

Planetary Bean Bouncer – Mechanical Build Guide

Before you begin

- Review the full guide once before assembling
- Verify you have all hardware listed in the BOM
- Do not fully tighten fasteners until alignment is confirmed

This guide documents the mechanical assembly of the Planetary Bean Bouncer coffee roaster. Electronics wiring and configuration are not covered in this document and will be addressed in a separate guide.

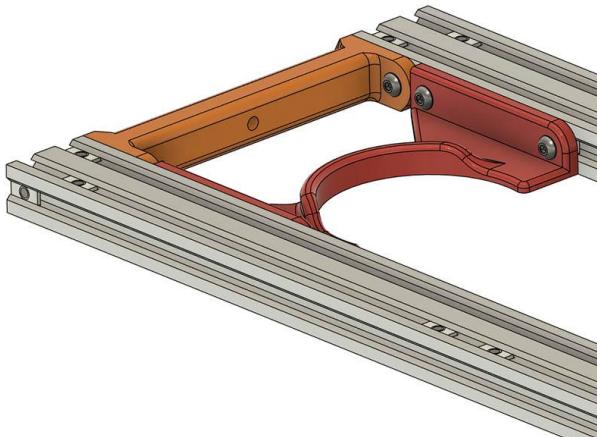


Frame

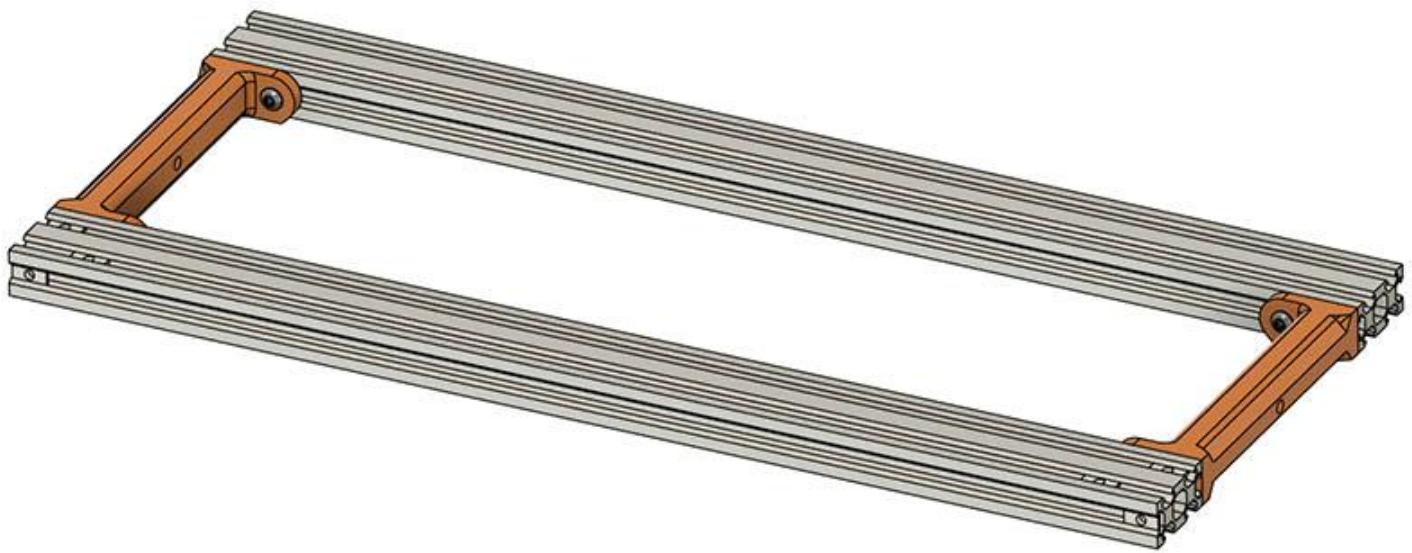
The aluminum extrusion part of the frame consists of 4-2040x500mm and 2-2040x140mm V-Slot extrusion. You should also be able to substitute T-Slot 2040 if you prefer, but I have not tested those. I am using 74 Tee Nuts and all the 3D printed parts are sized to use M5x12mm screws. I use 18-8 stainless steel button head screws as I prefer them.

Anything outside the sifter does not need to be stainless though. You might have less or more of these Tee Nuts depending on how you configure it. For instance, you will probably power the 12 V supply for the motor differently than I do or you might not want to bother with the planetary gear system.

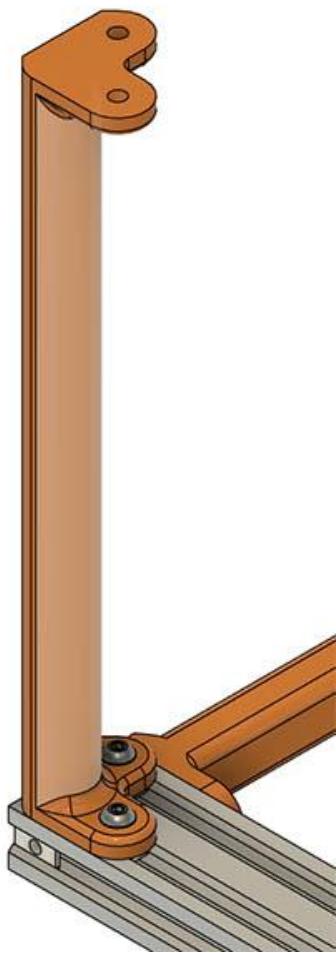
We will start with building the bottom frame. For the bottom frame we start by assembling **V2040_Bot_Connect_1** and the **Heatgun_Center_V2** 3D prints. The Heat gun center part is not necessary but makes it easy to line up the heat gun if you are using the same heat gun I have listed in BOM. You need 4-M5x12mm screws with Tee Nuts for the Heat gun center part and 2-M5x12mm screws with Tee Nuts for the **V2040_Bot_Connect_1**



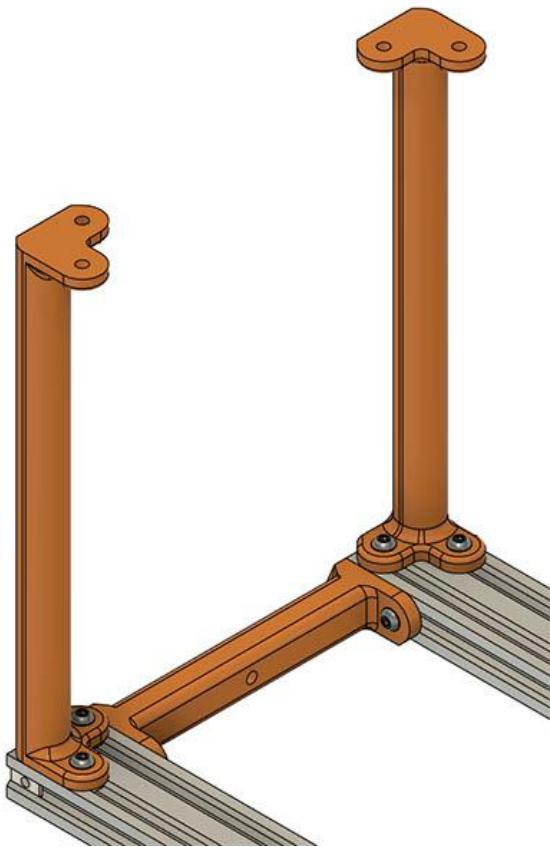
Connect **V2040_Bot_Connect_2** at each end of the frame with 2-M5x12mm screws and Tee Nuts like the other end.



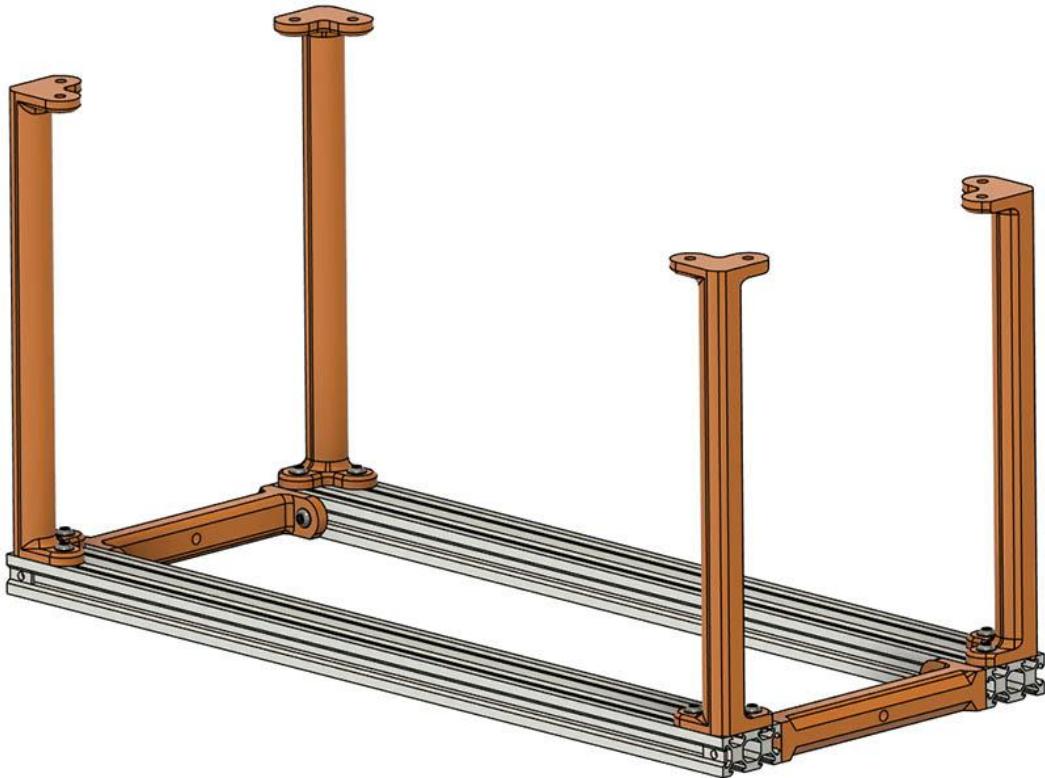
Add **V2020_Column_1** to the front corner below where sifter will be using 2-M5x12mm screws. These columns are slightly different because of print orientation, but essentially any of the 4 can go in any corner.



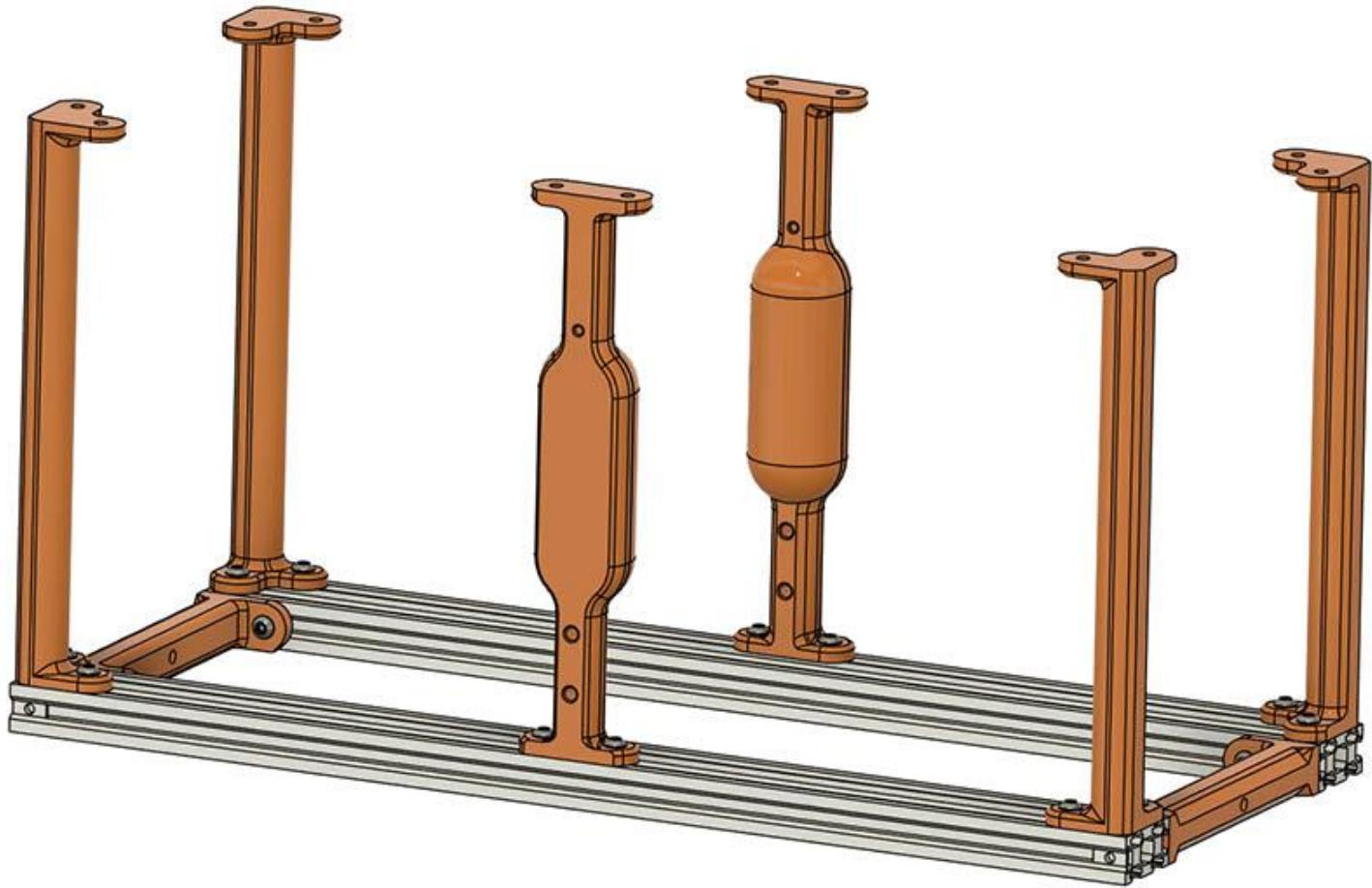
Add **V2020_Column_2** to opposite short side using 2-M5x12mm screws.



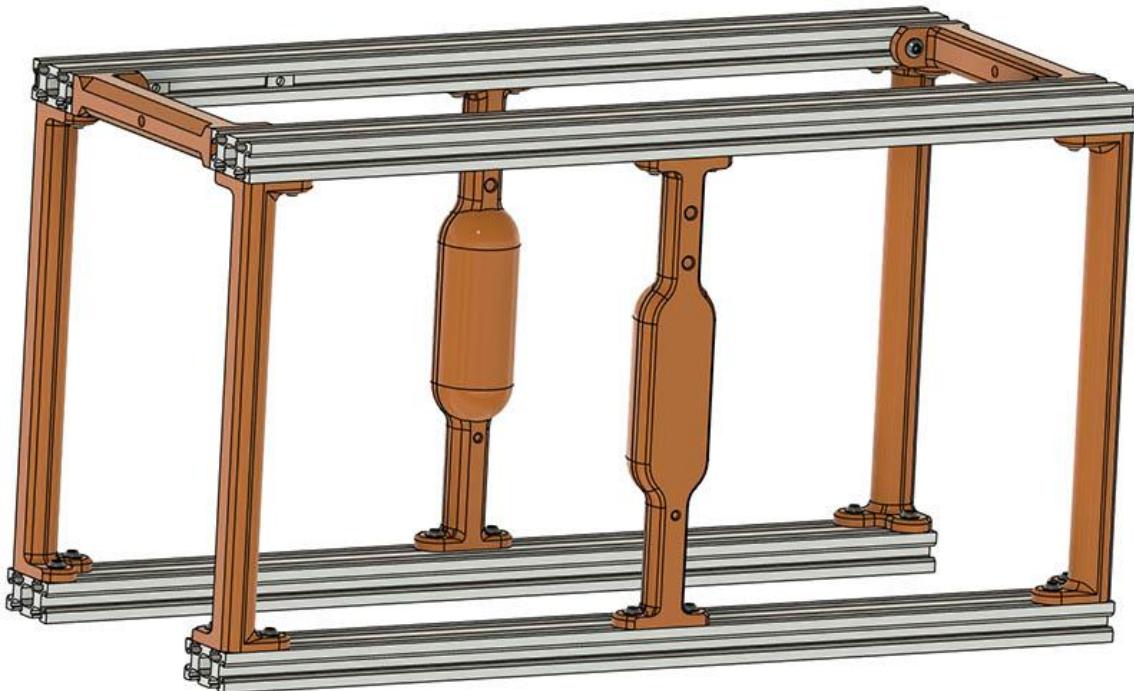
Do the same for the opposite side using 4 more M5x12mm screws.



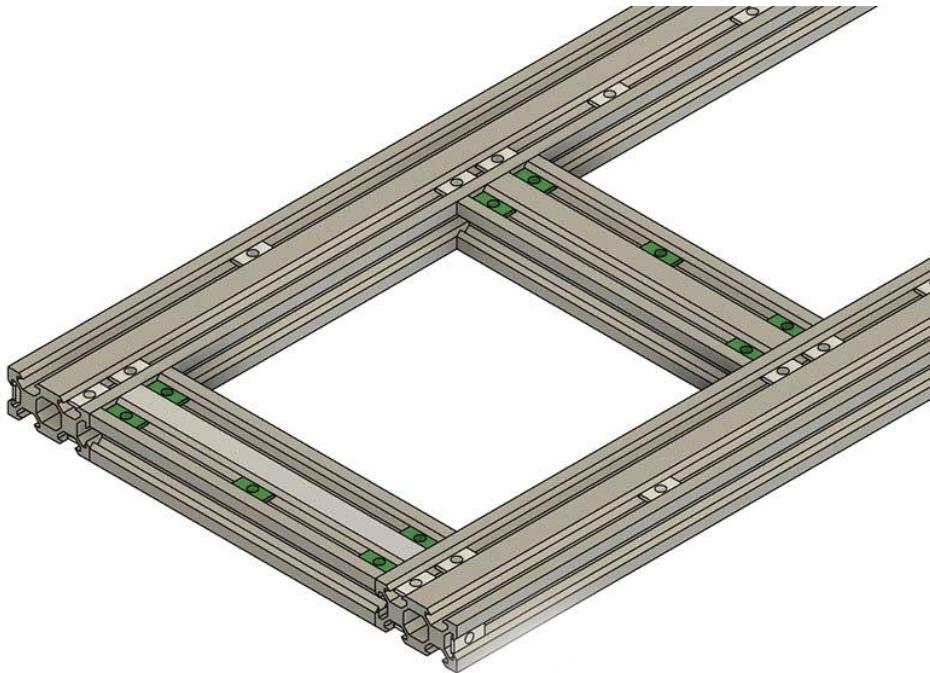
Assemble CenterColumn_1 and CenterColumn_2 to the bottom frame using a total of 4-M5x12mm screws as shown. They do not necessarily have to go in the middle. I have the back one in the middle for grabbing the center to dump roasted beans, but the front one I have closer to electronics to fasten MAX6675 and wire tie motor wire.



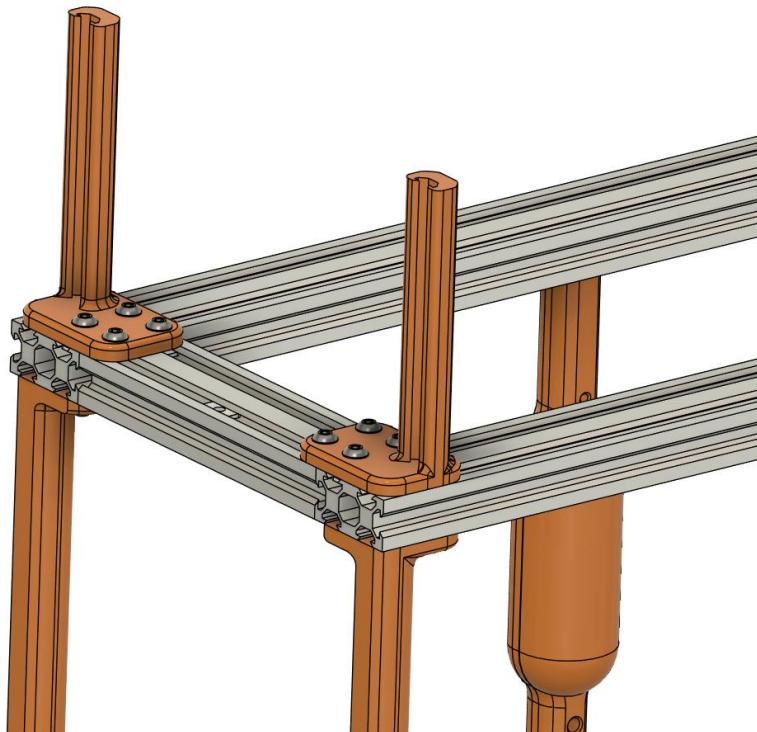
Turn the bottom frame upside down and assemble the 2-2040x500mm lengths to it using 12-M5x12mm screws with a Tee Nut for each screw.



Turn frame right side up again and add 10 Tee Nuts as shown in green to the 2 – 2040x140mm length extrusions. They do not need to be positioned correctly yet.



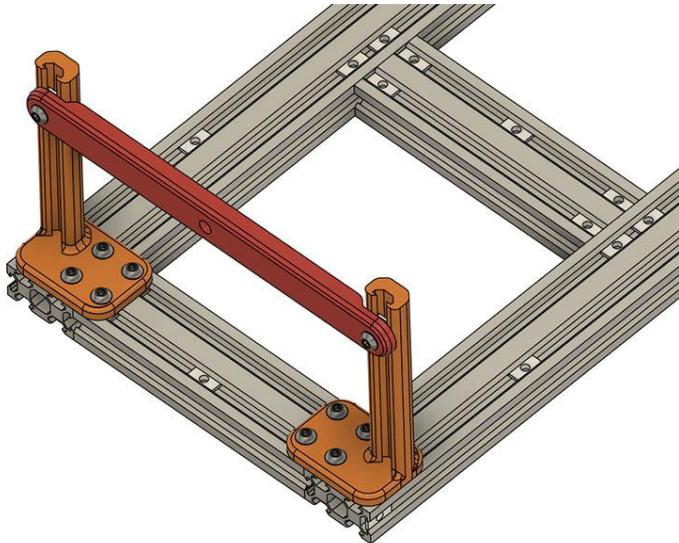
Attach Bearing_Column_1 and Bearing_Column_2 to the end of the 2040x500mm top frames and the short 2040x140mm extrusion as shown. Make sure you have a Tee Nut as shown in the middle of short 2040. It does not have to be centered yet. Use 8-M5x12mm screws with Tee Nuts in the extrusions to connect these.



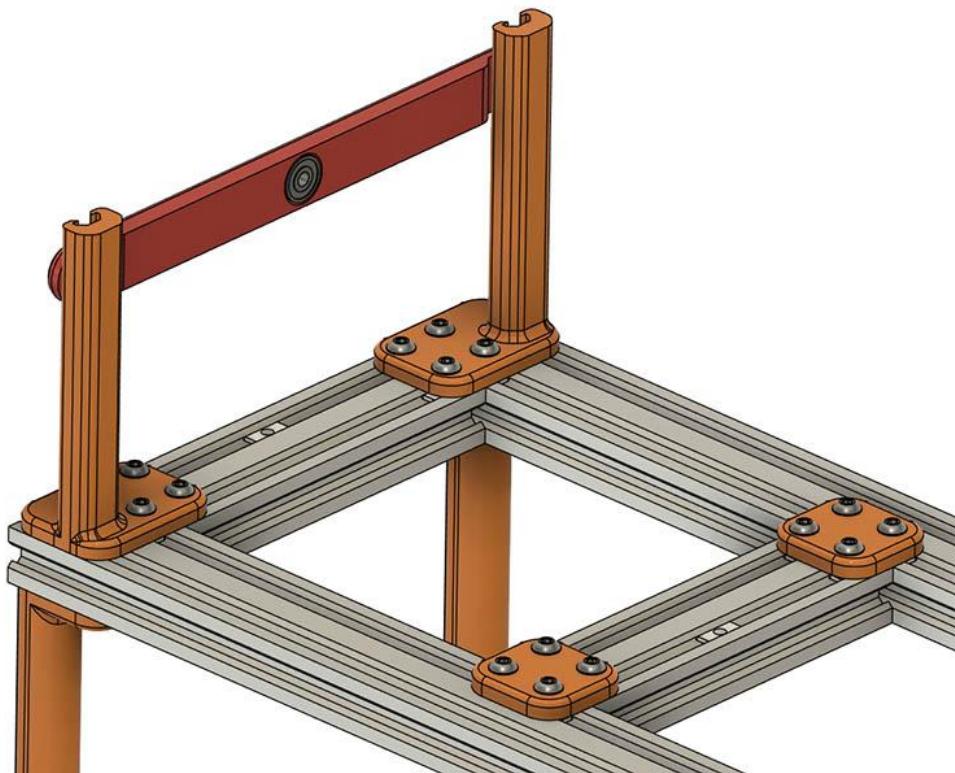
Take the **BearingBar** 3D print and insert a 625-2RS into it as shown here.



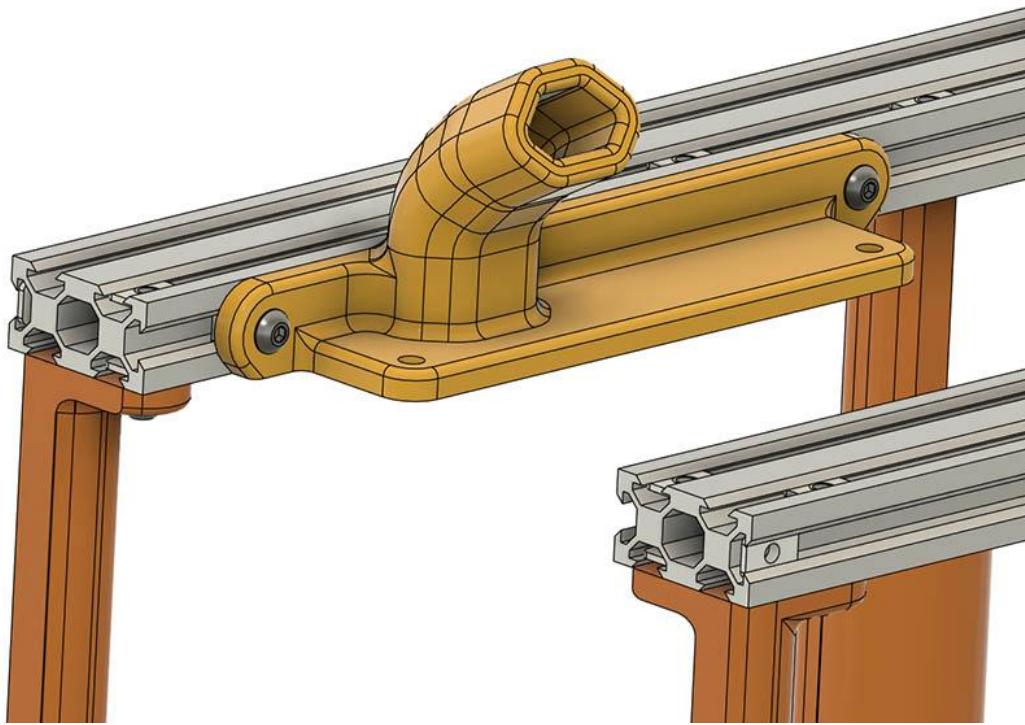
We are just putting this **BearingBar** temporarily in place. When you put the shaft through the flour sifter later, you will have to adjust this bar.



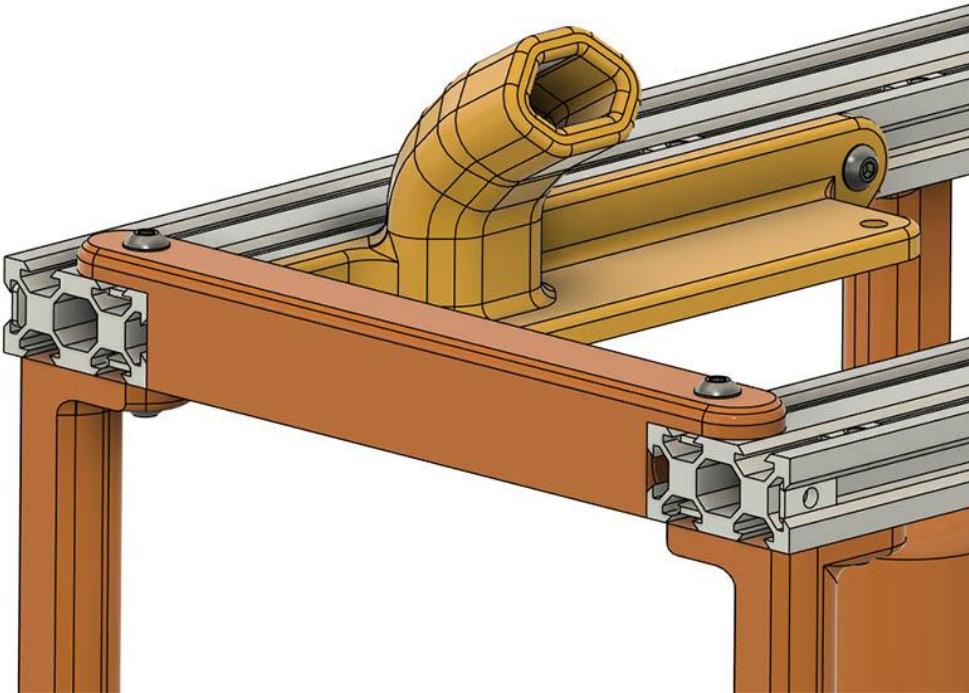
Assemble the 2 **V2040x240_End_Plates** to the other short 2040x140mm extrusion with 8 M5x12mm screws and Tee Nuts. Make sure you have a Tee Nut in the extrusion as we did in the other short 2040x140mm. Make sure it is in the correct groove as shown.



Add the **ShortV_Connect_V2** before putting the end piece on. This is used for connecting the Electronics case to the extrusion.



The next part to install is the **V2020x140_Mod** 3D print. You could also use a 2020x140mm length of extrusion, but this uses only 1 Tee Nut on each side and you do not have any grooves for chaff to get in.



Except for putting the end caps on this completes the top frame construction. I would not put them on until the end in case you need to insert some Tee Nuts somewhere you missed. Only the 2 Tee Nuts in the short 2040x140mm extrusion need to be in there at this point. The others are easy to put in when you need them until the endcaps go on.

Optional 5:1 Planetary Gear

Below is an exploded view of the planetary gear system. I am only showing the hardware for 1 planet to simplify the view.

Hardware:

Planet connection hardware:

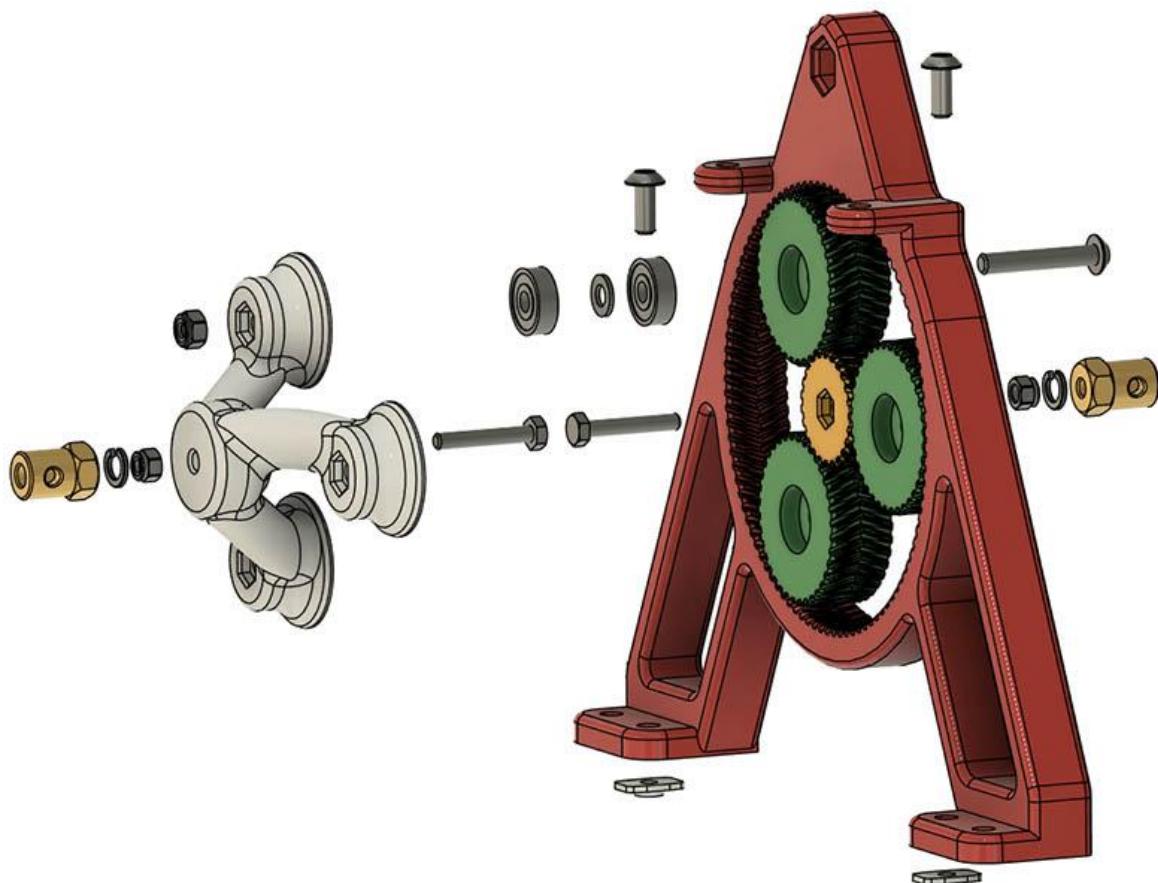
- 3 – M5x30mm button head screws
- 6 - 625-2RS bearings
- 3 – M5 Shim washers (flat washers will probably also work)
- 3 – M5 Locknuts

Shaft Connection hardware:

- 2 – M4x25mm Tap Bolts
- 2 – M4 Lock washers
- 2 – M4 Locknuts
- 2 – Brass Hex Coupler 5mm bore and M4 threads on Hex end

2040 Connection hardware:

- 2 – M5x12mm screws
- 2 – M5 Tee Nuts



Insert a M4 tap bolt through the bottom of the **PlanetDrive_5_1_Rev35** shown in white, Tighten M4 Locknut down on top of Planet drive and add a lock washer on top then thread the brass hex coupler down tight. Insert the other M4 tap bolt through the top of the sun shown in yellow. Before adding all that hardware, we want to add all the planet bearings as it will be easier. Add the 3 – M5x30mm screws through the bottom of each planet. While holding them in place with your fingers, place this gear system on a flat surface. Put a 625-2RS inside the top of each planet followed by M5 shim washer and bearing. Place the **PlanetDrive_5_1_Rev35** on top of the bearings. The M5x30mm screws should protrude through the top. Add a M5 locknut to each and tighten them all the way down, then loosen each M5x30mm screw a little until the gear system turns good. If you had put the M4 hardware on before this, you would not have been able to lay this planetary gear on a flat surface. Now add a M4 locknut down tight on the bottom of the sun and add a lock washer followed by the other brass hex coupler. Tighten the hex coupler all the way down. The M5 end of the coupler behind the sun gear connects to the motor and the other one connects to the shaft. The 2-M5x12mm screws and Tee Nuts connect this planetary gear to the top of the 2040 extrusion.

Nema 17 Motor Mount Assembly

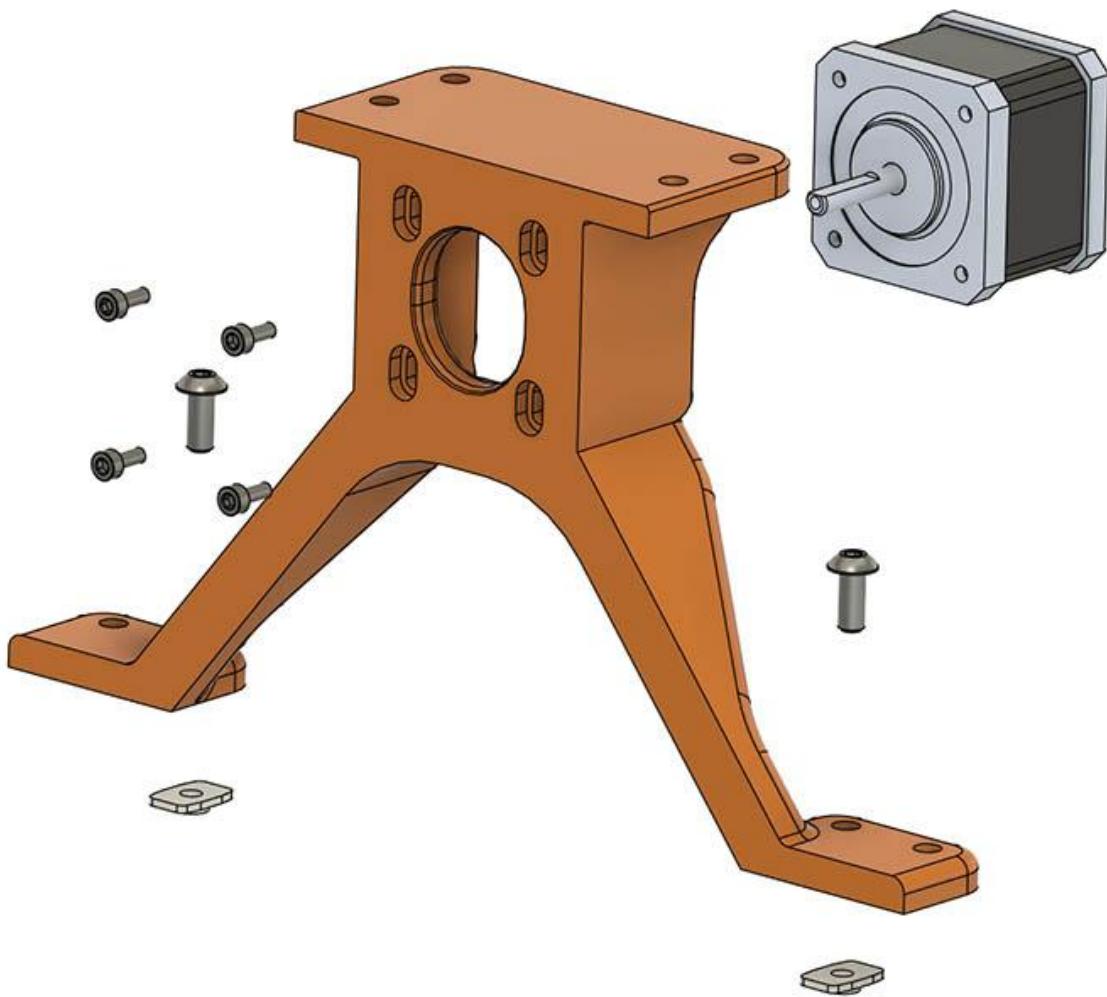
Hardware:

Nema 17 connection hardware:

- 1 – Nema 17 motor (Mine is a 0.9 degree 40mm deep specified in BOM)
- 4 – M3x10mm screws

2040 Connection hardware:

- 2 – M5x12mm screws
- 2 – M5 Tee Nuts



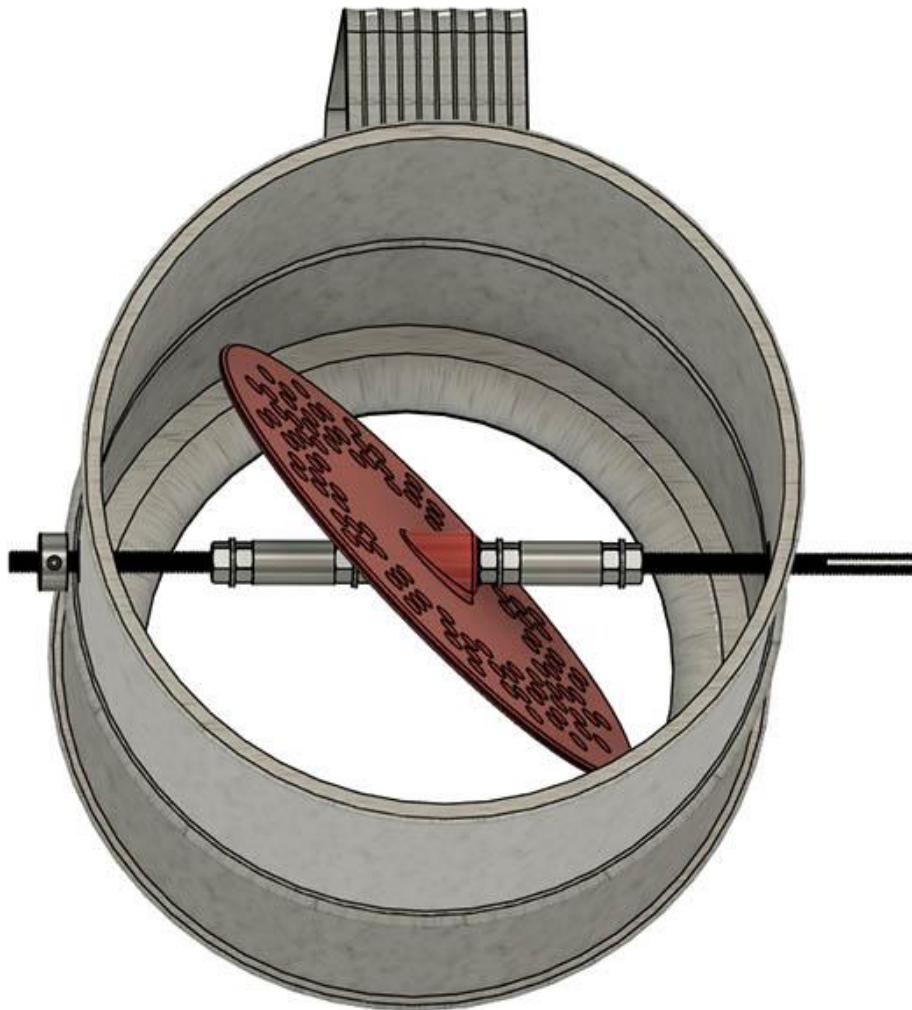
Wobble Disc Assembly with shaft

If you cut your own disc out of stainless steel sheet, your hardware will be different. Whatever method you use, I would recommend 3d printing [WobbleDisck_Mount_JamNuts.stl](#) out of PLA first to check the diameter size. Print it on a 45 degree angle and add manual tree support between bottom and mid-section. Mine ended up being about 5.14" or 130.175mm.

Hardware:

- 1 – 316L 3D Printed Stainless Steel Wobble disc
- 1 – M5x200mm fully threaded 18-8 stainless steel shaft (18-8 = 304 SS)
- 2 – 18-8 Stainless Steel External Tooth Lock Washers
- 4 – Regular M5 hex nuts (4mm thick to better get wrench on)
- 4 – M5 Serrated Flange Lock Nuts.
- 2 – M5x10x18mm 18-8 Stainless Steel Spacers

Only the 2 external tooth lock washers, 2 hex nuts, and 2 serrated flange lock nuts are really necessary. I added the spacers with hex nut, flange nut to cover the threads more. Using more spacers will make it more difficult to put the shaft in. I also recommend drilling out the shaft openings with a 3/8" cobalt drill bit so the shaft does not ride on the sifter at all. That larger hole also allows you to thread all the hardware on outside the sifter. I left about 15mm of the shaft on the outside bearing side and 31mm on the drive side. The coupling on the drive shaft side has 2 set screws 180 degrees apart, so I also filed down the shaft on the drive side on 2 sides so coupling gets better grip.

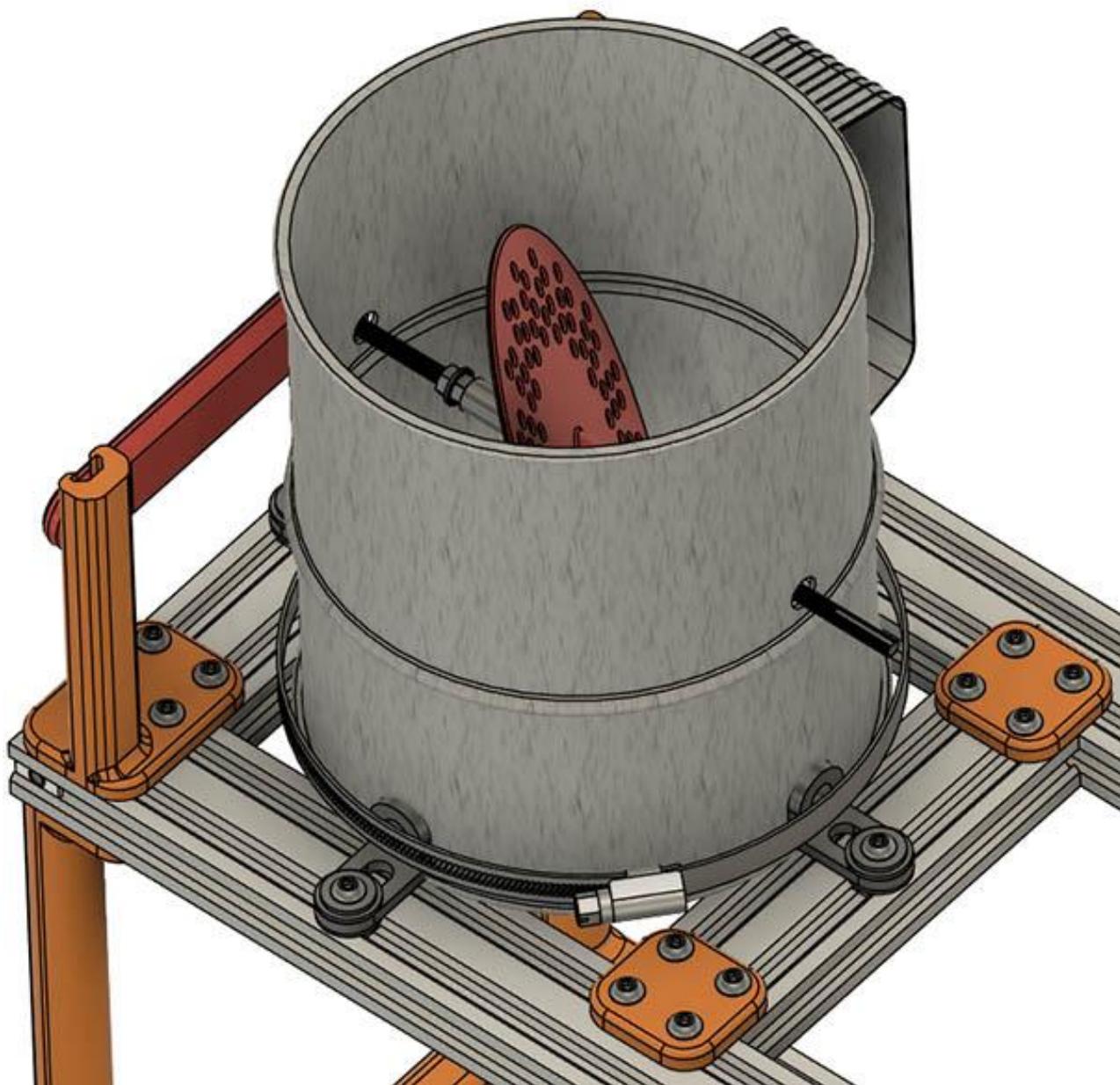


Mount Flour Sifter Assembly to Frame

Hardware:

- 1 – Assembly from previous procedure
- 1 - 5"-7" SS Band Clamp
- 4 – 18x18x30 L Brackets as shown in BOM
- 4 – M5x12mm screws
- 4 – Tee Nuts
- 12 - M5 fender washers as shown in BOM

Mount as shown in graphic below.



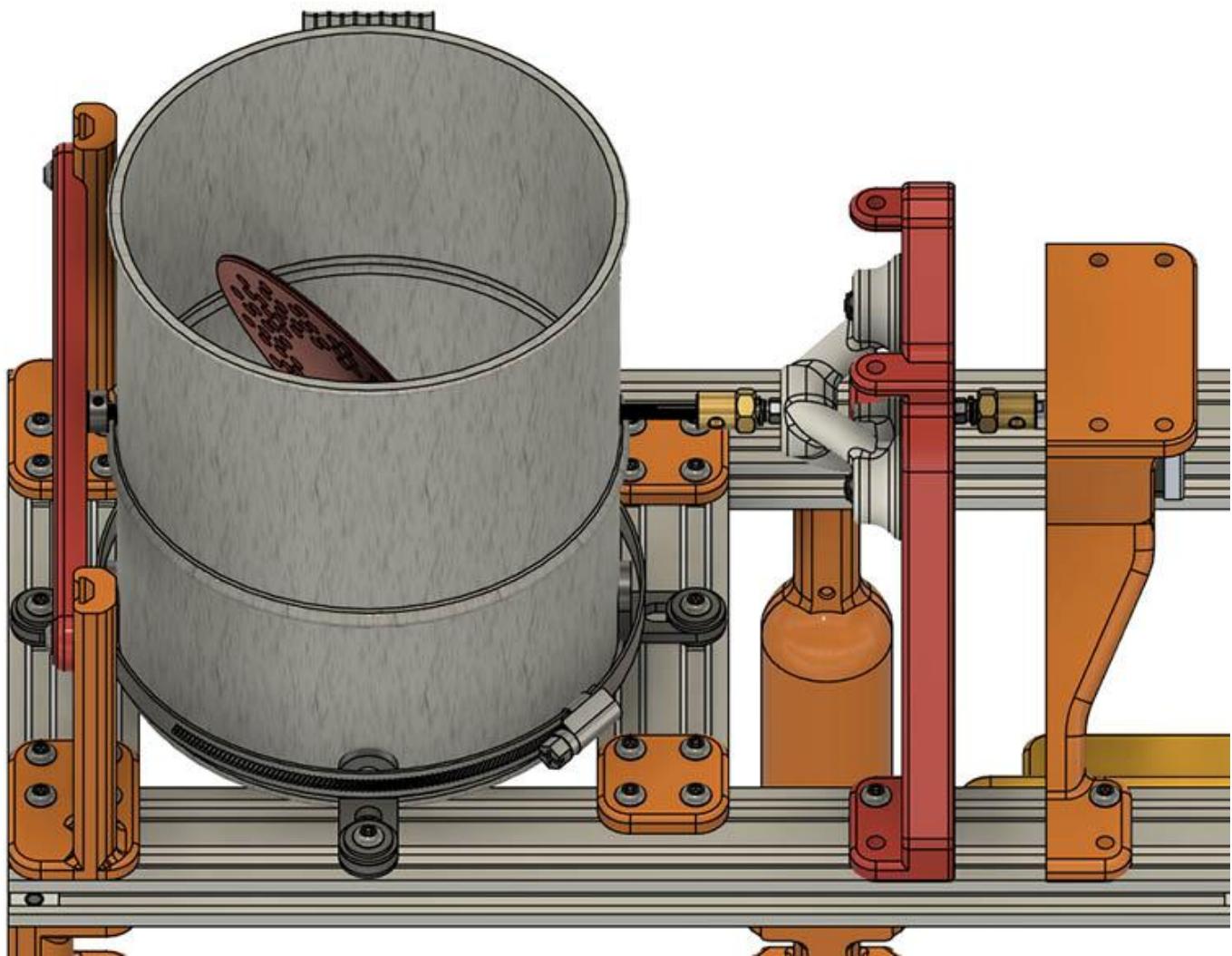
Mount Planetary gear assembly and Motor Mount Assembly

Hardware:

4 – M5x12mm screws

4 – Tee Nuts

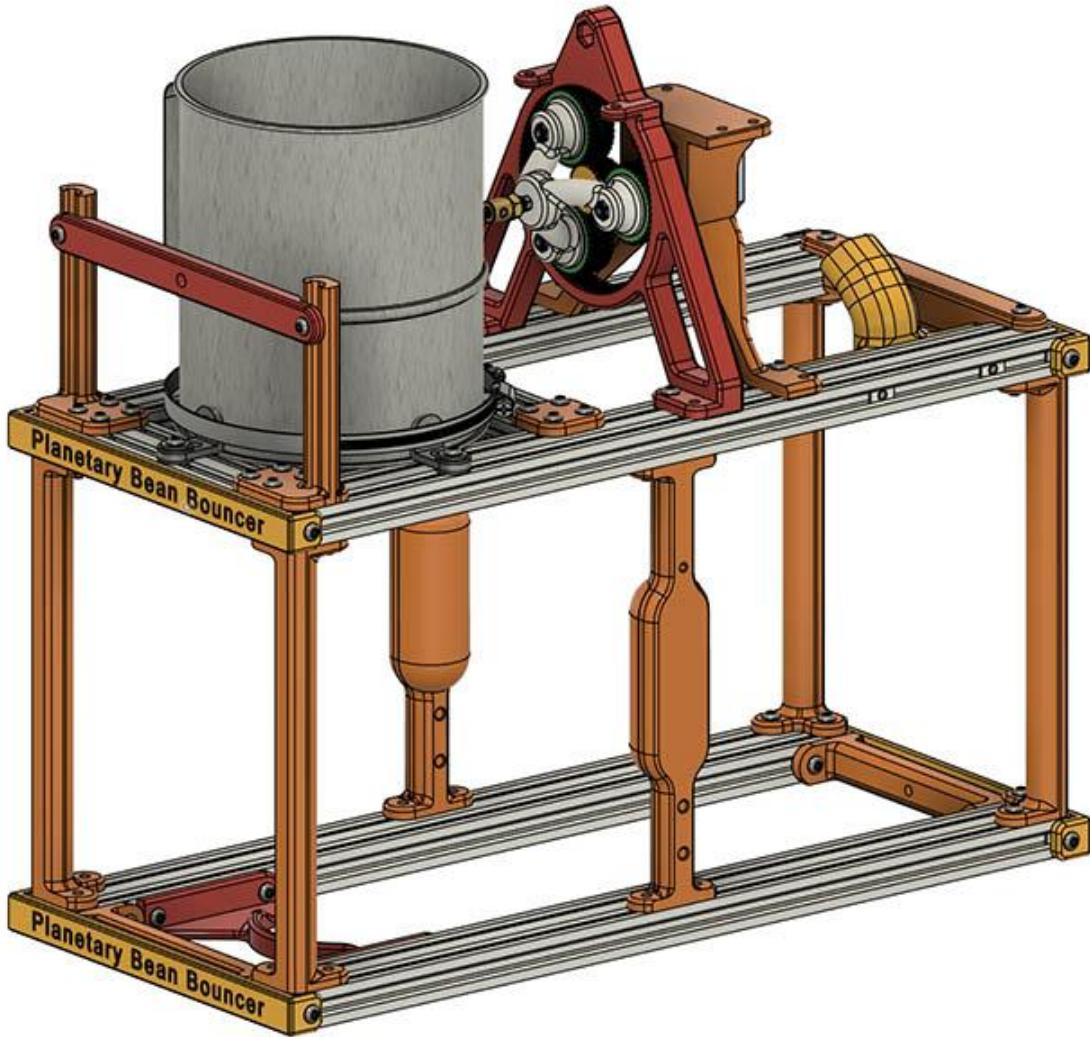
Now add the planetary gear assembly and motor mount assembly. There are 2 extra mounting holes on both the planetary gear and motor mount, but since they are tied together I only use one screw on each side of the mount as shown.



End Cap Assembly

4 – 3D printed End caps
8 – M5x12mm screws
8 – M5 Tee Nuts.

Add the End Caps as shown. They will be the same on both ends



This completes the frame and mechanical build.