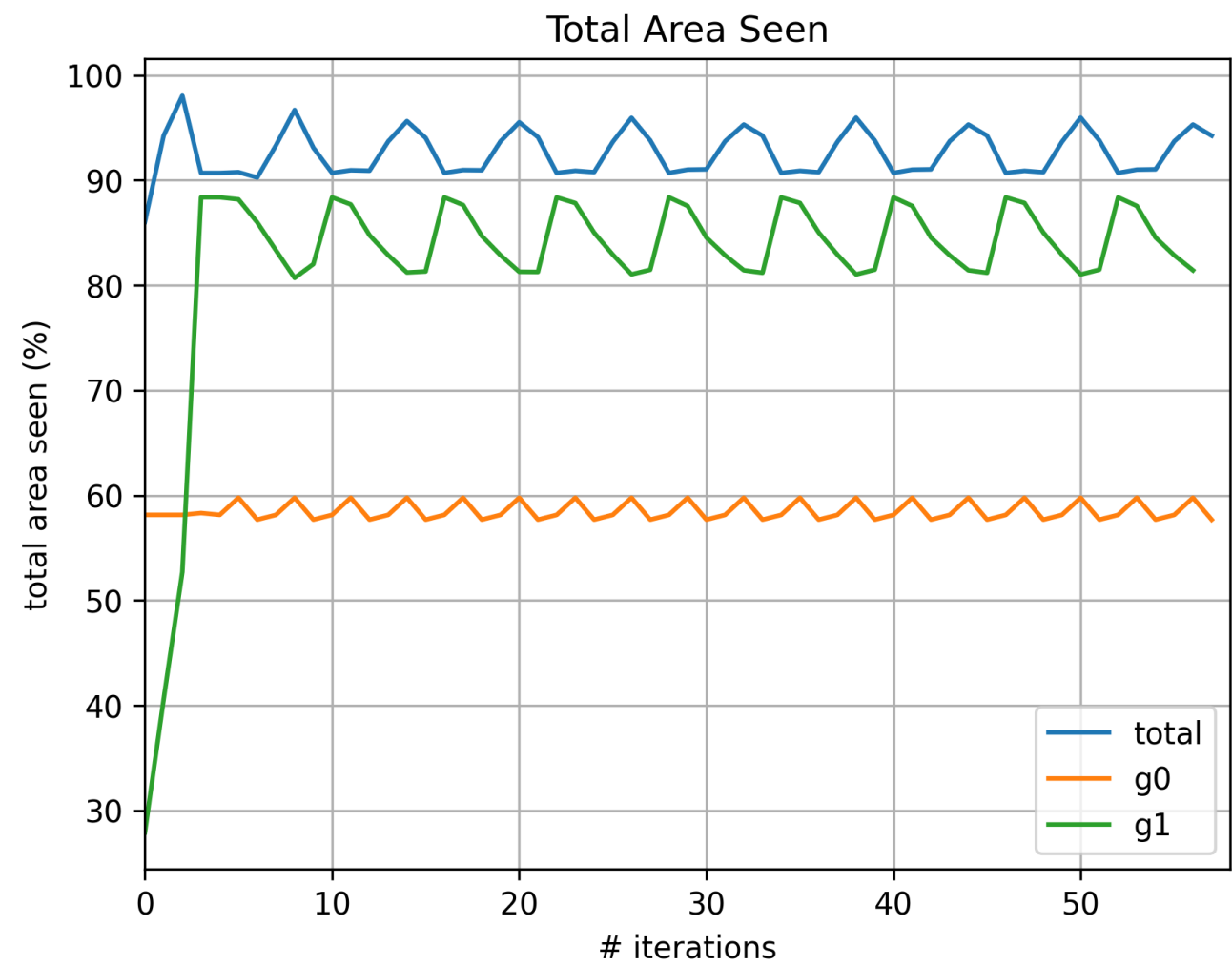
# Heuristics: Reflex area



# Heuristics: Reflex area

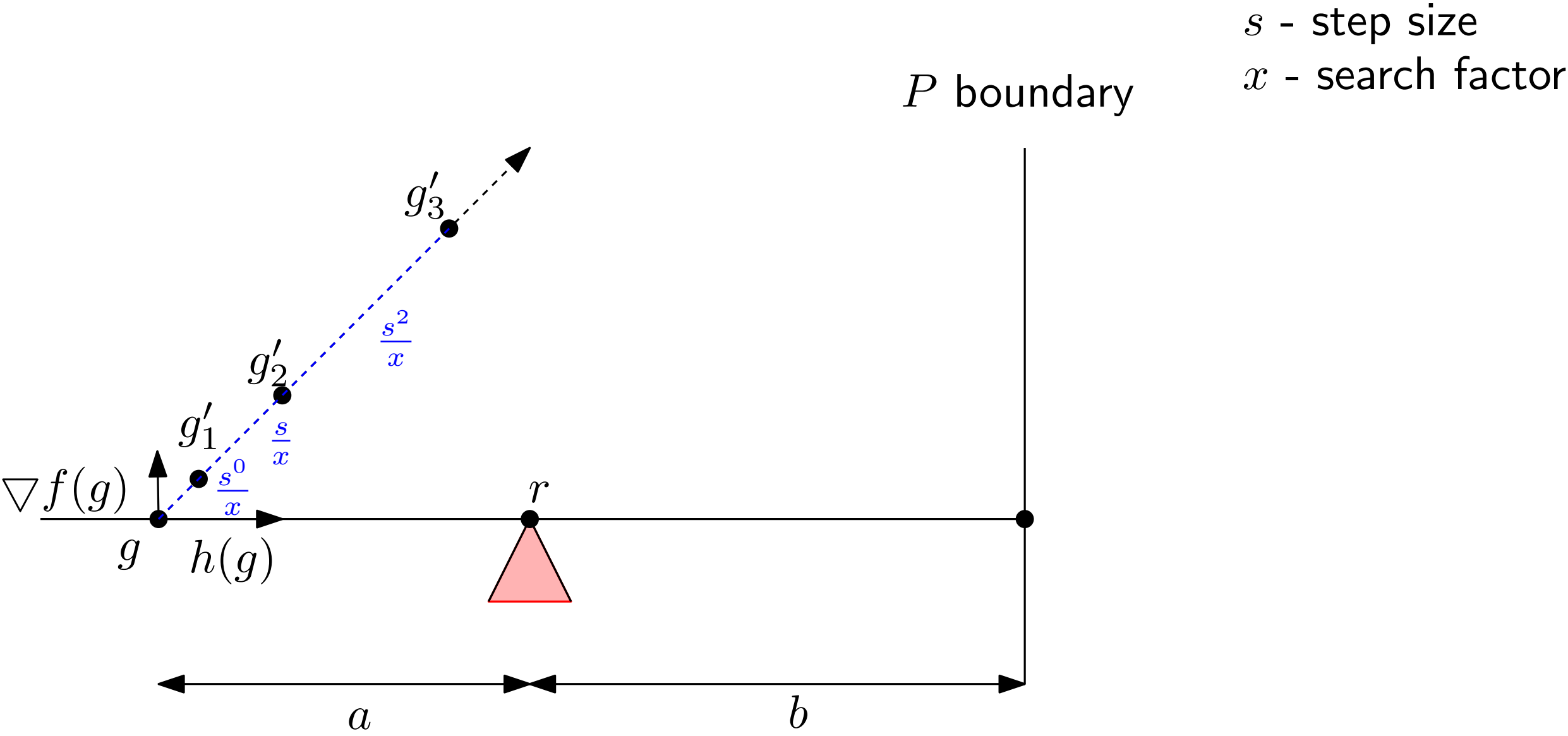


All heuristics

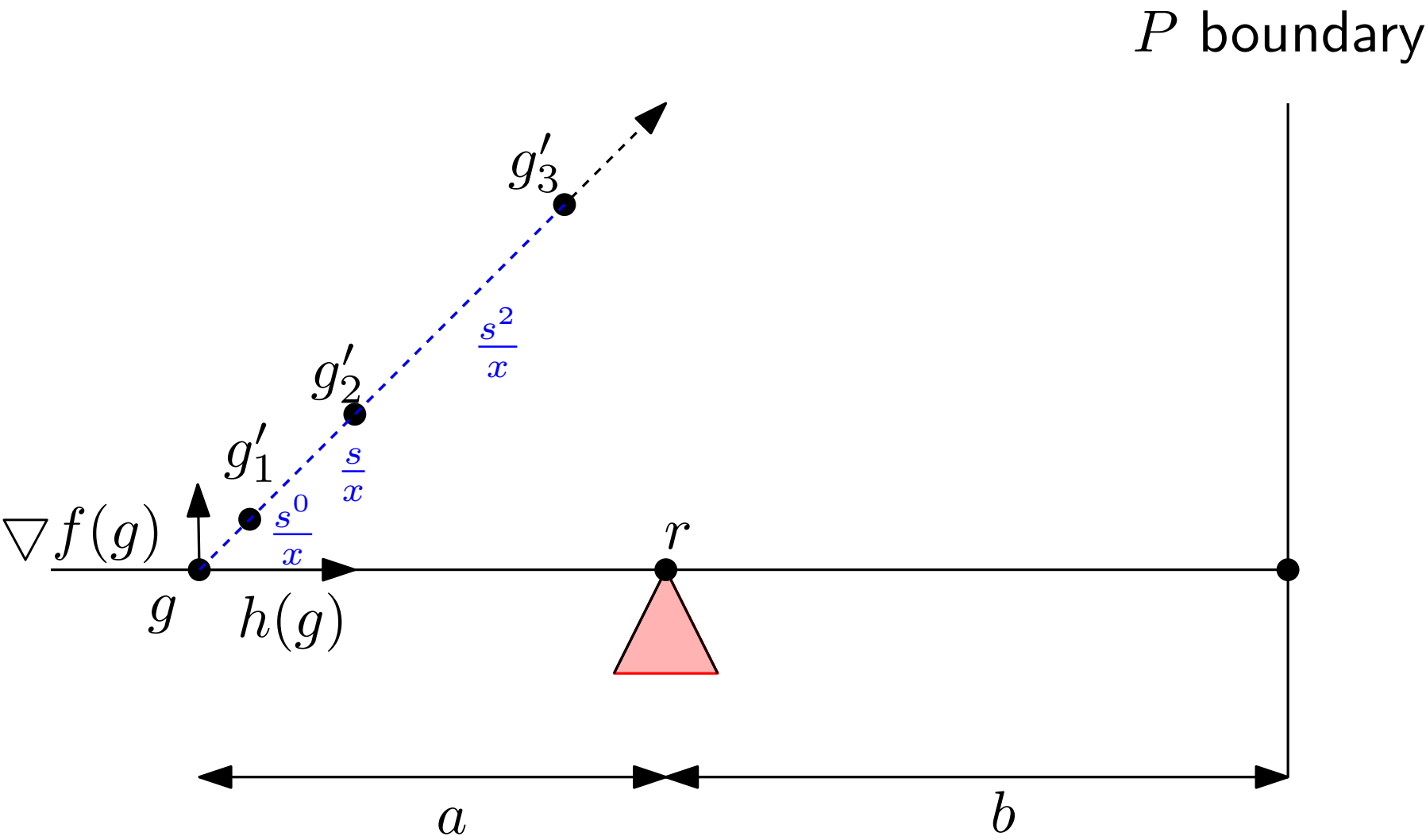


No reflex area

# Heuristics: Line Search



# Heuristics: Line Search



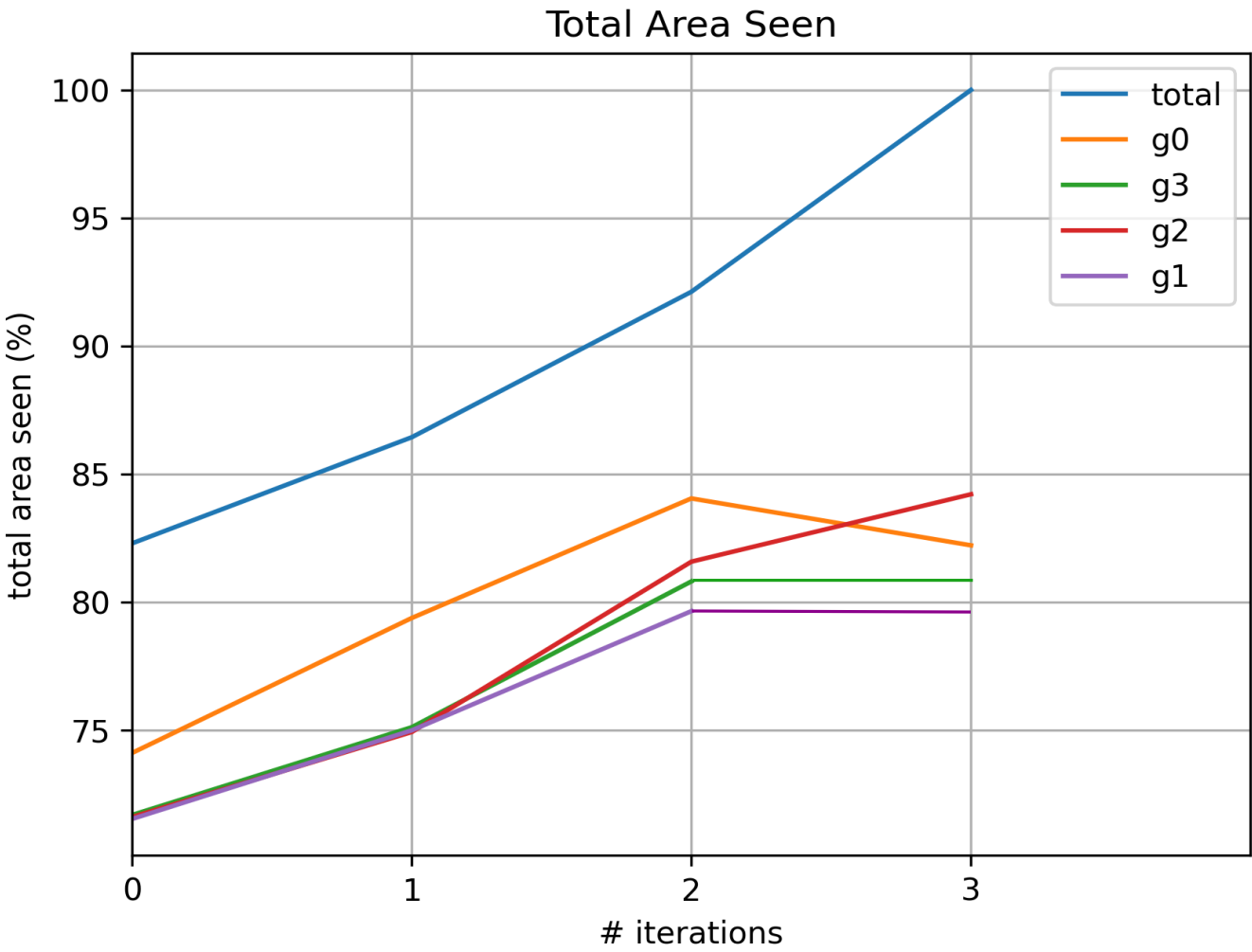
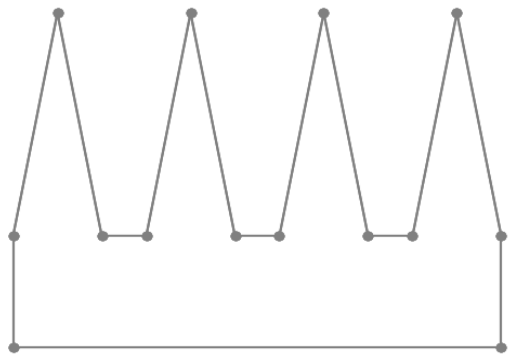
$s$  - step size  
 $x$  - search factor

$$g'_1 = g + \frac{1}{x} M(g)$$

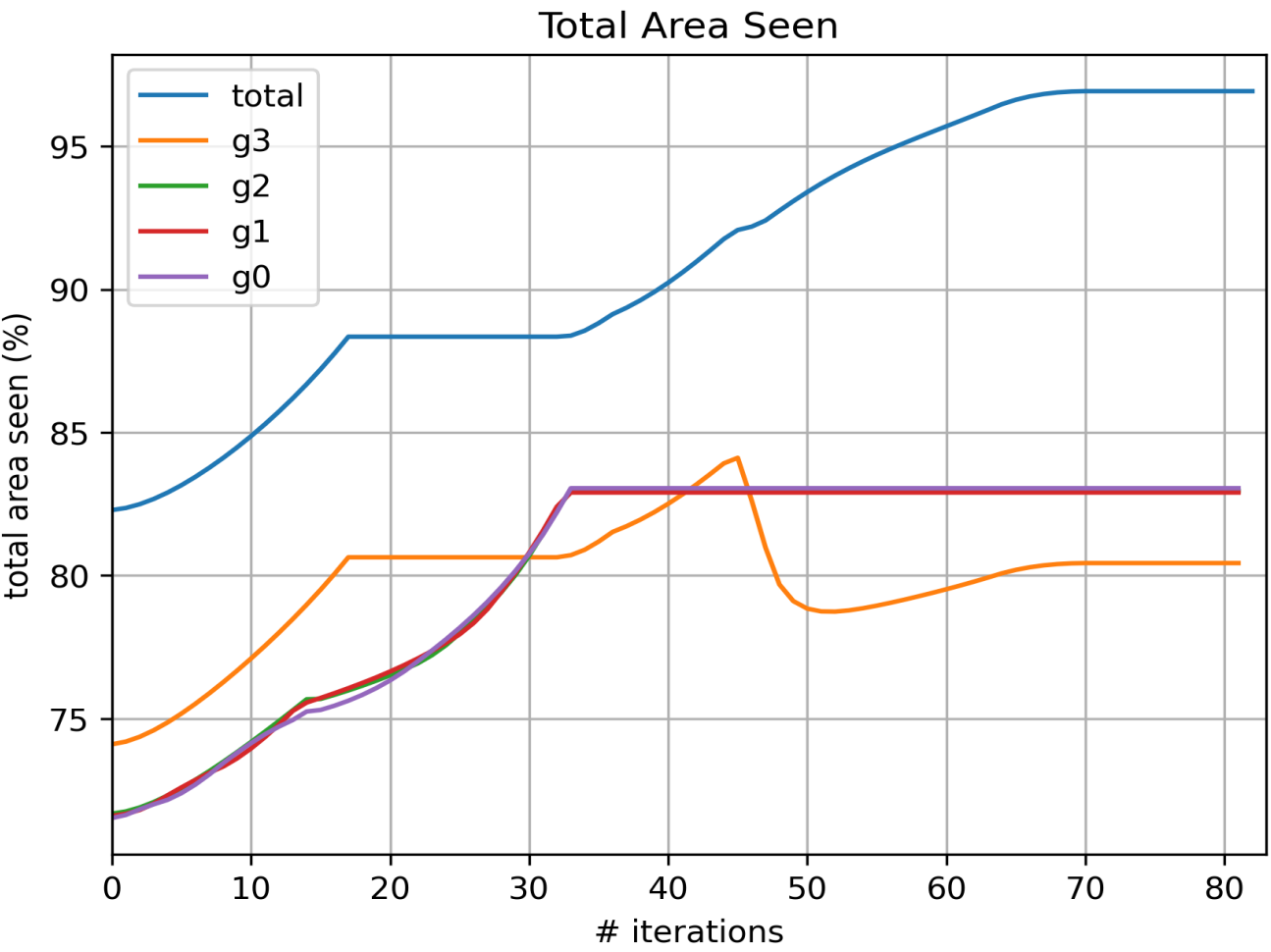
$$g'_2 = g + \frac{s}{x} M(g)$$

$$g'_3 = g + \frac{s^2}{x} M(g)$$

# Heuristics: Line Search

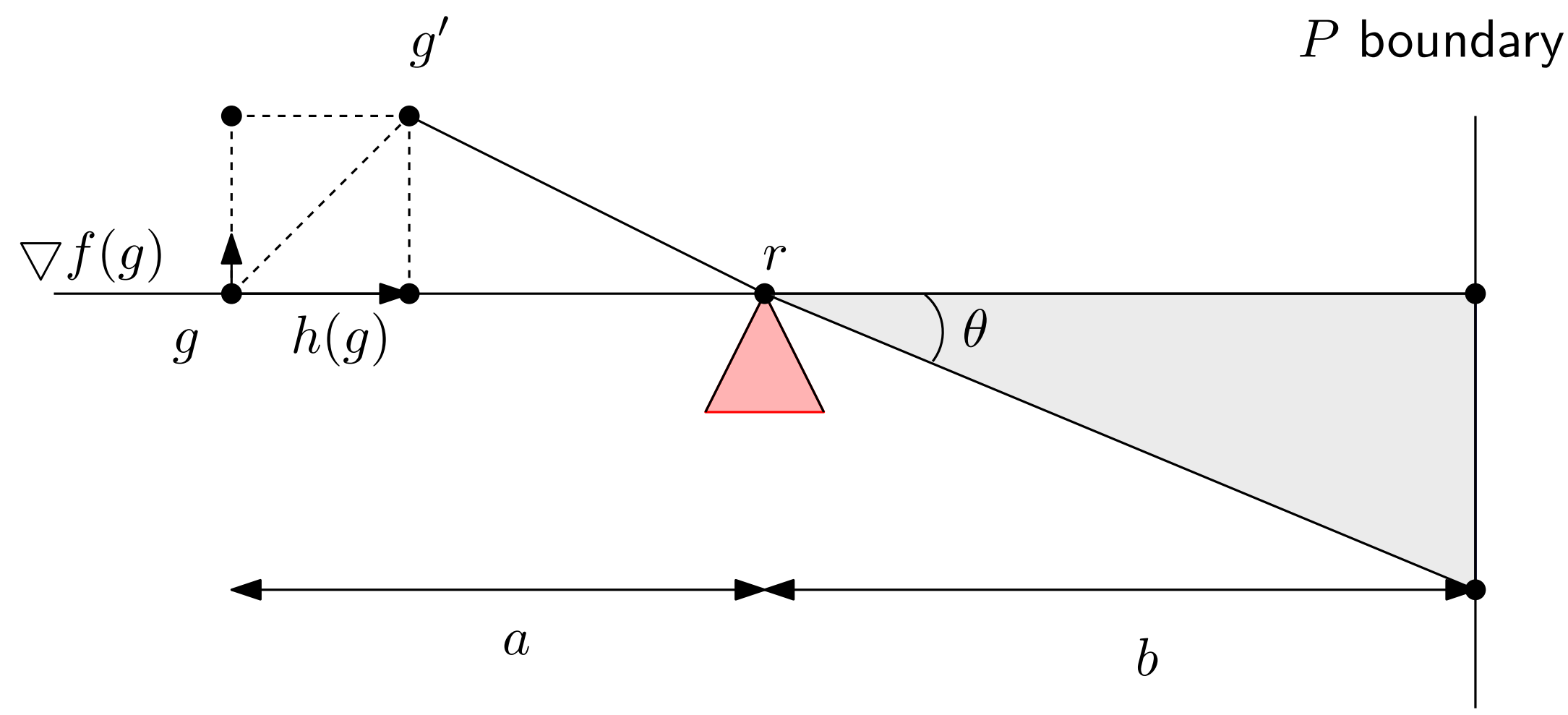


All heuristics



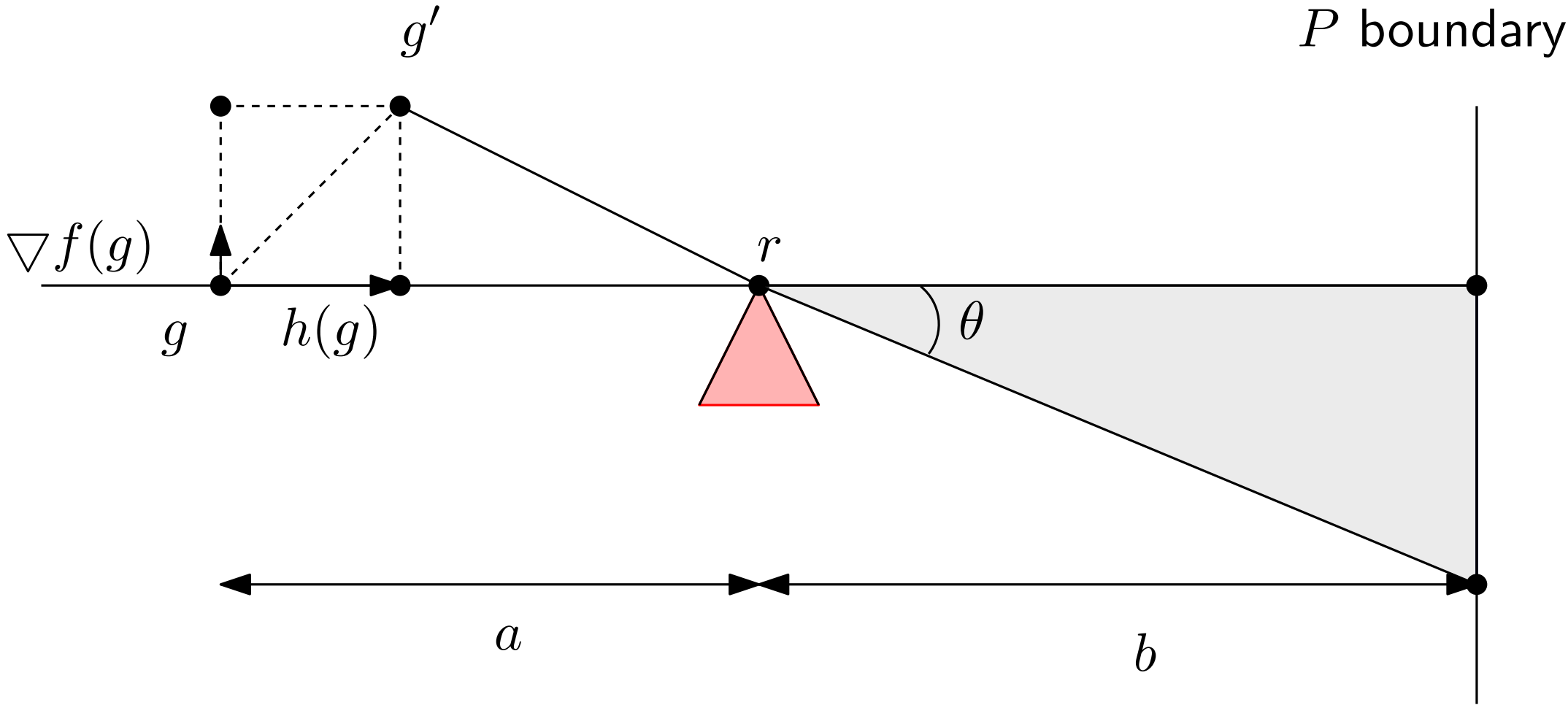
No line search

# Heuristics: Angle behind reflex vertex



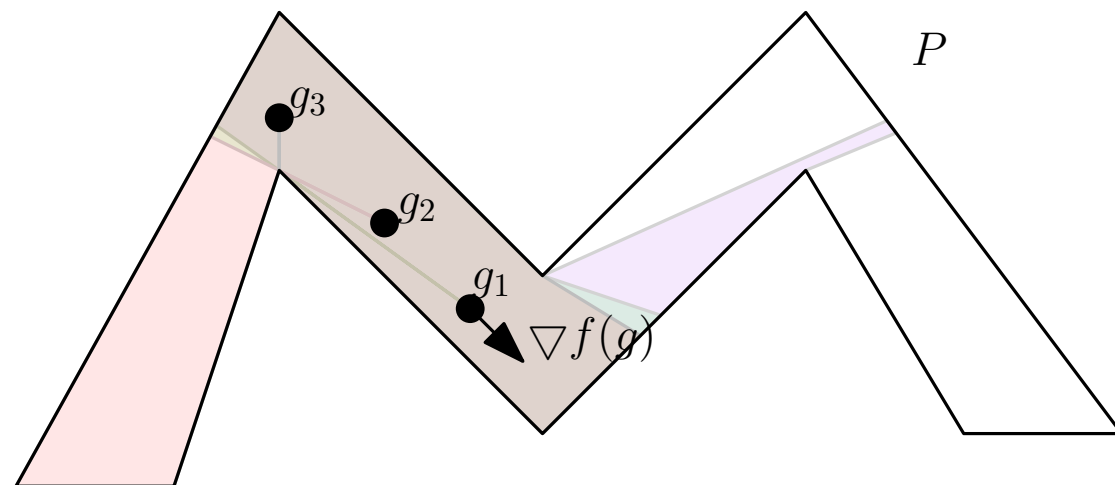
# Heuristics: Angle behind reflex vertex

$$g' = g + (\frac{\theta}{2\pi} + c)(\nabla f(g) + h(g))$$

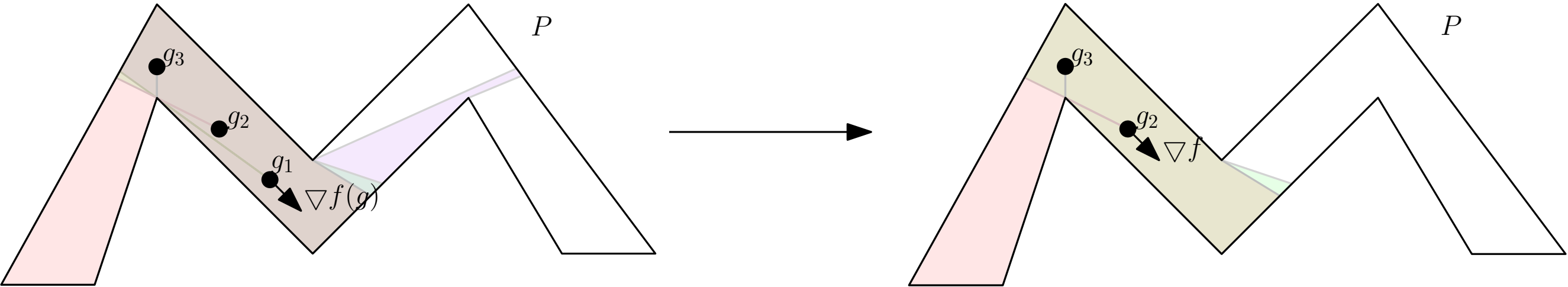




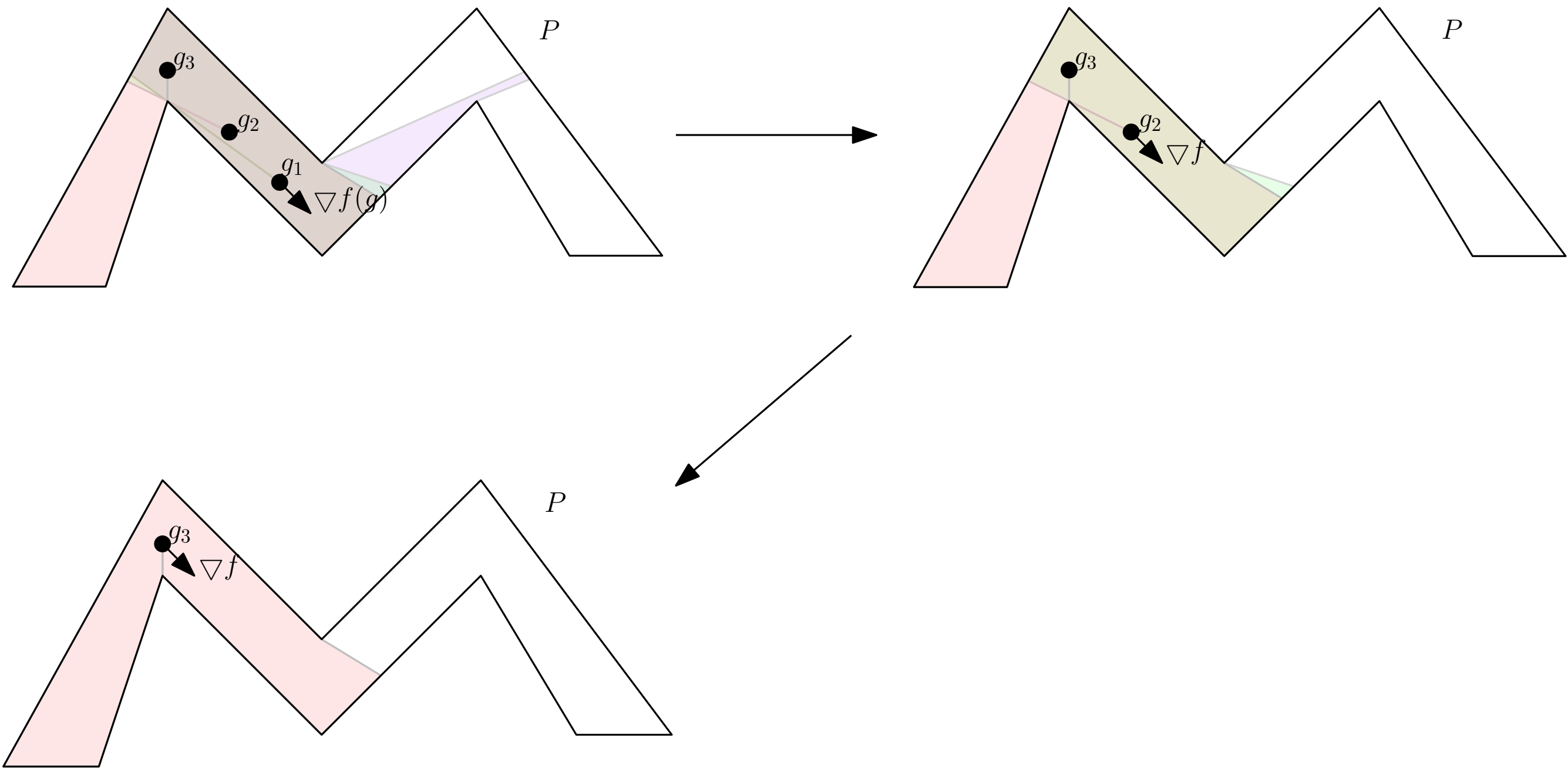
# Heuristics: Hidden movement



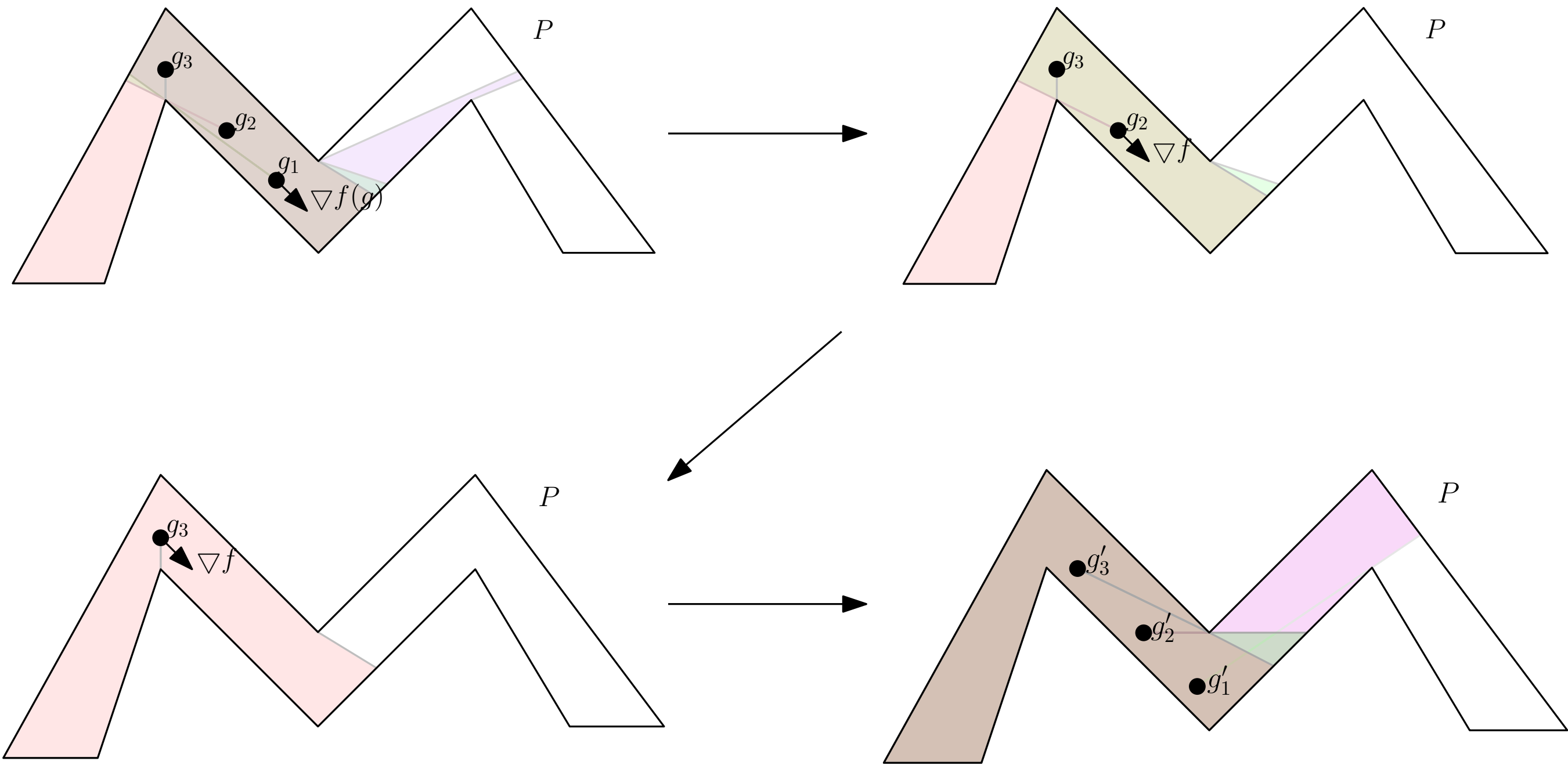
# Heuristics: Hidden movement



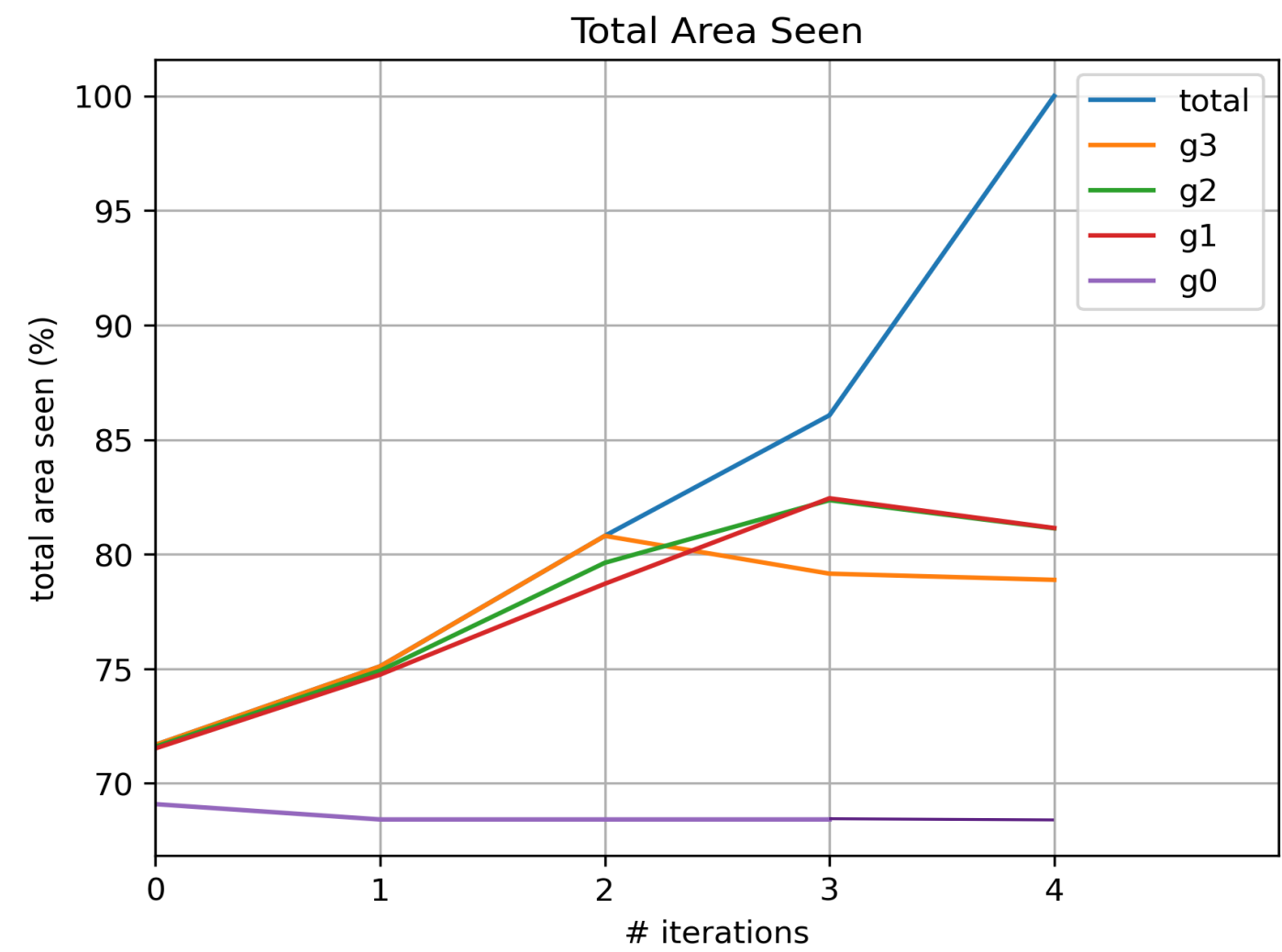
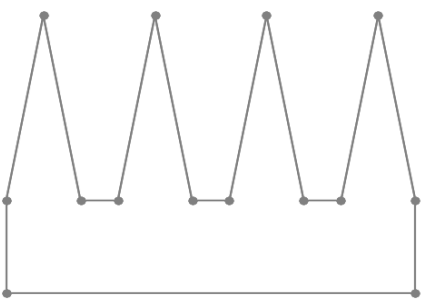
# Heuristics: Hidden movement



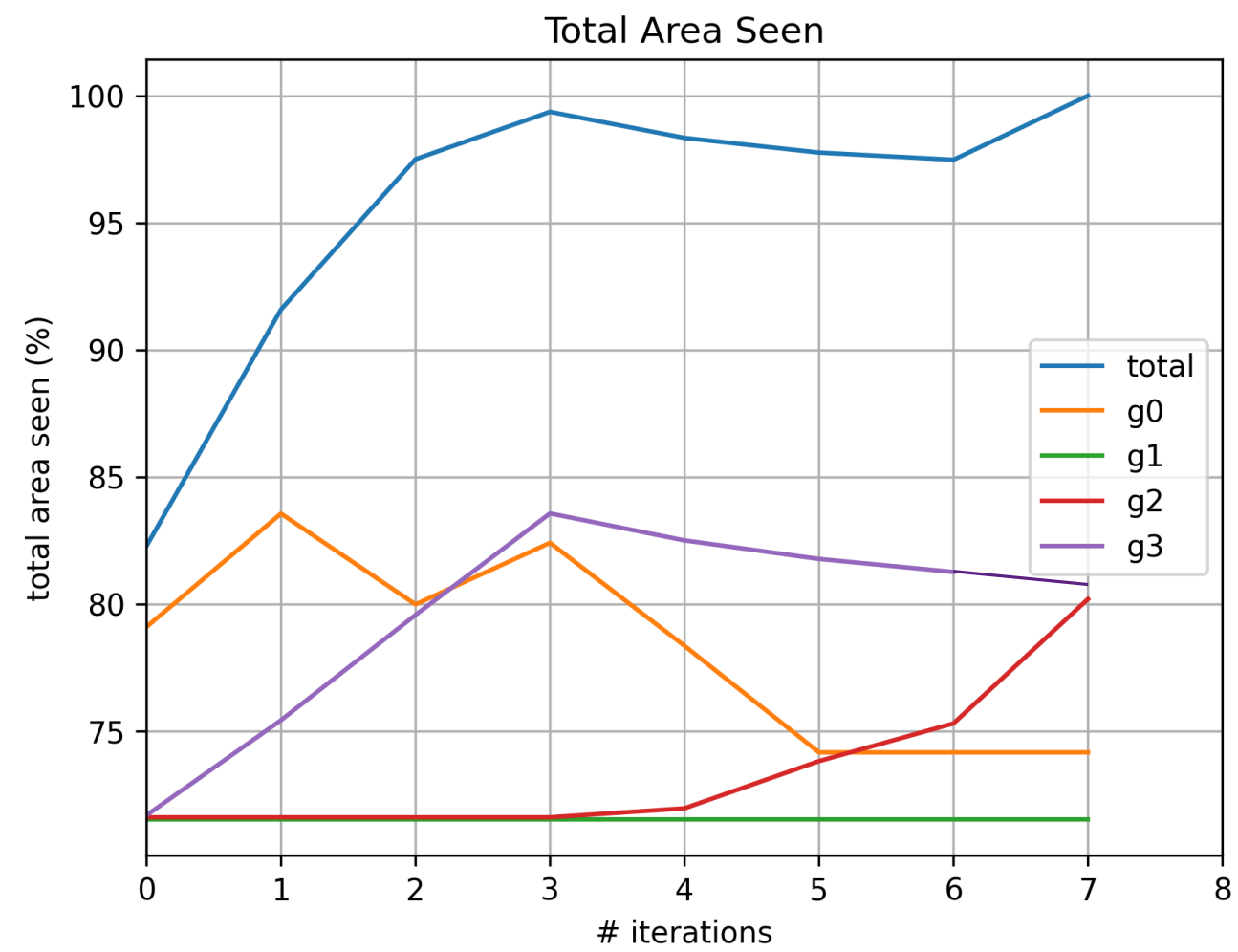
# Heuristics: Hidden movement



# Heuristics: Hidden movement

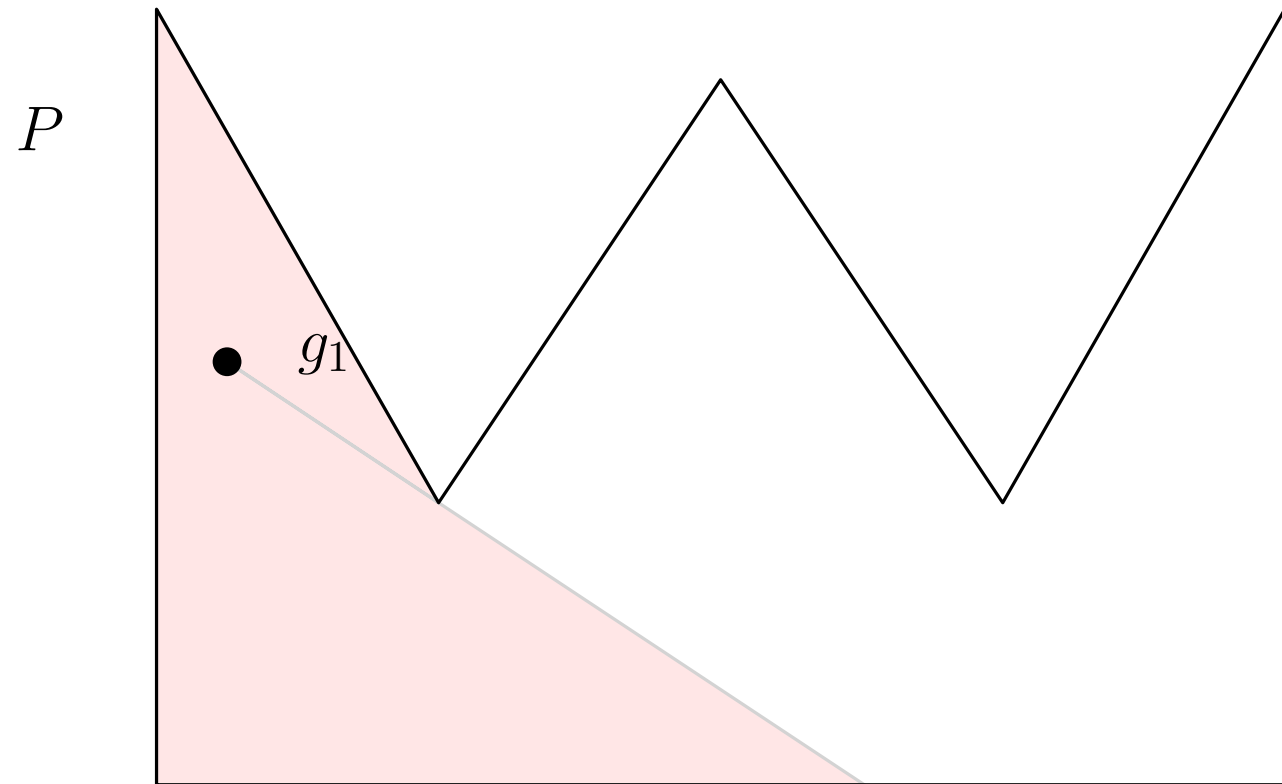


All heuristics

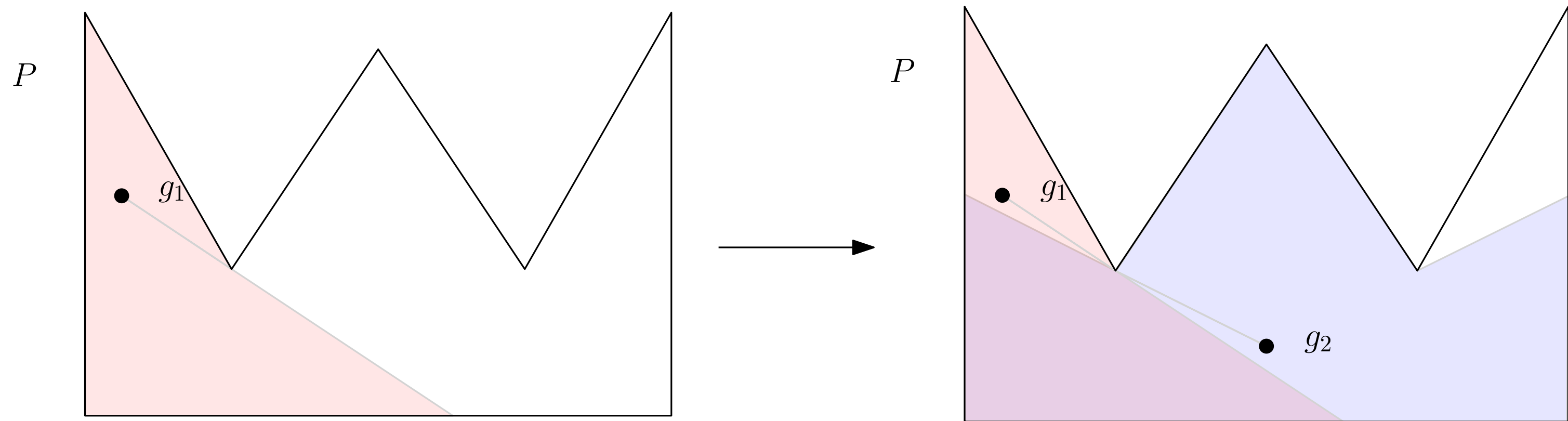


No hidden movement

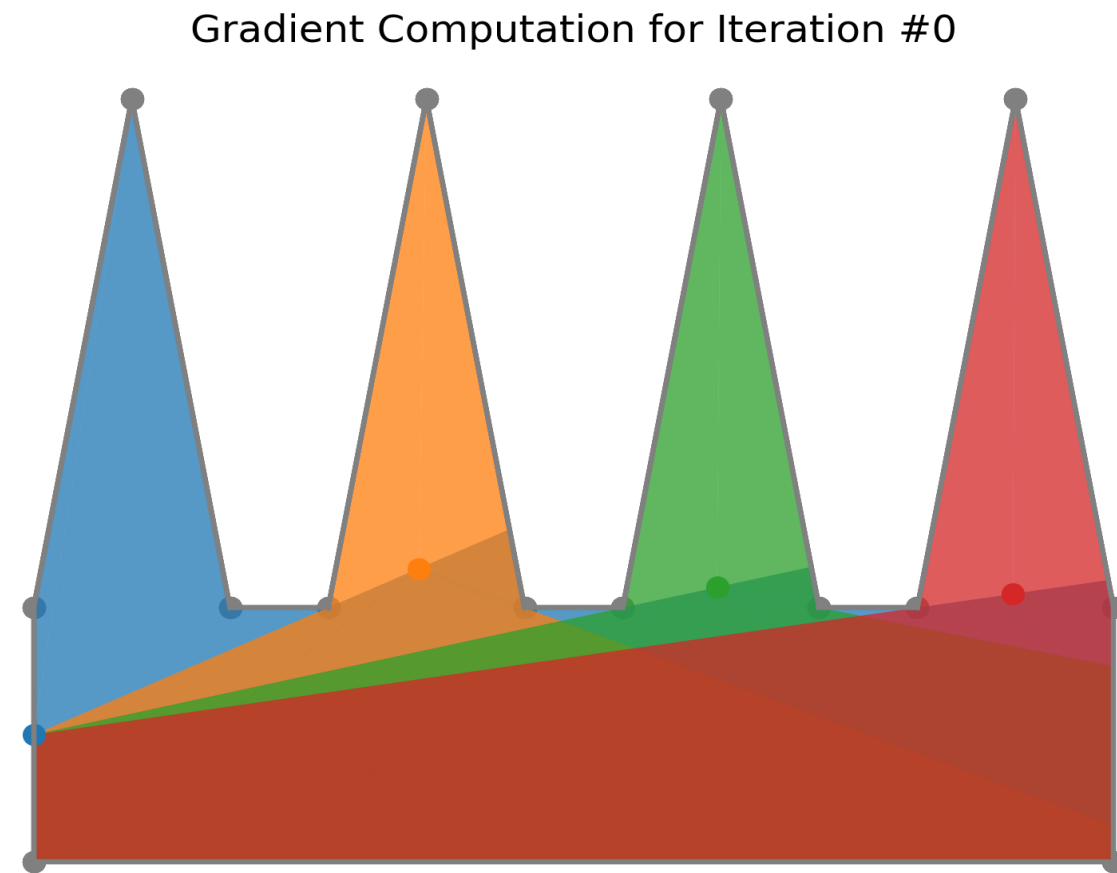
# Heuristics: Greedy initialisation



# Heuristics: Greedy initialisation

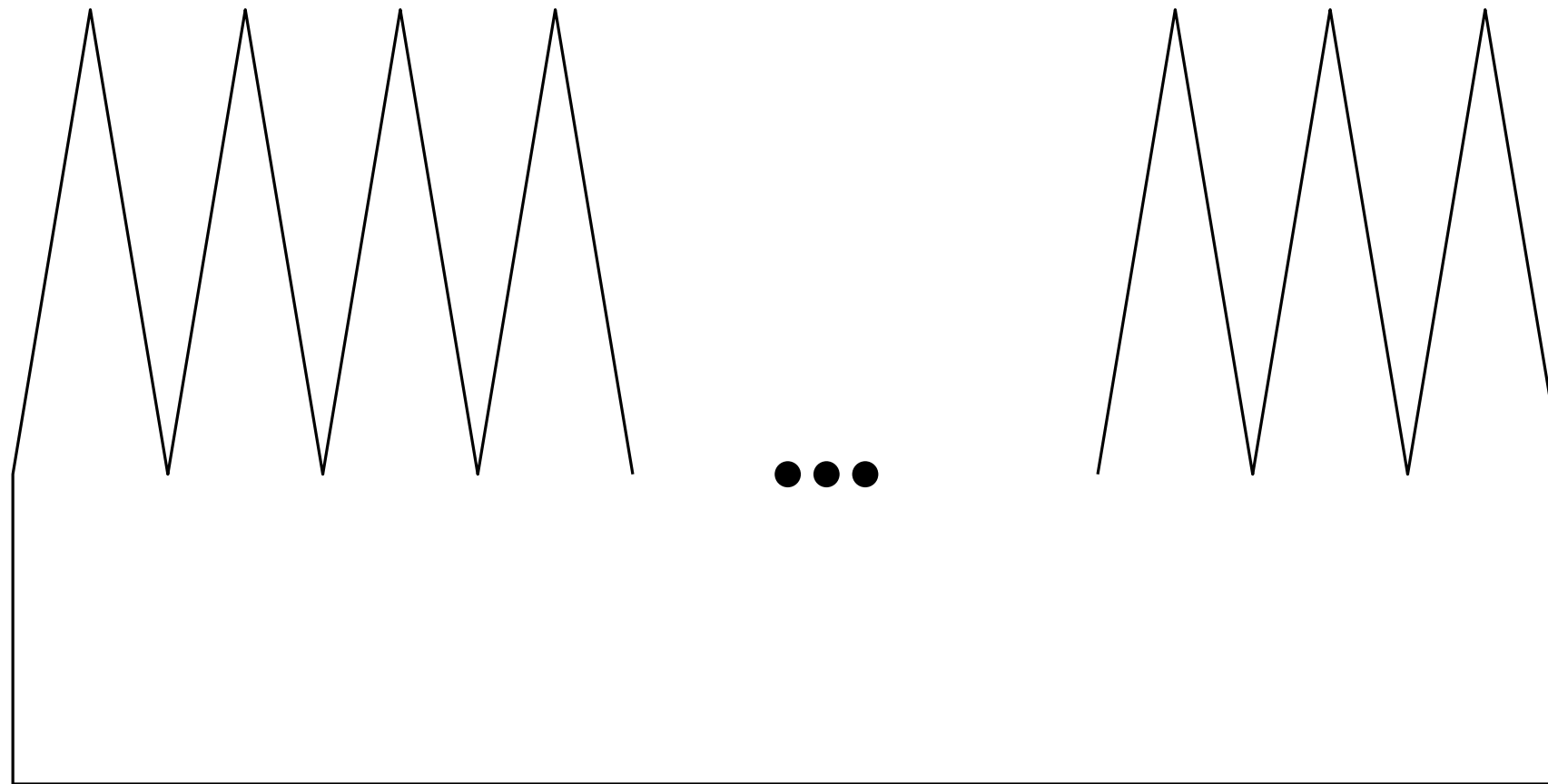


# Heuristics: Greedy initialisation



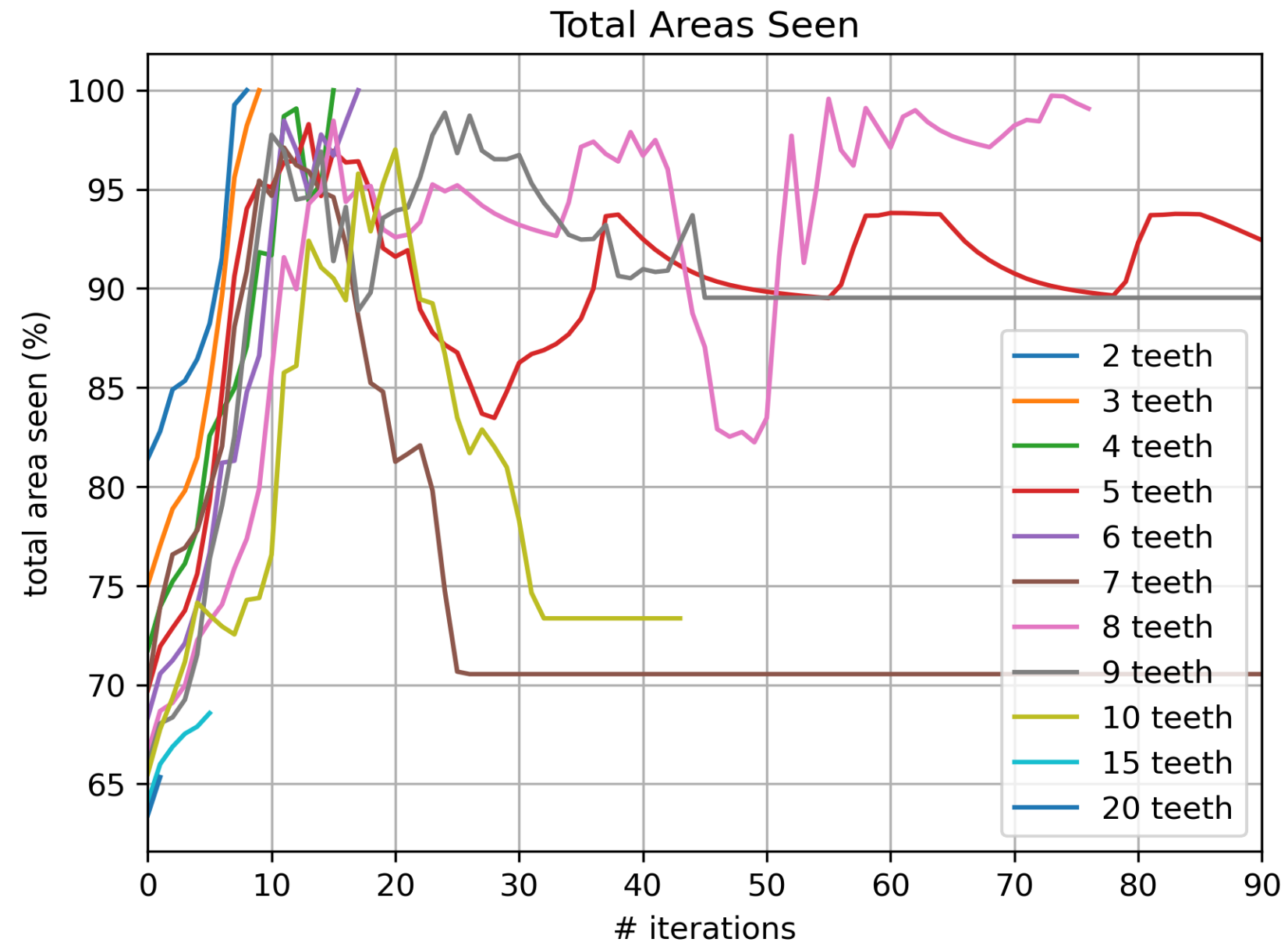


# Scalability for the comb polygon

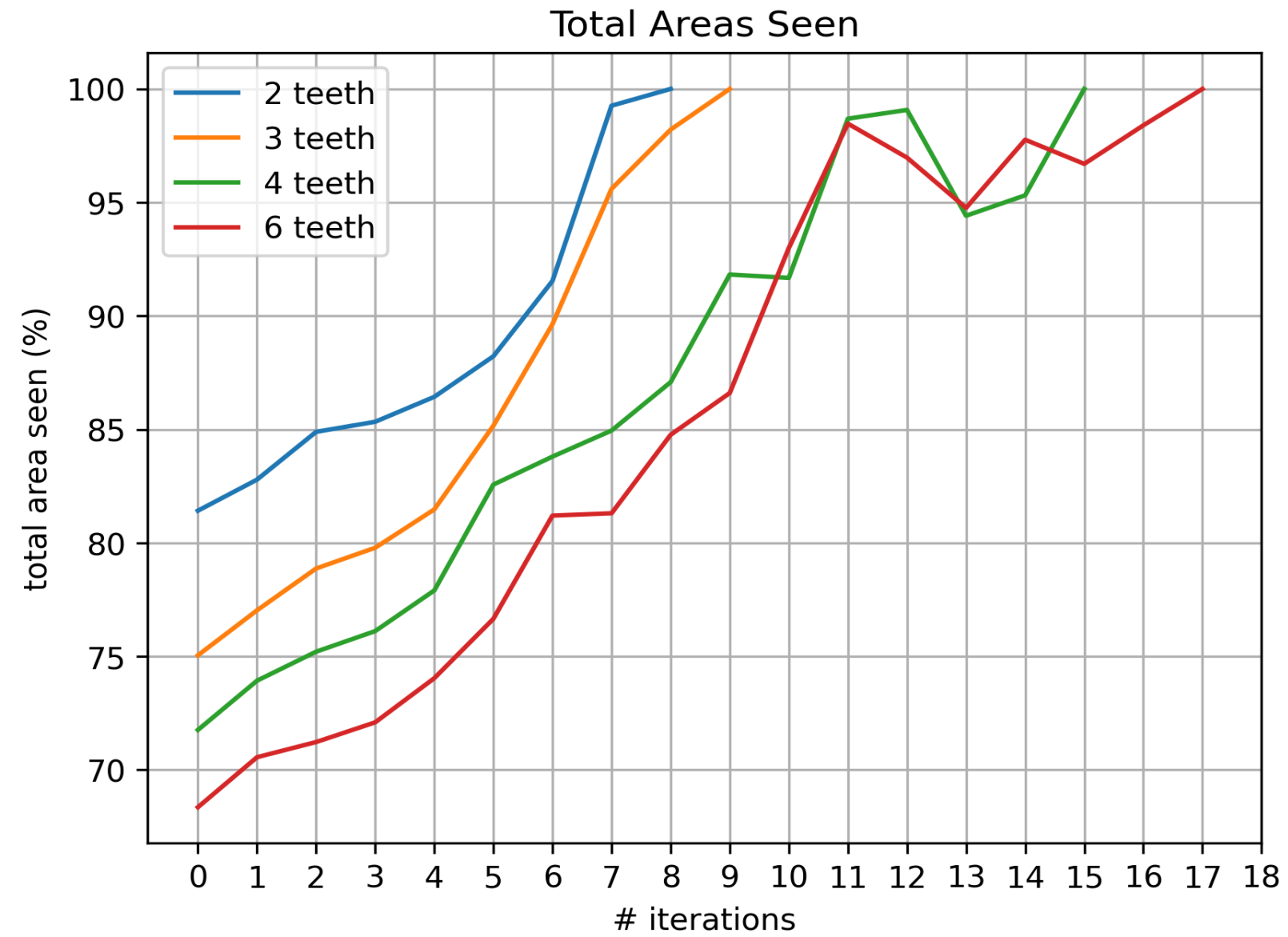


2, 3, ..., 10, 15, 20 teeth

# Scalability for the comb polygon



# Scalability for the comb polygon



# Problems encountered

# Future work

improve the algorithm's robustness, performance and scalability

implement other heuristics

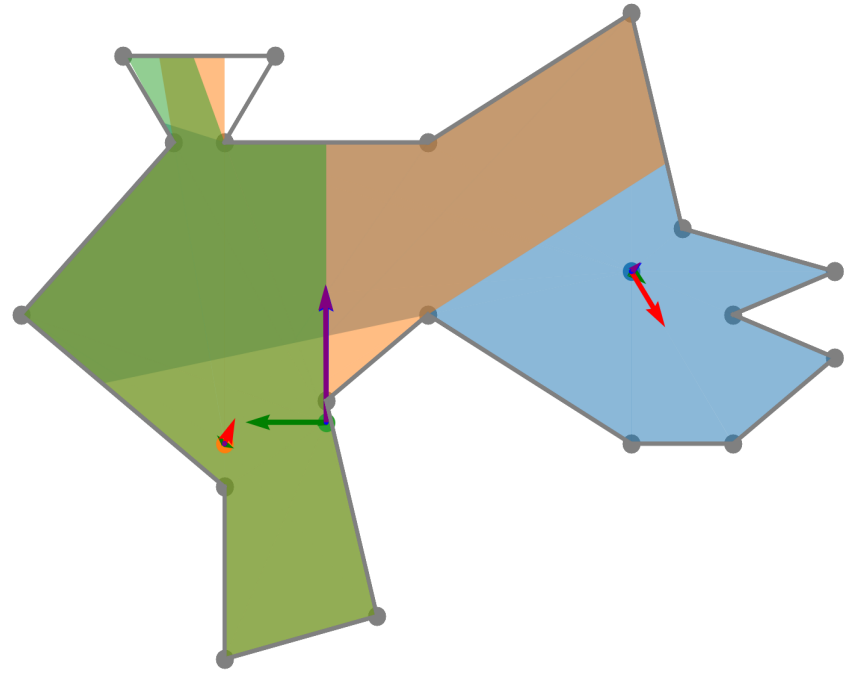
test the algorithm on larger polygons with more guards

solve existing bugs



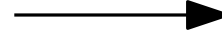
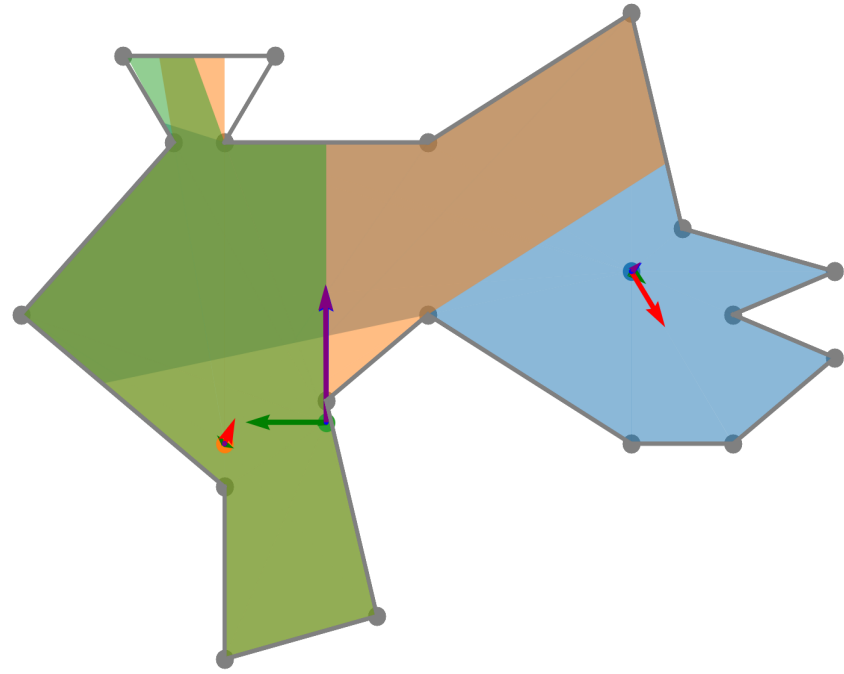
# The Art Gallery Problem

Gradient Computation for Iteration #0

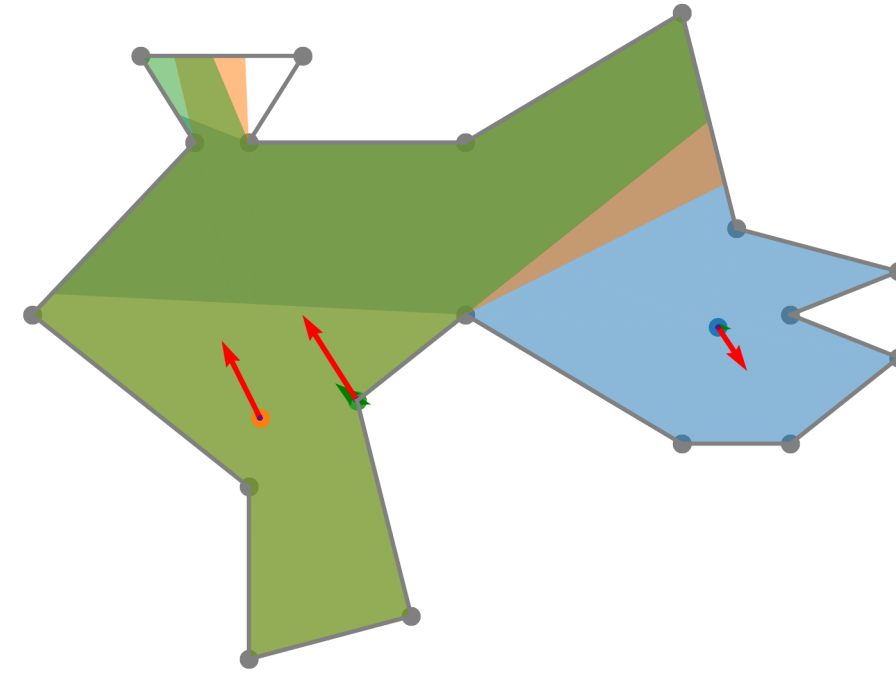


# The Art Gallery Problem

Gradient Computation for Iteration #0

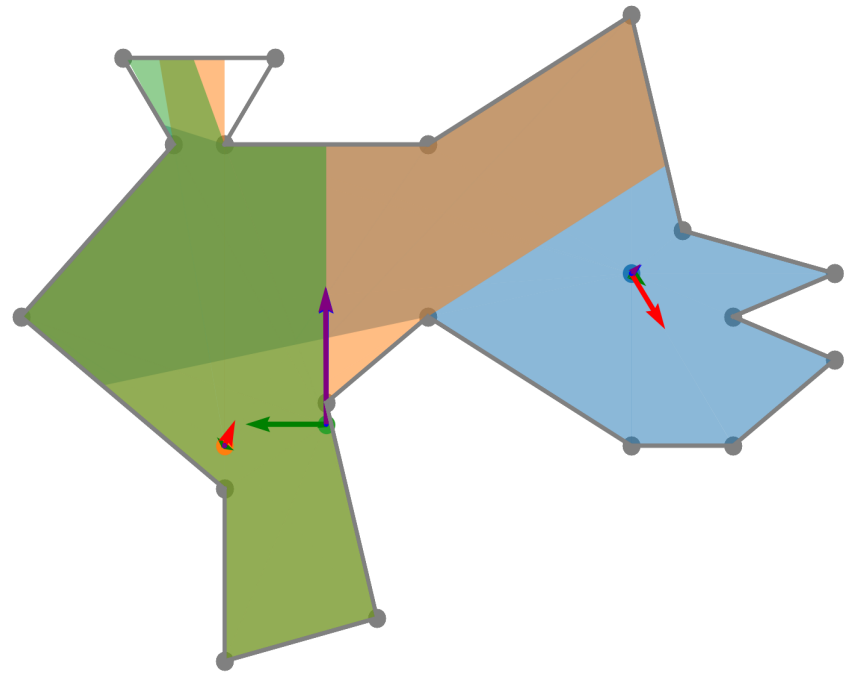


Gradient Computation for Iteration #1

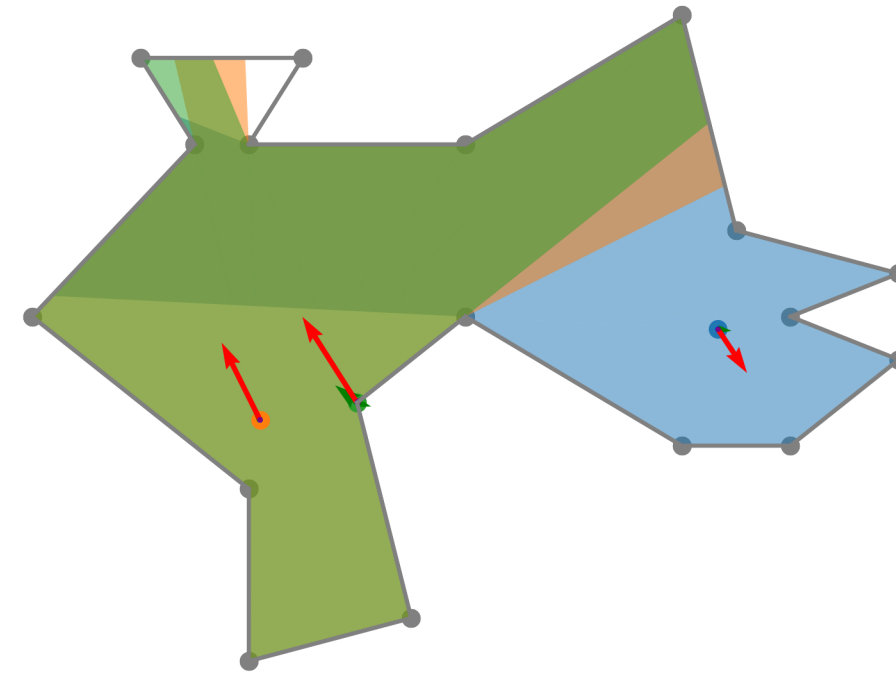


# The Art Gallery Problem

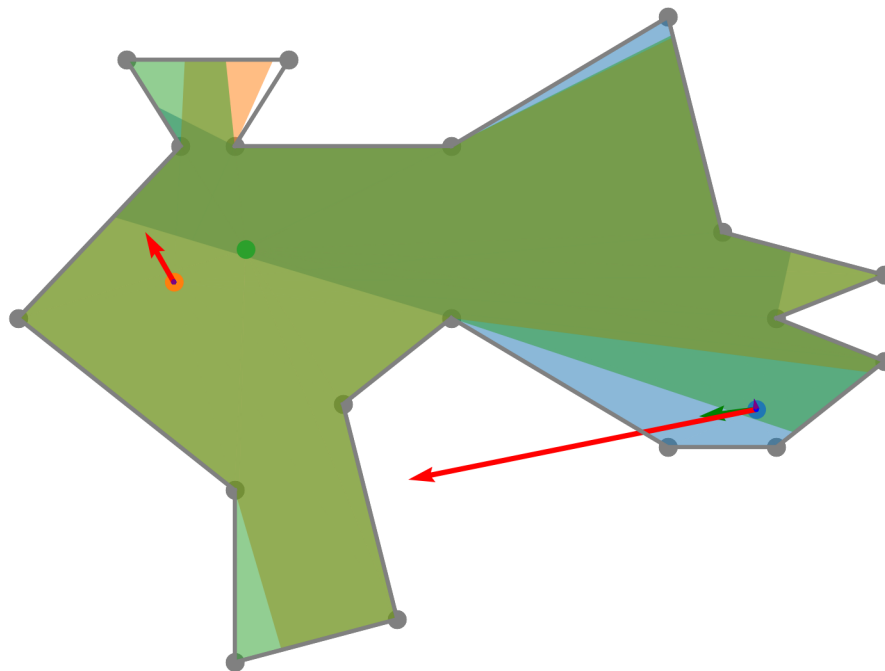
## Gradient Computation for Iteration #0



## Gradient Computation for Iteration #1



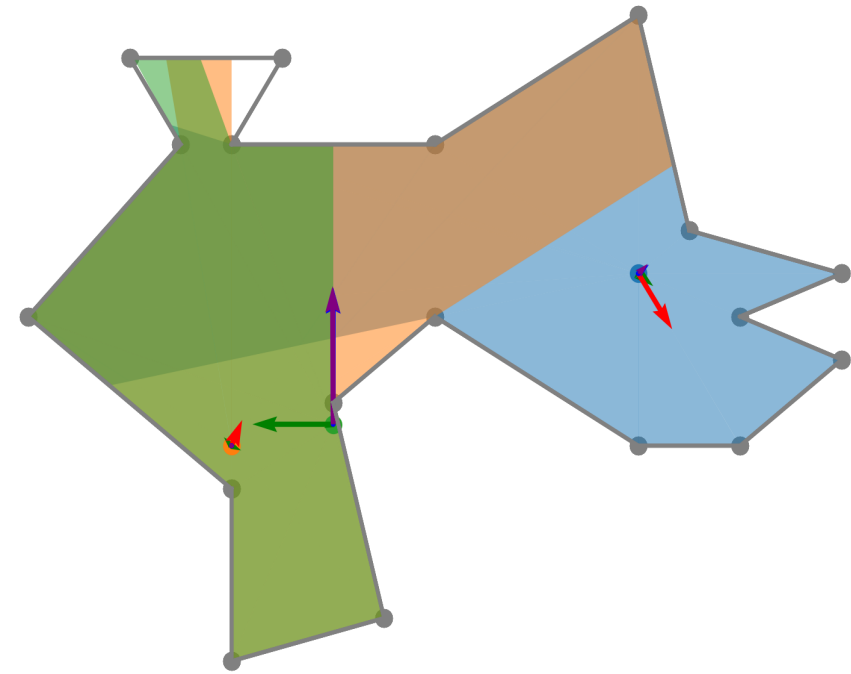
### Gradient Computation for Iteration #3



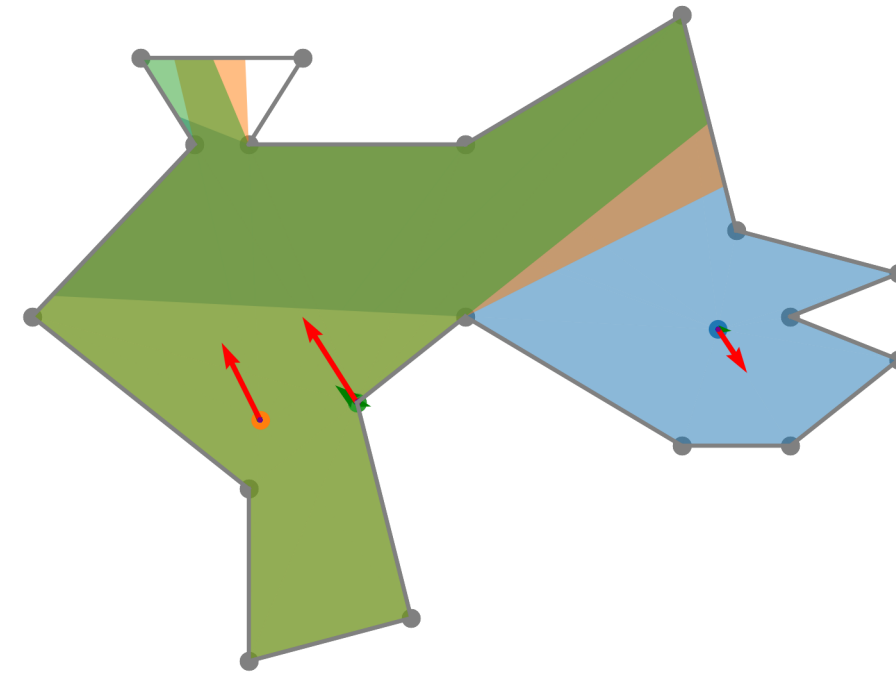


# The Art Gallery Problem

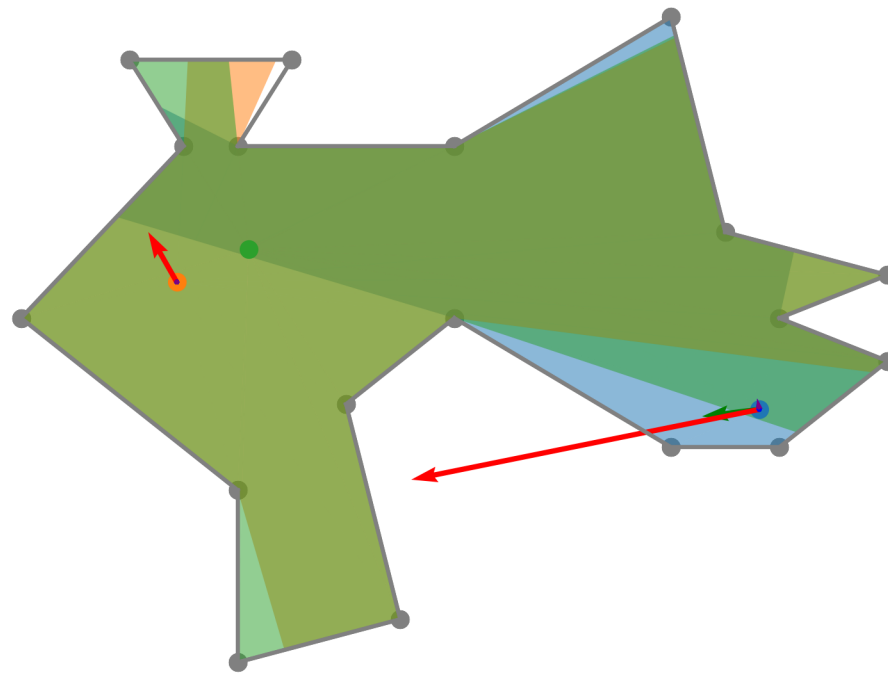
Gradient Computation for Iteration #0



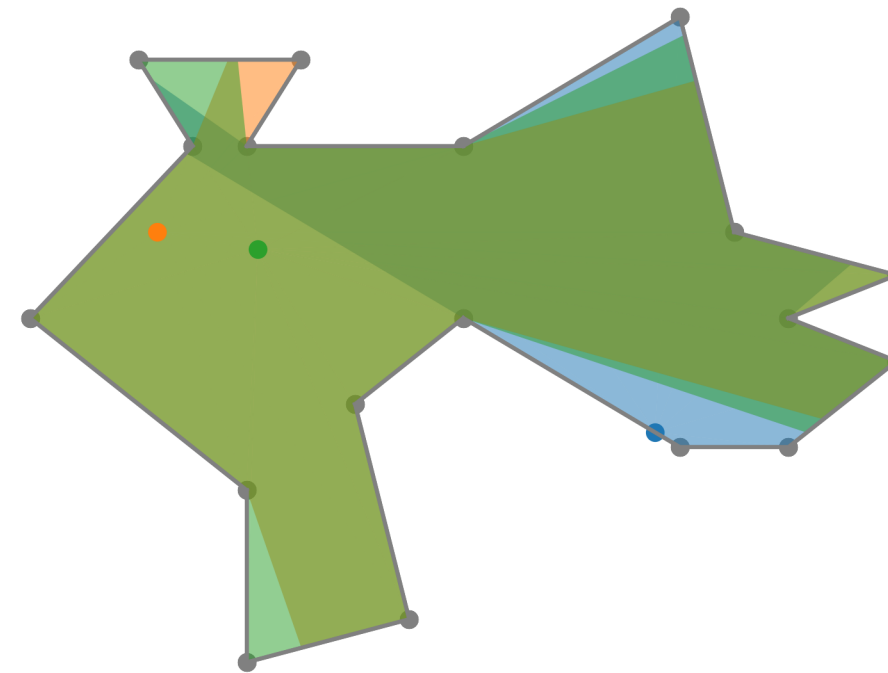
Gradient Computation for Iteration #1



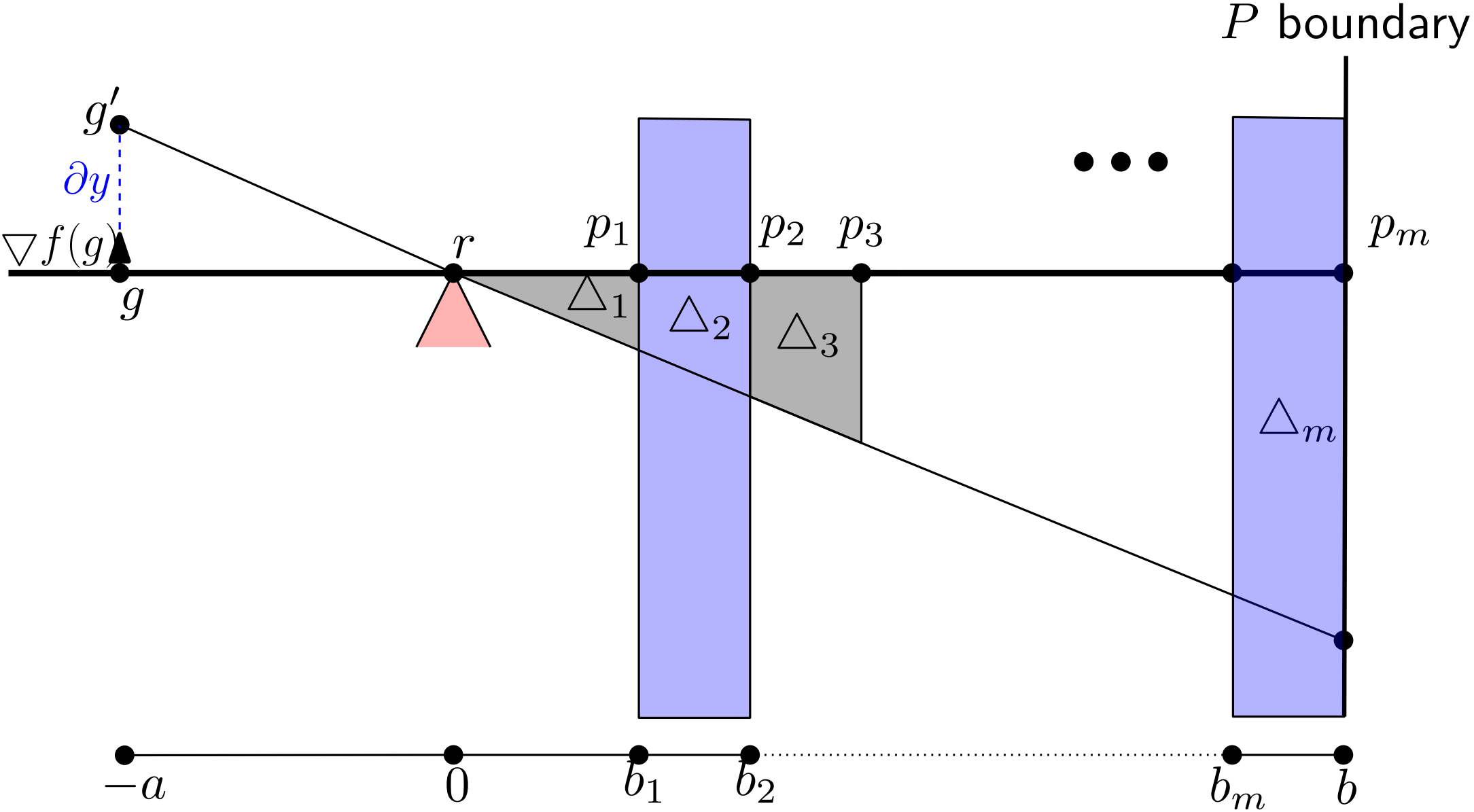
Gradient Computation for Iteration #3



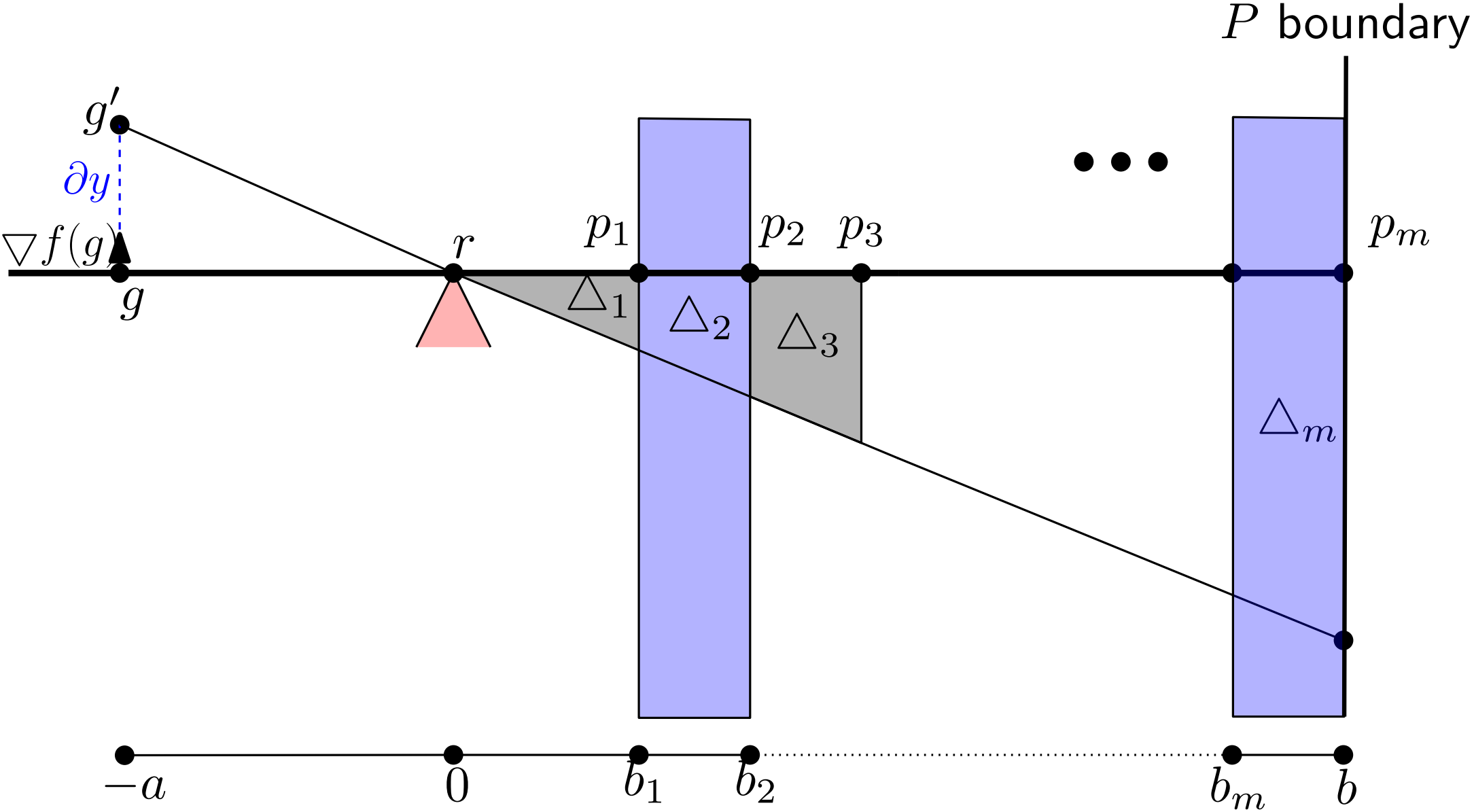
Gradient Computation for Iteration #4



# Computing the gradient for multiple guards

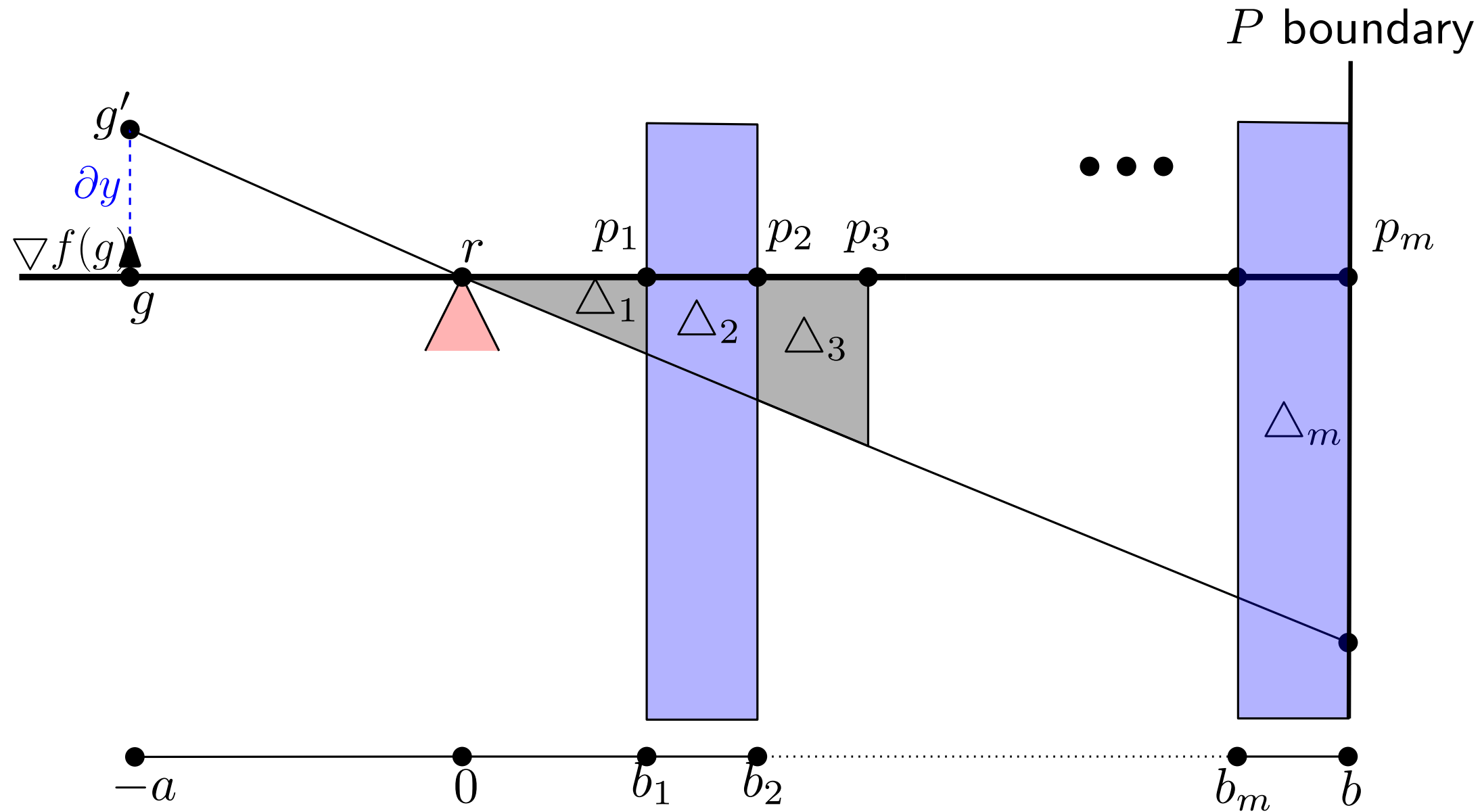


# Computing the gradient for multiple guards



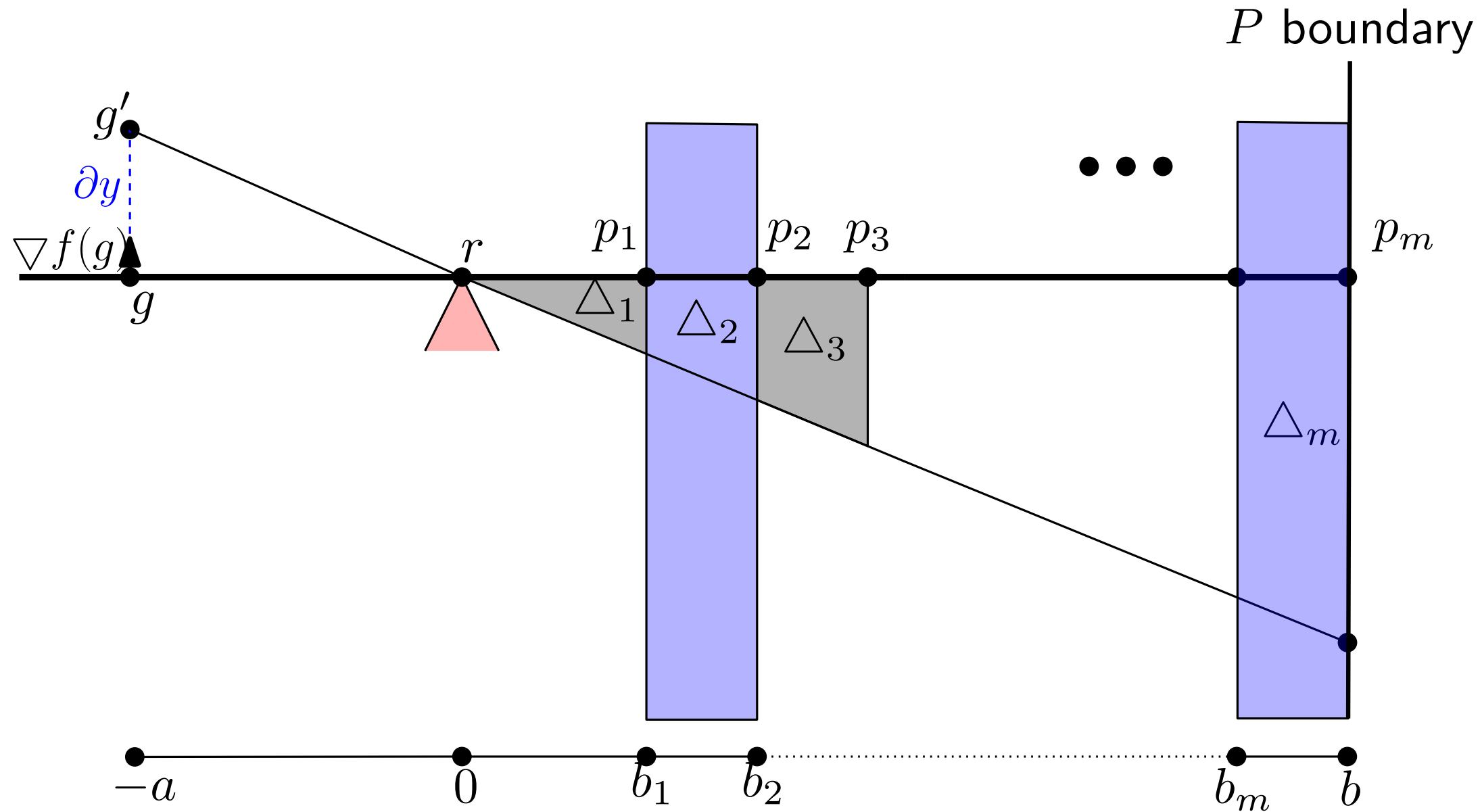
$\text{Area}_{\Delta_1 + \Delta_3 + \dots + \Delta_{m-1}}(g)$

# Computing the gradient for multiple guards



$$\text{Area}_{\Delta_1+\Delta_3+\dots+\Delta_{m-1}}(g) = \text{Area}_{\Delta_1+\dots+\Delta_m}(g) - \text{Area}_{\Delta_{m-1}}(g) + \text{Area}_{\Delta_{m-2}}(g) - \dots - \text{Area}_{\Delta_2}(g) + \text{Area}_{\Delta_1}(g)$$

# Computing the gradient for multiple guards



$$\begin{aligned} \text{Area}_{\Delta_1 + \Delta_3 + \dots + \Delta_{m-1}}(g) &= \text{Area}_{\Delta_1 + \dots + \Delta_m}(g) - \text{Area}_{\Delta_{m-1}}(g) + \text{Area}_{\Delta_{m-2}}(g) - \dots - \text{Area}_{\Delta_2}(g) + \text{Area}_{\Delta_1}(g) \\ &= \left( b^2 - b_m^2 + b_{(m-1)}^2 - \dots - b_2^2 + b_1^2 \right) \frac{\partial y}{2a} \end{aligned}$$