

Program 3 (2.daphne)

```
In [17]: from evaluator import evaluate, ast_helper
import pandas as pd
import matplotlib.pyplot as plt
import numpy as np
```

```
In [3]: i=2
fname='{}.daphne'.format(i)
exp = ast_helper(fname,directory='programs/')
%cat programs/2.daphne

(defn marsaglia-normal [mean var]
  (let [d (uniform-continuous -1.0 1.0)
        x (sample d)
        y (sample d)
        s (+ (* x x) (* y y))]
    (if (< s 1)
      (+ mean (* (sqrt var)
                  (* x (sqrt (* -2 (/ (log s) s))))))
      (marsaglia-normal mean var))))

(let [mu (marsaglia-normal 1 5)
      sigma (sqrt 2)
      lik (normal mu sigma)]
  (observe lik 8)
  (observe lik 9)
  mu)
```

```
In [21]: evaluate(exp, do_log=False) # example of the return
```

Out[21]: tensor(2.9357)

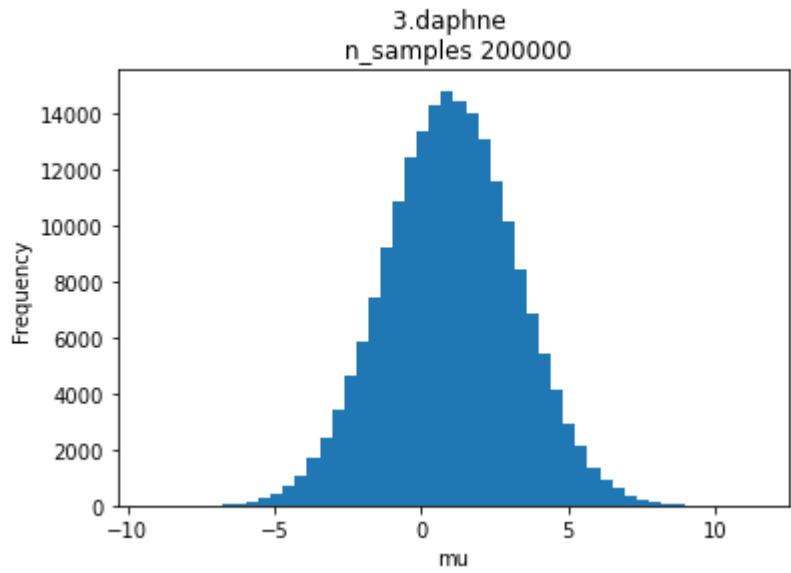
```
In [6]: import sys
sys.setrecursionlimit(1000000)
```

```
In [ ]: n_samples=1000*200
samples = [evaluate(exp).item() for sample in range(n_samples)]
# 10.2s / 1000 samples to 200k in 30 min
```

```
In [22]: # np.save('program3.npy',np.array(samples))
```

```
In [15]: sr = pd.Series(samples)
sr.plot.hist(bins=50)
plt.xlabel('mu')
plt.title('{} \n n_samples {}'.format(fname,n_samples))
```

Out[15]: Text(0.5, 1.0, '3.daphne \n n_samples 200000')



```
In [14]: print('expectation w.r.t. the prior {:.3f}'.format(sr.mean()))
print('std & var w.r.t. the prior {:.3f} & {:.1f}'.format(sr.std(),sr.var()))
```

expectation w.r.t. the prior 1.003
std & var w.r.t. the prior 2.239 & 5.0

The program follows its namesake, the [Marsaglia polar method](#), and so we know the distribution of the prior is $\mathcal{N}[\mu|0, 5]$. We can thus check that we are within 5% tolerance.

```
In [20]: gt_mean = 1
gt_var = 5

assert np.abs(gt_mean - sr.mean()) / gt_mean < 0.05
assert np.abs(gt_var - sr.var()) / gt_var < 0.05
```

A normally distributed random quantity, via transformation and rejection. Take a little time to think about the sampled values of x and y and be amazed that this works. Think a little about how to deal with this kind of case in amortized inference settings.

The prior is using control flow with the `if` statement, essentially rejection sampling to ensure (x,y) are "inside the unit circle".

So we can get a new type of distribution, a normal with two parameters, from just two continuous distributions x and y.

In amortized inference, we could use some NN transformation of uniform RVs, to learn a new distribution. If the distribution was normal, perhaps they would learn the Marsaglia polar method, or some other method to sample from a Normal (the wiki page mentioned a few).

If our posterior was some arbitrary distribution, we could fit the parameters of the NN in amortized inference, and learn the custom transform for that posterior.