Dynamic System Modeling & PID Controller Design for a Molten Salt Microreactor

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> Reactor Characterization

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About the Author

Experience

B.S Chemical Engineering (2015-2019) - Michigan Technological University M.S. Nuclear Engineering (2021-2023) - University of Idaho - NRC Fellow Modeling and Simulation Intern at Idaho National Lab

Select Publications

Root, S. J., et al., 2023. Thermodynamic analysis on xenon stripping to shorten restart time in molten salt microreactors.

Nuclear Engineering and Design 414, 112606

Root, S. J., et al., 2023. Cyber hardening of nuclear power plants with real-time nuclear reactor operation, 1. preliminary operational testing. Progress in Nuclear Energy 162, 104742

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- 3 Reactor Characterization
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Molten Salt Reactors

Microreactors

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This work and my coursework is being completed under a Graduate Fellowship funded by Nuclear Regulatory Commission (NRC).

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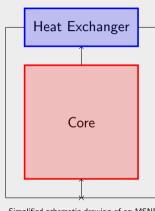
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Molten Salt Nuclear Battery (MSNB)

- Self-Contained liquid fueled molten salt micro-reactor - 10 year design
- 1 MW design using HALEU UF₄dissolved in FLiNaK
- Criticality is manipulated using axial control drums
 - Neutron absorber plate covering cylinders of neutron reflector
 - Drums are rotated to point more absorber towards the core to insert negative control reactivity



Simplified schematic drawing of an MSNB

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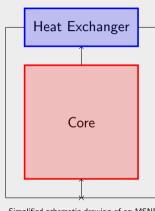
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Background on MSNB

Neutronics [3]

- Control drums give a uniform axial and radial flux profile for all reactivity insertions
- Fission product poisoning is the biggest challenge to reach the desired 10-year lifespan
- Control drum vs. reactivity curve is sinusoidal

Thermal Hydraulics [4]

Process Control

[3] Peterson, J., 8 2019. An analysis of the nuclear characteristics of a molten salt microreactor. Master's thesis. University of Idaho

[4] Carter, J. P., 2022. Multi-physics investigation of a natural circulation molten salt micro-reactor that utilizes an experimental in-pile device to improve core physics and system thermal-hydraulic performance. Ph.D. thesis. University of Idaho

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Background on MSNB

Neutronics [3]

Thermal Hydraulics [4]

- The counteracting passive feedback effects of temperature reactivity and flow reactivity produce stable autonomous load following for relatively small ramp function power demand transients
- An in-core helix device can be used to manipulate temperature and power profiles in the core, as well as minimize advective loss of delayed-neutron precursors

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[3] Peterson, J., 8 2019. An analysis of the nuclear characteristics of a molten salt microreactor. Master's thesis, University of Idaho

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Background on MSNB

Neutronics [3]

Thermal Hydraulics [4]

Process Control

- Design controller *compliment* the autonomous capabilities provided by the passive feedback mechanisms
- Allow larger faster, more aggressive power changes
- Additional focus on time periods with a high degree of time variance (start-up, shut-down, re-start)

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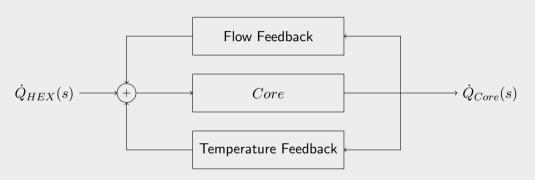
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Passive Feedback



Simplified block diagram of two primary passive feedback mechanisms in an MSNB

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Passive Feedback

Temperature Reactivity

- Doppler broadening of resonance peaks results in more epithermal neutrons absorbed by $^{238}U\,$ etc. [5, Ch. 6]
- Molten salt fuels have high thermal expansion coefficient [3]
- Increased temperature leads to lower heavy metal density and smaller macroscopic fission cross-section at high temperature
- Similar to moderator thinning in LWRs
- These two effects combine to result in less power production at higher temperature

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^[3] Peterson, J., 8 2019. An analysis of the nuclear characteristics of a molten salt microreactor. Master's thesis, University of Idaho

Passive Feedback

Flow Reactivity

- Driven by advection of delayed neutron precursors [6, Ch. 3]
 - Most fission events release daughter neutrons *promptly*
 - Sometimes, unstable nuclides which decay by neutron emission are produced instead
 - ullet $t_{1/2}$ from less than a second to over a minute [7, Ch. 6]
- Precursors produced near the core exit and long lived precursors may emit their neutrons outside of the core, so they are effectively *lost* from the fission chain reaction
- In natural circulation, larger power transport requires a higher flow rate, and greater delayed neutron losses

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- Start design process by discussing dynamics associated with anticipated transients
 - Natural circulation flow mode
 - Passive feedback mechanisms
 - Transport delays separating heat exchanger and core
- Thought Experiment
 - Step increase in power demand to a steady-state critical MSNB
 - Set-point is instantaneously equal to heat exchanger power consumption
 - Ideal controller which produces rapid load following with minimal overshoot

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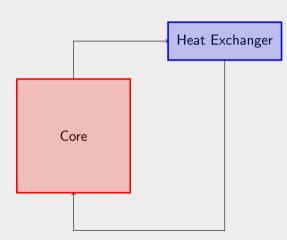
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Simplified schematic drawing of a natural circulation MSNB

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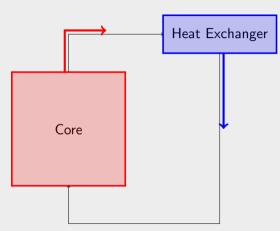
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Immediate Response



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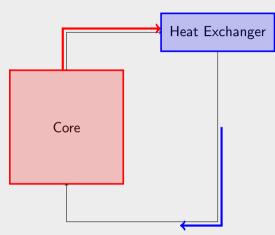
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Heat Exchanger Perturbation



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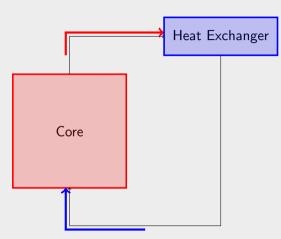
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Main Operational Control Problem - Transport Delay

Core Perturbation



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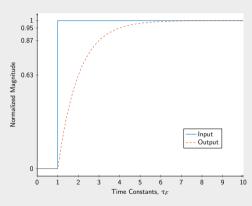
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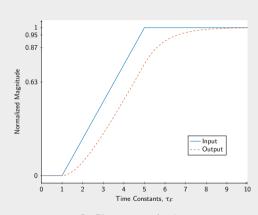
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Design Decisions

Pre-Filter



Pre-Filter on a step-function



Pre-Filter on a ramp-function

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Design Decisions

Dead-band

- Minor perturbations will cause power fluctuations
- Fine grain and constant control actuation would burn out servos prematurely
- When the error is small, allow the passive feedback mechanisms to fine tune

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Design Decisions

Disturbance Feedforward

• Disturbances, particularly temperature reactivity, are extremely high frequency - On order of mean neutron lifetime [7, Ch. 7]

- Control actuation is similarly quick
- Time delays on the order of dozens of seconds to minutes
- Inserting control reactivity to counteract temperature reactivity at the exact right moment would be difficult or impossible, so it is unlikely that a disturbance feedforward controller could reject the disturbance before it causes error [8, Ch. 10]
- Disturbance rejection best left to feedback PID controller

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Time-Variance and Non-Linearity

Operational Control

 Sinusoidal control drum angle vs. reactivity curve - non-linear reactivity actuation - Taylor Series approximation to linearize around the operating point [8, Ch. 2]

- Fissile depletion changes the amount of control reactivity required to make the core critical time-variant controller bias Bias and gain schedule [9]
- Control drums manipulate *criticality*, not power directly highly time-dependent control actuation

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Time-Variance and Non-Linearity

Special Cases

- Equilibrium Poisoning
 - \bullet Poisons like ^{135}Xe and ^{149}Sa build-up after the reactor starts this causes a negative reactivity insertion
 - Reach equilibrium over the first 100 hours
 - Gain/Bias schedule may be used
 - Alternatively, a burnable poison with appropriate *effective* half-life could be selected ^{157}Gd shows promise to counteract ^{135}Xe build-up
- Restart Poisoning
 - ^{135}Xe levels increase following shut-down because its beta-precursor (^{135}I) decays faster
 - Requires a lot of excess control reactivity and very good control to counteract the positive reactivity insertion of poison burn-out after restart
 - Low-flux burn-out instead of full shut-down
 - ullet Stripping ^{135}Xe and other fission gasses before re-start

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Control Drum Characterization

MCNP

- Use KCODE to develop control drum vs. reactivity curve at various points in the core lifespan
- Use Burn-up routine to study how the core criticality at different conditions effects the control drum vs. reactivity
 - Cold/clean start-up
 - Burnable poison start-up
 - Equilibrium poisoning
 - Long-term depletion of fissile isotopes
- Develop bias/unity point schedule
- Will to use HPC or Falcon

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Process Simulation

Python

 1D+time finite element model that accounts for passive feedback mechanisms during unsteady state subcritical, critical, and supercritical modes to calculate the core power and flow loop temperature profile over time

- Simulate system response to:
 - Control actuation
 - Heat exchanger transients
- Empirical fitting of reactor transfer function
- Studies can be conducted locally or with cluster resources

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Controller Tuning

MATLAB-Simulink

- Model control loop in Simulink
- Investigate system stability using frequency response tests
- Use built-in numerical methods to implement a PID controller tuning method
- Repeat for different core conditions to develop gain-schedule and/or look-up table for the controller parameters

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Implementation and Testing

Python

- Implement control drum reactivity, pre-filter, and PID controller into the process simulation
- Test autonomous response to heat exchanger power demand transients
- Repeat with controller active
- Quantitatively compare response using settling time, dampening ratio, peak overshoot ratio etc.

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Timeline

Table: Timeframe for Execution of Project

Tasks	Oct.	Nov.	Dec.	Jan.	Feb.	Mar.	Apr.
Control Drums	X	X	X				
Process Simulation		X	X	X			
Controller Tuning				X	X		
Implementation					X	X	
Cross-Cutting						X	Х
Defend							Х

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Other Considerations

- Poison perturbations following power transients [10]
- Melting of in-situ frozen salt
- SCRAM system must be passive
- Decay heat system [11]
- Flow rate control

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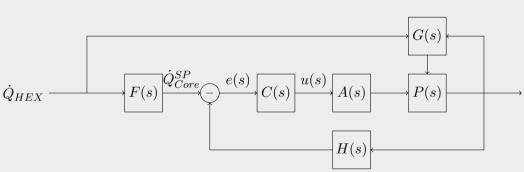
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Discussion

Control Loop



Simplified control loop of a natural circulation MSNB

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