Measuring Malaria in Complex Transmission Systems

A Time-at-Risk-Based Approach

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Introduction



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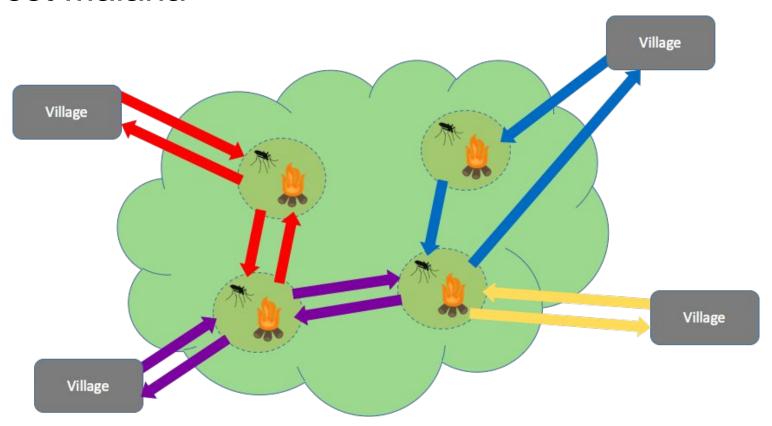


Ross-Macdonald Equations

$$\frac{dX}{dt} = abe^{-gn}\frac{Y}{H}(H - X) - rX$$

$$\frac{dY}{dt} = ac\frac{X}{H}(V - Y) - gY$$

Forest Malaria



Time-at-Risk (TaR)

$$\mathbf{\Psi} = \begin{bmatrix} p_{11} & p_{12} & \dots & p_{1n} \\ p_{21} & p_{22} & \dots & p_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ p_{n1} & p_{n2} & \dots & p_{nn} \end{bmatrix}$$

Objective

How does R₀ affect malaria transmission in complex systems with multiple interconnected locations?

RM Equations at Equilibrium

$$0 = R_0 \frac{X}{H + ScX} \left(H - X \right) - X$$

R_o as a Threshold

$$R_0 \begin{cases} < 1 & \text{transmission dies out over time} \\ > 1 & \text{sustained endemic transmission} \end{cases}$$

RM Equations in Matrix Form

$$\mathbf{X} = \begin{bmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{bmatrix} \qquad \mathbf{Y} = \begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{bmatrix} \qquad \mathbf{H} = \begin{bmatrix} H_1 \\ H_2 \\ \vdots \\ H_n \end{bmatrix} \qquad \mathbf{V} = \begin{bmatrix} V_1 \\ V_2 \\ \vdots \\ V_n \end{bmatrix}$$

Scaling by Time-at-Risk

$$\mathbf{X}_{\Psi} = \mathbf{\Psi}^{\mathbf{T}}\mathbf{X}$$

 $\mathbf{H}_{\Psi} = \mathbf{\Psi^T}\mathbf{H}$

RM Equations in Matrix Form

$$\frac{d\mathbf{Y}}{dt} = ac\frac{\mathbf{X}_{\Psi}}{\mathbf{H}_{\Psi}} \circ (\mathbf{V} - \mathbf{Y}) - g\mathbf{Y}$$

$$\frac{d\mathbf{X}}{dt} = abe^{-gn} \left(\mathbf{\Psi} \frac{\mathbf{Y}}{\mathbf{H}_{\Psi}} \right) \circ (\mathbf{H} - \mathbf{X}) - r\mathbf{X}$$

RM Equations in Matrix Form

$$0 = \left(\mathbf{\Psi} \left(\mathbf{R}_{\Psi} \circ \frac{\mathbf{X}_{\Psi}}{cS\mathbf{X}_{\Psi} + \mathbf{H}_{\Psi}} \right) \right) \circ (\mathbf{H} - \mathbf{X}) - \mathbf{X}$$

$$0 = \left(\mathbf{\Psi}\left(\mathbf{R}_{\Psi} \circ \frac{\mathbf{\Theta}_{\Psi}}{cS\mathbf{\Theta}_{\Psi} + 1}\right)\right) \circ (\mathbf{H} - \mathbf{X}) - \mathbf{X}$$

$$\mathbf{X} = \begin{bmatrix} X_V \\ X_F \end{bmatrix}$$

$$\mathbf{H} = egin{bmatrix} H_V \ H_F \end{bmatrix}$$

$$\mathbf{X} = egin{bmatrix} X_V \ X_F \end{bmatrix} \qquad \qquad \mathbf{H} = egin{bmatrix} H_V \ H_F \end{bmatrix} \qquad \qquad \mathbf{R}_{\Psi} = egin{bmatrix} R_{\Psi,V} \ R_{\Psi,F} \end{bmatrix}$$

$$\mathbf{X}_{\Psi} = \mathbf{\Psi}^{\mathbf{T}} \mathbf{X} = \begin{bmatrix} 1 & 1-p \\ 0 & p \end{bmatrix} \begin{bmatrix} X_V \\ X_F \end{bmatrix} = \begin{bmatrix} X_V + (1-p)X_F \\ pX_F \end{bmatrix}$$

$$\mathbf{H}_{\Psi} = \mathbf{\Psi^T} \mathbf{H} = \begin{bmatrix} 1 & 1-p \\ 0 & p \end{bmatrix} \begin{bmatrix} H_V \\ H_F \end{bmatrix} = \begin{bmatrix} H_V + (1-p)H_F \\ pH_F \end{bmatrix}$$

$$oldsymbol{\Theta}_{\Psi} = rac{\mathbf{X}_{\Psi}}{\mathbf{H}_{\Psi}} = egin{bmatrix} \Theta_{\Psi,V} \ \Theta_{\Psi,F} \end{bmatrix} = egin{bmatrix} rac{X_V + (1-p)X_F}{H_V + (1-p)H_F} \ rac{X_F}{H_F} \end{bmatrix}$$

$$0 = \begin{bmatrix} R_{\Psi,V} \cdot \frac{\Theta_{\Psi,V}}{cS\Theta_{\Psi,V} + 1} \cdot (H_V - X_V) - X_V \\ \left(R_{\Psi,F} \cdot (1 - p) \cdot \frac{\Theta_{\Psi,F}}{cS\Theta_{\Psi,F} + 1} + R_{\Psi,F} \cdot p \cdot \frac{\Theta_{\Psi,F}}{cS\Theta_{\Psi,F} + 1} \right) \cdot (H_F - X_F) - X_F \end{bmatrix}$$

Heatmap

3D Surface