

Algebraic Tools for Computing Polynomial Loop Invariants

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Joint work with Erdenebayar Bayarmagnai and Rémi Prébet

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Polynomial equations/inequalities that hold before & after every iteration.

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end while

- Values of (x, y) : $(1, 0), (1, 1), (2, 1), (3, 2), (5, 3), 8, 5)$

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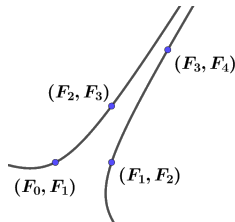
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- **Special classes of loops:**

- [Affine loops](#) (Hrushovski, Ouaknine, Pouly, Worrell; LICS '18)
- [P-solvable loops](#) Kovács; TACAS '08
- [Solvable loops](#) (Rodriguez-Carbonell, Kapur; Symb. Comput. '07)

- **Degree-bounded polynomial invariants:**

- [Synthesis for solvable loops](#) (Amrollahi, Bartocci, Kenison, Kovács, Moosbrugger, Stankovic; Formal Methods Syst. Des. '24)
- [Ideal-based reasoning](#) (Cyphert Kincaid; ACM '24)
- [Invariants from symbolic initialization](#) (Müller-Olm, Seidl; Inf. Process. Lett. '04)

(Semi)-algebraic loop

$(x_1, x_2, \dots, x_n) = (a_1, a_2, \dots, a_n)$

while $g_1 = \dots = g_k = 0$ and $h_1 > 0, \dots, h_s > 0$ **do**

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Outline

- Symbolic Computations – Algorithms:
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 - Algebraic formulation

Polynomial ideals

- Consider the polynomial ring $R = \mathbb{C}[x_1, \dots, x_n]$.
- A subset $I \subseteq R$ is called a **polynomial ideal** if:
 - If $f, g \in I$, then $f + g \in I$ (closed under addition)
 - If $f \in I$ and $h \in R$, then $hf \in I$ (closed under multiplication in R).

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Hilbert Basis Theorem

Every ideal in the polynomial ring $\mathbb{C}[x_1, x_2, \dots, x_n]$ is finitely generated.

- For any ideal $I \subseteq R$, there exist polynomials $f_1, \dots, f_r \in I$ such that

$$I = \langle f_1, \dots, f_r \rangle.$$

- For any polynomial g in I there exists h_1, \dots, h_r in R such that

$$g = h_1 f_1 + \dots + h_r f_r$$

Algebraic varieties

- Let $S = \{f_1, f_2, \dots, f_s\} \subseteq \mathbb{C}[x_1, x_2, \dots, x_n]$. Define

$$V(S) = \{(a_1, \dots, a_n) \in \mathbb{C}^n : f_i(a_1, \dots, a_n) = 0 \text{ for all } 1 \leq i \leq s\}.$$

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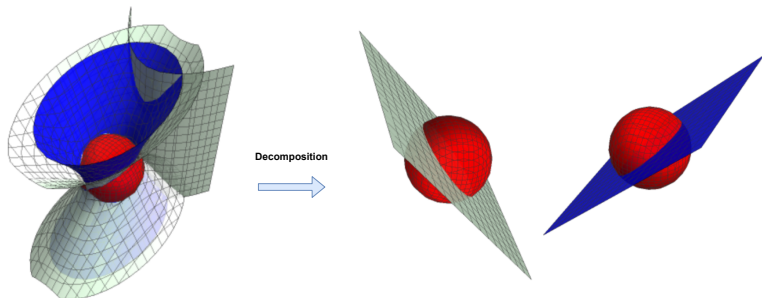
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- If $\{f_1, \dots, f_s\}$ and $\{g_1, \dots, g_t\}$ generate the same ideal I , then:

$$V(f_1, \dots, f_s) = V(g_1, \dots, g_t)$$

- Equivalent polynomial systems



$\{x^2+y^2+z^2=1, 3x^2y^2-6x^2z+9x^2+y^4-y^2z^2-2y^2z+2y^2+2z^3-3z^2+2z-3=0, 5x^2-z^2+2y^2=2\}$ is decomposed to $\{x^2+y^2+z^2=1, x-z=0\}$ and $\{x^2+y^2+z^2=1, x+z=0\}$

Radical of ideals

Given an ideal $I \subseteq \mathbb{C}[x_1, x_2, \dots, x_n]$, the **radical** of I is:

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$$\begin{aligned} I = & (x_1^5 x_5^5 + 5x_1^5 x_5^4 - 10x_1^4 x_3 x_5^4 + 5x_1^4 x_4 x_5^4 + 10x_1^5 x_5^3 - 40x_1^4 x_3 x_5^3 + 40x_1^3 x_3^2 x_5^3 + \\ & 20x_1^4 x_4 x_5^3 - 40x_1^3 x_3 x_4 x_5^3 + 10x_1^3 x_4^2 x_5^3 + 10x_1^5 x_5^2 - 60x_1^4 x_3 x_5^2 + 120x_1^3 x_3^2 x_5^2 - 80x_1^2 x_3^3 x_5^2 + \\ & 30x_1^4 x_4 x_5^2 - 120x_1^3 x_3 x_4 x_5^2 + 120x_1^2 x_3^2 x_4 x_5^2 + 30x_1^3 x_4^2 x_5^2 - 60x_1^2 x_3 x_4^2 x_5^2 + 10x_1^2 x_4^3 x_5^2 + \\ & 5x_1^5 x_5 - 40x_1^4 x_3 x_5 + 120x_1^3 x_3^2 x_5 - 160x_1^2 x_3^3 x_5 + 80x_1 x_4^4 x_5 + 20x_1^4 x_4 x_5 - 120x_1^3 x_3 x_4 x_5 + \\ & 240x_1^2 x_3^2 x_4 x_5 - 160x_1 x_3^3 x_4 x_5 + 30x_1^3 x_4^2 x_5 - 120x_1^2 x_3 x_4^2 x_5 + 120x_1 x_3^2 x_4^2 x_5 + 20x_1^2 x_4^3 x_5 - \\ & 40x_1 x_3 x_4^3 x_5 + 5x_1 x_4^4 x_5 + x_1^5 - 10x_1^4 x_3 + 40x_1^3 x_3^2 - 80x_1^2 x_3^3 + 80x_1 x_3^4 - 32x_3^5 + 5x_1^4 x_4 - \\ & 40x_1^3 x_3 x_4 + 120x_1^2 x_3^2 x_4 - 160x_1 x_3^3 x_4 + 80x_3^4 x_4 + 10x_1^3 x_4^2 - 60x_1^2 x_3 x_4^2 + 120x_1 x_3^2 x_4^2 - \\ & 80x_3^3 x_4^2 + 10x_1^2 x_4^3 - 40x_1 x_3 x_4^3 + 40x_3^2 x_4^3 + 5x_1 x_4^4 - 10x_3 x_4^4 + x_4^5, x_1^5 - 2x_3, x_3^3 x_4^6 + \\ & 3x_1 x_3^2 x_4^4 + 3x_1^2 x_3 x_4^2 + x_1^3) \end{aligned}$$

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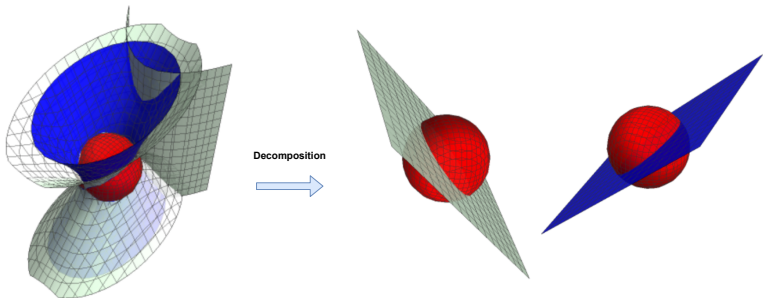
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$$\text{rad}(I) = (x_1 x_5 + x_1 - 2x_3 + x_4, x_1^5 - 2x_3, x_3 x_4^2 + x_1)$$

- $V(I) = V(\text{rad}(I))$
- $I \subseteq \text{rad}(I)$

Description of polynomial invariant ideals

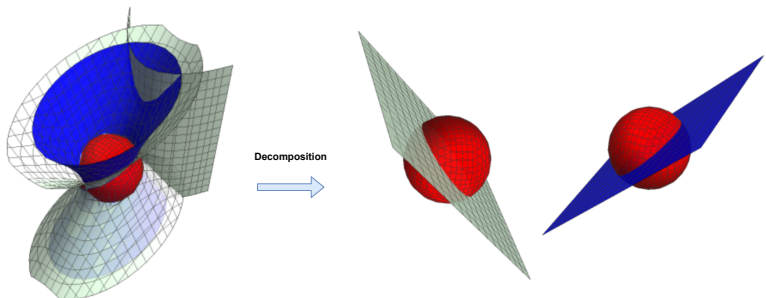
- Polynomial systems with the same solution set.



$\{x^2+y^2+z^2=1, 3x^2y^2-6x^2z+9x^2+y^4-y^2z^2-2y^2z+2y^2+2z^3-3z^2+2z-3=0, 5x^2-z^2+2y^2=2\}$ is decomposed to $\{x^2+y^2+z^2=1, x-z=0\}$ and $\{x^2+y^2+z^2=1, x+z=0\}$

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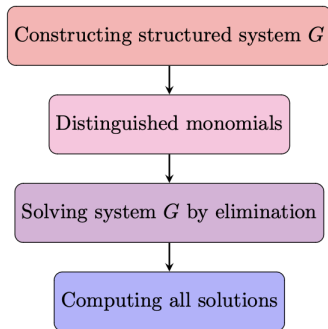
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- Goals:
 - Find a **minimal** generating set for the ideal of polynomial invariants.
 - Decompose the associated variety into smaller ones
 - Generate equivalent generating sets which are easier to represent

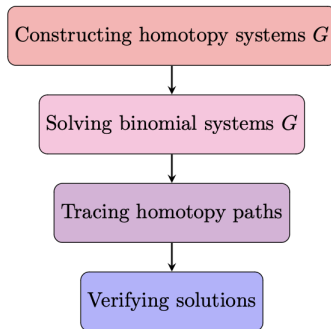
Symbolic-numerical algebraic computation

- Approach: Degenerating a given system F to a more-structured system

Symbolic method: solving system F



Numeric method: solving system F



- Main idea: Gröbner degenerations.

Algebraic formulation

g is a P.I. of $\mathcal{L}(a, F)$:

$x \leftarrow a$

while true **do**

$x \leftarrow F(x)$

end while

\iff

$g(a) = 0$

$g \circ F(a) = 0$

$g \circ F^{(2)}(a) = 0$

...

$g \circ F^{(k)}(a) = 0$ for all $k \in \mathbb{N}$

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Definition

The **invariant set** of (F, g) is

$$S_{(F,g)} = \{x \in \mathbb{C}^n \mid \forall m \in \mathbb{Z}_{\geq 0} : g \circ F^{(m)}(x) = 0\}.$$

Invariant sets are algebraic varieties.

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Proposition

Let $a \in \mathbb{C}^n$. Then, g is a P.I. of $\mathcal{L}(a, F)$ if and only if $a \in S_{(F,g)}$.

Computing Invariant Sets

Theorem

Given a polynomial map $F : \mathbb{C}^n \rightarrow \mathbb{C}^n$ and a polynomial g , there exists an integer $N \in \mathbb{N}$ such that:

$$S_{(F,g)} = V(g) \cap V(g \circ F) \cap \dots \cap V(g \circ F^{(N)}).$$

INVARIANTSETCOMPUTATION

Input: g and $F = (f_1, \dots, f_n)$ in $\mathbb{Q}[x_1, \dots, x_n]$

Output: A finite set of polynomials whose common zero set is $S_{(F,g)}$

```
1:  $S \leftarrow \{g\}$ 
2:  $\tilde{g} \leftarrow g \circ F$ 
3: while  $V(S) \neq V(S \cup \{\tilde{g}\})$  do
4:    $S \leftarrow S \cup \{\tilde{g}\}$ 
5:    $\tilde{g} \leftarrow \tilde{g} \circ F$ 
6: end while
7: return  $S$ 
```

Example

```
(x1, x2) ← (a1, a2)  
while true do  
     $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \leftarrow \begin{pmatrix} 10 & -8 \\ 6 & -4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$   
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- Consider $g = x_1^2 - x_1 x_2 + 9x_1^3 - 24x_1^2 x_2 + 16x_1 x_2^2$

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- Consider $g = x_1^2 - x_1 x_2 + 9x_1^3 - 24x_1^2 x_2 + 16x_1 x_2^2$
- $g \circ F = 360x_1^3 - 1248x_1^2 x_2 + 40x_1^2 + 1408x_1 x_2^2 - 72x_1 x_2 - 512x_2^3 + 32x_2^2$

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- Gröbner basis computation shows $V(g) \neq V(g, g \circ F)$.
- $g \circ F^2 = 7488x_1^3 - 26880x_1^2 x_2 + 832x_1^2 + 31744x_1 x_2^2 - 1600x_1 x_2 - 12288x_2^3 + 768x_2^2$
- This time, $V(g, g \circ F) = V(g, g \circ F, g \circ F^2)$.

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- This time, $V(g, g \circ F) = V(g, g \circ F, g \circ F^2)$.

Conclusion: g is a P.I. for $\mathcal{L}((a_1, a_2), F)$ if and only if $(a_1, a_2) \in V(g, g \circ F)$.

Polynomial invariants of degree d

$g = \sum_{|\alpha_j| \leq d} b_j x^{\alpha_j} \in \mathbb{C}[x]$ is a P.I.

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$h = \sum_{|\alpha_i| \leq d} y_i x^{\alpha_i} \in \mathbb{C}[x, y]$ is a P.I.

```
(x, y) ← (a, b)
while true do
  (x, y) ← G(x, y) = (F(x), y)
end while
```

- Let $I_{d, \mathcal{L}}$ denote the set of all polynomial invariants of degree $\leq d$.
- It forms a finite-dimensional vector space and can thus be uniquely characterized by a system of linear equations.

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x ← a
while true do
  x ← F(x)
end while
```

$h = \sum_{|\alpha_i| \leq d} y_i x^{\alpha_i} \in \mathbb{C}[x, y]$ is a P.I.

```
(x, y) ← (a, b)
while true do
  (x, y) ← G(x, y) = (F(x), y)
end while
```

- Let $I_{d, \mathcal{L}}$ denote the set of all polynomial invariants of degree $\leq d$.
- It forms a finite-dimensional vector space and can thus be uniquely characterized by a system of linear equations.

Theorem (ISSAC 2024)

Let $F = (f_1, \dots, f_n)$ be a sequence of polynomials in $\mathbb{Q}[x_1, \dots, x_n]$ and let $d \geq 1$. Then, there is an algorithm that computes a polynomial matrix A , s.t.

$$I_{d, \mathcal{L}} = \left\{ \sum_{|\alpha_i| \leq d} b_i x^{\alpha_i} \mid (b_1, \dots, b_m) \in \ker A(\mathbf{a}) \right\}.$$

Example

```
(x1, x2) ← (a1, a2)  
while true do  
     $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \leftarrow \begin{pmatrix} 10 & -8 \\ 6 & -4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$   
end while
```

- **Goal:** Compute all polynomial invariants of degree ≤ 2 .
- Consider $F = (10x_1 - 8x_2, \quad 6x_1 - 4x_2, \quad y_1, \dots, y_6)$
- The general polynomial: $g = y_1 + y_2x_1 + y_3x_2 + y_4x_1^2 + y_5x_1x_2 + y_6x_2^2$
- The algorithm returns a matrix $M(x_1, x_2)$ such that

$$M(x_1, x_2) \cdot (y_1 \ y_2 \ \cdots \ y_6)^T = 0$$

encodes the polynomial invariants.

Output matrix and basis cases

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 3x_1 - 4x_2 & 3x_1 - 4x_2 & 0 & 0 & 0 \\ 0 & 64x_2 & 112x_2 - 48x_1 & 48x_2^2 & 84x_2^2 - 36x_1x_2 & 27x_1^2 - 126x_1x_2 + 147x_2^2 \\ 0 & 32x_2 & 56x_2 - 24x_1 & 24x_1x_2 & -9x_1^2 + 21x_1x_2 + 12x_2^2 & -18x_1x_2 + 42x_2^2 \\ 0 & 4x_2 & 7x_2 - 3x_1 & 3x_1^2 & 3x_1x_2 & 3x_2^2 \end{bmatrix}$$

Output matrix and basis cases

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 3x_1 - 4x_2 & 3x_1 - 4x_2 & 0 & 0 & 0 \\ 0 & 64x_2 & 112x_2 - 48x_1 & 48x_2^2 & 84x_2^2 - 36x_1x_2 & 27x_1^2 - 126x_1x_2 + 147x_2^2 \\ 0 & 32x_2 & 56x_2 - 24x_1 & 24x_1x_2 & -9x_1^2 + 21x_1x_2 + 12x_2^2 & -18x_1x_2 + 42x_2^2 \\ 0 & 4x_2 & 7x_2 - 3x_1 & 3x_1^2 & 3x_1x_2 & 3x_2^2 \end{bmatrix}$$

- We compute an explicit basis for the vector space $I_{2,\mathcal{L}}$ by computing the kernel of the above matrix, depending on the initial values (a_1, a_2) .

Output matrix and basis cases

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 3x_1 - 4x_2 & 3x_1 - 4x_2 & 0 & 0 & 0 \\ 0 & 64x_2 & 112x_2 - 48x_1 & 48x_2^2 & 84x_2^2 - 36x_1x_2 & 27x_1^2 - 126x_1x_2 + 147x_2^2 \\ 0 & 32x_2 & 56x_2 - 24x_1 & 24x_1x_2 & -9x_1^2 + 21x_1x_2 + 12x_2^2 & -18x_1x_2 + 42x_2^2 \\ 0 & 4x_2 & 7x_2 - 3x_1 & 3x_1^2 & 3x_1x_2 & 3x_2^2 \end{bmatrix}$$

- We compute an explicit basis for the vector space $I_{2,\mathcal{L}}$ by computing the kernel of the above matrix, depending on the initial values (a_1, a_2) .
- Performing Gaussian elimination on M leads to four cases:

Initial values	Basis of $I_{2,\mathcal{L}}$
$a_1 = a_2 = 0$	$\{x_1, x_2, x_1x_2, x_1^2, x_2^2\}$
$a_1 = a_2 \neq 0$	$\{x_1 - x_2, x_1^2 - x_1x_2, -x_1x_2 + x_2^2\}$
$a_1 = \frac{4}{3}a_2 \neq 0$	$\{3x_1 - 4x_2, -3x_1^2 + 16x_1x_2 - 16x_2^2, -3x_1x_2 + 4x_2^2\}$
$a_1 \neq \frac{4}{3}a_2,$ $a_1 \neq a_2$	$\{(3a_1 - 4a_2)^2x_1 - (3a_1 - 4a_2)^2x_2 - 9(a_1 - a_2)x_1^2 + 24(a_1 - a_2)x_1x_2 - 16(a_1 - a_2)x_2^2\}$

Experiments (comparison with Polar)

- Polar: Moosbrugger, Stankovic, Bartocci, Kovács OOPSLA2, 2022
- Polar can handle **probabilistic loops**, whereas ours is limited to **deterministic** ones.
- We compute **all** possible polynomial invariants up to a specified degree,
- Ours are **minimal** generating polynomials of degree 1 to 4. TL = Timeout (360 seconds).

Degree	1		2		3		4	
Benchmark	Ours	Polar	Ours	Polar	Ours	Polar	Ours	Polar
Fib1	0.014	0.2	0.046	0.32	0.17	0.68	1.31	1.58
Fib2	0.017	0.23	0.056	0.46	6.3	1.18	TL	3.69
Fib3	0.013	0.21	0.056	0.4	0.137	1.26	0.61	3.82
Nagata	0.026	0.25	0.07	0.55	0.15	1.21	0.35	2.84
Yagzhev9	0.12	0.43	TL	5.2	TL	131.5	TL	TL
Yagzhev11	0.095	0.45	2.7	6.83	241	359	TL	TL
Ex 9	0.016	0.28	0.06	0.64	0.19	2.38	0.55	11.5
Ex 10	0.02	0.51	0.07	1.7	0.16	16.21	0.75	TL
Squares	0.02	0.5	0.06	0.67	0.15	1.15	0.38	2.25

Degree	1		2		3		4	
Benchmark	d	Polar	d	Polar	d	Polar	d	Polar
Fib1	0	0	0	0	1	1	4	1
Fib2	0	0	0	0	1	1	TL	1
Fib3	0	0	0	0	1	1	4	1
Nagata	1	0	5	1	13	1	26	2
Yagzhev9	3	0	TL	3	TL	3	TL	TL
Yagzhev11	0	0	0	0	TL	1	TL	TL
Ex 9	0	0	0	0	3	1	11	1
Ex 10	0	0	2	0	8	0	19	0
Squares	1	0	5	0	13	0	26	0

Summary

Summary

- Compute the set of initial values for which given polynomials are P.I.
- Compute all polynomial invariants up to a given degree:
 - For each possible initial value
 - For a fixed initial value
- Compute all polynomial invariants of a given form (fixed terms).
- Exploit the structure of polynomial systems for efficiency.
- Extend methods to loops with inequality guards (ISSAC 2024).

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- Bayarmagnai, Mohammadi, Prébet. ISSAC 2024

Thank you for your attention!