

2-2. This is the Lagrangian for a harmonic oscillator.

$$L = \frac{m}{2}(\dot{x}^2 - \omega^2 x^2)$$

Let  $T = t_b - t_a$ . Show that the classical action is

$$S_{cl} = \frac{m\omega}{2\sin(\omega T)} \left( (x_b^2 + x_a^2) \cos(\omega T) - 2x_b x_a \right)$$

From the above Lagrangian we have

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{x}} \right) = m\ddot{x}$$

and

$$\frac{\partial L}{\partial x} = -m\omega^2 x$$

By equation (2.7) which is

$$\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{x}} \right) = \frac{\partial L}{\partial x}$$

we have

$$\ddot{x} = -\omega^2 x \tag{1}$$

The well-known solution to (1) is

$$x(t) = A \sin(\omega t) + B \cos(\omega t)$$

We have the following boundary conditions.

$$x(0) = x_a$$

$$x(T) = x_b$$

Solve for  $B$ .

$$x(0) = B = x_a$$

For  $x(T)$  we have

$$x(T) = A \sin(\omega T) + B \cos(\omega T)$$

Solve for  $A$ .

$$A = \frac{x(T) - B \cos(\omega T)}{\sin(\omega T)} = \frac{x_b - x_a \cos(\omega T)}{\sin(\omega T)}$$

Hence the equation of motion is

$$x(t) = \frac{x_b - x_a \cos(\omega T)}{\sin(\omega T)} \sin(\omega t) + x_a \cos(\omega t) \quad (2)$$

Differentiate  $x(t)$  to obtain velocity  $\dot{x}(t)$ .

$$\dot{x}(t) = \frac{d}{dt}x(t) = \omega \left( \frac{x_b - x_a \cos(\omega T)}{\sin(\omega T)} \cos(\omega t) - x_a \sin(\omega t) \right) \quad (3)$$

Using the action integral

$$S = \int_0^T L dt$$

we have for the classical action

$$\begin{aligned} S_{cl} &= \frac{m}{2} \int_0^T (\dot{x}^2 - \omega^2 x^2) dt \\ &= \frac{m}{2} \left( \int_0^T \dot{x}^2 dt - \int_0^T \omega^2 x^2 dt \right) \end{aligned}$$

Let  $u = v = \dot{x}$  and note that

$$\begin{aligned} \dot{u} &= \ddot{x} \\ \int v dt &= x \end{aligned}$$

Apply integration by parts to the integral of  $\dot{x}^2$ .

$$\begin{aligned} \int_0^T \dot{x}^2 dt &= \int_0^T uv dt \\ &= \left( u \int v dt \right)_0^T - \int_0^T \dot{u} \left( \int v dt \right) dt \\ &= \dot{x}x \Big|_0^T - \int_0^T \ddot{x}x dt \end{aligned}$$

Hence

$$S_{cl} = \frac{m}{2} \left( \dot{x}x \Big|_0^T - \int_0^T \ddot{x}x dt - \int_0^T \omega^2 x^2 dt \right)$$

The remaining integrals cancel by  $\ddot{x} = -\omega^2 x$  from equation (1).

We now have

$$\begin{aligned} S_{cl} &= \frac{m}{2} \dot{x}x \Big|_0^T \\ &= \frac{m}{2} \left( \dot{x}(T)x(T) - \dot{x}(0)x(0) \right) \end{aligned} \tag{4}$$

By substitution and simplification

$$S_{cl} = \frac{m\omega}{2 \sin(\omega T)} \left( (x_b^2 + x_a^2) \cos(\omega T) - 2x_b x_a \right) \tag{5}$$