Modeling Voter Behaviour and Electoral Dynamics using Cellular Automata

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Basic 1: Voter model with local interaction - Linear voter model

Two Party System: Opinion 0 and opinion 1

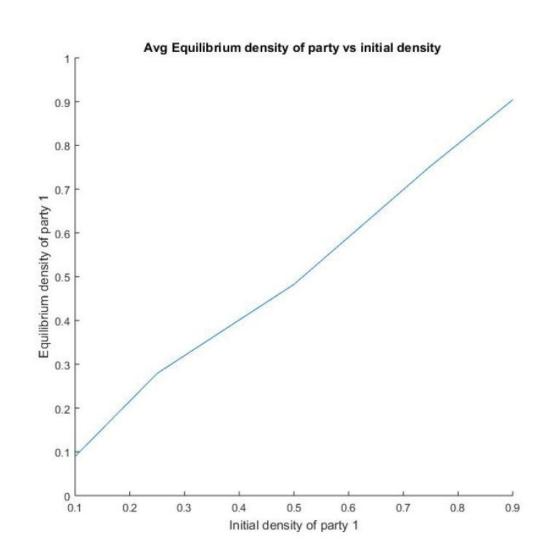
Rules:

- 1. For every time step, an agent is selected at random.
- 2. The agent further selects a random neighbour in his Moore Neighbourhood and takes his opinion.
- 3. Periodic Boundary Condition

Basic model

Important observations -

- 1. Relation is linear
- As if results are predetermined by initial density.
- Even for initial density 0.9 on an average, the stronger opinion cannot establish complete dominance.
- 4. Weak are resilient. This is because of the rule which allows the minority to potentially contribute to the cell's opinion.



Basic 2: Nonlinear voter models

Rules:

- 1. For every time step, an agent is selected at random.
- 2. The Von Neumann neighborhood of the agent is considered. The sum of the opinions of the five agents is considered (The opinion is either 0 or 1). A probability mass function is used to decide whether the agent remains with party/opinion 1.

Probability mass functions of different models:

Sum of opinions in neighborhood	0	1	2	3	4	5
p.m.f for Majority model	0	0	0	1	0.8	1
p.m.f for Linear voter model	0	0.2	0.4	0.6		
p.m.f for Threshold model	0	0.5	0.5	0.5	0.5	1

Sub Models

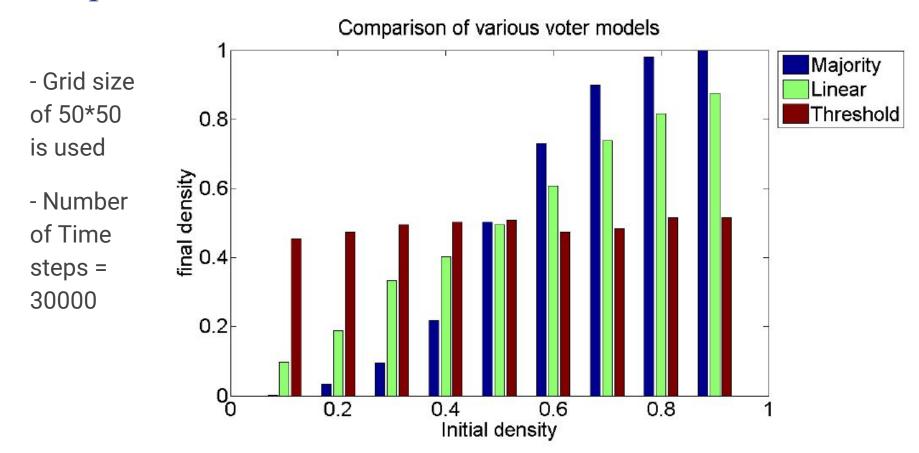
1. Majority rule model -

- -The agent always goes with the **majority** in the group/locality.
- -This reflects **crowd mentality** of being influenced by the majority rather than sticking to your own opinion.

2. Threshold model -

- -The agents' thinking is binary. If the neighborhood has absolute majority, they remain in the same state.
- -Otherwise, the agent flips a coin to decide the party.
- -Illiterate voters

Comparison of linear and non-linear models:



Basic 3: Random Discussion Groups

In this model, **spatial locality** (local neighbourhood) is not considered. In the real world, this model can be used to model voter behaviour due to **interactions** between voters in offices, markets, public transport facilities and other public places.

Rules:

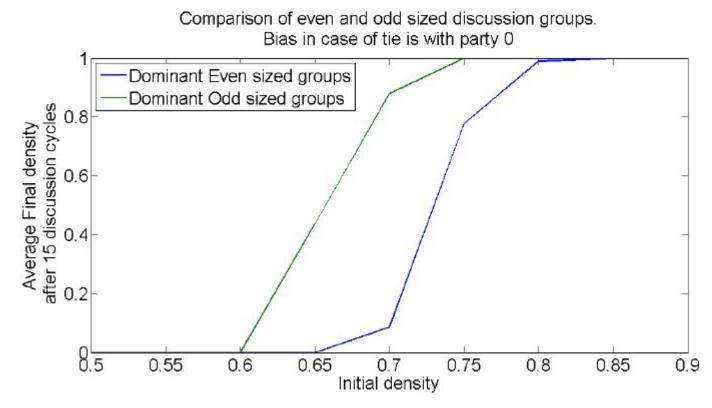
- In each discussion cycle, the entire population is divided into randomly sized discussion groups. The size of the discussion group is decided by a probability mass function.
- 2. The entire group adopts a single opinion decided by majority. In case of a tie, opinion 0 is adopted. This represents some sort of bias for opinion 0.

Probability mass function for different group sizes used for simulation

Size of Group	1	2	3	4	5	6
Probability for odd dominance	0	0.3	0.6	0.05	0.05	0
Probability for even dominance	0	0.3	0.3	0.3	0.1	0

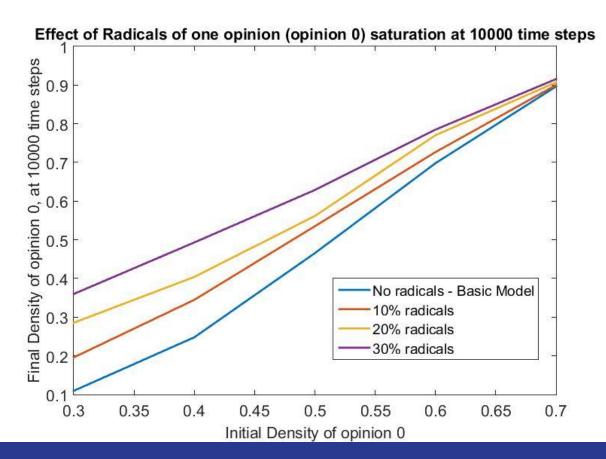
Random Discussion: Comparison of Even-Odd Group

- Grid size -20*20



Extensions 1: Effect of Radicals

- Extension of Majority Model
- Radicals: Never change their opinion
- Radicals of One opinion
- Effect of radicals decreases with increase in initial density.



Extension 2: Tri-Party System

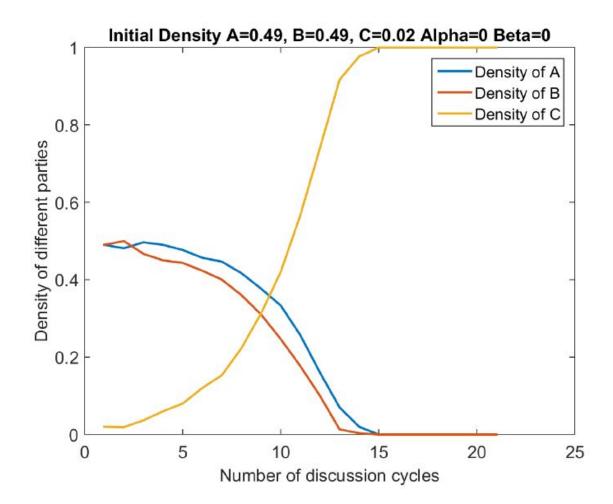
Basic Model: Random Discussion Group

Rules:

- 1. In each discussion cycle, the entire population is divided into discussion groups of size 3.
- 2. The entire group adopts a single opinion decided by majority of the 3 people.
- 3. In case of a tie,
 - a. Opinion A is adopted with probability α
 - b. Opinion B is adopted with probability β
 - c. Opinion C is adopted with probability $(1 \alpha \beta)$

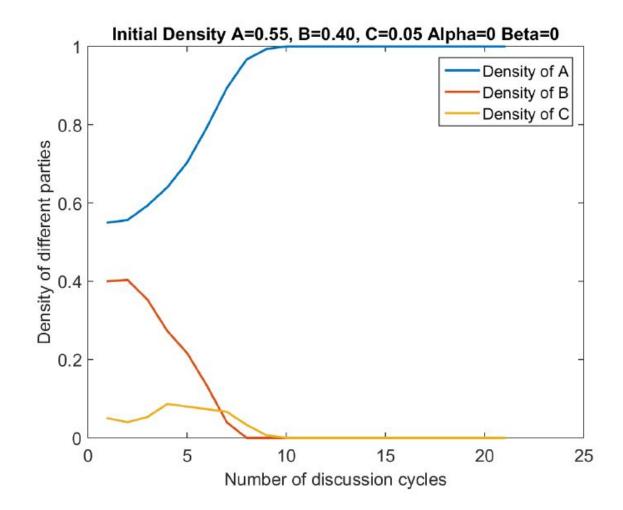
Case I

- Initially no opinion has majority.
- Grid 30*30
- Mathematics behind
 Opinion C winning
- While two fight, the third wins!



Case II

- One opinion has clear Majority (>50%).
- It eventually wins irrespective of other conditions.



Extension 3: Effect of Mass Media - Consensus

A) Media influence in a population with consensus based decision rule.

Basic Model: Global Effect of Media - Reaches Consensus (Media Opinion) - Trivial

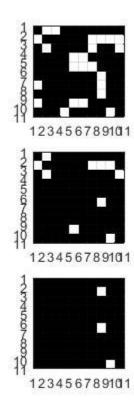
Modification:

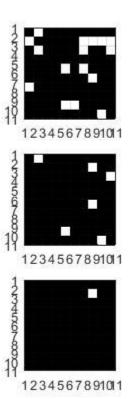
Rule:

- Pick a random cell. Appoint cells in its Von Neumann neighbourhood as its advisers.
- 2. If they are able to reach a consensus, the cell takes their opinion.
- 3. If this fails, the person takes the opinion of the media with some probability p.

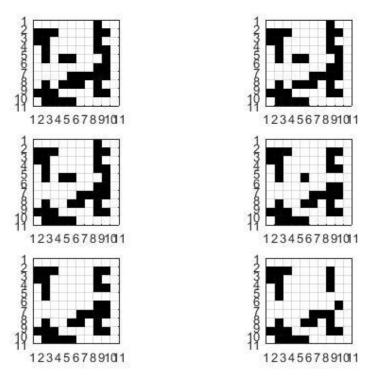
Media hegemony in consensus based society (p=1)

- No. of Iterations = 200
- Randomly initialize the grid with 50:50 density of opinions.
- Media is able to quickly establish its hegemony over public opinion.
- Probability of a consensus is just ¼ for Von Neumann neighbourhood.





Stalemate when media is ineffective (p=0)



Effect of Mass Media

- Consensus based systems are too boring. Can effect of media be studied in more interesting systems?
- Use mass media in a system where decision making is very effective, a majority based system.
- Can we use mass media to subversively?

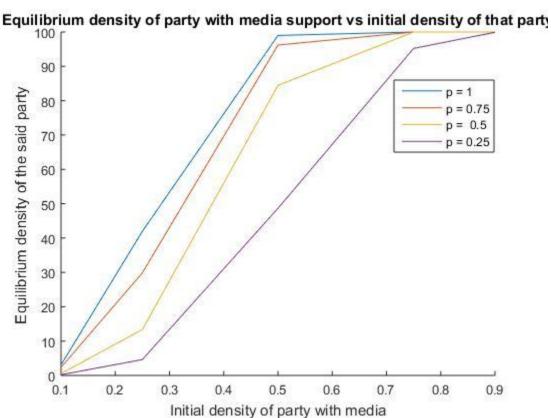
Extension 3: Effect of Mass Media - Majority

Extension of majority model

Rules -

- Same as in consensus, but this time the voter seeks media's opinion in case a tie happens.
- 2. Note that the probability of media affecting the proceedings is low because ties happen rarely.
- 3. But we will see that in spite of this in some situations the media is able to influence the voter opinion.

Influence of media in majority based system



Conclusion

- Several factors considered in isolation to ensure we are able to analyze them systematically without them interacting with each other.
- Simple local rules lead to emergent global behaviours which we can interpret and get insights about the real politics and complex voter behaviour.
- Effect of Random Discussion Groups more realistic insights.
- Impact of important real world factors like mass media and radicals.
- Tri-Party model to observe basic behaviour of multi-party systems.

References

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Thank you! Long live democracy.

Any questions?