8-4. Show that the ground-state wave function for the Lagrangian of equation (8.78) can be written

$$\Phi_0 = A \exp\left(-\frac{1}{2\hbar} \sum_{\alpha=1}^{N-1} \omega_\alpha Q_\alpha^* Q_\alpha\right)$$
(8.83)

(where A is a constant) by starting with the wave function in terms of the real variables Q^c_{α} and Q^s_{α} .

$$L = \frac{1}{2} \sum_{\alpha=0}^{N-1} \left(\dot{Q}_{\alpha}^* \dot{Q}_{\alpha} - \omega_{\alpha}^2 Q_{\alpha}^* Q_{\alpha} \right)$$
 (8.78)

Consider the following equation from p. 216.

$$Q_{\alpha} = \frac{1}{\sqrt{2}} (Q_{\alpha}^{c} - iQ_{\alpha}^{s})$$

It follows that

$$Q_{\alpha}^* Q_{\alpha} = \frac{1}{2} (Q_{\alpha}^c)^2 + \frac{1}{2} (Q_{\alpha}^s)^2 \tag{1}$$

Substitute (1) into (8.78).

$$L = \frac{1}{4} \sum_{\alpha=0}^{N-1} \left((\dot{Q}_{\alpha}^{c})^{2} + (\dot{Q}_{\alpha}^{s})^{2} - \omega_{\alpha}^{2} (Q_{\alpha}^{c})^{2} - \omega_{\alpha}^{2} (Q_{\alpha}^{s})^{2} \right)$$
 (2)

From equation (2.7),

$$\frac{d}{dt}\frac{\partial L}{\partial \dot{Q}} = \frac{\partial L}{\partial Q} \tag{3}$$

Use (2) and (3) to obtains the following equations of motion.

$$\ddot{Q}_{\alpha}^{c} = -\omega_{\alpha}^{2} Q_{\alpha}^{c} \qquad \ddot{Q}_{\alpha}^{s} = -\omega_{\alpha}^{2} Q_{\alpha}^{s}$$

$$\tag{4}$$

From (8.7), let ϕ_0 be the ground state wave function associated with (4).

$$\phi_0(x_\alpha) = \exp\left(-\frac{\omega_\alpha x_\alpha^2}{2\hbar}\right)$$

Then by equation (8.62),

$$\Phi_0 = \prod_{\alpha=0}^{N-1} \phi_0(Q_{\alpha}^c) \phi_0(Q_{\alpha}^s) = \exp\left(-\frac{1}{2\hbar} \sum_{\alpha=0}^{N-1} \omega_{\alpha}(Q_{\alpha}^c + Q_{\alpha}^s)\right)$$