

# Rigidity and Stability of Three-tori

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## 1 Rigidity

## 2 How Different is the Stability Case?

## 3 Producing a Good Map

- Successive Minima and Hebda's Lemma
- Estimates in Terms of the Stable Systoles

# Rigidity

## Theorem

Let  $g$  be a smooth Riemannian metric on  $\mathbb{T}^3$ . Denote by  $S$  the scalar curvature of  $g$ . If  $S_g \geq 0$ , then the metric  $g$  is flat.

## Proof.

- We have  $\mathbb{Z}^3 = H^1(\mathbb{T}^3; \mathbb{Z}) \simeq H^1(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}}$ . Let  $\{w^i\}_{i=1}^3$  be a basis of  $H^1(M; \mathbb{Z})_{\mathbb{R}}$ .
- For each  $i$ , find an harmonic one-form  $\omega^i \in w^i$ , and let  $u^i : \mathbb{T}^3 \rightarrow \mathbb{S}$  be the map generated by  $\omega^i$ . Let  $\mathbb{U} : \mathbb{T}^3 \rightarrow \mathbb{T}^3$  be  $(u^1, u^2, u^3)$ .
- Observe that  $\mathbb{U}^*(d\theta^1 \wedge d\theta^2 \wedge d\theta^3) = du^1 \wedge du^2 \wedge du^3$ . Since  $du^i = \omega^i \in w^i$ , and the  $w^i$  form a basis, it follows that  $du^1 \wedge du^2 \wedge du^3$  represent a basis element of  $H^3(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}}$ : so  $\int_{\mathbb{T}^3} du^1 \wedge du^2 \wedge du^3 = \pm 1$ .

## Proof.

- Force  $\mathbb{U}$  to have  $\deg(\mathbb{U}) = 1$ . In particular, we see that  $\mathbb{U}$  is surjective.
- Consider the matrix of functions  $g_{ij} = g(du^i, du^j)$ . Observe that  $dg_{ij}(X) = g(\nabla_X du^i, du^j) + g(du^i, \nabla_X du^j)$ .
- Take the norm and integrate to obtain

$$\int_{\mathbb{T}^3} |dg_{ij}| \text{vol}_g \leq \int_{\mathbb{T}^3} |\nabla du^i| |du^j| + |\nabla du^j| |du^i| \text{vol}_g.$$

## Proof.

- From Stern's inequality, we have

$$-\int_{\mathbb{T}^3} S|du^i| \geq \int_{\mathbb{T}^3} \frac{|\nabla du^i|^2}{|du^i|} \text{vol}_g.$$

- If  $S \geq 0$ , this means that  $|\nabla du^i| = 0$ , and so  $g_{ij}$  is constant for all  $i, j$ .
- $\det(g_{ij}) = |du^1 \wedge du^2 \wedge du^3|^2$ . Since  $\int_{\mathbb{T}^3} du^1 \wedge du^2 \wedge du^3 = 1$ , this shows that  $\det(g_{ij}) > 0$ , and  $du^1 \wedge du^2 \wedge du^3$  never vanishes.
- Recall that

$$\deg(\mathbb{U}) = \sum_{x \in \mathbb{U}^{-1}\{y\}} \text{sign}(du^1 \wedge du^2 \wedge du^3)(x)$$

## Proof.

- Let  $a = (g_{ij})^{-1}$ , and consider the metric  $g_F = a_{kl}d\theta^k d\theta^l$ . Then, we see that  $\mathbb{U} : (\mathbb{T}, g) \rightarrow (\mathbb{T}^3, g_F)$  is an isometry:

$$\mathbb{U}^*g_F(\nabla u^i, \nabla u^j) = a_{kl}du^k du^l(\nabla u^i, \nabla u^j) = g_{ij} = g(\nabla u^i, \nabla u^j).$$



# To Stability

## What Changes

- The term  $\int_{\mathbb{T}^3} S|du|\text{vol}_g$  will no longer be zero.
- We should only expect integral control: all we can say initially is that  $\int_{\mathbb{T}^3} \frac{|\nabla du|^2}{|du|}\text{vol}_g$  is small.
- Controlling  $\int_{\mathbb{T}^3} |S||du|\text{vol}_g$  means finding some control on  $|du|$ .

## Goal

Let  $g$  be a metric  $\mathbb{T}^3$ . We wish to find geometric conditions on  $g$  which ensure that there exists a basis  $w^i$  of  $H^1(M; \mathbb{Z})_{\mathbb{R}}$  with harmonic representatives  $\omega^i$  whose  $L^2$  norms are well controlled.

## Definition

Let  $g$  be a Riemannian metric on  $\mathbb{T}^3$ , let  $w \in H^1(M; \mathbb{Z})_{\mathbb{R}}$ , and let  $\omega$  be the harmonic representative of  $w$ . Then, we define  $\|w\|_g = (\int_{\mathbb{T}^3} |\omega|^2 \text{vol}_g)^{\frac{1}{2}}$ . This gives  $H^1(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}}$  an innerproduct, also denoted  $g$ .

## Definition

Let  $g$  be a Riemannian metric on  $\mathbb{T}^3$ , then we define  
 $\lambda_1 = \min \{ |w|_g : w \in H^1(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}} \}$ , and we call it the first successive minima of the lattice  $H^1(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}}$ .

## Definition

We define

$$\lambda_2 = \min \{ \lambda : \exists \text{ independent } v, w \in H^1(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}}, \max\{|v|, |w|\} \leq \lambda \},$$

and  $\lambda_3$  is defined similarly.

## Lemma

There exists a basis of  $H^1(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}}$ , say  $\{w^i\}_{i=1}^3$  such that  $|w^1|_g = \lambda_1$ ,  $|w^2|_g \leq \lambda_2$ , and  $|w^3|_g \leq \frac{3}{2}\lambda_3$ .

## Proof.

An application of a few results that can be found in the book by Cassels.



## Remark

These results apply to arbitrary lattices in  $\mathbb{R}^n$  with arbitrary norms. In particular, the definition of the successive minima holds for any lattice, and in general we have  $n$  of them.

# The Lemma of Hebda

## Lemma (Hebda)

Let  $(M, g)$  be a smooth closed oriented Riemannian manifold. For  $a \in H_{dR}^{m-1}(M)$  we have  $\text{PD}(a) \in H_1(M; \mathbb{R})$ , and

$$\|\text{PD}(a)\|_1 \leq \text{Vol}_g(M)^{\frac{1}{2}} C(m, 1) \min \left\{ \left( \int_M |\omega|^2 \text{vol}_g \right)^{\frac{1}{2}} : \omega \in a \right\}.$$

## Lemma

For all  $w$  in  $H^1(\mathbb{T}^n; \mathbb{Z})_{\mathbb{R}}$ , we have that  $\text{PD}(w)H_1(\mathbb{T}^n; \mathbb{R})$  has a representative  $c = \sum_i z_i \sigma_i$  where the  $z_i \in \mathbb{Z}$ .

## Definition

We set  $H_1(\mathbb{T}^n; \mathbb{Z})_{\mathbb{R}} = \{a \in H_1(\mathbb{T}^n; \mathbb{R}) : \exists c = \sum_i z_i \sigma_i \in a, z_i \in \mathbb{Z}\}$ . The one stable-systole, denoted  $\text{stabsys}_1(\mathbb{T}^n g)$ , is defined to be

$$\text{stabsys}_1(\mathbb{T}^n, g) = \inf \{\|a\|_1 : a \in H_1(\mathbb{T}^n; \mathbb{Z})_{\mathbb{R}}\}.$$

## Lemma

Let  $g$  be a Riemannian metric on  $\mathbb{T}^3$ , then we have that

$$\text{stabsys}_1(\mathbb{T}^3, g) \leq \text{Vol}_g(\mathbb{T}^3)^{\frac{1}{2}} C(3, 1) \min \{|w|_g : w \in H^2(\mathbb{T}^3, \mathbb{Z})_{\mathbb{R}}\}$$

## Proof.

Every element  $w \in H^1(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}}$  has Poincaré Dual  $\text{PD}(w) \in H_1(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}}$ . Therefore,  $\text{PD}(w)$  is a competitor in the definition of  $\text{stabsys}_1(\mathbb{T}^3, g)$ . It follows from Hebda's result that we have

$$\text{stabsys}_1(\mathbb{T}^3, g) \leq \text{Vol}_g(\mathbb{T}^3)^{\frac{1}{2}} C(3, 1) \min \{|w|_g : w \in H^2(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}}\}.$$



## Definition

We set  $H_m(\mathbb{T}^n; \mathbb{Z})_{\mathbb{R}} = \{a \in H_m(\mathbb{T}^3; \mathbb{R}) : \exists c = \sum_i z_i \sigma_i \in a, z_i \in \mathbb{Z}\}$ . Then, we define  $\text{stabsys}_m(\mathbb{T}^n, g)$  to be

$$\text{stabsys}_1(\mathbb{T}^3, g) = \inf \{\|a\|_m : a \in H_m(\mathbb{T}^n; \mathbb{Z})_{\mathbb{R}}\}.$$

## Lemma

Let  $g$  be a Riemannian metric on  $\mathbb{T}^3$ . Then, we have that

$$\text{stabsys}_2(\mathbb{T}^3, g) \leq \text{Vol}_g(\mathbb{T}^3)^{\frac{1}{2}} C(3, 2) \min \{ |w|_g : w \in H^1(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}} \}$$

## Where we are

Let  $\lambda_1$  denote the first successive minima of  $H^1(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}}$  and let  $\mu_1$  denote the first successive minima of  $H^1(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}}$ . Then, we have that

$$\text{stabsys}_1(\mathbb{T}^3, g) \leq C \text{Vol}_g(\mathbb{T}^3)^{\frac{1}{2}} \mu_1$$

and

$$\text{stabsys}_2(\mathbb{T}^3, g) \leq C \text{Vol}_g(\mathbb{T}^3)^{\frac{1}{2}} \lambda_1.$$

## Lemma

Let  $g$  be a Riemannian metric on  $\mathbb{T}^3$ . Then, we have that

$$1 = \det_g (H^1(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}}) \cdot \det_g (H^2(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}}) \quad (1)$$

## Proof.

Let  $w^i$  be a basis of  $H^1(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}}$  and let  $\theta_j$  be the dual elements such that  $\theta_j(w^i) = \delta_{ij}$ . Since the cohomology of  $\mathbb{T}^3$  is free, the  $\theta_j$  are represented by elements  $v^j \in H^2(\mathbb{T}^3)$ , and since  $\star$  is an isometry, we may associate  $H_{dR}^2(\mathbb{T}^3)$  with  $H_{dR}^1(\mathbb{T}^3)$ .



## Lemma

Let  $L \subset \mathbb{R}^n$  be a lattice, let  $|\cdot|$  be the usual Euclidean norm on  $\mathbb{R}^n$ , and let  $\lambda_1, \dots, \lambda_n$  be the successive minima of  $L$ . Then, there is a constant  $C(n)$  depending only on  $n$  such that

$$\det(L) \leq \lambda_1 \cdots \lambda_n \leq C(n) \cdot \det(L)$$

## Lemma

Let  $g$  be a Riemannian metric on  $\mathbb{T}^3$  and suppose that

$\min\{\text{stabsys}_1(\mathbb{T}^3, g), \text{stabsys}_2(\mathbb{T}^3, g)\} \geq \sigma > 0$ . Then, there is a constant  $C(\sigma, |\mathbb{T}^3|)$  such that  $\max_{i=1,2,3} \lambda_i \leq C(\sigma, |\mathbb{T}^3|_g)$ , and so there is a basis of  $H^1(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}}$ , say  $\{w^i\}_{i=1}^3$ , such that  $|w^i|_g \leq C(\sigma, |\mathbb{T}^3|_g)$ .

## Proof.

Let  $\{\lambda_i\}_{i=1}^3$  be the successive minima of  $H^1(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}}$  and let  $\{\mu_i\}_{i=1}^3$  be the successive minima of  $H^2(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}}$ . Then, we have

$$\begin{aligned}\lambda_1^{-3} &\geq \lambda_1^{-1} \lambda_2^{-1} \lambda_3^{-1} \geq \frac{1}{C \det(H^1(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}})} = \frac{\det(H^2(\mathbb{T}^3; \mathbb{Z})_{\mathbb{R}})}{C} \\ &\geq \frac{\mu_1 \mu_2 \mu_3}{C^2} \\ &\geq \frac{\mu_1^3}{C^2} \\ &\geq \frac{\text{stabsys}_1^3}{|\mathbb{T}|_g^{\frac{3}{2}} C^2}\end{aligned}$$

