

## Homework 3: Support Vector Machines

Lecturer: Georgios P. Karagiannis

georgios.karagiannis@durham.ac.uk

---

 Instructions: For Formative assessment, submit the solutions to all of the parts of the Exercise
 

---

**Exercise 1.** Consider a training data set  $\mathcal{S} = \{z_i = (x_i, y_i)\}_{i=1}^m$ . Consider the Soft-SVM Algorithm that requires the solution of the following quadratic minimization problem (in a slightly modified but equivalent form to what we have discussed)

### Primal problem

$$(w^*, b^*, \xi^*) = \arg \min_{(w, b, \xi)} \left( \frac{1}{2} \|w\|_2^2 + C \sum_{i=1}^m \xi_i \right) \quad (1)$$

$$\text{subject to: } y_i (\langle w, x_i \rangle + b) \geq 1 - \xi_i, \quad \forall i = 1, \dots, m \quad (2)$$

$$\xi_i \geq 0, \quad \forall i = 1, \dots, m \quad (3)$$

for some user-specified fixed parameter  $C > 0$ .

1. Specify the Lagrangian function  $L$  associated to the above primal quadratic minimization problem, where  $\{\alpha_i\}$  are the Lagrange coefficients wrt (2), and  $\{\beta_i\}$  are the Lagrange coefficients wrt (3). Write down any possible restrictions on the Lagrange coefficients.
2. Compute the dual Lagrangian function denoted as  $\tilde{L}$  as a function of the Lagrange coefficients and the data points  $\mathcal{S}$ .
3. Apply the Karush–Kuhn–Tucker (KKT) conditions to the above problem, and write them down.
4. Derive and write down the dual Lagrangian quadratic maximization problem, along with the inequality and equality constraints, where you seek to find  $\{\alpha_i\}$ .
5. Justify why the  $i$ -th point  $x_i$  lies on the margin boundary when  $\alpha_i \in (0, C)$  (beware it is  $\alpha_i \neq C$ ), and why the  $i$ -th point  $x_i$  lies inside the margin when  $\alpha_i = C$ .

6. Given optimal values  $\{\alpha_i^*\}$  for Lagrangian coefficients  $\{\alpha_i\}$  as they are derived by solving the dual Lagrangian maximization problem in part 4, derive the optimal values  $w^*$  and  $b^*$  for the parameters  $w$  and  $b$  as function of the support vectors. Regarding parameter  $b$  it should be in the derived in the form

$$b^* = \frac{1}{|\mathcal{M}|} \sum_{i \in \mathcal{M}} \left( y_i - \sum_{j \in \mathcal{S}} \alpha_j^* y_j \langle x_j, x_i \rangle \right)$$

where you determine the sets  $\mathcal{M}$  and  $\mathcal{S}$ .

7. Report the halfspace predictive rule  $h_{w,b}(x)$  of the above problem as a function of  $\alpha^*$  and  $b^*$ .