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CSE 460

Lab 3 – Processes, Signals, and Study of XV6

1. Replacing a Process Image

test_exec.cpp:

```
//test_exec.cpp
#include <unistd.h>
#include <iostream>

using namespace std;

int main()
{
    cout << "Running ps with execl\n" ;
    execl( "ps", "ps", "-ax", 0 );

    cout << "Done!\n";

    return 0;
}
```

Output:

```
georgesuarez at MacBook-Pro in ~/University/CSE-460/Labs/Lab 3 on master*
$ ./test_exec
Running ps with execl
Done!
```

2. Duplicating a Process Image

test_fork.cpp:

```
// test_fork.cpp
#include <sys/types.h>
#include <unistd.h>
#include <iostream>
```

```

using namespace std;

int main()
{
    pid_t pid; //process id
    char *message;
    int n;
    cout << "fork program starting\n";
    pid = fork();
    switch (pid)
    {
    case -1:
        cout << "Fork failure!\n";
        return 1;
    case 0:
        message = "This is the child\n";
        n = 5;
        break;
    default:
        message = "This is the parent\n";
        n = 3;
        break;
    }
    for (int i = 0; i < n; ++i)
    {
        cout << message;
        sleep(1);
    }

    return 0;
}

```

Output:

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\$./test_fork

fork program starting

This is the parent

This is the child

This is the child

This is the parent

This is the child

This is the parent

This is the child

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\$ This is the child

Explanation:

The program first outputs the string “fork program starting”. Next, the program then outputs “This is the parent” because the value that is returned after using *fork()* returns a value greater than 1 which means it is a parent process and it assigns the variable *n* to 3, but it gets interesting because right after it outputted “This is the child” and assigns *n* to 5. This makes sense since child processes run concurrently with its’ parent process. The parent process does not wait for the children process to finish. That is why it outputs “This is the child” for a second time as it is trying to output that message five times; meanwhile, the parent process is running normally which is trying to output “This is the parent” three times. The parent process finishes before the child process which is why it outputs the “This is the child” in the next line followed by a newline.

3. Waiting for a Process

test_wait.cpp:

```
//test_wait.cpp
#include <sys/types.h>
#include <sys/wait.h>
#include <unistd.h>
#include <iostream>
#include <stdio.h>
#include <stdlib.h>

using namespace std;

int main()
{
```

```

pid_t pid; //process id
char *message;
int n;
int exit_code;

cout << "fork program starting\n";
pid = fork();
switch (pid)
{
case -1:
    cout << "Fork failure!\n";
    return 1;
case 0:
    message = "This is the child\n";
    n = 5;
    exit_code = 9;
    break;
default:
    message = "This is the parent\n";
    n = 3;
    exit_code = 0;
    break;
}
for (int i = 0; i < n; ++i)
{
    cout << message;
    sleep(1);
}

//waiting for child to finish
if (pid != 0)
{ //parent
    int stat_val;
    pid_t child_pid;

    child_pid = wait(&stat_val); //wait for child
    cout << "Child finished: PID = " << child_pid << endl;
    if (WIFEXITED(stat_val))
        cout << "child exited with code " << WEXITSTATUS(stat_val) << endl;
    else
        cout << "child terminated abnormally!" << endl;
}
exit(exit_code);
}

```

Output:

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```
$ ./test_wait
```

```
fork program starting
```

```
This is the parent
```

```
This is the child
```

```
This is the child
```

```
This is the parent
```

```
This is the child
```

```
This is the parent
```

```
This is the child
```

```
This is the child
```

```
Child finished: PID = 55784
```

```
child exited with code 9
```

Explanation:

This program almost does the same thing as *test_fork.cpp*, except that the parent process waits for the child process to terminate before the program ends.

test_wait.cpp (modified):

```
//test_wait.cpp
```

```
#include <sys/types.h>
```

```
#include <sys/wait.h>
```

```
#include <unistd.h>
```

```
#include <iostream>
```

```
#include <stdio.h>
```

```
#include <stdlib.h>
```

```
using namespace std;
```

```
int main()
```

```
{
```

```
    pid_t pid; //process id
```

```
    pid_t grandparent = getpid();
```

```
    char *message;
```

```
    int n;
```

```
    int exit_code;
```

```

cout << "fork program starting\n";
pid = fork();
switch (pid)
{
case -1:
    cout << "Fork failure!\n";
    return 1;
case 0:
    pid = fork();
    switch (pid)
    {
    case -1:
        cout << "Fork failure!\n";
        return 1;
    case 0:
        cout << "This is the grandchild PID = " << getpid() << "\nThis is the parent PID = " << getppid() << "\nThis is the
grandparent PID = " << grandparent << endl;
        break;
    default:
        break;
    }
    message = "This is the child\n";
    n = 5;
    exit_code = 9;
    break;
default:
    message = "This is the parent\n";
    n = 3;
    exit_code = 0;
    break;
}
for (int i = 0; i < n; ++i)
{
    cout << message;
    sleep(1);
}

//waiting for child to finish
if (pid != 0)
{ //parent
    int stat_val;
    pid_t child_pid;

```

```

        child_pid = wait(&stat_val); //wait for child
        cout << "Child finished: PID = " << child_pid << endl;
        if (WIFEXITED(stat_val))
            cout << "child exited with code " << WEXITSTATUS(stat_val) << endl;
        else
            cout << "child terminated abnormally!" << endl;
    }

    exit(exit_code);
}

```

Output:

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\$./test_wait

fork program starting

This is the parent

This is the child

This is the grandchild PID = 13736

This is the parent PID = 13735

This is the grandparent PID = 13734

This is the child

This is the child

This is the child

This is the parent

This is the child

This is the parent

This is the child

This is the child

This is the child

This is the child

This is the child

Child finished: PID = 13736

child exited with code 9

Child finished: PID = 13735

child exited with code 9

4. Signals

test_signal.cpp:

```

//test_signal.cpp
#include <signal.h>
#include <unistd.h>
#include <iostream>

```

```

using namespace std;

void func(int sig)
{
    cout << "Oops! -- I got a signal " << sig << endl;
}

int main()
{
    (void)signal(SIGINT, func); //catch terminal interrupts

    for (int i = 0; i < 20; ++i)
    {
        cout << "CSUSB CS 460 lab on signals" << endl;
        sleep(1);
    }
    return 0;
}

```

Output:

georgesuarez at MacBook-Pro in ~/University/CSE-460/Labs/Lab 3 on master*

\$./test_signal

CSUSB CS 460 lab on signals

CSUSB CS 460 lab on signals

^COops! -- I got a signal 2

CSUSB CS 460 lab on signals

CSUSB CS 460 lab on signals

CSUSB CS 460 lab on signals

^COops! -- I got a signal 2

CSUSB CS 460 lab on signals

CSUSB CS 460 lab on signals

CSUSB CS 460 lab on signals

^COops! -- I got a signal 2

CSUSB CS 460 lab on signals

CSUSB CS 460 lab on signals

CSUSB CS 460 lab on signals

^COops! -- I got a signal 2

CSUSB CS 460 lab on signals

CSUSB CS 460 lab on signals

CSUSB CS 460 lab on signals

CSUSB CS 460 lab on signals

^COops! -- I got a signal 2


```
CSUSB CS 460 lab on signals
CSUSB CS 460 lab on signals
CSUSB CS 460 lab on signals
CSUSB CS 460 lab on signals
^COops! -- I got a signal 2
CSUSB CS 460 lab on signals
```

Explanation:

This program outputs “CSUSB CS 460 lab on signals” twenty times for every 1 second.

When *Ctrl-C* is pressed a few times, it outputs “Oops! – I got a signal 2 “because it is sending a signal to the process to interrupt it and the *SIGINT* is the second option that you can send in the *signal* function which is why it is outputting 2.

test_alarm.cpp:

```
//test_alarm.cpp
#include <signal.h>
#include <unistd.h>
#include <iostream>

using namespace std;

//simulates an alarm clock
void ding(int sig)
{
    cout << "Alarm has gone off " << endl;
}

//tell child process to wait for 5 seconds before sending
//a SIGALRM signal to its parent.

int main()
{
    int pid;

    cout << "Alarm testing!" << endl;

    if ((pid = fork()) == 0)
    { //child
        sleep(5);
    }
    /*
```

```

    Get parent process id, send SIGALRM signal to it.
    */
    kill(getppid(), SIGALRM);
    return 1;
}

//parent process arranges to catch SIGALRM with a call
//to signal and then waits for the inevitable.

cout << "Waiting for alarm to go off!" << endl;
(void)signal(SIGALRM, ding);

pause(); //process suspended, waiting for signals to wake up
cout << "Done!" << endl;

return 1;
}

```

Output:

```

georgesuarez at MacBook-Pro in ~/University/CSE-460/Labs/Lab 3 on master*
$ ./test_alarm
Alarm testing!
Waiting for alarm to go off!
Alarm has gone off
Done!

```

Explanation:

This program starts a new process by using *fork()* which then makes the child process sleep for five seconds. Soon after that, a *SIGALARM* is being sent to the parent process and then it exits. The parent process catches *SIGALARM* with a call by *signal()*, and then pauses until a signal has been received. The *pause()* function suspends the execution of the program until a signal occurs. The *kill()* function does not terminate the process right away, but it instead sends a specified signal to the specified process so that it can be terminated. If no signal has been received, then a *TERM* signal is sent instead which will kill processes that do not catch this signal.

Test_signal.cpp (modified):

```

//test_signal.cpp
#include <signal.h>
#include <unistd.h>
#include <iostream>

using namespace std;

void func(int sig)
{
    cout << "Oops! -- I got a signal " << sig << endl;
}

int main()
{
    struct sigaction act;

    (void)sigaction(SIGINT, &act, NULL); //catch terminal interrupts

    while ( 1 );
    return 0;
}

```

Output:

```

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$ ./test_signal
^\\Quit: 3

```

5. Study of XV6

Sample code of XV6:

Dump of assembler code for function acquire:

```

0x801042e0 <+0>:    push  ebp
0x801042e1 <+1>:    mov   ebp,esp
0x801042e3 <+3>:    push  esi
0x801042e4 <+4>:    push  ebx
0x801042e5 <+5>:    call  0x801042a0 <pushcli>
0x801042ea <+10>:   mov   ebx,DWORD PTR [ebp+0x8]

```

```

0x801042ed <+13>:  mov  eax,DWORD PTR [ebx]

0x801042ef <+15>:  test  eax,eax

0x801042f1 <+17>:  jne   0x80104378 <acquire+152>

0x801042f7 <+23>:  mov   edx,0x1

0x801042fc <+28>:  jmp   0x80104303 <acquire+35>

0x801042fe <+30>:  xchg  ax,ax

=> 0x80104300 <+32>:  mov   ebx,DWORD PTR [ebp+0x8]

0x80104303 <+35>:  mov   eax,edx

0x80104305 <+37>:  lock xchg DWORD PTR [ebx],eax

0x80104308 <+40>:  test  eax,eax

0x8010430a <+42>:  jne   0x80104300 <acquire+32>

0x8010430c <+44>:  lock or  DWORD PTR [esp],0x0

0x80104311 <+49>:  mov   ebx,DWORD PTR [ebp+0x8]

0x80104314 <+52>:  call  0x80103750 <mycpu>

0x80104319 <+57>:  xor   edx,edx

0x8010431b <+59>:  lea   ecx,[ebx+0xc]

0x8010431e <+62>:  mov   DWORD PTR [ebx+0x8],eax

0x80104321 <+65>:  mov   eax,ebp

0x80104323 <+67>:  nop

0x80104324 <+68>:  lea   esi,[esi+eiz*1+0x0]

0x80104328 <+72>:  lea   ebx,[eax-0x80000000]

0x8010432e <+78>:  cmp   ebx,0x7fffffe

0x80104334 <+84>:  ja    0x80104350 <acquire+112>

0x80104336 <+86>:  mov   ebx,DWORD PTR [eax+0x4]

0x80104339 <+89>:  mov   DWORD PTR [ecx+edx*4],ebx

0x8010433c <+92>:  add   edx,0x1

0x8010433f <+95>:  mov   eax,DWORD PTR [eax]

0x80104341 <+97>:  cmp   edx,0xa

0x80104344 <+100>:  jne   0x80104328 <acquire+72>

0x80104346 <+102>:  lea   esp,[ebp-0x8]

```

0x80104349 <+105>: pop ebx

0x8010434a <+106>: pop esi

0x8010434b <+107>: pop ebp

0x8010434c <+108>: ret

0x8010434d <+109>: lea esi,[esi+0x0]

0x80104350 <+112>: lea eax,[ecx+edx*4]