

Question 1:

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function
[postT,velT,timeT,dV1,dV2]=twoImpulseHohmann(r1,r2,i1,i2,Omega1,Omega2,mu)

%This function calculates the two impulses needed to complete a Hohmann
%transfer

%Input: r1, radius of orbit 1
%Input: r2, radius of orbit 2
%Input: i1, inclination of orbit 1
%Input: i2, inclination of orbit 2
%Input: Omega1, longitude of ascending node of orbit 1
%Input: Omega2, longitude of ascending node of orbit 2
%Input: mu, gravitaional parameter

%Output: postT, 500x3 matrix containing postions along the transfer orbit
%Output: timeT, column matrix of times associated with positions in postT
%Output: dV1, impulse at periapsis of transfer
%Output: dV2, impulse at apoapsis of transfer

nu=0:0.001:2*pi;
e=0;
omega=0;
oe1=[r1,e,Omega1,i1,omega,0];
oe2=[r2,e,Omega2,i2,omega,0];
position1=zeros(length(nu),3);
velocity1=zeros(length(nu),3);
position2=zeros(length(nu),3);
velocity2=zeros(length(nu),3);
for i=1:length(nu)
    oe1(6)=nu(i);
    oe2(6)=nu(i);
    [r,v]=oe2rv_Hackbardt_Chris(oe1,mu);
    position1(i,:)=r';
    velocity1(i,:)=v';
    [r,v]=oe2rv_Hackbardt_Chris(oe2,mu);
    position2(i,:)=r';
    velocity2(i,:)=v';
end

v1=sqrt(mu/r1);
v2=sqrt(mu/r2);
hvec1=cross(position1(1,:),velocity1(1,:));
hvec2=cross(position2(1,:),velocity2(1,:));
lvec=cross(hvec1,hvec2);
lvec=lvec/norm(lvec);
position1T=r1*lvec;
aT=(r1+r2)/2;
deltaV1=sqrt(((2*mu)/r1)-(mu/aT))-v1;
ulvec=cross(hvec1,lvec)/norm(hvec1);
V1b4=v1*ulvec;
dV1=deltaV1*ulvec;
V1aft=V1b4+dV1;

M=500;

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tauT=2*pi*sqrt(aT^3/mu);
timeT=linspace(0,tauT/2,M);
posT=zeros(length(timeT),3);
velT=zeros(length(timeT),3);
for i=1:length(timeT)
    [r,v] = propagateKepler_Hackbardt_Chris(position1T,V1aft,0,timeT(i),mu);
    posT(i,:)=r';
    velT(i,:)=v';
end

v2bf=sqrt(((2*mu)/r2)-(mu/aT));
V2b4=-v2bf*u1vec;
u2vec=-cross(hvec2,lvec)/norm(hvec2);
V2aft=v2*u2vec;
dV2=V2aft-V2b4;

end

```

Question 2:

```

function
[postT,timeT,dVP,dVA,totDV]=twoNImpulseOrbitTransfer(r1,r2,i1,i2,Omega1,Omega2
,N,mu)
%This function calculates the impulses needed to complete N Hohmann
%transfers

%Input: r1, radius of orbit 1
%Input: r2, radius of orbit 2
%Input: i1, inclination of orbit 1
%Input: i2, inclination of orbit 2
%Input: Omega1, longitude of ascending node of orbit 1
%Input: Omega2, longitude of ascending node of orbit 2
%Input: N, number of Ho
%Input: mu, gravitaional parameter

%Output: postT, 500x3 matrix containing postions along the transfer orbit
%Output: timeT, column matrix of times associated with positions in postT
%Output: dV1, impulse at periapsis of transfer
%Output: dV2, impulse at apoapsis of transfer
%Output: totDV, the total delta V required to complete the transfer

rn=r1+(1:N)/N*(r2-r1);
Omegan=Omega1+(1:N)/N*(Omega2-Omega1);
in=i1+(1:N)/N*(i2-i1);

rn=[r1,rn];
Omegan=[Omega1,Omegan];
in=[i1,in];

dOmega=Omegan(2)-Omegan(1);

dVP=zeros(N,1);

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```

dVA=zeros(N,1);
post=[];
velT=[];
timeT=[0];

N=1:N;
for i=1:length(N)
    %elliptic

    [post,velT,timet,dV1,dV2]=twoImpulseHohmann(rn(i),rn(i+1),in(i),in(i+1),Omega
n(i),Omegan(i+1),mu);
    post=[post;post];
    velT=[velT;velT];
    timet=timet+timeT(length(timeT));
    timeT=[timeT;timet'];
    dVP(i)=norm(dV1);
    dVA(i)=norm(dV2);
    %circular
    if i<length(N)
        taut=2*pi*sqrt(rn(i+1)^3/mu);
        dOmegaTime=dOmega/sqrt(mu/rn(i+1)^3);
        [timet, post] =
propagateOnCircle(post(end,:),velT(end,:)+dV2,timeT(end),timeT(end)+(taut/2)+
dOmegaTime,mu,500);
        post=[post;post];
        timeT=[timeT;timet];
    end
end

timeT(1)=[];

totDV=sum(dVP)+sum(dVA);
fprintf('The total time to complete the transfer is %g seconds or %g
hours\n',timeT(end),timeT(end)/3600)

%Plots 3D view of transfer
figure
hold on
earthSphere
plot3(post(:,1),post(:,2),post(:,3))
hold off

%Plots the ground track;
OmegaE = (2*pi)/((23*3600)+(56*60)+4);
rvValuesECEF = eci2ecef(timeT,post,OmegaE);
[lonE,lat] = ecef2LonLat(rvValuesECEF);
figure
earth = imread('earth.jpg');
hold on
image('CData',earth,'XData',[-180 180],'YData',[90 -90])
plot(lonE*180/pi,lat*180/pi,'r*');
end

```

Question 3:

```
clc;clear;
mu=398600;
N=[1,2,3,4,5,6];
r1=500+6378.145;
i1=28.5;
Omega1=60;

r2=20200+6378.145;
i2=57;
Omega2=120;

i1=deg2rad(i1);
i2=deg2rad(i2);
Omega1=deg2rad(Omega1);
Omega2=deg2rad(Omega2);

dVAs=[];
dVPs=[];
totdVs=[];
totTimes=[];
for i=1:length(N)

[postT,timeT,dVP,dVA,totDV]=twoNImpulseOrbitTransfer(r1,r2,i1,i2,Omega1,Omega2
,N(i),mu);
    dVAs(i)=sum(dVA);
    dVPs(i)=sum(dVP);
    totdVs(i)=totDV;
    totTimes(i)=timeT(end);
end

figure
plot(N,dVAs)
title('Magnitude of Apoapsis Impulses vs N')
xlabel('N')
ylabel('Apoapsis Impulses (km/s)')
set(gca,'XTick',0:N(end))
figure
plot(N,dVPs)
title('Magnitude of Periapsis Impulses vs N')
xlabel('N')
ylabel('Periapsis Impulses (km/s)')
set(gca,'XTick',0:N(end))
figure
plot(N,totdVs)
title('Magnitude of Total Impulse vs N')
xlabel('N')
ylabel('Total Impulse (km/s)')
set(gca,'XTick',0:N(end))
figure
plot(N,totTimes)
title('Total Time Required for Transfer vs Time')
xlabel('N')
ylabel('Time (sec)')
set(gca,'XTick',0:N(end))
```

The total time to complete the transfer is 10766 seconds or 2.99055 hours

The total time to complete the transfer is 34796 seconds or 9.66556 hours

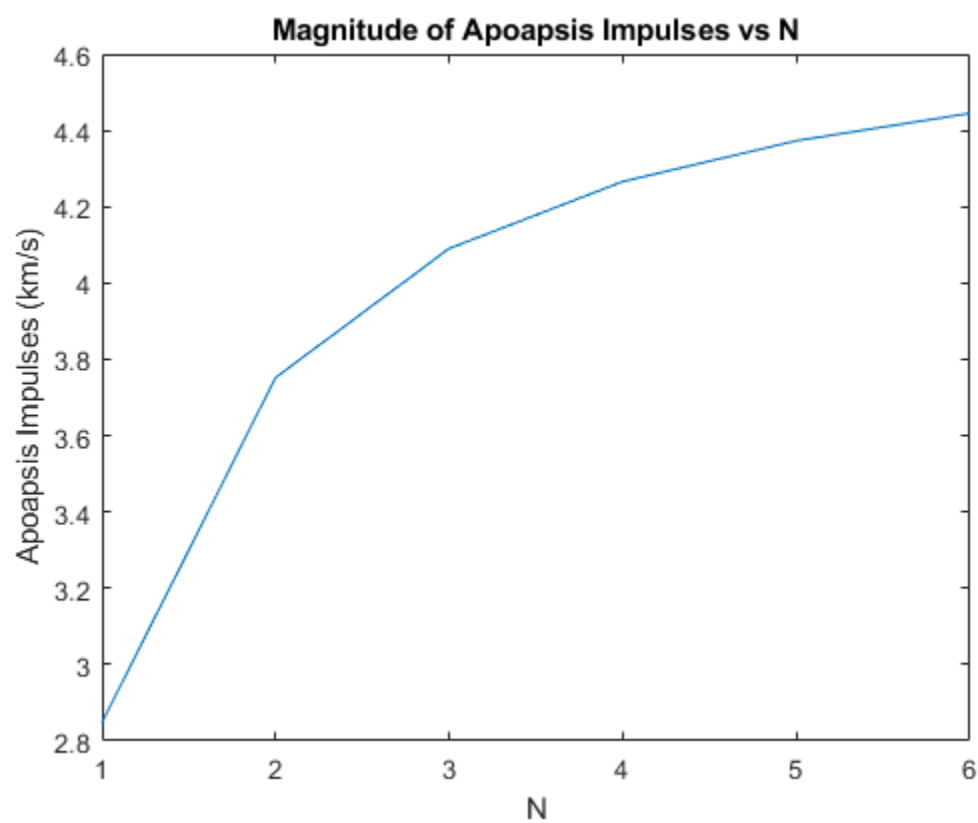
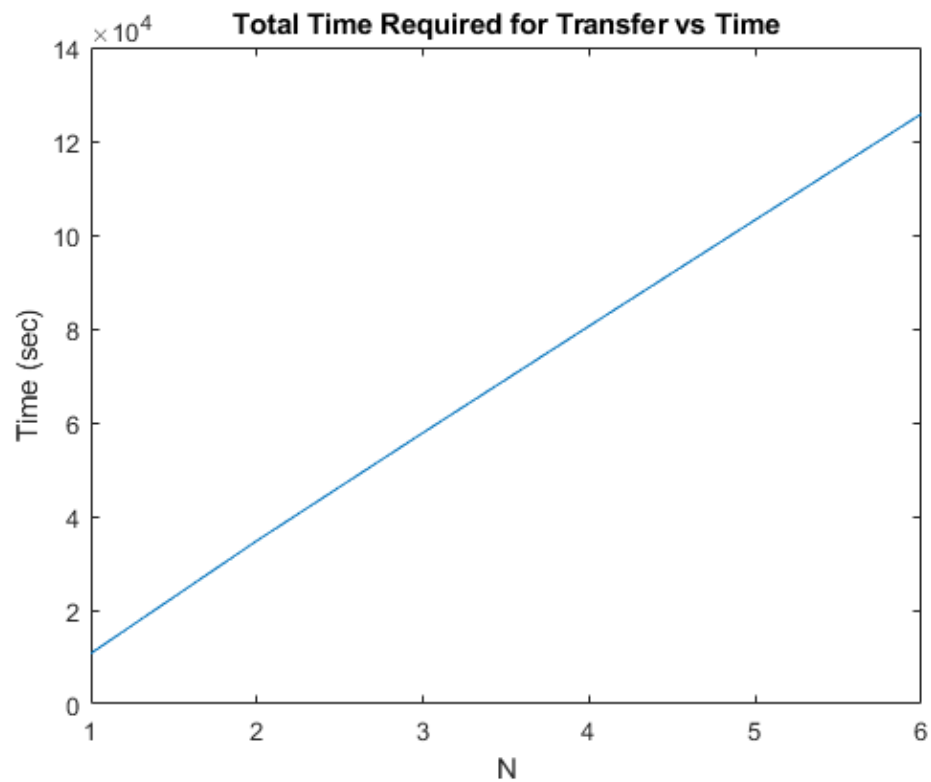
The total time to complete the transfer is 57825.5 seconds or 16.0626 hours

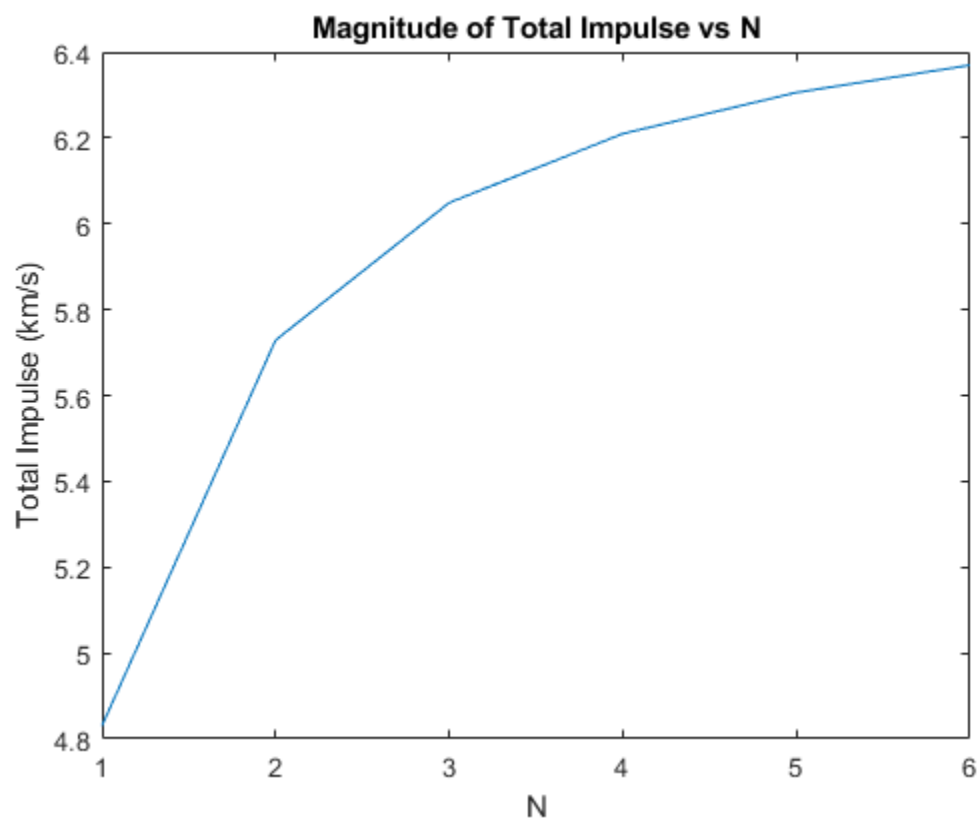
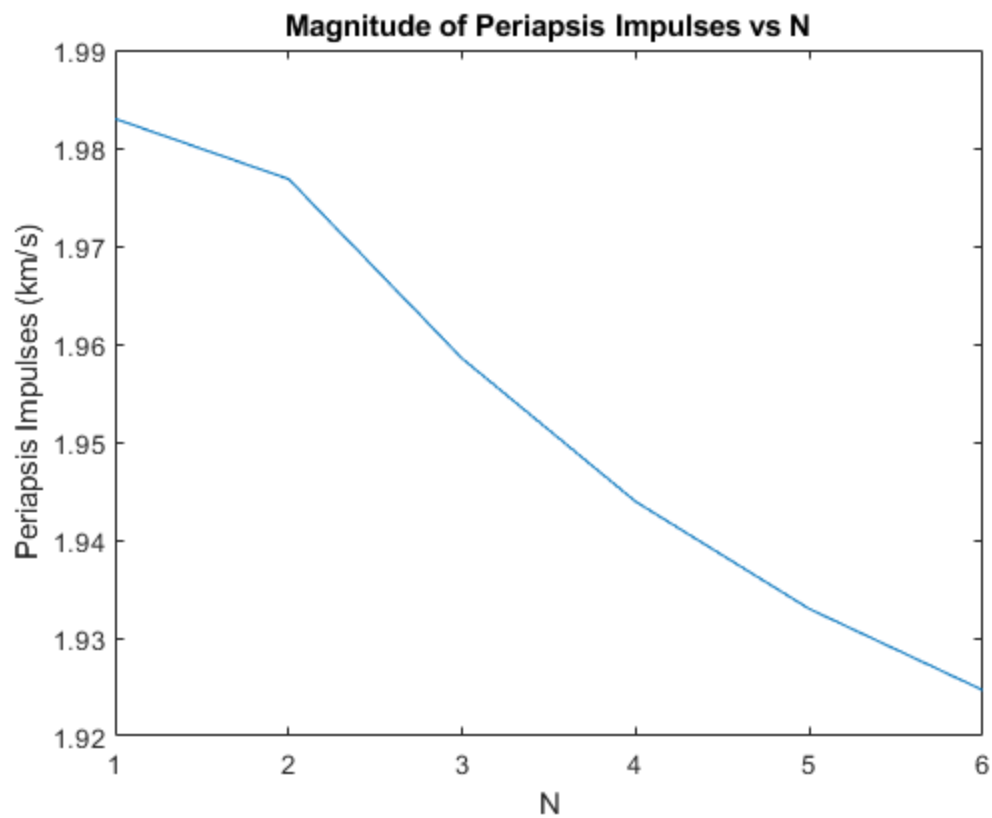
The total time to complete the transfer is 80586 seconds or 22.385 hours

The total time to complete the transfer is 103236 seconds or 28.6766 hours

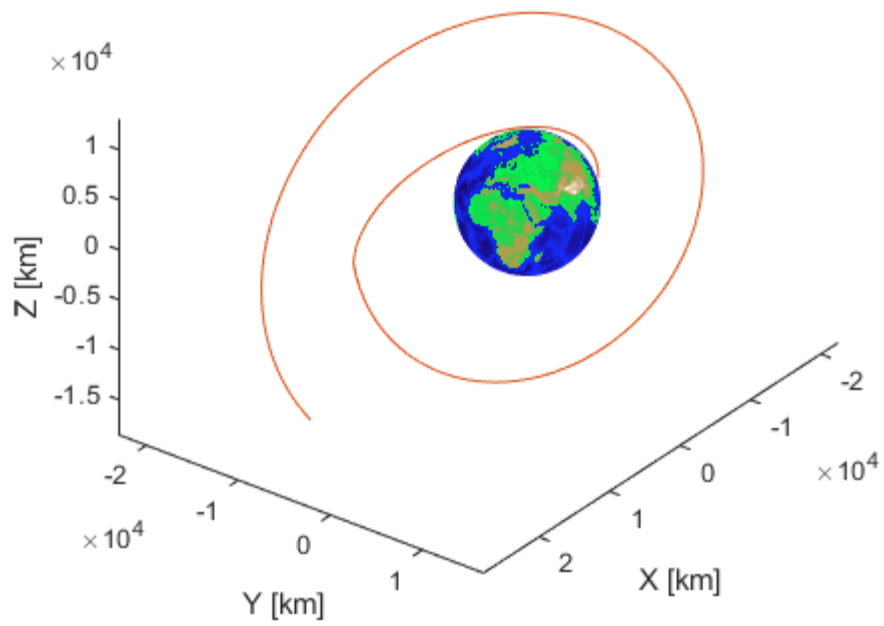
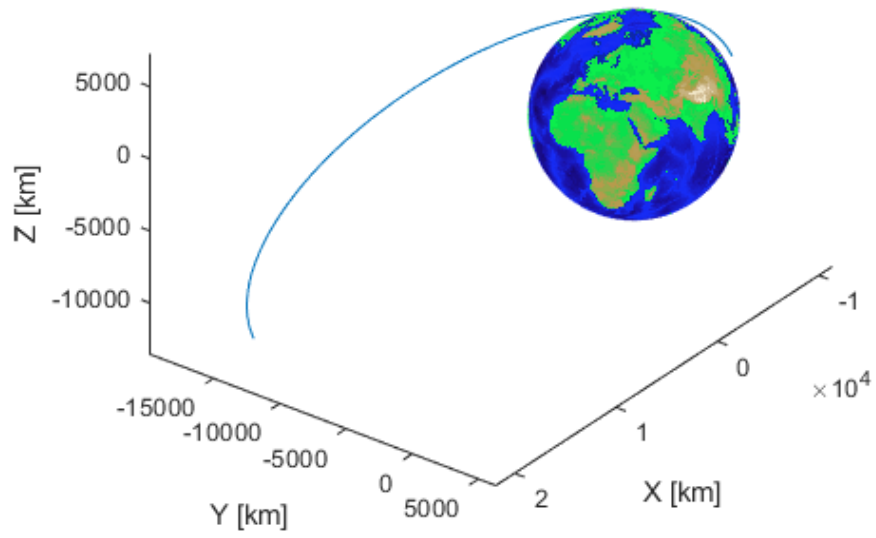
The total time to complete the transfer is 125829 seconds or 34.9526 hours

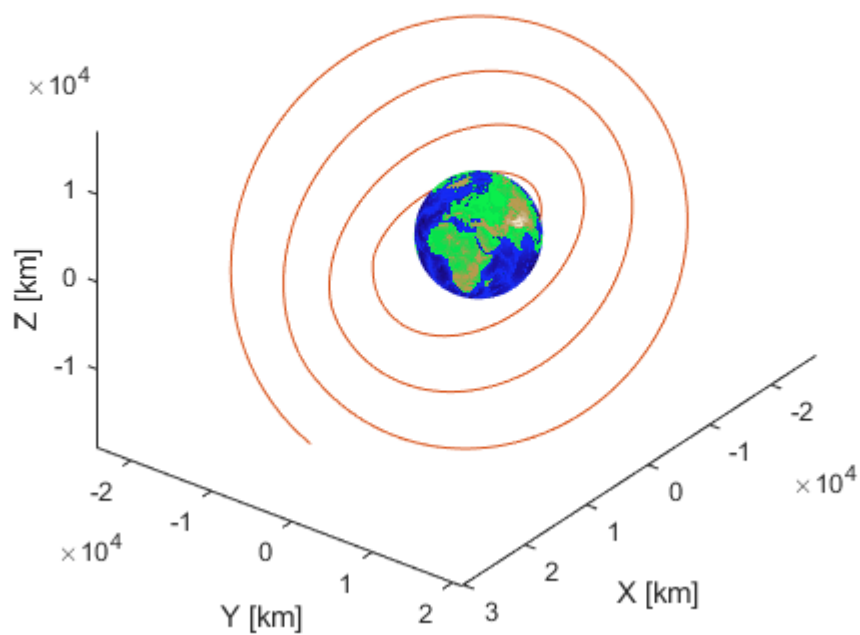
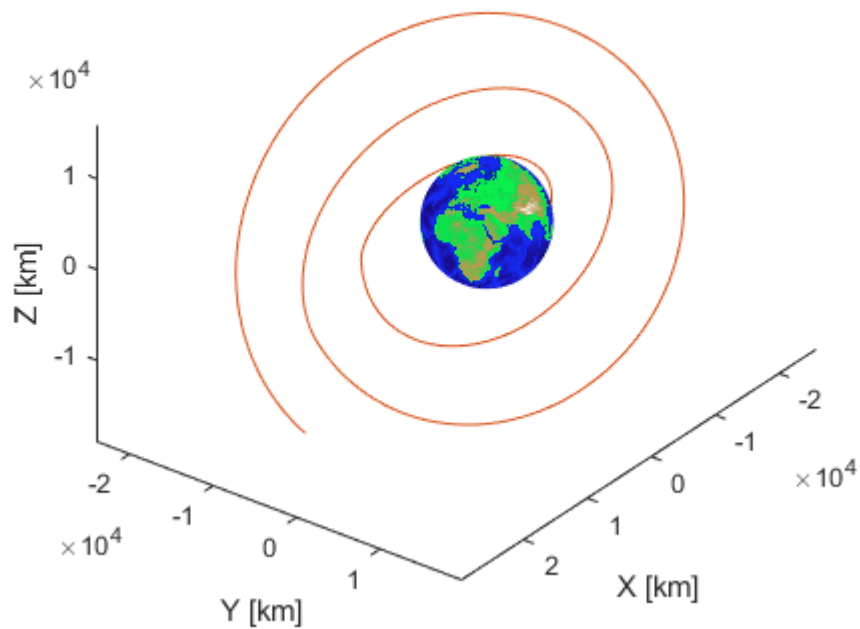
The total impulse required increases as a function of N because it is inefficient to change the plane of an orbit at a lower orbit than the final, highest orbit. So as N increases, more of the plane changes are completed at lower orbits.

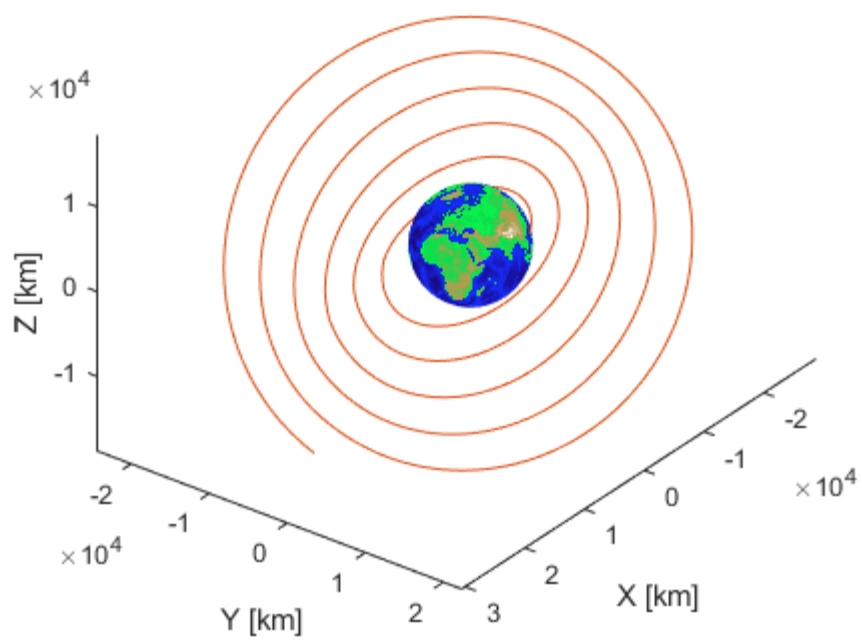
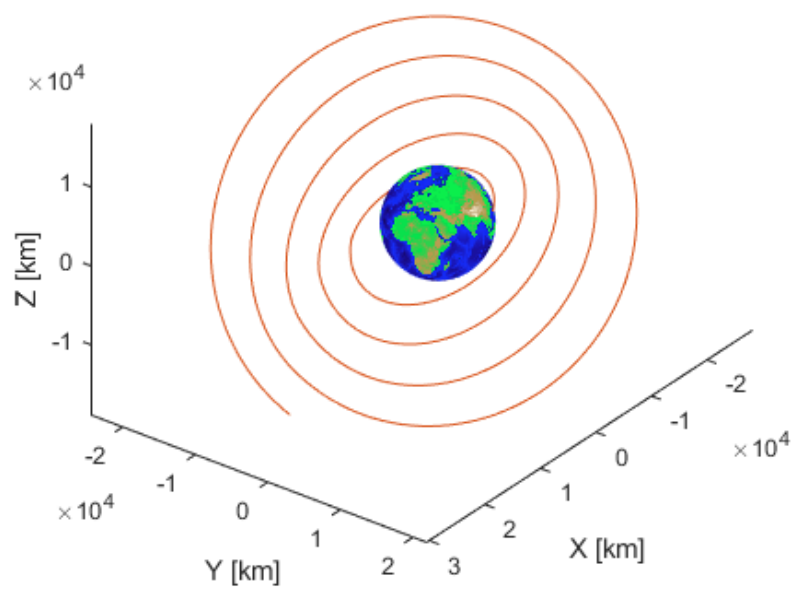




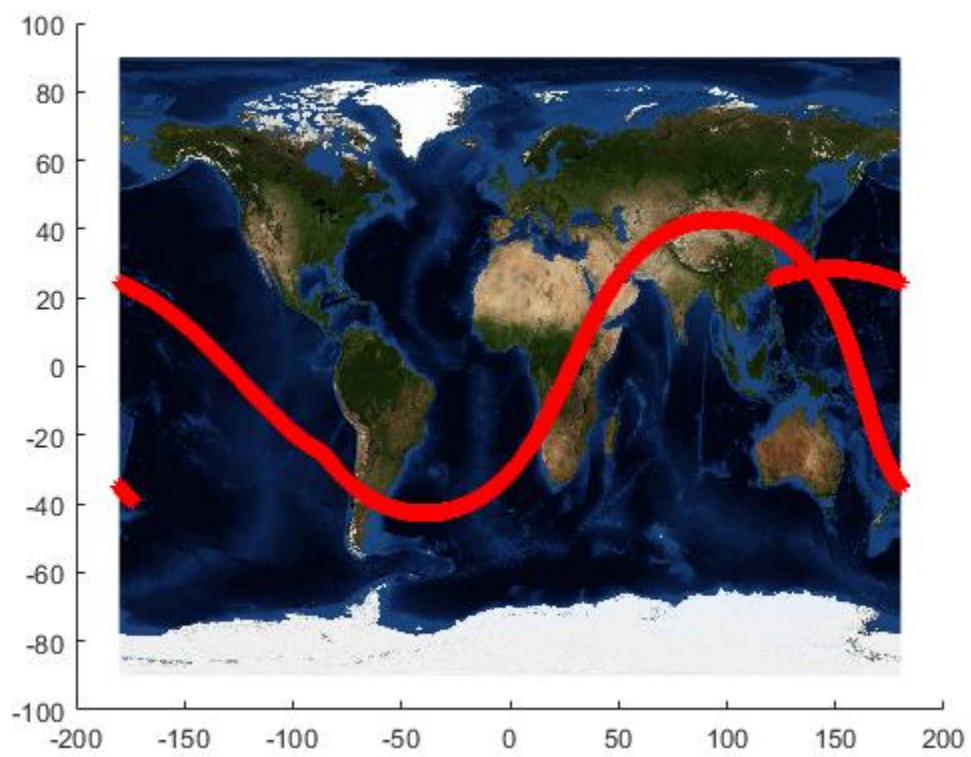
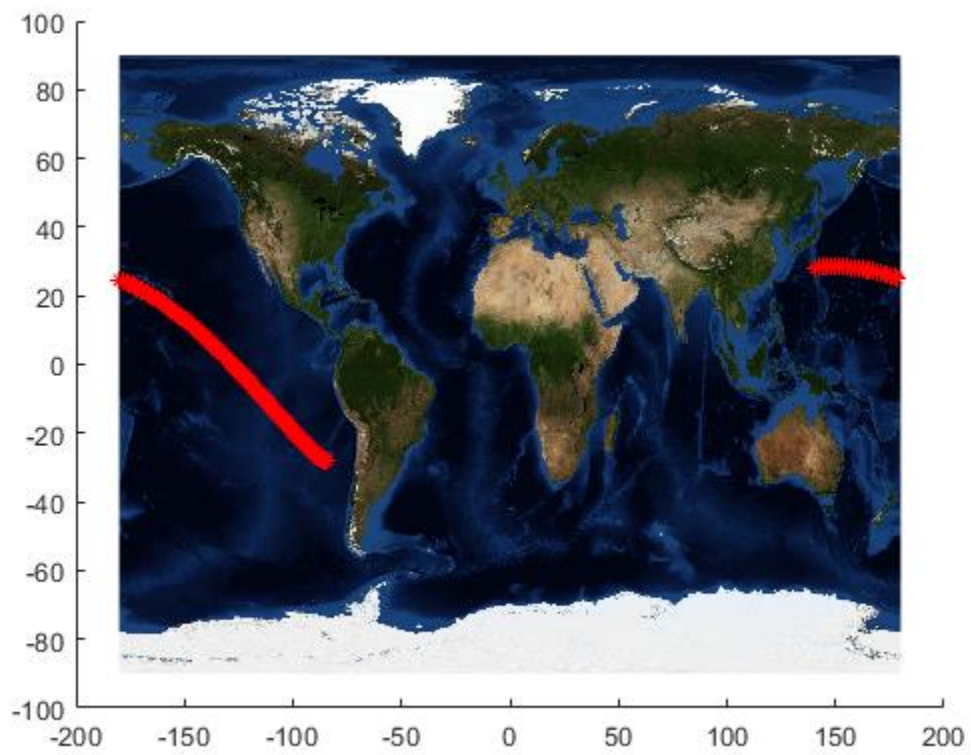
3D Views:

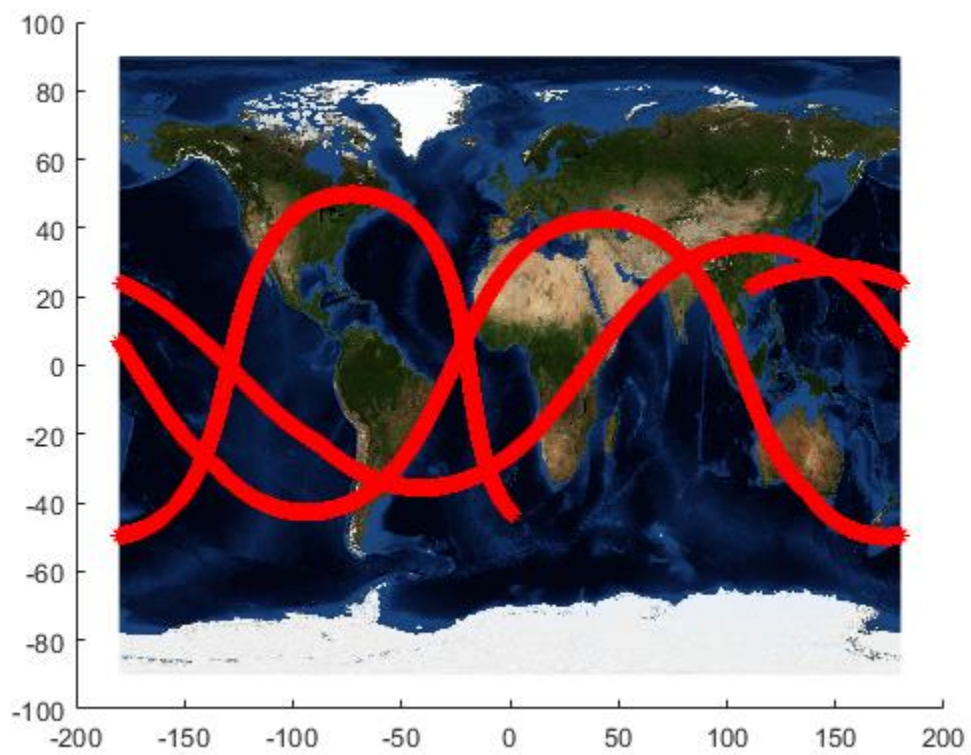
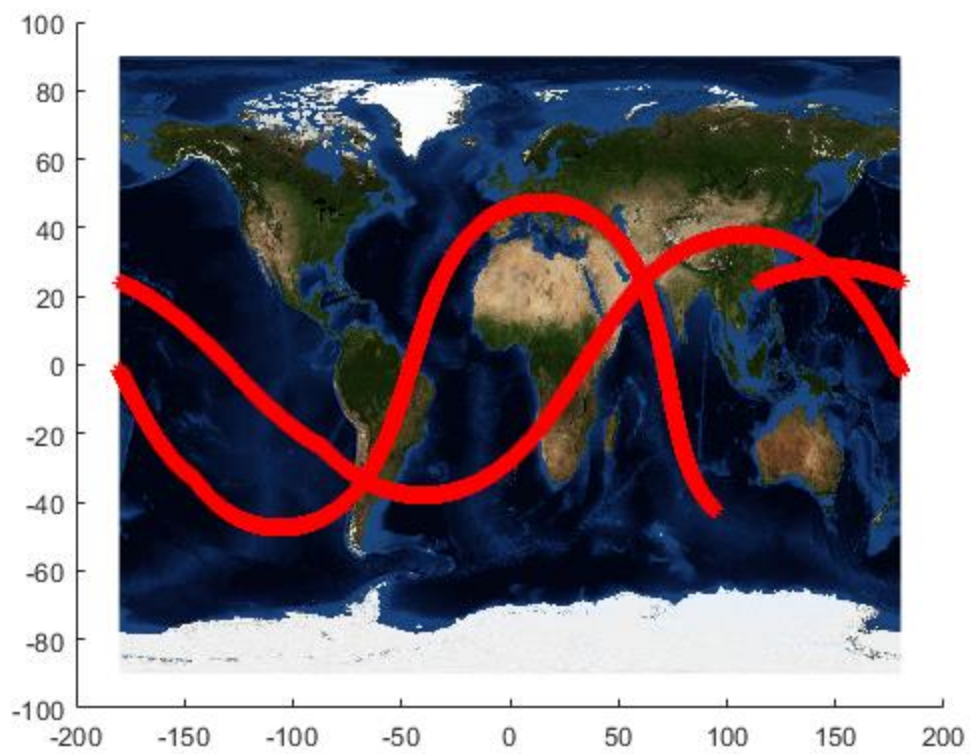


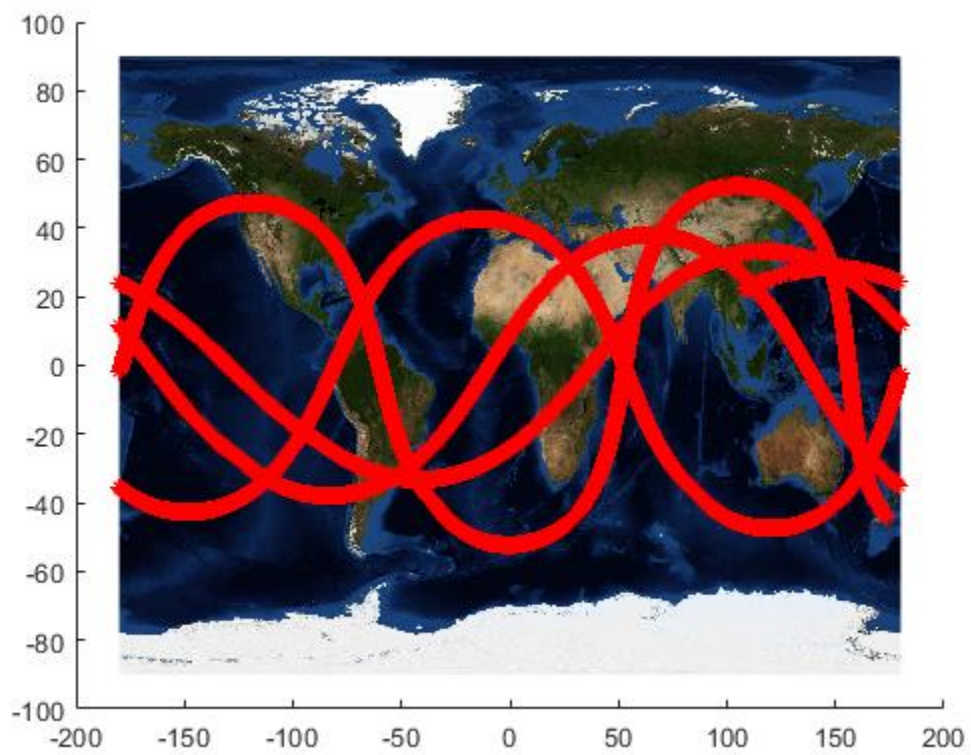
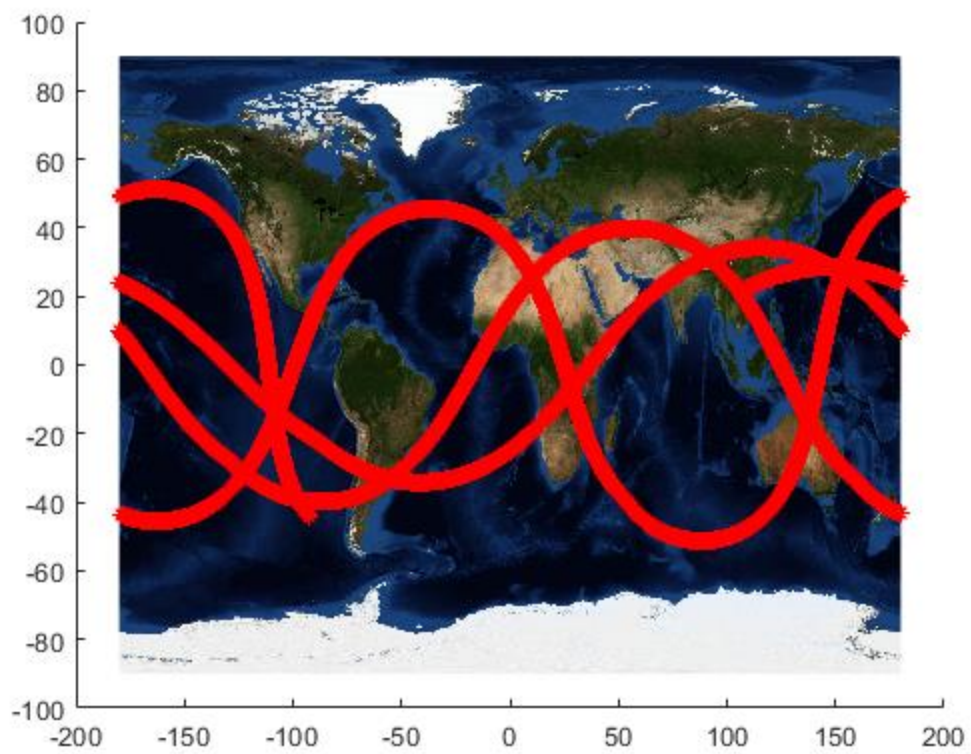




Groundtracks:







Additional Code Used:

```
function oe = rv2oe_Hackbardt_Chris(rPCI,vPCI,mu)

% This function calculates the six orbital elements from the position vector
and velocity vector
% Function Call: oe = rv2oe_Hackbardt_Chris(rPCI,vPCI,mu)
%
% Inputs:
%   rPCI: Cartesian planet-centered inertial (PCI) position (3 by 1)
%   vPCI: Cartesian planet-centered inertial (PCI) velocity (3 by 1)
%   mu:   gravitational parameter of centrally attracting body
% Outputs: orbital elements
%   oe(1): semi-major axis
%   oe(2): eccentricity
%   oe(3): longitude of the ascending node (rad)
%   oe(4): inclination (rad)
%   oe(5): argument of the periapsis (rad)
%   oe(6): true anomaly (rad)

rvec = rPCI;
vvec = vPCI;

Ix = [1;0;0];
Iy = [0;1;0];
Iz = [0;0;1];

hvec = cross(rvec,vvec);
h = norm(hvec);
p = h^2/mu;
r = norm(rvec);
evec = ((cross(vvec,hvec))/mu)-(rvec/r);
e = norm(evec);
a = p/(1-e^2);
nvec = cross(Iz,hvec);
n = norm(nvec);
Omega = atan2(dot(nvec,Iy),dot(nvec,Ix));
if Omega < 0
    Omega = Omega + (2*pi);
end
inc = atan2(dot(hvec,cross(nvec,Iz)),n*dot(hvec,Iz));
omega = atan2(dot(evec,cross(hvec,nvec)),h*dot(evec,nvec));
if omega < 0
    omega = omega + (2*pi);
end
nu = atan2(dot(rvec,cross(hvec,evec)),h*dot(rvec,evec));
if nu < 0
    nu = nu + (2*pi);
end

oe = [a; e; Omega; inc; omega; nu];
end
```

```

function [rPCI,vPCI] = oe2rv_Hackbardt_Chris(oe,mu)

% This function calculates the position and velocity vector with respect to
% the planet using orbital elements.
% Function Call: [rPCI,vPCI] = oe2rv_Hackbardt_Chris(oe,mu)
% Input:  Orbital Elements: (6 by 1 column vector)
%   oe(1): Semi-major axis
%   oe(2): Eccentricity
%   oe(3): Longitude of the ascending node (rad)
%   oe(4): Inclination (rad)
%   oe(5): Argument of the periapsis (rad)
%   oe(6): True anomaly (rad)
%   mu:    Planet gravitational parameter      (scalar)
% Outputs:
%   rPCI:   Planet-Centered Inertial (PCI) Cartesian position
%           (3 by 1 column vector)
%   vPCI:   Planet-Centered Inertial (PCI) Cartesian inertial velocity
%           (3 by 1 column vector)

a = oe(1);
e = oe(2);
Omega = oe(3);
i = oe(4);
omega = oe(5);
nu = oe(6);

p = a*(1-e^2);
r = p/(1+(e*cos(nu)));

rvecP = [r*cos(nu);r*sin(nu);0];
vvecP = (sqrt(mu/p))*[-sin(nu);e+cos(nu);0];

T_NI = [cos(Omega),-sin(Omega),0;sin(Omega),cos(Omega),0;0,0,1];
T_QN = [1,0,0;0,cos(i),-sin(i);0,sin(i),cos(i)];
T_PQ = [cos(omega),-sin(omega),0;sin(omega),cos(omega),0;0,0,1];
T_PI = T_NI * T_QN * T_PQ;

rPCI = T_PI * rvecP;
vPCI = T_PI * vvecP;
end

```

```

function E = KeplerSolver_Hackbardt_Chris(a,e,mu,t0,t,E0,k)
%This function solves Kepler's equation using fixed point iteration
%
%Input: a, semi-major axis
%Input: e, eccentricity
%Input: mu, gravitational parameter
%Input: t0, the initial time in seconds
%Input: t, the final time in seconds
%Input: E0, initial eccentric anomaly
%Input: k, number of periapsis crossings
%
%Output: E, eccentric anomaly

C=sqrt(mu/a^3)*(t-t0)-(2*pi*k)+(E0-(e*sin(E0)));
f = @(x) e*sin(x)+C;
n=10*ceil(1/(1-e));
guessE=E0-(e*sin(E0));
for i=1:n
    guessE=f(guessE);
end
E=guessE;
end

function [r,v,E,nu] = propagateKepler_Hackbardt_Chris(r0,v0,t0,t,mu)
%This function finds the position and velocity in an orbit at final time, t
%
%Input: r0, a column vector with the initial position
%Input: v0, a column vector with the initial velocity
%Input: t0, the initial time in seconds
%Input: t, the final time in seconds
%Input: mu, gravitational parameter
%
%Output: r, a column vector with the position
%Output: v, a column vector with the velocity
%Output: E, eccentric anomaly
%Output: nu, true anomaly

oe = rv2oe_Hackbardt_Chris(r0,v0,mu);
a = oe(1);
e = oe(2);
nu0 = oe(6);
E0 = 2*atan2(sqrt(1-e)*sin(nu0/2),sqrt(1+e)*cos(nu0/2));
tau=2*pi*sqrt(a^3/mu);
k=floor((t)/tau);
E = KeplerSolver_Hackbardt_Chris(a,e,mu,t0,t,E0,k);
nu= 2*atan2(sqrt(1+e)*sin(E/2),sqrt(1-e)*cos(E/2));
oe(6)=nu;
[r,v] = oe2rv_Hackbardt_Chris(oe,mu);
end

```



```

function [times, positions, velocities] =
propagateOnCircle(pos,vel,t0,tf,mu,N)
%This function calculates position and veolocity N times evenly spaced between
t0 and tf
%
%Function call: [times, postions, velocities] =
propagateOnCircle(pos,vel,t0,tf,mu,N);
%
%Input: pos, a column vector with the initial ECI postion
%Input: vel, a column vector with the initial ECI inertial velocity
%Input: t0, the initial time. Time from apoapsis to initial postion
%Input: tf, the final time
%Input: mu, gravitational parameter
%Input: N, number of time intervals
%
%Output: times, column vector of times, starting at t0 and ending at tf.
Length of N with even spacing
%Output: postions, matrix of size Nx3 containing ECI positions stored row-
wise at every time in the times vector
%Output: velocities, matrix of size Nx3 containing ECI velocities stored row-
wise at every time in the times vector
%

times=linspace(t0,tf,N);
times=times';

oe = rv2oe_Hackbardt_Chris(pos,vel,mu);
nui=oe(6);
a=oe(1);
thetaDot=sqrt(mu/a^3);

positions=zeros(N,3);
velocities=zeros(N,3);

positions(1,:)=pos';
velocities(1,:)=vel';

for i=2:N
    theta=thetaDot*(times(i)-times(i-1));
    nuOfT=nui+theta;
    oe(6)=nuOfT;
    [rPCI,vPCI] = oe2rv_Hackbardt_Chris(oe,mu);
    positions(i,:)=rPCI';
    velocities(i,:)=vPCI';
    nui=nuOfT;
end
end

```