

Course 211
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(Slides courtesy of Cristian Cadar)

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What Are Threads?

Execution streams that share the **same address space**

When multithreading is used, each process can contain one or more threads

Per process items	Per thread items
Address space	Program counter (PC)
Global variables	Registers
Open files	Stack
Child processes	
Signals	

Why Threads?

Many applications contain multiple activities

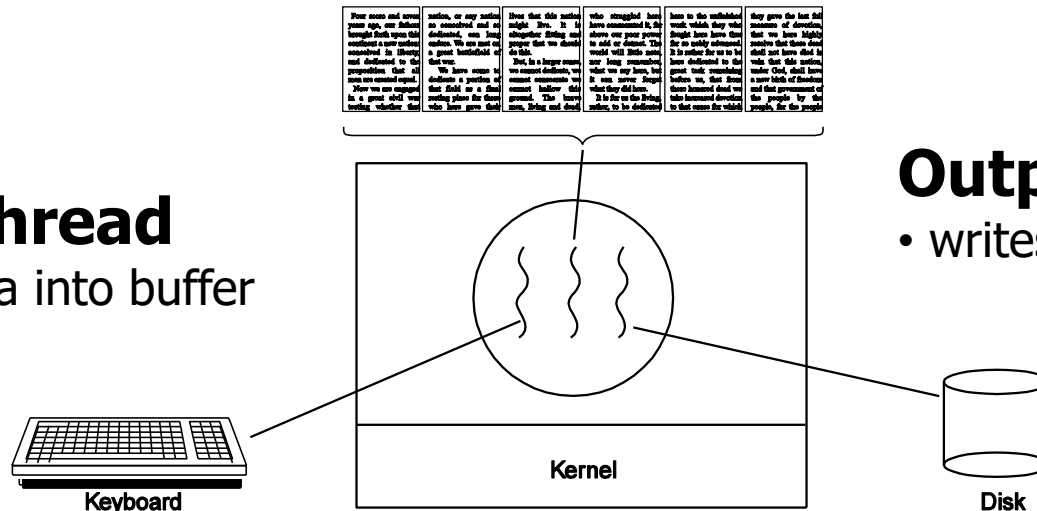
- Which execute in parallel
- Which access and process the same data
- Some of which may block

Processing thread

- processes input buffer
- writes result into output buffer

Input thread

- reads data into buffer



Output thread

- writes output buffer to disk

Why Not Processes?

Many applications contain multiple activities

- Which execute in parallel
- Which access and process the same data
- Some of which might block

Processes are too heavyweight

- Difficult to communicate between different address spaces
- Activity that blocks may switch out the entire application
- Expensive to context switch between activities
- Expensive to create/destroy activities

Threads – Problems/Concerns

Shared address space

- Memory corruption
 - One thread can write another thread's stack
- Concurrency bugs
 - Concurrent access to shared data (e.g. global variables)

Forking

- What happens on a `fork()`?
 - Create a new process with the same number of threads?
 - Create a new process with a single thread?

Signals

- When a signal arrives, which thread should handle it?

Case Study: PThreads

PThreads (Posix Threads)

Defined by IEEE standard 1003.1c

- Implemented by most UNIX systems

```
#include <pthread.h>
#include <sys/types.h>
```

<code>pthread_t</code>	→ type representing a thread
<code>pthread_attr_t</code>	→ type representing the attributes of a thread

Creating Threads

```
int pthread_create(pthread_t *thread, const pthread_attr_t *attr,  
                  void *(*start_routine)(void*), void *arg);
```

Creates a new thread

- Newly created thread is stored in ***thread**
- Function returns 0 if thread was successfully created, or error code

Arguments:

- **attr** -> specifies thread attributes, can be **NULL** for default attributes (attributes include: minimum stack size, guard size, detached/ joinable, ...)
- **start_routine** -> C function the thread will start execute once created
- **arg** -> Argument to be passed to **start_routine** (of pointer type **void***).
Can be **NULL** if no arguments are to be passed.

Terminating Threads

```
void pthread_exit(void *value_ptr);
```

Terminates the thread and makes `value_ptr` available to any successful join with the terminating thread

Called implicitly when the thread's start routine returns

- But not for the initial thread which started `main()`
- If `main()` terminates before other threads w/o calling `pthread_exit()`, the entire process is terminated
- If `pthread_exit()` is called in `main()`, the process continues executing until last thread terminates (or `exit()` is called)

PThread Example (1)

```
#include <pthread.h>
#include <stdio.h>

void *thread_work(void *threadid) {
    long id = (long) threadid;
    printf("Thread %ld\n", id);
}

int main (int argc, char *argv[]) {
    pthread_t threads[5];
    long t;
    for (t=0; t<5; t++)
        pthread_create(&threads[t], NULL,
                      thread_work, (void *)t);
}
```

```
$ gcc pt.c -lpthread
$ ./a.out
Thread 0
Thread 1
Thread 2
Thread 3
Thread 4
```

Question: Passing Arguments to Threads

What if we want to pass more than one argument to the start routine?

Yielding the CPU

```
int pthread_yield(void)
```

Releases CPU to let another thread run

Returns 0 on success, or an error code

Always succeeds on Linux

Why would a thread ever yield? (think of `nice()` for processes)

Joining Other Threads

```
int pthread_join(pthread_t thread, void **value_ptr);
```

Blocks until `thread` terminates

Value passed to `pthread_exit()` by terminating thread is available in location referenced by `value_ptr`

`value_ptr` can be `NULL`

Join Example

```
#include <pthread.h>
#include <stdio.h>

long a, b, c;
void *work1(void *x) { a = (long)x *
    (long)x;}
void *work2(void *y) { b = (long)y *
    (long)y;}

int main (int argc, char *argv[]) {
    pthread_t t1, t2;
    pthread_create(&t1, NULL, work1, (void*)
3);
    pthread_create(&t2, NULL, work2, (void*)
4);
    pthread_join(t1, NULL);
    pthread_join(t2, NULL);
    c = a + b;
    printf("3^2 + 4^2 = %ld\n", c);
}
```

```
$ ./a.out
3^2 + 4^2 = 25
```

Two Ways to Implement Threads

User-level threads

- The kernel is not aware of threads
- Each process manages its own threads

Kernel-level threads

- Managed by the kernel

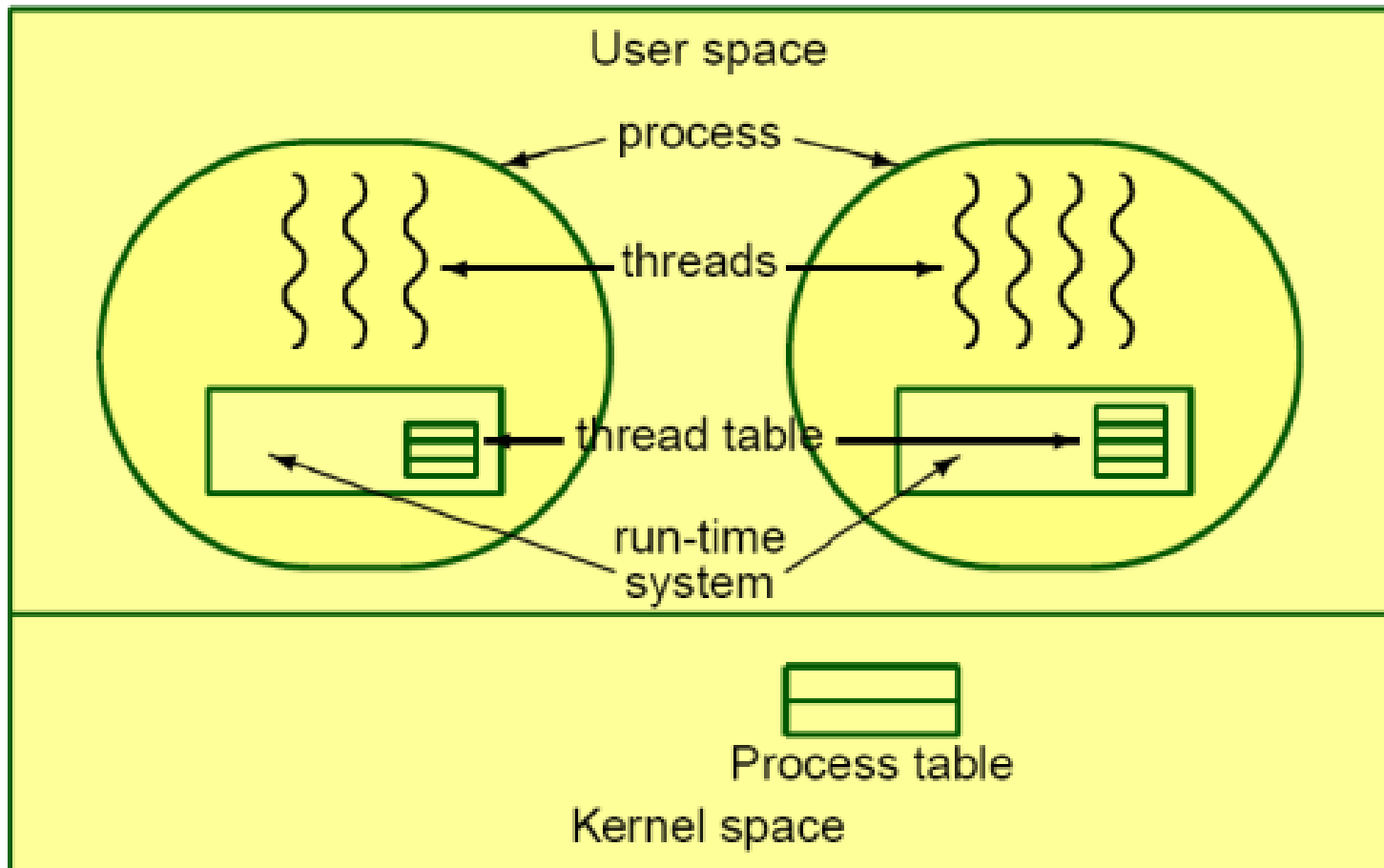
Trade-offs on each side

Various hybrid approaches possible

User-Level Threads

Kernel thinks it is managing processes only

- Threads implemented by software library
- Process maintains **thread table** for **thread scheduling**



Advantages of User-Level Threads

Better performance

- Thread creation and termination are fast
- Thread switching is fast
- Thread synchronisation (e.g. joining other threads) is fast
- All these operations do not require any kernel involvement

Each application can have its own scheduling algorithm

Disadvantages of User-Level Threads

Blocking system calls stops **all threads** in process

- Denies one of core motivations for using threads

Non-blocking I/O can be used (e.g. `select()`)

- Harder to use and understand, inelegant

During page fault, OS blocks whole process...

- But other threads may be runnable

Tutorial Question

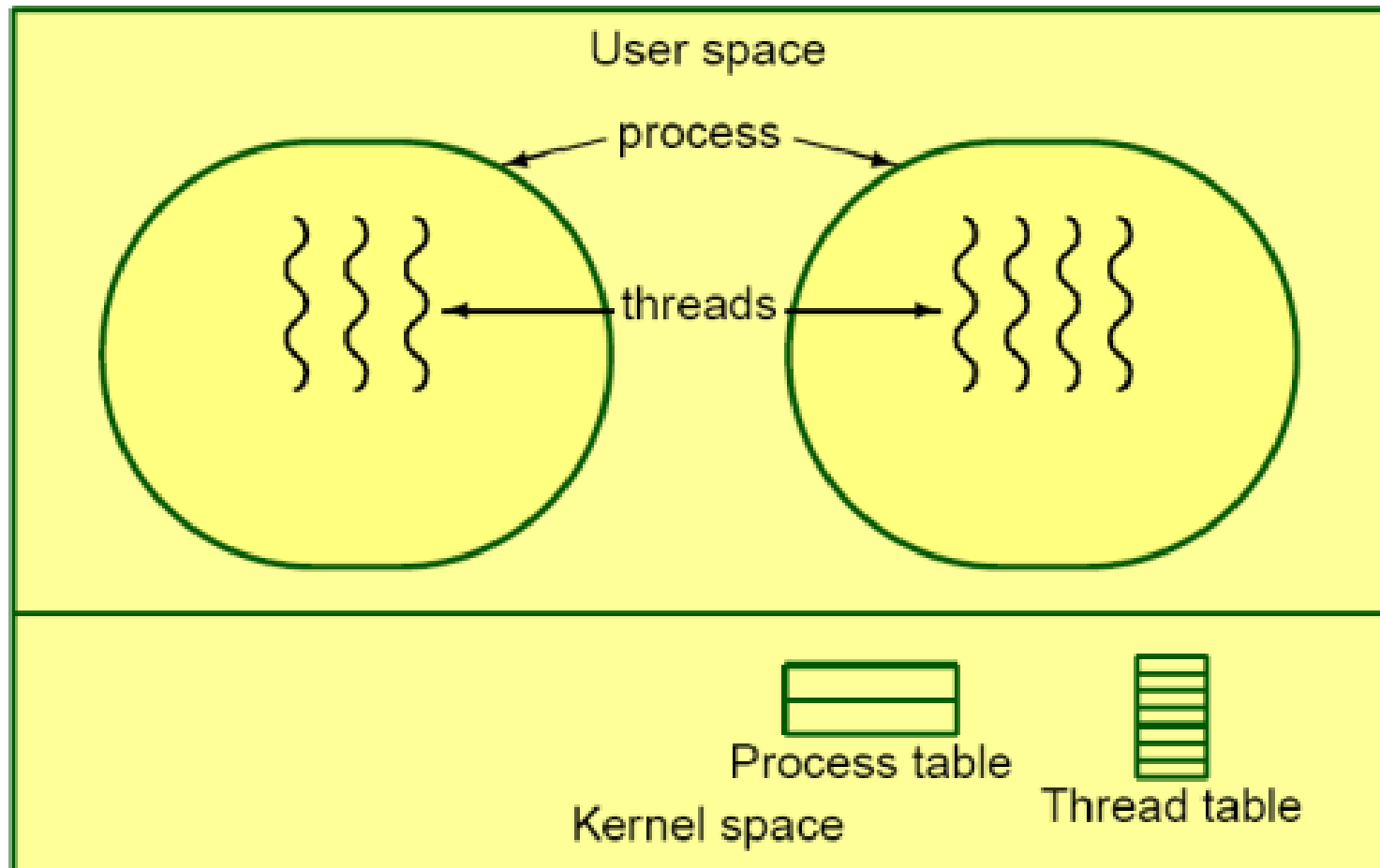
In this problem, you are to compare reading a file using a **single-threaded file server** and a **multithreaded server**, running on a single-CPU machine.

It takes 15 msec to get a request for work, dispatch it, and do the rest of the necessary processing, assuming that the data needed are in the block cache.

A disk operation is needed $1/3$ of the time, requiring an additional 75 msec, during which time the thread sleeps. Assume that thread switching time is negligible.

How many requests/sec can the server handle if it is single-threaded?

Kernel Threads



Advantages of Kernel Threads

Blocking system calls/page faults can be easily accommodated

- If one thread calls a blocking system call or causes a page fault, the kernel can schedule a runnable thread from the same process

Disadvantages of Kernel Threads

Thread creation and termination more expensive

- Require system calls
 - But still much cheaper than process creation/termination
- One mitigation strategy is to recycle threads (**thread pools**)

Thread synchronisation more expensive

- Requires blocking system calls

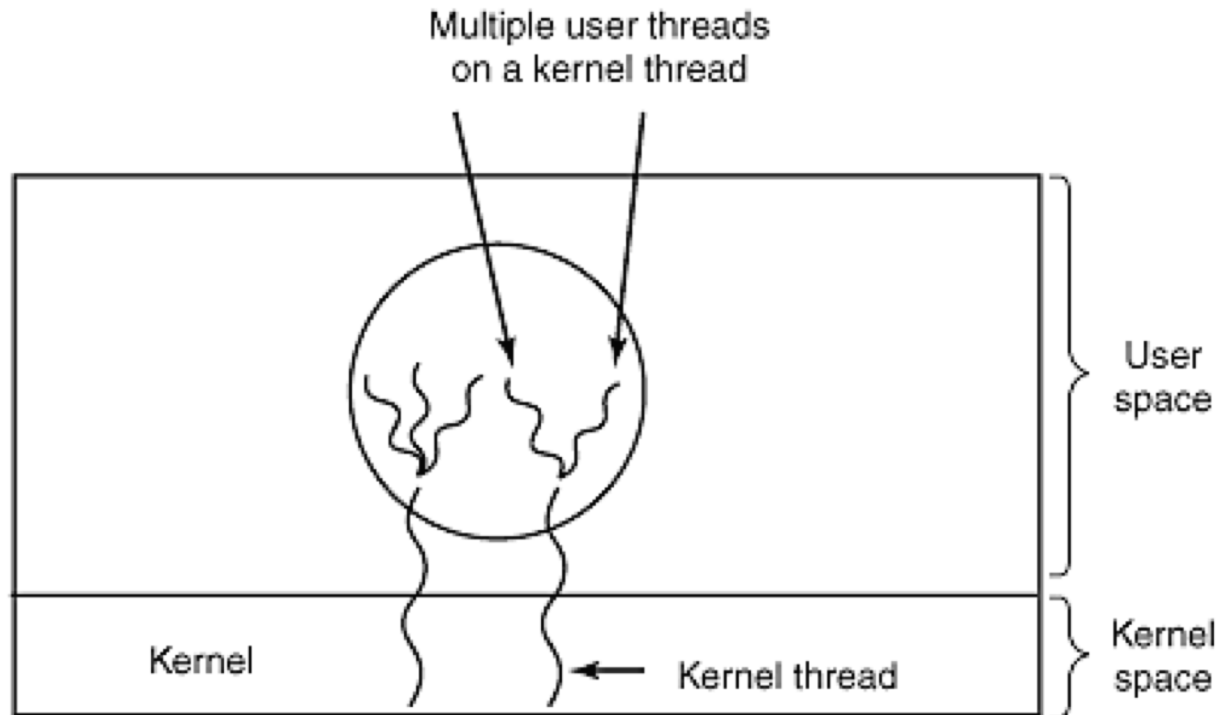
Thread switching more expensive

- Requires system call
 - But still much cheaper than process switches (same address space)

No application-specific schedulers

Hybrid Approaches

Use kernel threads and multiplex user-level threads onto some (or all) kernel threads



Tutorial Question

If in a multithreaded web server the only way to read from a file is the normal blocking **read()** system call, do you think user-level threads or kernel-level threads are being used? Why?