

Session 4

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In this session we are using the prioritizr package to create a set of conservation scenarios for protecting the future distribution of koalas in the SEQ region.

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Install the rcbc package for the cbc optimization solver

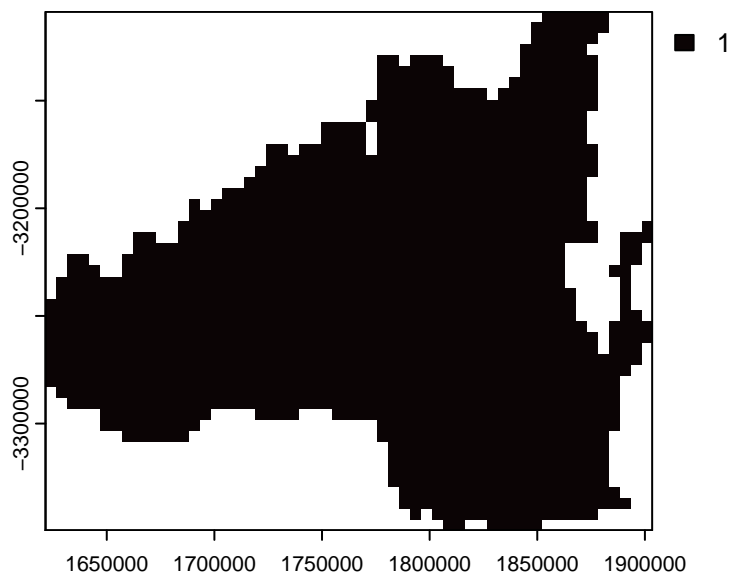
```
if (!require(remotes))
  install.packages("remotes")
remotes::install_github("dirkschumacher/rcbc")
```

Install packages

```
# Load required packages
library(terra)
library(viridisLite)
library(prioritizr)
library(raster)
library(sf)
library(rcbc)
```

Load Spatial Data

```
# Load the Planning unit
PU <- terra::rast("data/otherdata/PlanningUnits.tif")
plot(PU, col = viridisLite::mako(n = 1))
```

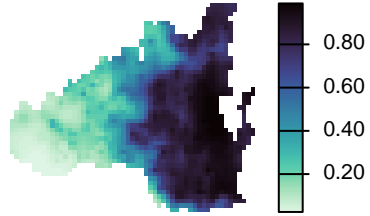


```
# Get the file names of the testing data
spp.list <- list.files(path = "data/SpeciesDistributions/", full.names = TRUE, recursive = T)
```

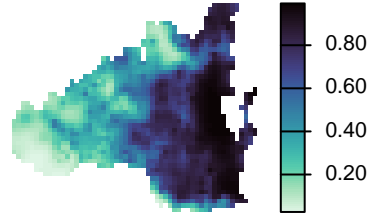
Load current species distribution

```
spp <- rast(spp.list[grept("current", spp.list)])
new_names <- tools::file_path_sans_ext(basename(spp.list[grept("current", spp.list)]))
names(spp) <- new_names
plot(spp, axes = FALSE, col = viridisLite::mako(n = 100, direction = -1), main = names(spp))
```

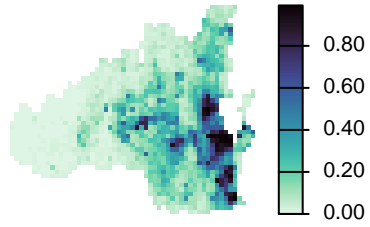
current_koala_glm1



current_koala_glm2



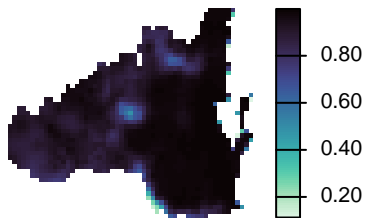
current_koala_RF



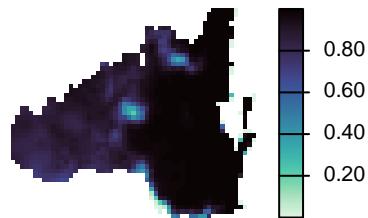
Load future species distribution

```
spp <- rast(spp.list[grepl("future", spp.list)])  
new_names <- tools::file_path_sans_ext(basename(spp.list[grepl("future", spp.list)]))  
names(spp) <- new_names  
plot(spp, axes = FALSE, col = viridisLite::mako(n = 100, direction = -1), main = names(spp))
```

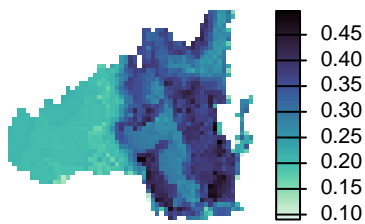
future_koala_glm1



future_koala_glm2



future_koala_RF



Load protected areas, urban centers, and cost layer

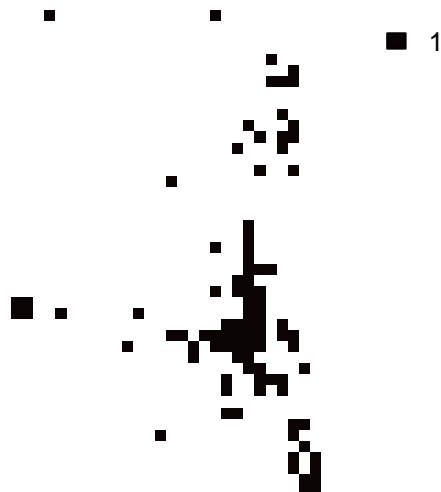
```
PA <- rast("data/otherdata/protected_areas.tif")  
plot(PA, axes = FALSE, col = viridisLite::mako(n = 100, direction = -1), main = "Protected A
```

Protected Areas (I & II)

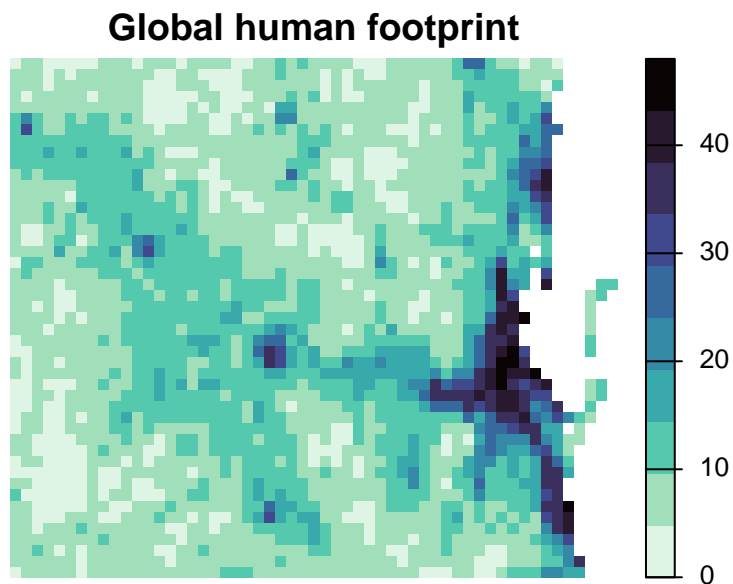


```
urban <- rast("data/otherdata/urban_centers.tif")  
plot(urban, axes = FALSE, col = viridisLite::mako(n = 100, direction = -1), main = "Urban Ce
```

Urban Centers



```
hfp <- rast("data/otherdata/cost_hfp2013.tif")
plot(hfp, axes = FALSE, col = viridisLite::mako(n = 10, direction = -1), main = "Global human footprint")
```



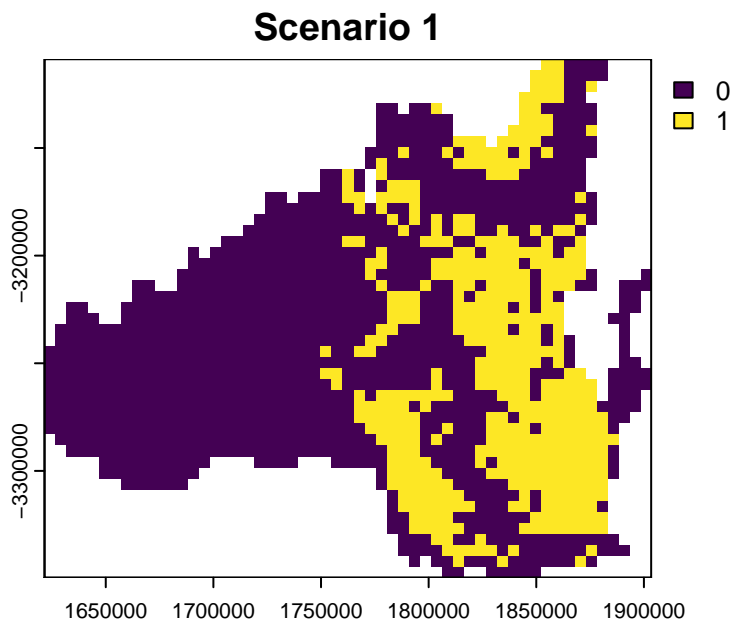
Define Budget

```
budget.area <- round(0.3 * length(cells(PU)))
```

Scenario 1: Basic Shortfall Objective

```
p <- problem(PU, spp) %>%
  add_min_shortfall_objective(budget = budget.area) %>%
  add_relative_targets(targets = 1) %>%
  add_default_solver() %>%
  add_proportion_decisions()

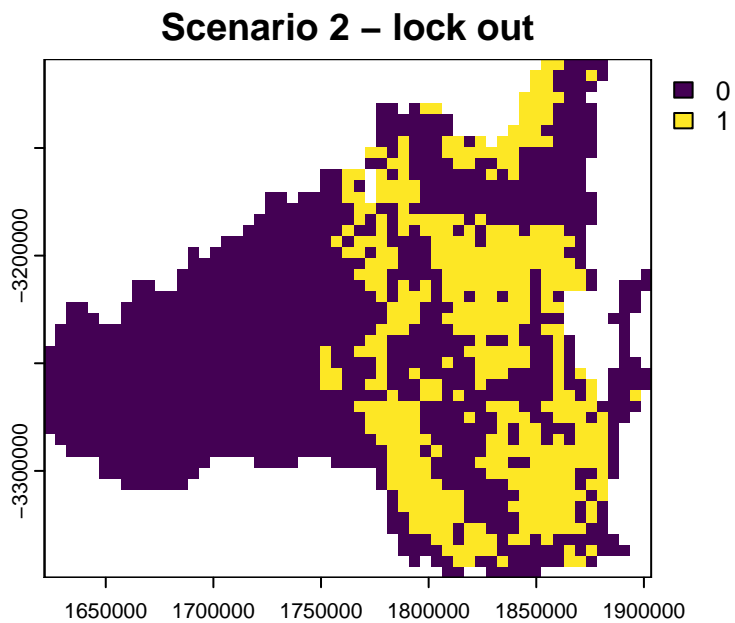
s1 <- solve(p)
plot(s1, main = "Scenario 1")
```



Scenario 2: Lock Out Urban Areas

```
p <- problem(PU, spp) %>%
  add_min_shortfall_objective(budget = budget.area) %>%
  add_relative_targets(targets = 1) %>%
  add_proportion_decisions() %>%
  add_locked_out_constraints(urban) %>%
  add_default_solver()

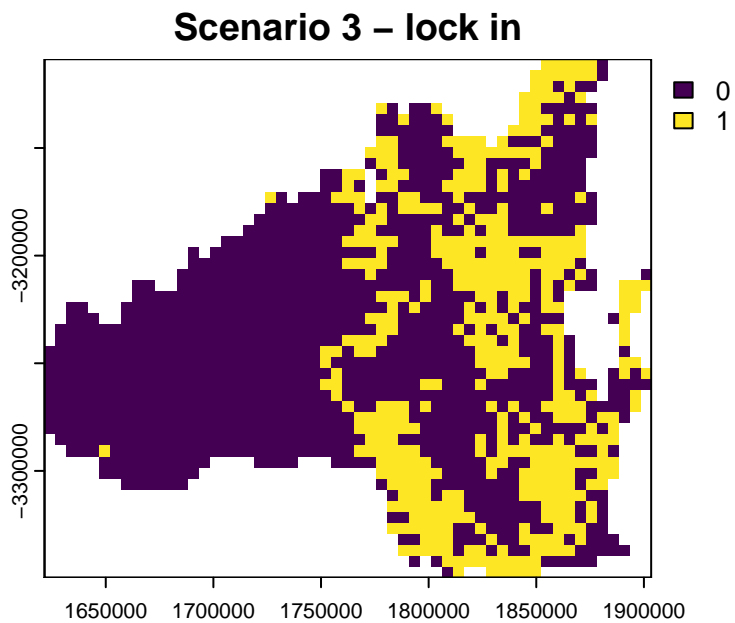
s2 <- solve(p)
plot(s2, main = "Scenario 2 - lock out")
```



Scenario 3: Lock In Protected Areas

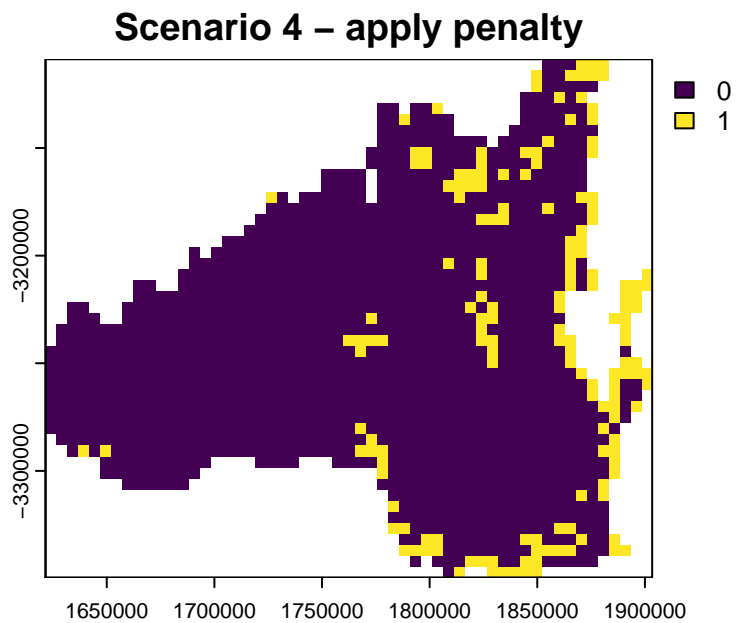
```
p <- problem(PU, spp) %>%
  add_min_shortfall_objective(budget = budget.area) %>%
  add_relative_targets(targets = 1) %>%
  add_proportion_decisions() %>%
  add_locked_in_constraints(PA) %>%
  add_locked_out_constraints(urban) %>%
  add_default_solver()

s3 <- solve(p)
plot(s3, main = "Scenario 3 - lock in")
```



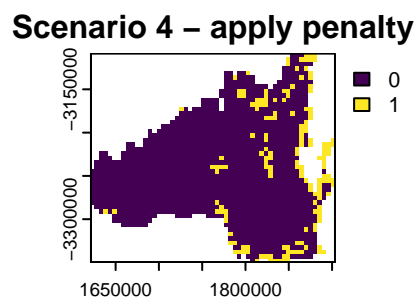
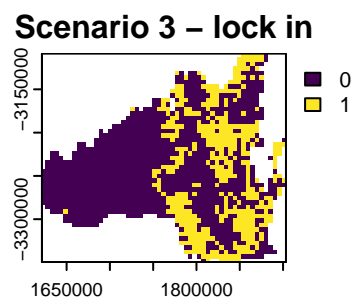
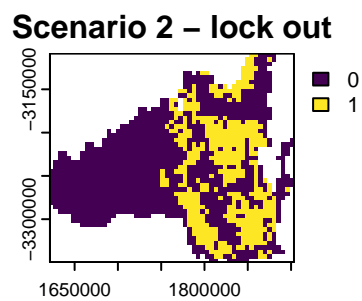
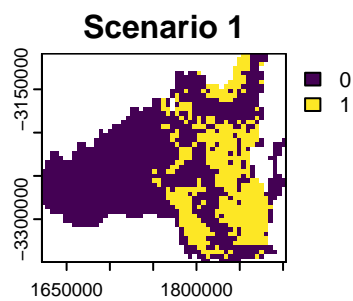
Scenario 4: Penalize Human Footprint

```
p <- problem(PU, spp) %>%  
  add_min_shortfall_objective(budget = budget.area) %>%  
  add_relative_targets(targets = 1) %>%  
  add_linear_penalties(penalty = 1, data = hfp) %>%  
  add_proportion_decisions() %>%  
  add_locked_in_constraints(PA) %>%  
  add_locked_out_constraints(urban) %>%  
  add_default_solver()  
  
s4 <- solve(p)  
plot(s4, main = "Scenario 4 - apply penalty")
```

Plot All Scenarios Side by Side

```
par(mfrow = c(2, 2), mar = c(3, 3, 3, 1))
plot(s1, main = "Scenario 1")
plot(s2, main = "Scenario 2 - lock out")
plot(s3, main = "Scenario 3 - lock in")
plot(s4, main = "Scenario 4 - apply penalty")
```



```
par(mfrow = c(1, 1))
```

Evaluate Metrics

```
rpz_target_spp_s1 <- eval_target_coverage_summary(p, s1)
mean(rpz_target_spp_s1$relative_held)
```

```
[1] 0.3464172
```

```
mean(rpz_target_spp_s1$relative_shortfall)
```

```
[1] 0.6535828
```

```
rpz_target_spp_s2 <- eval_target_coverage_summary(p, s2)
mean(rpz_target_spp_s2$relative_held)
```

```
[1] 0.3440511
```

```
mean(rpz_target_spp_s2$relative_shortfall)
```

```
[1] 0.6559489
```

```
rpz_target_spp_s3 <- eval_target_coverage_summary(p, s3)
mean(rpz_target_spp_s3$relative_held)
```

```
[1] 0.3294218
```

```
mean(rpz_target_spp_s3$relative_shortfall)
```

```
[1] 0.6705782
```

```
rpz_target_spp_s4 <- eval_target_coverage_summary(p, s4)
mean(rpz_target_spp_s4$relative_held)
```

```
[1] 0.1013999
```

```
mean(rpz_target_spp_s4$relative_shortfall)
```

```
[1] 0.8986001
```