Imperial College London



Operating Systems Synchronisation I

Course 211 Spring Term 2018-2019

http://www.imperial.ac.uk/computing/current-students/courses/211/calendar/

(Slides courtesy of Cristian Cadar)

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Process Synchronisation

How do processes **synchronise** their operation to perform a task?

Key concepts:

- Critical sections
- Mutual exclusion
- Atomic operations
- Race conditions
- Deadlock
- Starvation
- Synchronisation mechanisms
 - Locks, semaphores, monitors, etc.

Concepts relevant to both **processes** and **threads**

Shared Data Example

Account #1234: £10,000



Extract £1000 from account 1234



Extract £1000 from account 1234

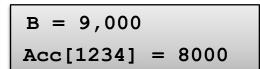
Shared Data Example

```
void Extract(int acc_no, int sum)
{
   int B = Acc[acc_no];
   Acc[acc_no] = B - sum;
}
```

```
Acc[1234] 10,000
```



```
B = 10,000
Acc[1234] = 9000
```





Extract(1234, 1000)

Extract(1234, 1000)

Shared Data Example

```
void Extract(int acc_no, int sum)
{
  int B = Acc[acc_no];
  Acc[acc_no] = B - sum;
}
Critical section!
Need mutual exclusion
```

Acc[1234] 10,000

B = 10,000



Acc[1234] = 9000

B = 10,000





Extract(1234, 1000)

Extract(1234, 1000)

Critical Sections and Mutual Exclusion

Critical section/region: section of code in which processes access a shared resource

Mutual exclusion ensures that if a process is executing its critical section, no other process can be executing it

Processes must request **permission** to enter critical sections

A **synchronisation mechanism** is required at the entry and exit of the critical section

Requirements for Mutual Exclusion

No two processes may be simultaneously inside a critical section

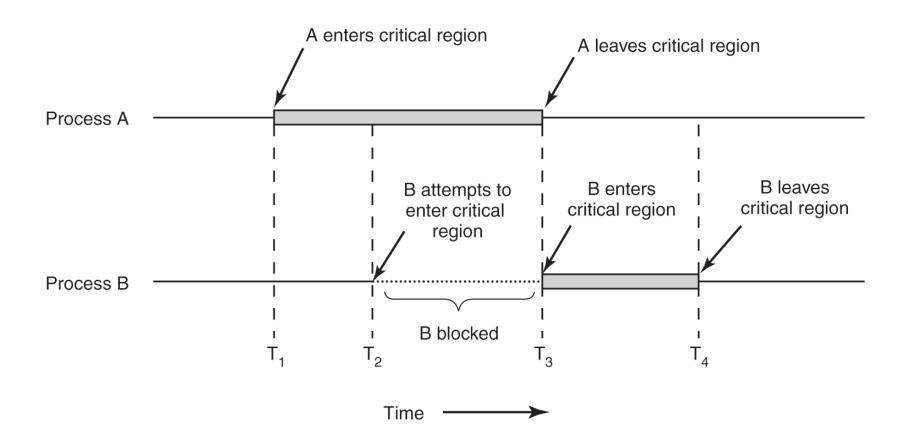
No process running outside the critical section may prevent other processes from entering the critical section

 When no process is inside a critical section, any process requesting permission to enter must be allowed to do so immediately

No process requiring access to its critical section can be delayed forever

No assumptions are made about relative the speed of processes

Critical Sections and Mutual Exclusion



Disabling Interrupts

```
void Extract(int acc_no, int sum)
{
   CLI();
   int B = Acc[acc_no];
   Acc[acc_no] = B - sum;
   STI();
}
```

Works only on single-processor systems

Misbehaving/buggy processes may never release CPU

Mechanism usually only used by kernel code

Software Solution – Strict Alternation

What happens if T_0 takes a long time in its non-critical section?

 Remember: No process running outside its critical section may prevent other processes from entering the critical section

Can we have T_1 execute its loop twice in a row (w/o T_0 executing in-between)?

Busy Waiting

Strict alternation solution requires continuously testing the value of a variable

Called **busy waiting**

- Wastes CPU time
- Should only be used when the wait is expected to be short

Peterson's Solution

```
int turn = 0;
int interested[2] = \{0, 0\};
// thread is 0 or 1
void enter critical(int thread)
{
   int other = 1 - thread;
   interested[thread] = 1;
   turn = other;
   while (turn == other &&
          interested[other])
      /* loop */ ;
void leave critical(int thread)
   interested[thread] = 0;
```

TO

```
enter_critical(0);
critical_section();
leave_critical(0);
```

T1

```
enter_critical(1);
critical_section();
leave_critical(1);
```

Peterson's Solution – Mutual Exclusion Proof

```
int turn = 0;
int interested[2] = {0, 0};
// thread is 0 or 1
void enter_critical(int thread)
{
   int other = 1 - thread;
   interested[thread] = 1;
   turn = other;
   while (turn == other &&
          interested[other])
      /* loop */ ;
leave critical(int thread)
{
   interested[thread] = 0;
```

First note that when T_K tries to enter or is in CS, interested[k]=1.

Assume both T_0 and T_1 try to enter CS. Then:

interested[0]=interested[1]=1
and turn allows only one thread to
enter.

Assume T_0 is in CS. T_1 has to wait for T_0 to set **interested[0]** to 0, which only happens when T_0 leaves CS.

Assume T_1 is in CS. T_0 has to wait for T_1 to set **interested[1]** to 0, which only happens when T_1 leaves CS.

Atomic Operations

Does this work?

Atomic operation: a sequence of one or more statements that is/appears to be indivisible

Lock Variables

```
void Extract(int acc_no, int sum)
{
  lock(L);
  int B = Acc[acc_no];
  Acc[acc_no] = B - sum;
  unlock(L);
}
```

Does this work?

```
void unlock(int L)
{
   L = 0;
}
```

TSL (Test and Set Lock) Instruction

Atomic instruction provided by most CPUs TSL(LOCK)

- Test-and-Set-Lock
- Atomically sets memory location LOCK to 1 and returns old value

```
void lock(int L)
{
   while (TSL(L) != 0)
   /* wait */;
}
```

 Locks using busy waiting are called spin locks

Spin Locks

Waste CPU

Should only be used when the wait is expected to be short
 May run into priority inversion problem

Priority Inversion Problem and Spin Locks

Two processes:

- H with high priority
- L with low priority
- H should always be scheduled if runnable

Assume the following scenario:

- H is waiting for I/O
- L acquires lock A and enters critical section
- I/O arrives and H is scheduled
- H tries to acquire lock A that L is holding

What happens?

Lock Granularity

```
void Extract(int acc_no, int sum)
{
   lock(L);
   int B = Acc[acc_no];
   Acc[acc_no] = B - sum;
   unlock(L);
}
```

```
T1: Extract(1, 40);

T2: Extract(2, 40);
```

What happens if there are concurrent accesses to **different** accounts?

Lock Granularity

```
void Extract(int acc_no, int sum)
{
   lock(L[acc_no]);
   int B = Acc[acc_no];
   Acc[acc_no] = B - sum;
   unlock(L[acc_no]);
}
```

```
T1: Extract(1, 40);

T2: Extract(2, 40);
```

Lock granularity: the amount of data a lock is protecting

Lock Overhead and Lock Contention

Lock overhead: measure of cost associated with using locks

- Memory space
- Initialization
- Time required to acquire and release locks

Lock contention: measure of number of processes waiting for lock

More contention, less parallelism

Coarser granularity:

- Lock overhead?
- Lock contention?
- Complexity?

Finer granularity:

- Lock overhead?
- Lock contention?
- Complexity?

Minimising Lock Contention/Maximising Concurrency

Choose finer lock granularity

But understand tradeoffs

Release a lock as soon as it is not needed

– Make critical sections small!

```
void AddAccount(int acc_no, int balance)
{
    lock(L_Acc);
    CreateAccount(acc_no);
    lock(L[acc_no]);
    Acc[acc_no] = balance;
    unlock(L[acc_no]);
    unlock(L_Acc);
}
```

```
void ViewHistory(int acc_no)
{
   print_transactions(acc_no);
}

T1: ViewHistory(1234);

T2: ViewHistory(1234);

T3: ViewHistory(1234);
```

Any locks needed?

```
void ViewHistory(int acc_no)
{
   print_transactions(acc_no);
}
```

```
T1: ViewHistory(1234);

T2: ViewHistory(1234);

T3: Extract(1234,500);
```

Any extra locks needed?

```
void ViewHistory(int acc_no)
{
    lock(L[acc_no]);
    print_transactions(acc_no);
    unlock(L[acc_no]);
}
```

```
T1: ViewHistory(1234);

T2: ViewHistory(1234);

T3: Extract(1234,500);
```

What if later only T1 and T2 run?

```
void ViewHistory(int acc_no)
{
    lock_RD(L[acc_no]);
    print_transactions(acc_no);
    unlock(L[acc_no]);
}
```

Read/write locks:

- lock_RD(L) →
 acquire L in read
 mode
- lock_WR(L) → acquire L in write mode
- In write mode, the thread has exclusive access
- Multiple threads can acquire the lock in read mode!

Race Condition

Occurs when multiple threads or processes read and write **shared data** and the final result depends on the relative timing of their execution

i.e. on the exact process or thread interleaving

E.g. the Extract example → final value of account 8,000 or 9,000

Thread Interleavings

| a = 1 | a = 1 | a = 1 | b = 2 | b = 2 | b = 2 |
|--------|--------|--------|--------|--------|--------|
| b = 1 | b = 2 | b = 2 | a = 2 | a = 1 | a = 1 |
| b = 2 | b = 1 | a = 2 | a = 1 | a = 2 | b = 1 |
| a = 2 | a = 2 | b = 1 | b = 1 | b = 1 | a = 2 |
| (2, 2) | (2, 1) | (2, 1) | (1, 1) | (2, 1) | (2, 1) |

Tutorial Question

Consider the following three threads:

T1 T2 T3
$$a = 1;$$
 $b = 1;$ $a = 2;$ $b = 2;$

How many possible interleaving are there?

4

8

12

16

If all thread interleavings are as likely to occur, what is the probability to have a=1 and b=1 after all threads complete execution?

All Thread Interleavings

Memory models

In this course, we assume **sequential consistency**:

The operations of each thread appear in program order

The operations of all threads are executed in some sequential order atomically

But other memory models (due to hardware behaviour and compiler optimisations) exist!

Sequential Consistency vs Weak Memory Models

Under sequential consistency, it is impossible for both threads to read flag1 = flag2 = 0 in their if statements Under weak memory models, this is possible!

Advanced reading:

https://www.cs.princeton.edu/courses/archive/fall10/cos597C/docs/memory-models.pdf

Happens-Before Relationship

Formulated by Leslie Lamport in 1976
Partial order relation between events (e.g. instructions) in a trace
Denoted by $a \rightarrow b$ where a, b are events in a trace

Consider a, b with a occurring before b in the trace:

- If a, b are in the same thread, then a \rightarrow b
- If a is unlock(L) and b is lock(L), then a \rightarrow b
 - (can generalise for other synchronisation mechanisms)

Irreflexive: ∀a, a ≯ a

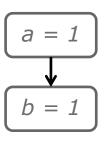
Antisymmetric: $\forall a, b: a \rightarrow b \text{ then } b \not\rightarrow a$

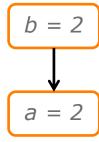
Transitive: $\forall a, b, c: a \rightarrow b \land b \rightarrow c$ then $a \rightarrow c$

Happens-Before Relationship

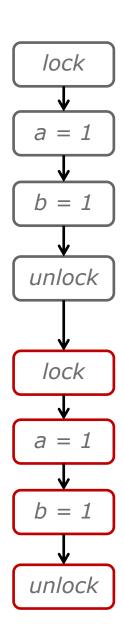
A data race occurs between a, b in the trace iff:

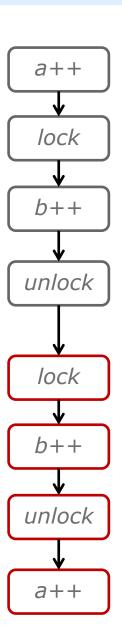
- they access the same memory location
- at least one of them is a write
- they are unordered according to happens-before





Date race between a = 1, a = 2 and between b = 1, b = 2





Order a dynamic execution trace only

