Consider the following equation from p. 216.

$$Q_{\alpha} = \frac{1}{\sqrt{2}} (Q_{\alpha}^{c} - iQ_{\alpha}^{s})$$

It follows that

$$Q_{\alpha}^* Q_{\alpha} = \frac{1}{2} (Q_{\alpha}^c)^2 + \frac{1}{2} (Q_{\alpha}^s)^2 \tag{1}$$

Substitute (1) into (8.78).

$$L = \frac{1}{4} \sum_{\alpha=0}^{N-1} \left( (\dot{Q}_{\alpha}^{c})^{2} + (\dot{Q}_{\alpha}^{s})^{2} - \omega_{\alpha}^{2} (Q_{\alpha}^{c})^{2} - \omega_{\alpha}^{2} (Q_{\alpha}^{s})^{2} \right)$$
 (2)

Consider equation (2.7).

$$\frac{d}{dt}\frac{\partial L}{\partial \dot{Q}} = \frac{\partial L}{\partial Q} \tag{2.7}$$

Substitute (2) into (2.7) to obtain the following equations of motion.

$$\ddot{Q}_{\alpha}^{c}(t) = -\omega_{\alpha}^{2} Q_{\alpha}^{c}(t) \qquad \ddot{Q}_{\alpha}^{s}(t) = -\omega_{\alpha}^{2} Q_{\alpha}^{s}(t)$$
(3)

From equation (8.58) and the associated text on p. 210, the unnormalized ground state eigenfunction corresponding to (3) is

$$\phi_0(x_\alpha) = \exp\left(-\frac{\omega_\alpha x_\alpha^2}{2\hbar}\right)$$

Then by equation (8.62)

$$\Phi_0 = \prod_{\alpha=0}^{N-1} \phi_0(Q_\alpha^c) \phi_0(Q_\alpha^s) = \exp\left(-\frac{1}{2\hbar} \sum_{\alpha=0}^{N-1} \omega_\alpha(Q_\alpha^c + Q_\alpha^s)\right)$$