Coding Challenges: OOP

Pillars of Object Oriented Programming

Challenge I

Create a class called **Vehicle**. The **Vehicle** class should have the following:

- An enum publicly available called Medium with the values LAND, AIR, WATER
- A property called Speed. This should be read-only outside of the class. This is not allowed to be negative
- A property called Name. This should be read-only outside of the class
- A property called Occupants. This is not allowed to be negative
- A constant called Capacity. This must be at least 1
- A variable called Media, which is a list of Mediums. This should only be accessible by the class and any of its children

Challenge II

Add the following methods to Vehicle:

- A constructor that sets Speed, Occupants, Name, and Capacity to default values
- A method called Accelerate which changes Speed by the specified amount
- An abstract method called Turn
- A method called ToString that prints out the current Speed, all Media, the Name, and the number of Occupants

Challenge III

Create a class called Car that extends Vehicle. Car should have the following:

- A variable called <u>SteeringRotation</u>. This should not be accessible outside of the class. It must be between -1440 and 1440, inclusive
- A property called **TireRotation**. This should be read-only outside of the class. It must be between -90 and 90, inclusive
- A property called Gear. This should be read-only outside of the class
- A constructor that calls the base constructor of Vehicle and then sets the two rotation values to 0 and adds the LAND Medium to Media
- Implement Turn to rotate the SteeringRotation by the specified amount, in degrees, and the TireRotate by 1/16th the specified amount, in degrees.

Challenge IV

Make the following modifications to **Vehicle**:

• Implement constructor chaining to allow for values set by the constructor to be input instead

Make the following modifications to Car:

- Implement constructor chaining to allow inputs for values that Vehicle's constructor
- Override the Accelerate function to call the base implementation, and then set the Gear via the following equation: Gear = (Integer)Math.ceil(0.4444 * (Math.sqrt(Speed)))