

# Numerical Optimization Methods in Imaging

## Exercise .

Let  $\mathcal{H}$  and  $\mathcal{G}$  be real Hilbert spaces (e.g.,  $\mathcal{H} = \mathbb{R}^N$  and  $\mathcal{G} = \mathbb{R}^M$ ). Let  $f \in \Gamma_0(\mathcal{H})$ , let  $g \in \Gamma_0(\mathcal{G})$ , and let  $L \in \mathcal{B}(\mathcal{H}, \mathcal{G})$  (e.g.,  $L \in \mathbb{R}^{M \times N}$ ). Let  $\tilde{x} \in \mathcal{H}$  and  $\gamma \in ]0, +\infty[$ . We denote by  $L^*$  the adjoint of  $L$  (e.g.,  $L^* = L^\top$  in the finite dimensional case).

1. Consider the operator defined as

$$(\forall y \in \mathcal{G}) \quad B(y) = -L \operatorname{prox}_f(\tilde{x} - L^*y).$$

Show that  $B$  is  $\beta_B$ -cocoercive where  $\beta_B$  will be specified.

2. In the following, we assume that  $\gamma \in ]0, 2/\|L\|^2[$ . Deduce from the previous question that the operator defined as

$$(\forall y \in \mathcal{G}) \quad T(y) = \operatorname{prox}_{\gamma g^*}(y + \gamma L \operatorname{prox}_f(\tilde{x} - L^*y))$$

is  $\alpha_T$ -averaged where  $\alpha_T$  will be specified.

3. Assume that  $\operatorname{Fix} T \neq \emptyset$ . Consider the iterative algorithm :

$$(\forall n \in \mathbb{N}) \quad y_{n+1} = y_n + \lambda_n(T(y_n) - y_n).$$

where  $y_0 \in \mathcal{G}$ . Give a sufficient condition on  $(\lambda_n)_{n \in \mathbb{N}}$  for the weak convergence of  $(y_n)_{n \in \mathbb{N}}$ . What can be said about the limit point ?

4. Show that the fixed points of  $T$  are the minimizers of a function to be determined.
5. Let  $y \in \operatorname{Fix} T$ . Show that  $x = \operatorname{prox}_f(\tilde{x} - L^*y)$  is the solution to a minimization problem.