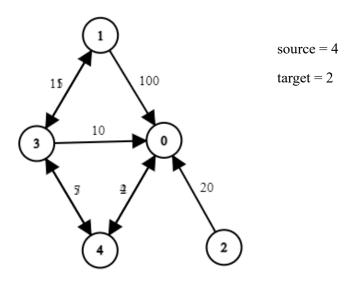


	Changed	Edge(x,y)	Dist_dictionary	Pred_dictionary
initialization	true		0 1 2 3 4 0 00 00 00 00	0 1 2 3 4 0 -1 -1 -1 -1
Iteration 1	False False False True True True	(3,0) (1,3) (4,0) (0,4) (4,3) (3,1)	0 1 2 3 4 0 00 00 00 00 0 00 00 00 00 0 00 00 00 00 0 00 00 00 4 0 00 00 9 4 0 14 00 9 4	0 1 2 3 4 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 0 -1 -1 -1 4 0 -1 3 -1 4 0
Iteration 2	False		0 1 2 3 4 0 00 00 00 00 0 00 00 00 00 0 00 00 00 00 0 00 00 00 4 0 00 00 9 4 0 14 00 9 4	0 1 2 3 4 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 0 -1 -1 -1 4 0 -1 3 -1 4 0

Min. cost walk from 0 to 3: dist[3] = 9 and it's built backwards from predecessor dictionary:

Target=3 => pred[3]=4 => pred[4]=0

Walk: 0,4,3



	Changed	Edge(x,y)	Dist_dictionary	Pred_dictionary
initialization	true		0 1 2 3 4 0 00 00 00 00	0 1 2 3 4 0 -1 -1 -1 -1
Iteration 1	False False False True True True	(4,0) (4,3) (4,0) (0,4) (4,3) (3,1)	0 1 2 3 4 0 00 00 00 00 0 00 00 5 0 0 10 00 00 00 2 00 00 00 4	0 1 2 3 4 -1 -1 -1 -1 -1 -1 -1 -1 4 -1 -1 3 -1 -1 -1 4 -1 -1 -1 0
Iteration 2	False		0 1 2 3 4 0 00 00 00 00 0 00 00 5 0 0 10 00 00 00 2 00 00 00 4	0 1 2 3 4 -1 -1 -1 -1 -1 -1 -1 -1 4 -1 -1 3 -1 -1 -1 4 -1 -1 -1 0

Min. cost walk from 4 to 2: dist[2] = 999999 => There is no walk possible from 4 to 2.