A quantum computer can be simulated by applying rotations to a unit vector $u \in \mathbb{C}^{2^n}$ where n is the number of qubits. The dimension is 2^n because a register with n qubits has 2^n eigenstates. Quantum operations are "rotations" because they preserve |u| = 1. Mathematically, a rotation of u is equivalent to the product Ru where R is a $2^n \times 2^n$ matrix.

The Eigenmath function rotate(u, s, k, ...) rotates vector u and returns the result. Vector u is required to have 2^n elements where n is an integer from 1 to 15. Arguments s, k, ... are a sequence of rotation codes where s is an upper case letter and k is a qubit number from 0 to n-1. Rotations are evaluated from left to right. The available rotation codes are

C, kControl prefix H, kHadamard P, k, ϕ Phase modifier Q, kQuantum Fourier transform V, kInverse quantum Fourier transform W, k, jSwap bits X, kPauli X Y, kPauli Y Z, kPauli Z

Control prefix C, k modifies the next rotation code so that it is a controlled rotation with k as the control qubit. Fourier rotations Q, k and V, k are applied to qubits 0 through k. (Q and V ignore any control prefix.)

Error codes

- 1 Argument u is not a vector or does not have 2^n elements where n = 1, 2, ..., 15.
- 2 Unexpected end of argument list (i.e., missing argument).
- 3 Bit number format error or range error.
- 4 Unknown rotation code.

Eigenstates $|j\rangle$ are represented by the following vectors. (Each vector has 2^n elements.)

$$|0\rangle = (1, 0, 0, \dots, 0)$$

$$|1\rangle = (0, 1, 0, \dots, 0)$$

$$|2\rangle = (0, 0, 1, \dots, 0)$$

$$\vdots$$

$$|2^{n} - 1\rangle = (0, 0, 0, \dots, 1)$$

A quantum computer algorithm is a sequence of rotations applied to the initial state $|0\rangle$. (The sequence could be combined into a single rotation by associativity of matrix multiplication.) Let ψ_f be the final state of the quantum computer after all the rotations have been applied. Like any other state, ψ_f is a linear combination of eigenstates.

$$\psi_f = \sum_{j=0}^{2^n - 1} c_j |j\rangle, \quad |\psi_f| = 1$$

The last step is to measure ψ_f and get a result. Measurement rotates ψ_f to an eigenstate $|j\rangle$. The measurement result is $|j\rangle$. The probability P_j of getting a specific result $|j\rangle$ is

$$P_j = |c_j|^2 = c_j c_j^*$$

Note that if ψ_f is already an eigenstate then no rotation occurs. (The probability of rotating to a different eigenstate is zero.) Since the measurement result is always an eigenstate, the coefficients c_j cannot be observed. However, the same calculation can be run multiple times to obtain a probability distribution of results. The probability distribution is an estimate of $|c_j|^2$ for each $|j\rangle$ in ψ_f .

Eigenmath code snippets for before and after rotate:

-- number of eigenstates

Initialize $\psi = |0\rangle$.

n = 4

 $N = 2^n$

Example.

```
psi = zero(N)
psi[1] = 1
Compute the probability distribution for state \psi.
P = psi conj(psi)
Hence
                             P[1] = \text{probability that } |0\rangle \text{ will be the result}
                             P[2] = \text{probability that } |1\rangle \text{ will be the result}
                             P[3] = \text{probability that } |2\rangle \text{ will be the result}
                             P[N] = \text{probability that } |N-1\rangle \text{ will be the result}
Draw a probability distribution.
xrange = (0,N)
yrange = (0,1)
draw(P[ceiling(x)],x)
Compute an expectation value.
sum(k,1,N, (k-1) P[k])
Make the high order qubit "don't care."
for(k,1,N/2, P[k] = P[k] + P[k + N/2])
Hence for N = 16
                            P[1] = \text{probability that the result will be } |0\rangle \text{ or } |8\rangle
                            P[2] = \text{probability that the result will be } |1\rangle \text{ or } |9\rangle
                            P[3] = \text{probability that the result will be } |2\rangle \text{ or } |10\rangle
                            P[8] = \text{probability that the result will be } |7\rangle \text{ or } |15\rangle
```

-- number of qubits (example)

```
-- Verify the following truth table for cnot
      Input Output
      00
            00
      01
            11
      10
            10
      11
            01
U(psi) = rotate(psi,C,0,X,1) -- cnot
M(psi) = psi conj(psi) -- measure
ket00 = (1,0,0,0)
ket01 = (0,1,0,0)
ket10 = (0,0,1,0)
ket11 = (0,0,0,1)
M(U(ket00)) == M(ket00)
M(U(ket01)) == M(ket11)
M(U(ket10)) == M(ket10)
M(U(ket11)) == M(ket01)
```