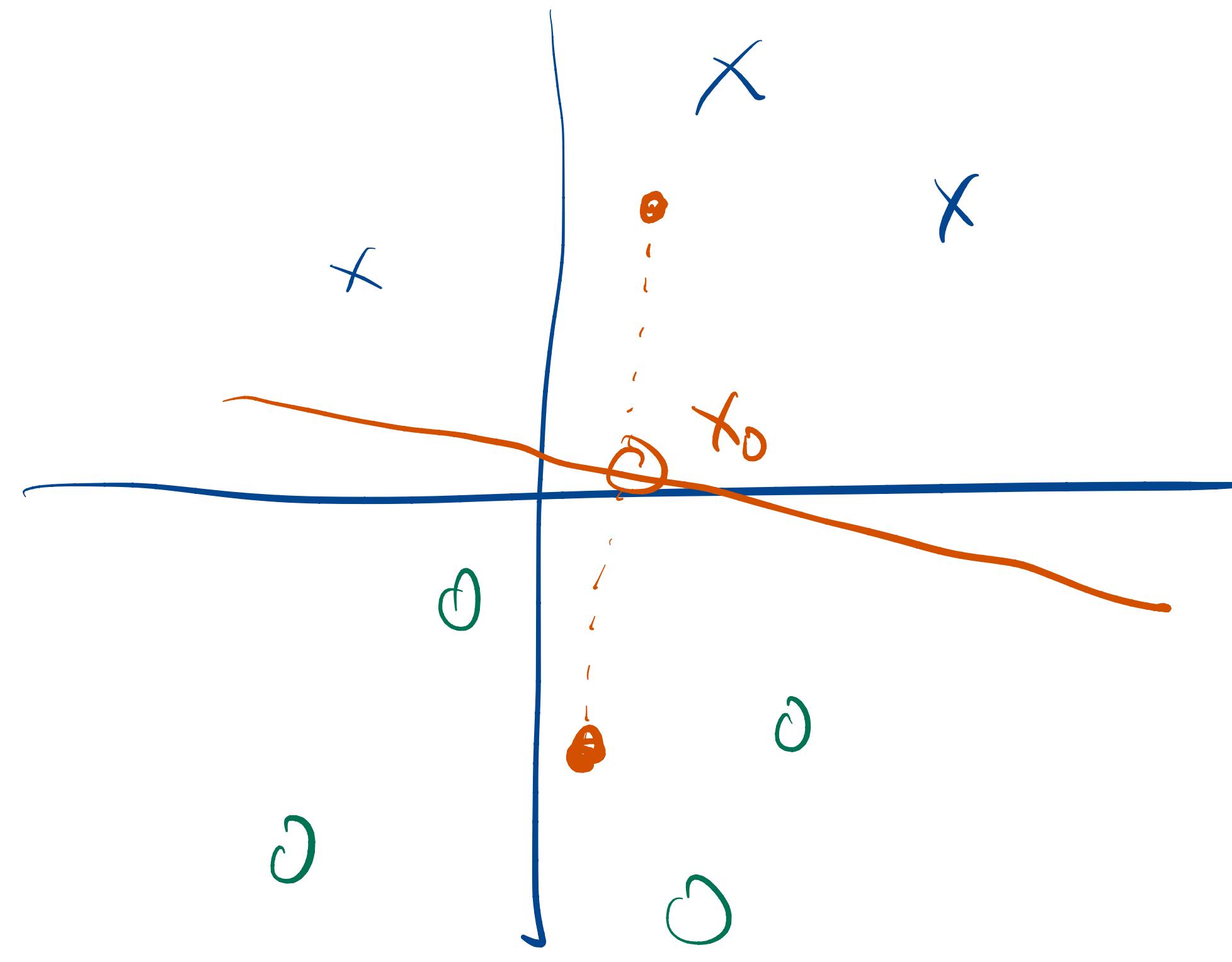


# **Math Foundations for ML**

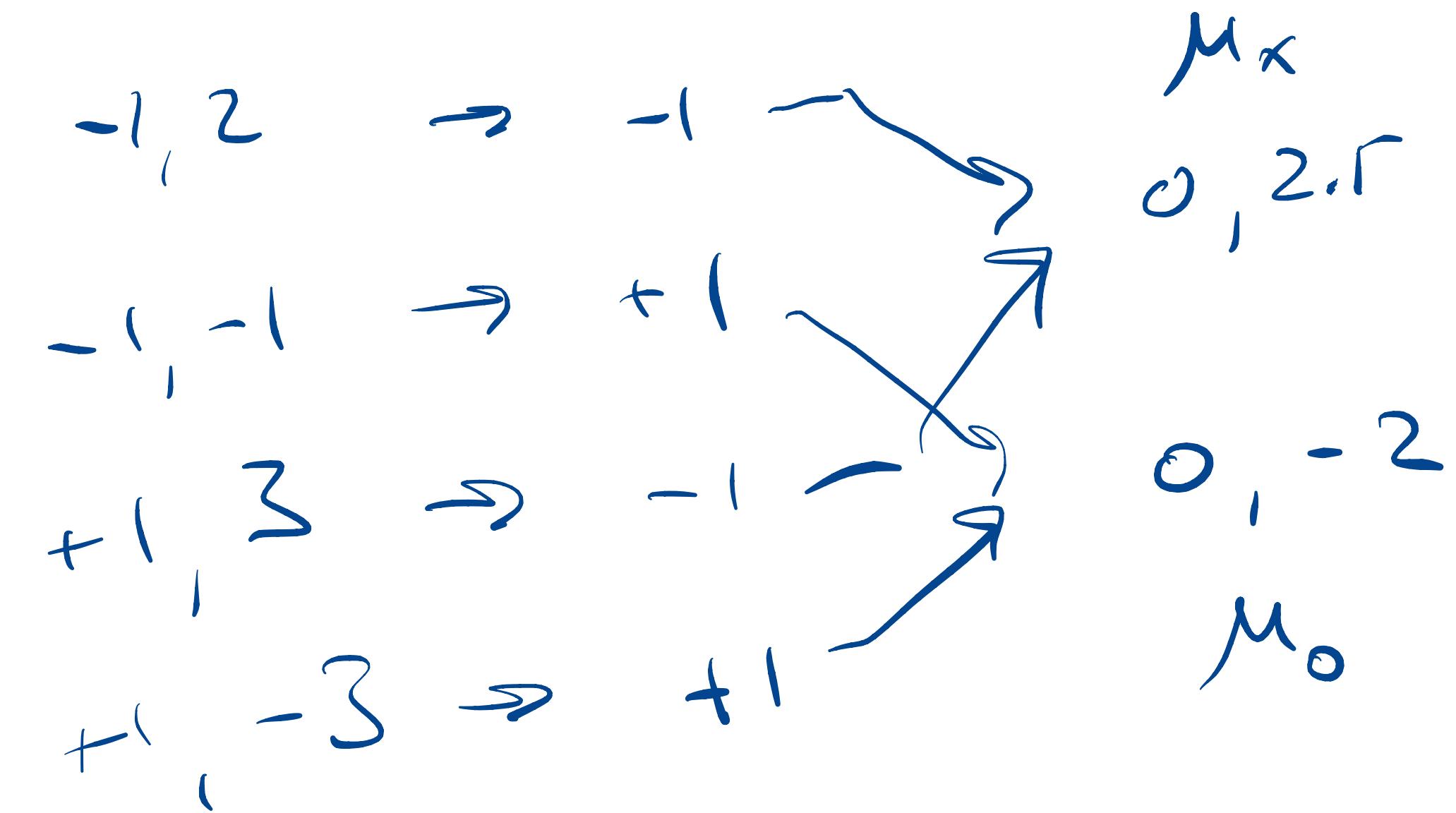
**10-606**

**Geoff Gordon**



$$\begin{pmatrix} 0 \\ -4.5 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 0.25 \end{pmatrix} = 5$$

$\boxed{-1.125}$



$$w - x_0 = b$$

$$x_0 = \frac{\mu_x + \mu_o}{2}$$

$$= (0, 0.25)$$

$$w = \mu_o - \mu_x$$

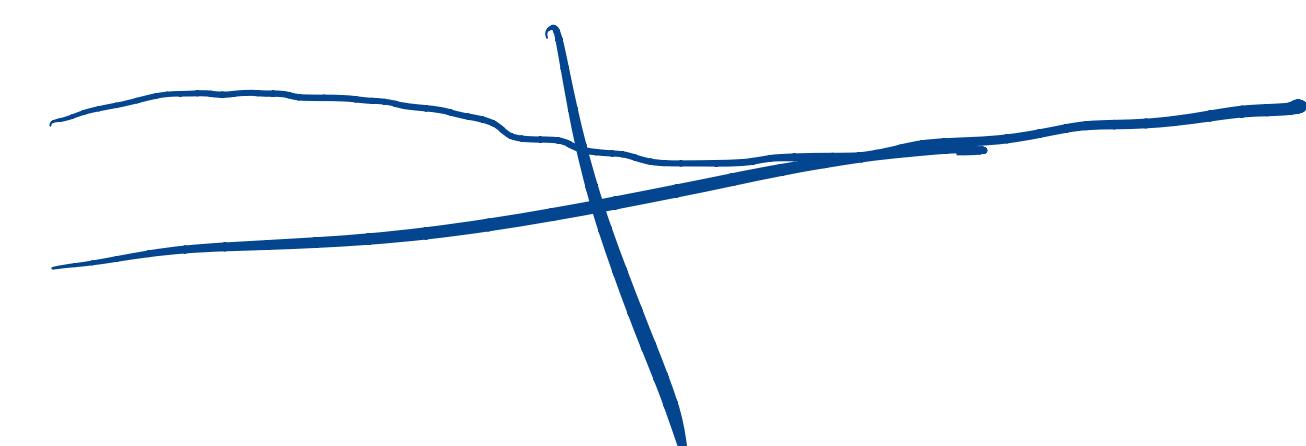
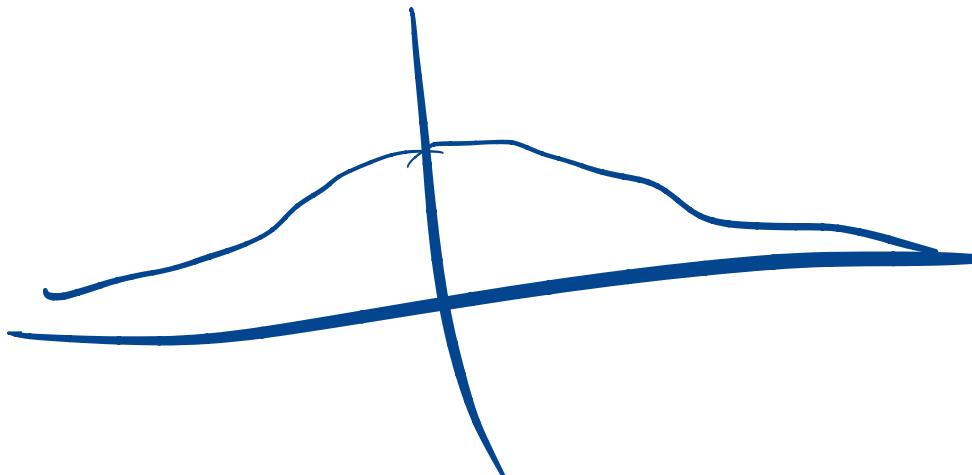
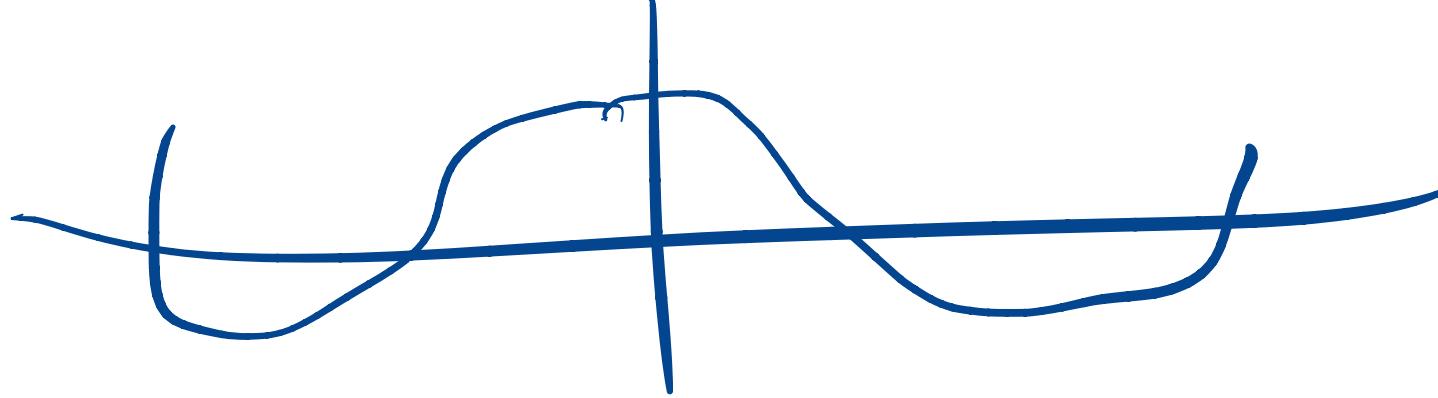
$$= (0, -4.5)$$

$$\begin{pmatrix} & & 0 \\ & \ddots & \\ a_{ij} & & \end{pmatrix}$$

take  $a_{ij}$  times row  $j$   
add to row  $i$

---


$$\text{Span}(\cos(x), e^{-x^2}, \frac{1}{1+e^x}) = \checkmark$$



$$f \in V$$

$$f(0) = 3 \quad f(1) = 2 \quad f(2) = 1$$

$$a \cos(\theta) + b e^{-\theta^2} + c \sqrt{1+e^\theta} = 3$$

$$a + b + \frac{1}{2}c = 3$$

$$A = \begin{pmatrix} 3 & 1 & ? \\ 2 & 4 & -1 \\ -1 & 0 & 3 \end{pmatrix} \xrightarrow{\quad} \begin{pmatrix} 3 & 1 & ? \\ 2 & 4 & -1 \\ 0 & \frac{1}{3} & 5\frac{1}{3} \end{pmatrix} = R_1 A$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{pmatrix} \xrightarrow{\quad} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \frac{1}{3} & 0 & 1 \end{pmatrix} = R_1$$

$$\begin{pmatrix} 3 & 1 & ? \\ 2 & 4 & -1 \\ 0 & \frac{1}{3} & 5\frac{1}{3} \end{pmatrix} \xrightarrow{\quad} \begin{pmatrix} 3 & 1 & ? \\ 0 & 3\frac{1}{3} & 5\frac{2}{3} \\ 0 & \frac{1}{3} & 5\frac{1}{3} \end{pmatrix} = R_2 R_1 A$$

$$R_2 = \begin{pmatrix} 1 & 0 & 0 \\ +\frac{2}{3} & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \xrightarrow{\quad} \begin{pmatrix} 0 & 0 & 0 \\ -2/3 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = R_2$$

$$\tilde{U} = R_2 R_1 A$$

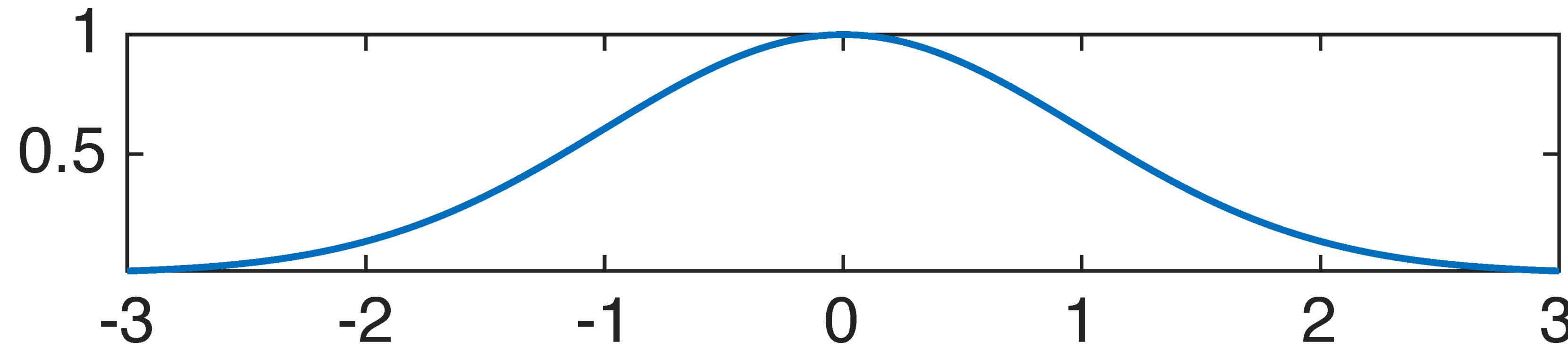
$$(R_2^{-1} \tilde{U}) = F_1 A$$

$$(R_1^{-1} R_2^{-1}) \tilde{U} = A$$

# Gaussian radial basis function

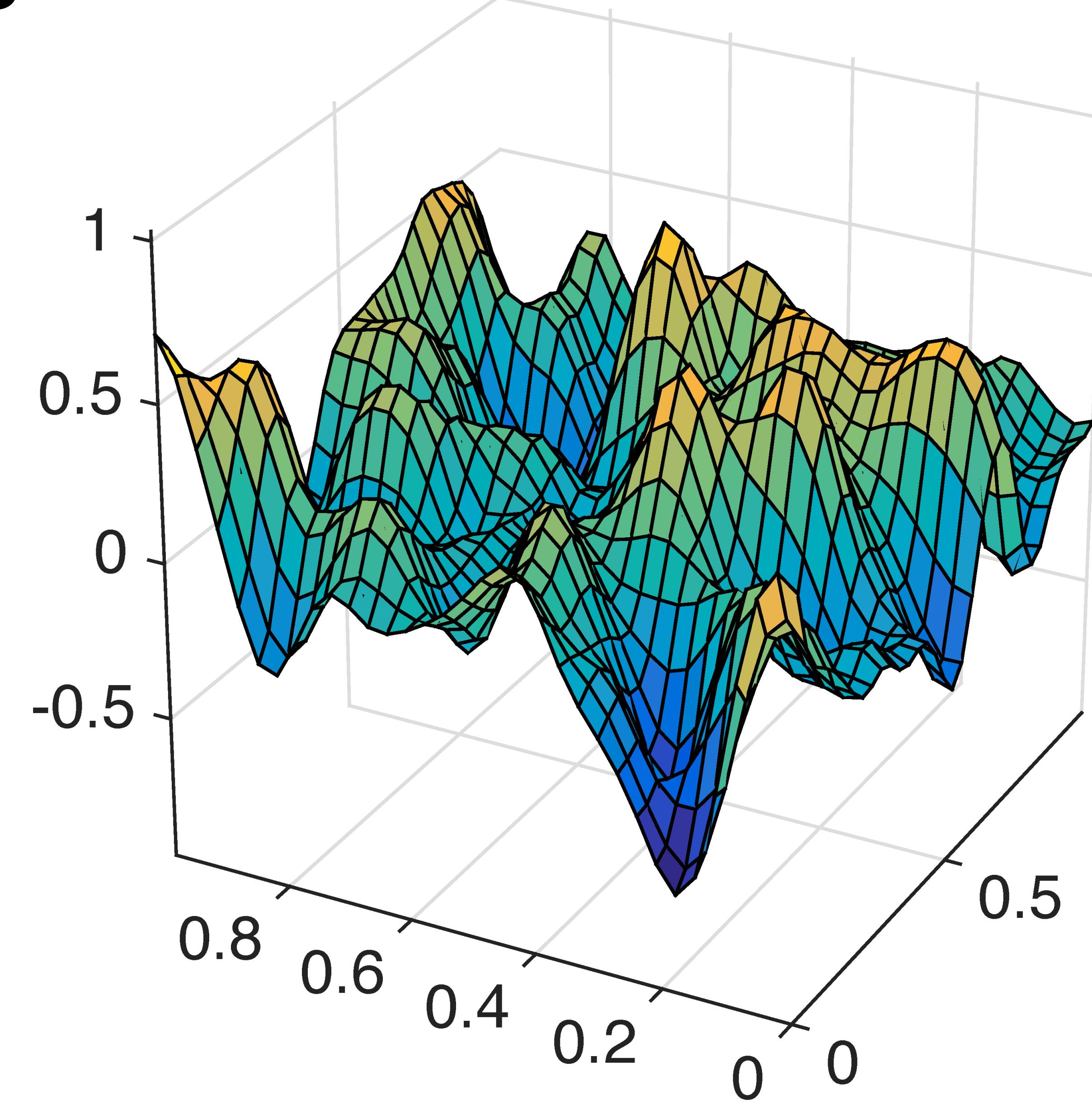
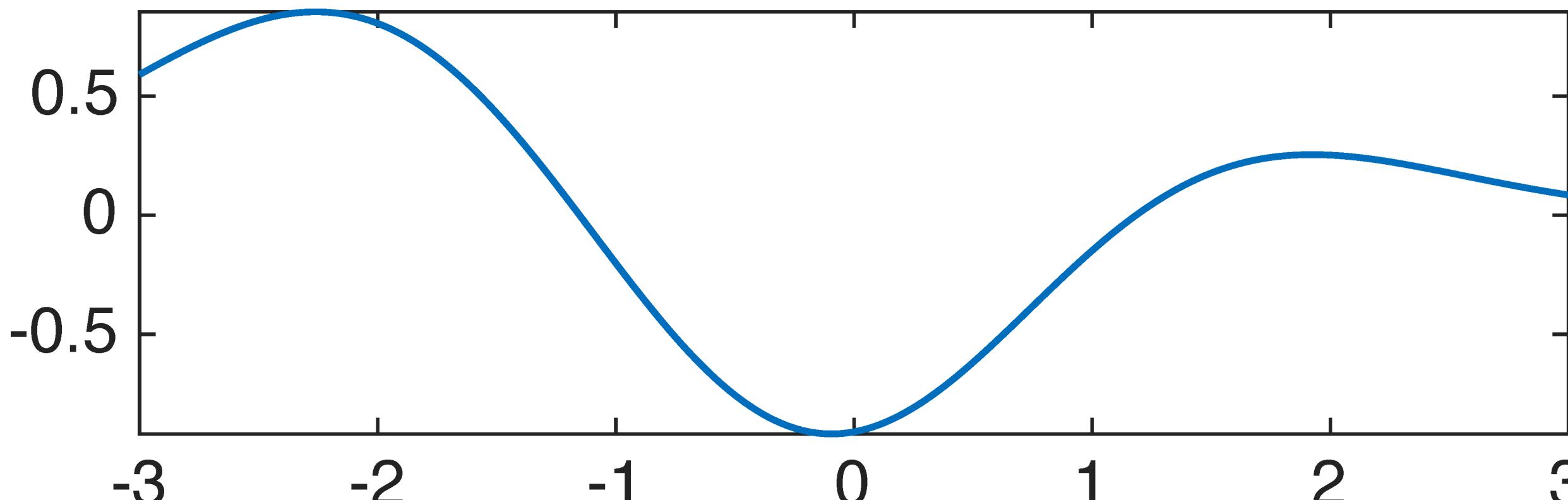
also called squared exponential function

$$e^{-\frac{1}{2} (x - x_0)^2}$$
$$e^{-\frac{1}{2} \|x - x_0\|^2}$$

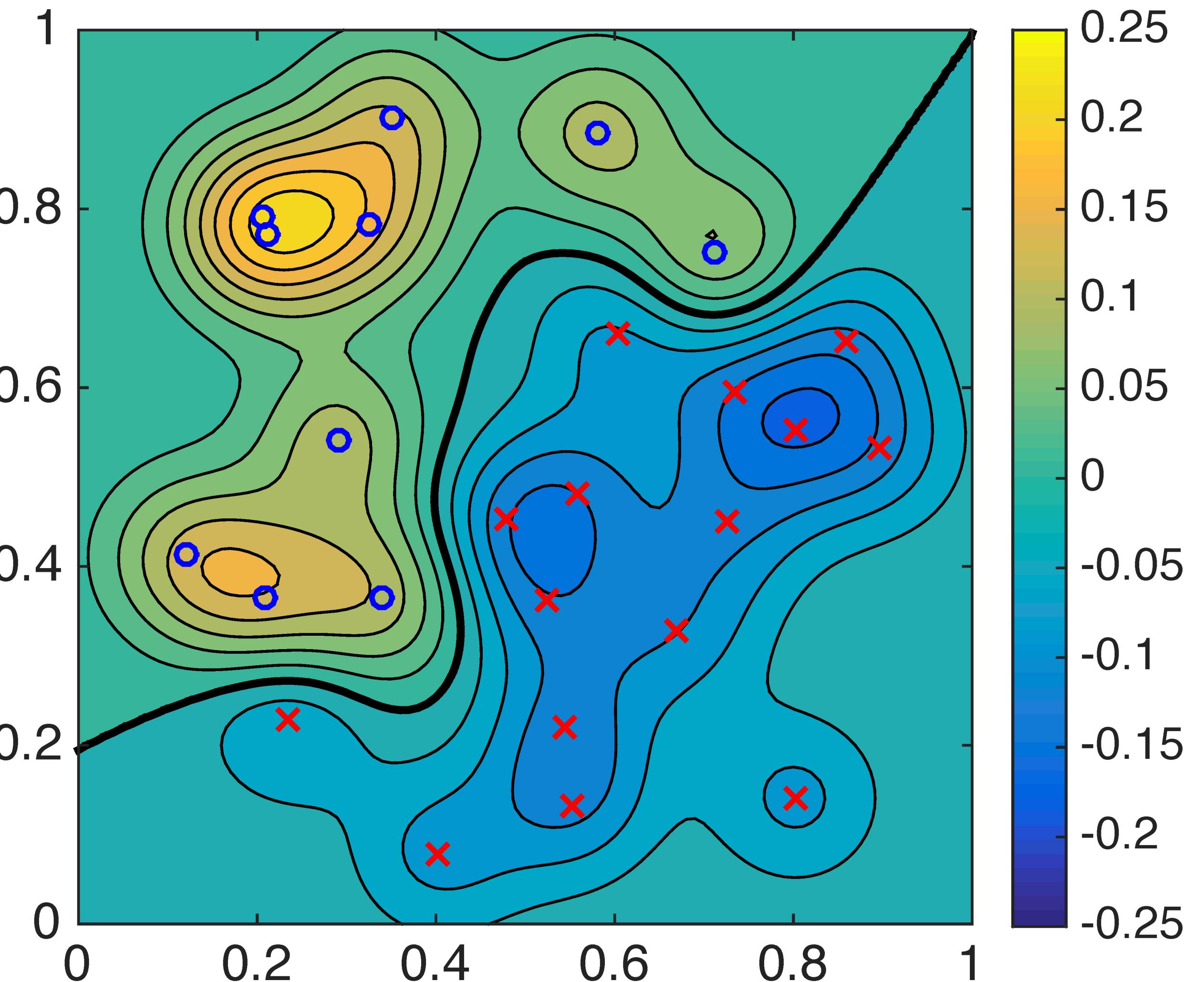
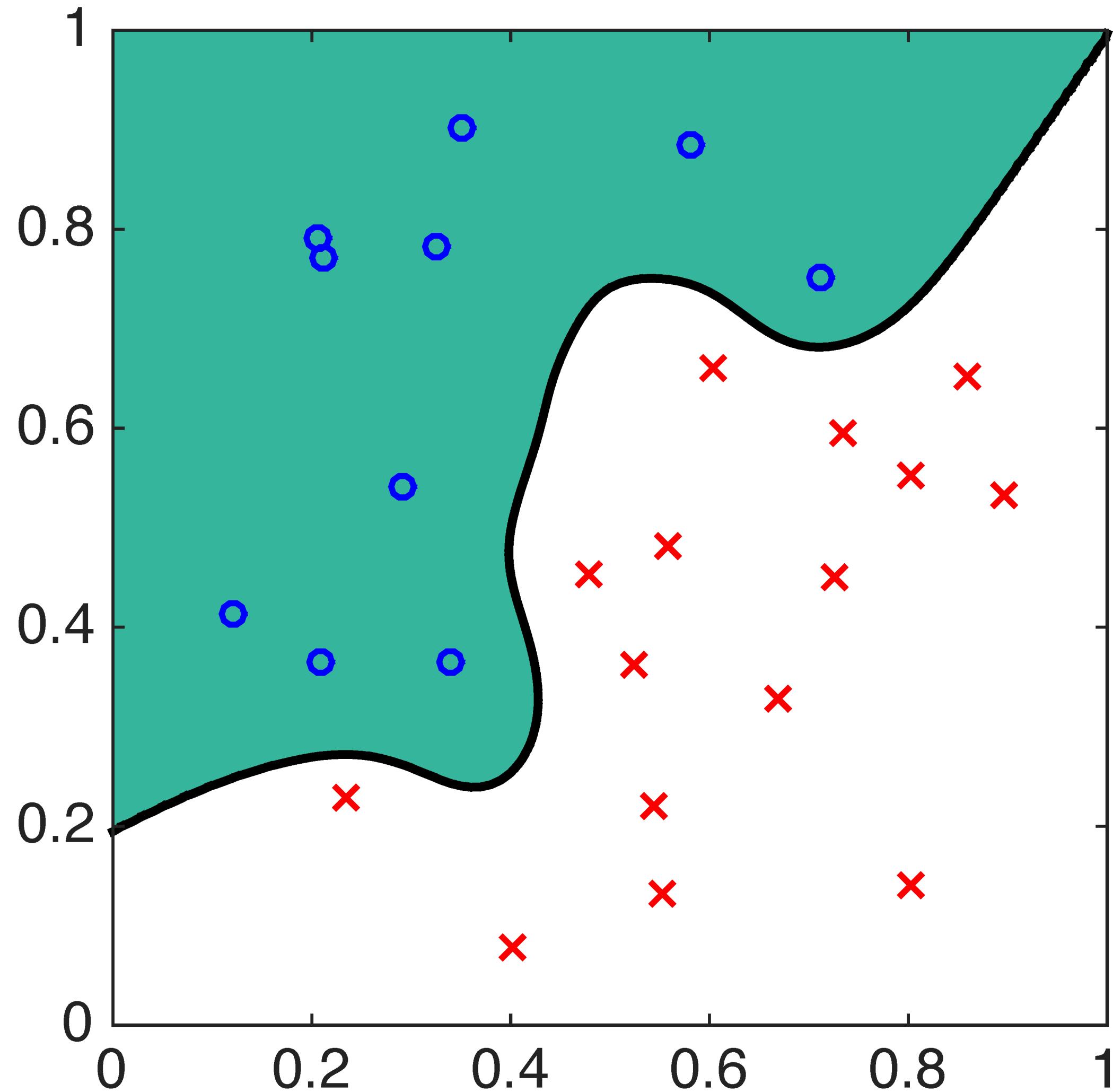


$$\text{at } x_0 = 0$$

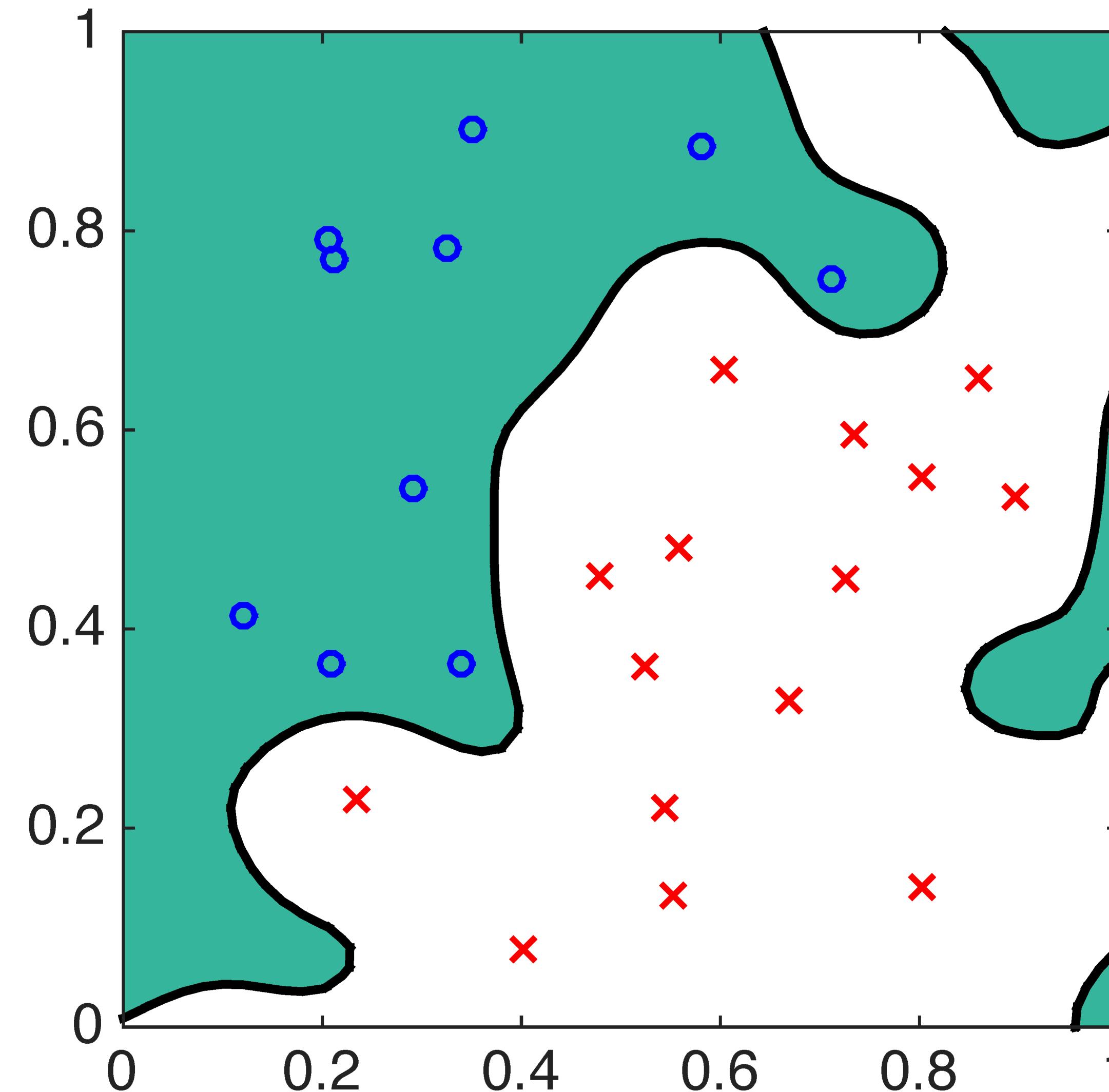
# GRBF vector examples

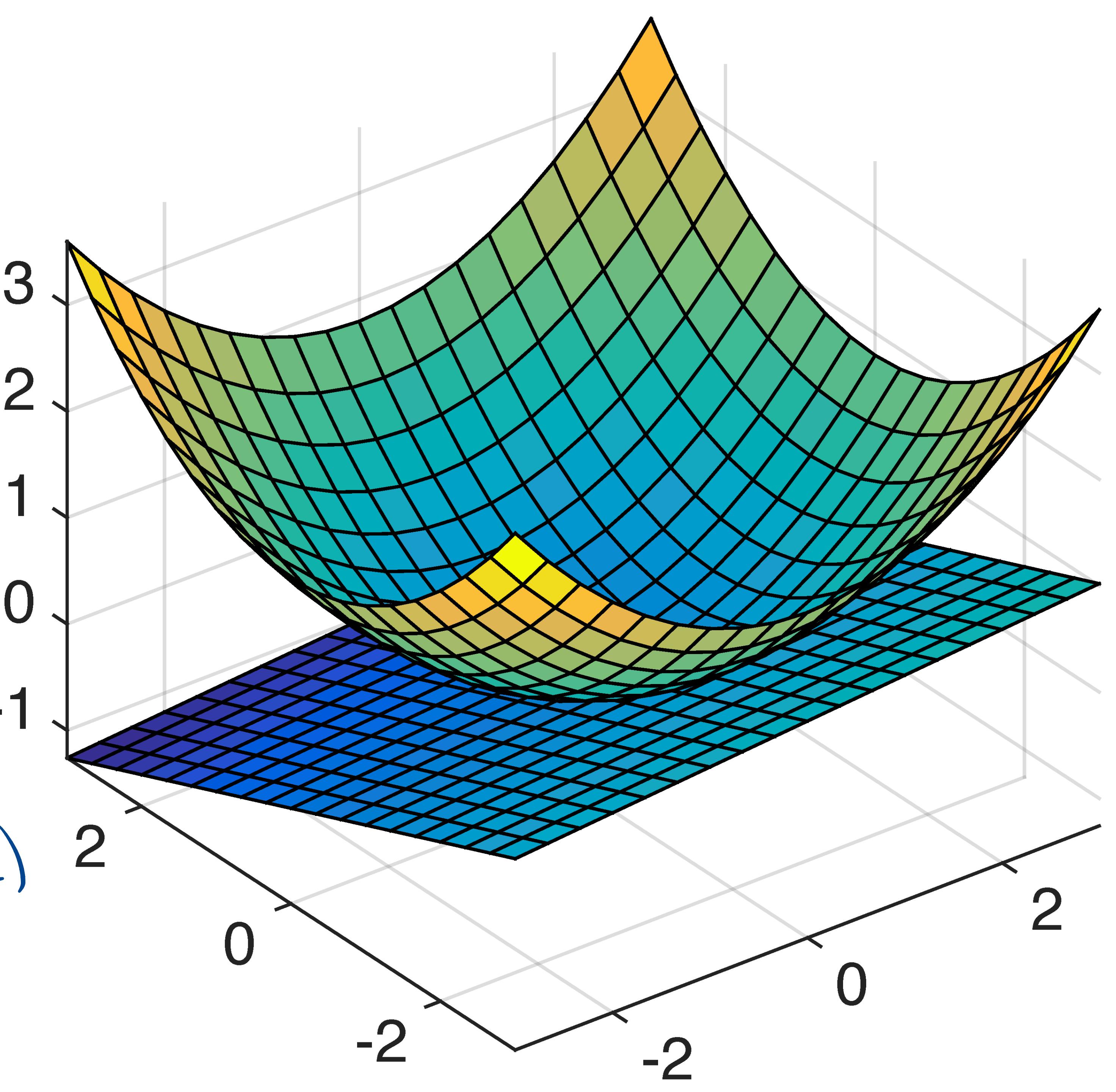
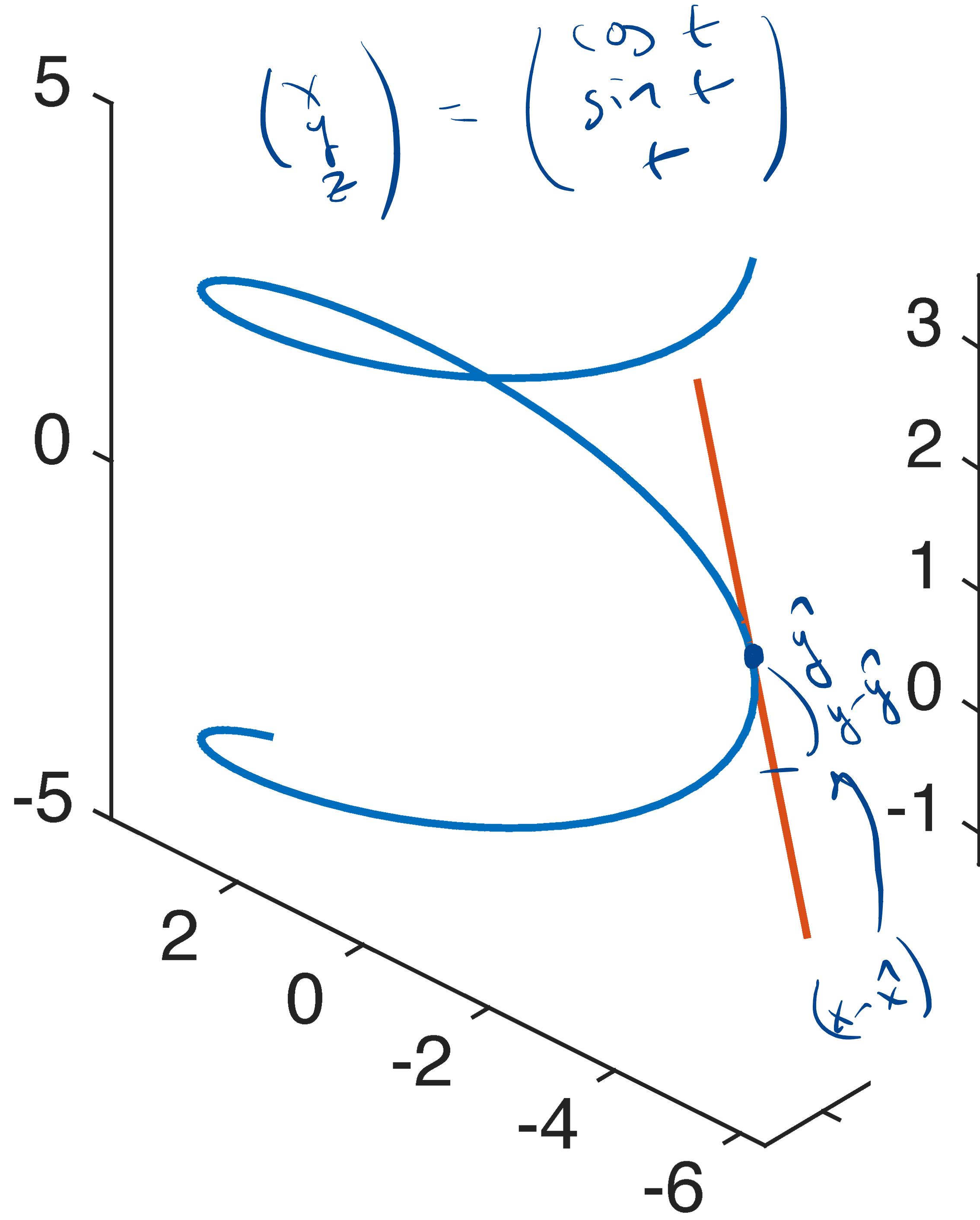


# Linear discriminant in function space



# Narrower RBFs





$$f \in \mathbb{R}^n \rightarrow \mathbb{R}^m$$

$$(y - \hat{y}) = A(x - \hat{x})$$

$\uparrow$  Jacobian       $\uparrow$  point where tangent

$f(\hat{x})$

$$A_{ij} = \frac{\partial y_i}{\partial x_j}$$

$$\frac{dy}{dx} = A dx$$

$$df(x) = f'(x) dx$$
$$d(x^3 + 2x + 3) = (3x^2 + 2) dx$$

$$d \ln \det A = \langle A^{-1}, dA \rangle$$

$$d\|x\| = \frac{x}{\|x\|} dx \quad x \neq 0$$

$$d(a f + b g) = a df + b dg$$

$$d(A^T x + 3y) = A^T dx + 3 dy$$

$$d(fg) = (df)g + f(dg)$$

if  $\Sigma \text{ const}_1 = f dg$

$$d(fgh) = (df)gh + f(dg)h + fg(dh)$$

$$df = f'(x)dx$$

$$f = [-\dots x \dots]$$

$$df = [-\dots x \dots dx \dots]$$

↑  
 $\frac{df}{dx} = f'(x)$

linear index

$$df = \underbrace{\{ \dots x \dots \}}_{\text{Linear function}} dx$$

$$\hookrightarrow f'(x)$$

$$f(x) = u^3 + v^3$$

$$x = \begin{pmatrix} u \\ v \end{pmatrix}$$

$$\begin{aligned} df(x) &= 3u^2 du + 3v^2 dv \\ &= \underbrace{(3u^2 \ 3v^2)}_{\hookrightarrow f'(x)} \begin{pmatrix} du \\ dv \end{pmatrix} \end{aligned}$$

$$\hookrightarrow \frac{df(x)}{dx}$$