

EECS 391

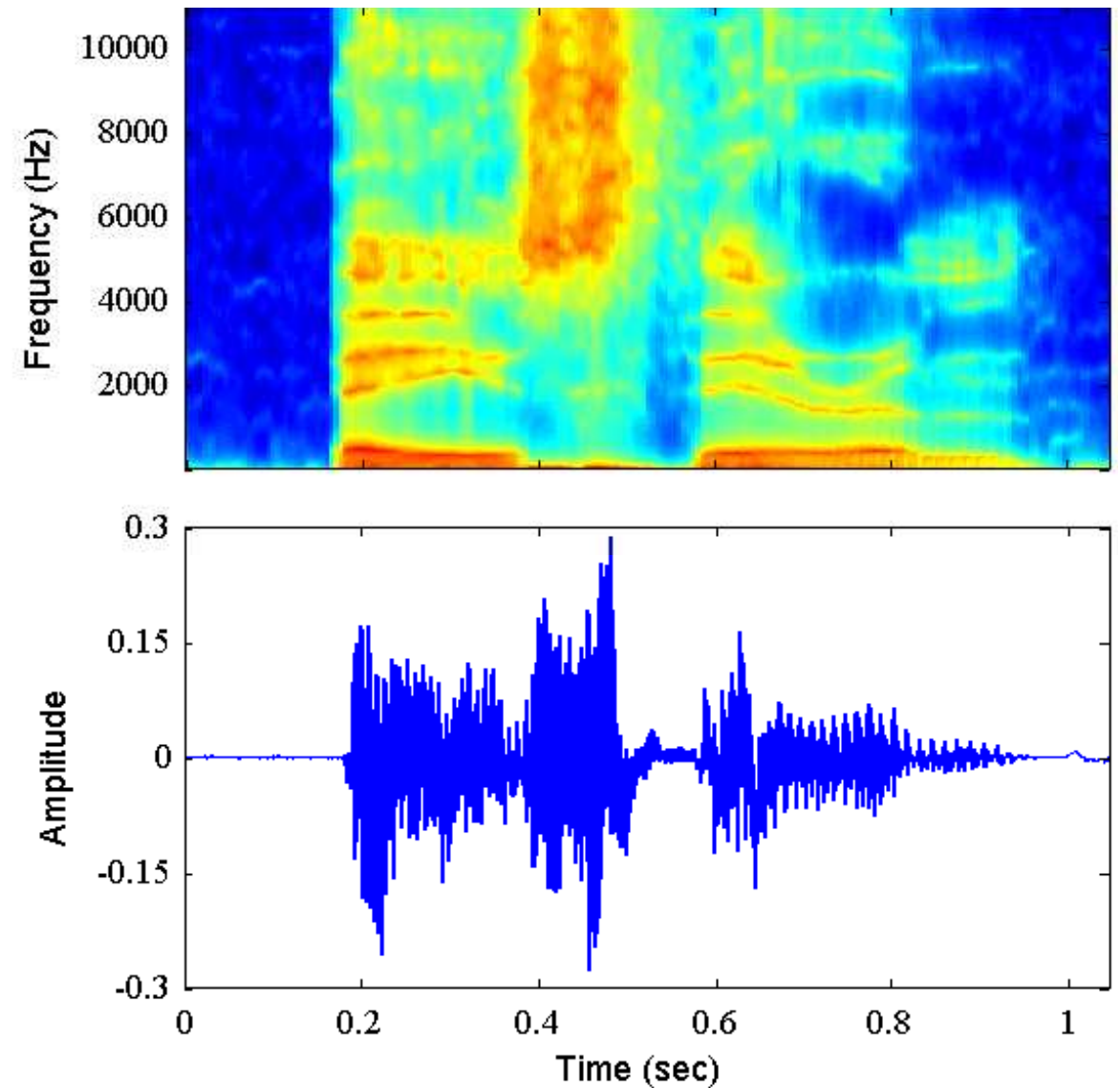
Intro to AI

Models for Sequential Data

L22 Thu Nov 30

Examples of sequential data

- speech spectrogram
 - sequences of power spectra
 - typically 30 ms with 10 ms overlap
- audio waveform: raw sample values
- sequences of syllables and words



| | | | | | | |
|--------|----|---|---------|----|----|----|
| b | ey | z | th | ih | er | em |
| Bayes' | | | Theorem | | | |

Speech Sounds

Speech sounds: Phones

Phone Models

Frame features in $P(\text{features}|\text{phone})$ summarized by

- an integer in $[0 \dots 255]$ (using **vector quantization**); or
- the parameters of a mixture of Gaussians

Three-state phones: each phone has three phases (Onset, Mid, End)

E.g., [t] has silent Onset, explosive Mid, hissing End

$\Rightarrow P(\text{features}|\text{phone}, \text{phase})$

Triphone context: each phone becomes n^2 distinct phones, depending on the phones to its left and right

E.g., [t] in “star” is written [t(s,aa)] (different from “tar” !)

Triphones useful for handling **coarticulation** effects: the articulators have inertia and cannot switch instantaneously between positions

E.g., [t] in “eighth” has tongue against front teeth

Markov processes (Markov chains)

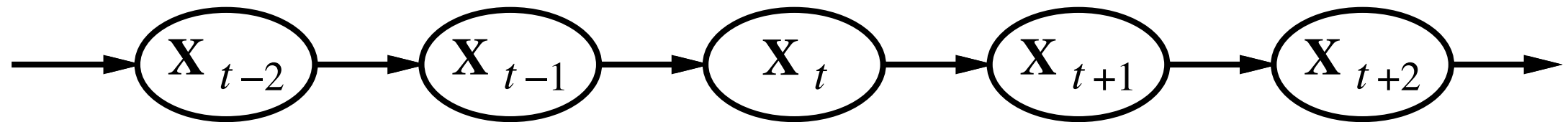
Construct a Bayes net from these variables: parents?

Markov assumption: \mathbf{X}_t depends on **bounded** subset of $\mathbf{X}_{0:t-1}$

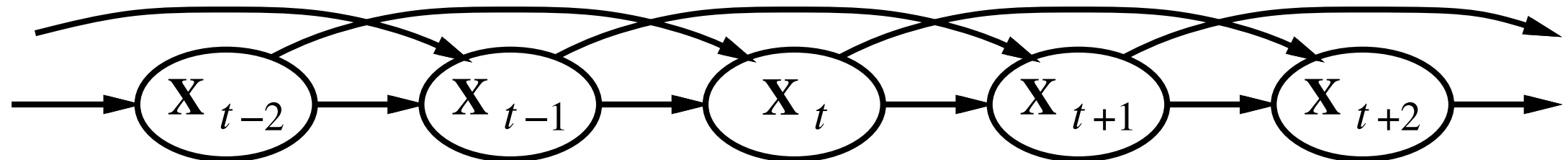
First-order Markov process: $\mathbf{P}(\mathbf{X}_t | \mathbf{X}_{0:t-1}) = \mathbf{P}(\mathbf{X}_t | \mathbf{X}_{t-1})$

Second-order Markov process: $\mathbf{P}(\mathbf{X}_t | \mathbf{X}_{0:t-1}) = \mathbf{P}(\mathbf{X}_t | \mathbf{X}_{t-2}, \mathbf{X}_{t-1})$

First-order



Second-order



(notes on board)

Markov model examples

Markov model examples

Markov model examples

Markov model examples

Markov model examples

Markov model examples: word sequences

6. *First-order word model.* (The words are chosen independently but with frequencies as in English.)

REPRESENTING AND SPEEDILY IS AN GOOD APT OR COME
CAN DIFFERENT NATURAL HERE HE THE A IN CAME THE TO
OF TO EXPERT GRAY COME TO FURNISHES THE LINE
MESSAGE HAD BE THESE.

Markov model examples: word sequences

6. *First-order word model.* (The words are chosen independently but with frequencies as in English.)

REPRESENTING AND SPEEDILY IS AN GOOD APT OR COME
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7. *Second-order word model.* (The word transition probabilities match English text.)

THE HEAD AND IN FRONTAL ATTACK ON AN ENGLISH
WRITER THAT THE CHARACTER OF THIS POINT IS
THEREFORE ANOTHER METHOD FOR THE LETTERS THAT THE
TIME OF WHO EVER TOLD THE PROBLEM FOR AN
UNEXPECTED

Simple language model

Prior probability of a word sequence is given by chain rule:

$$P(w_1 \cdots w_n) = \prod_{i=1}^n P(w_i | w_1 \cdots w_{i-1})$$

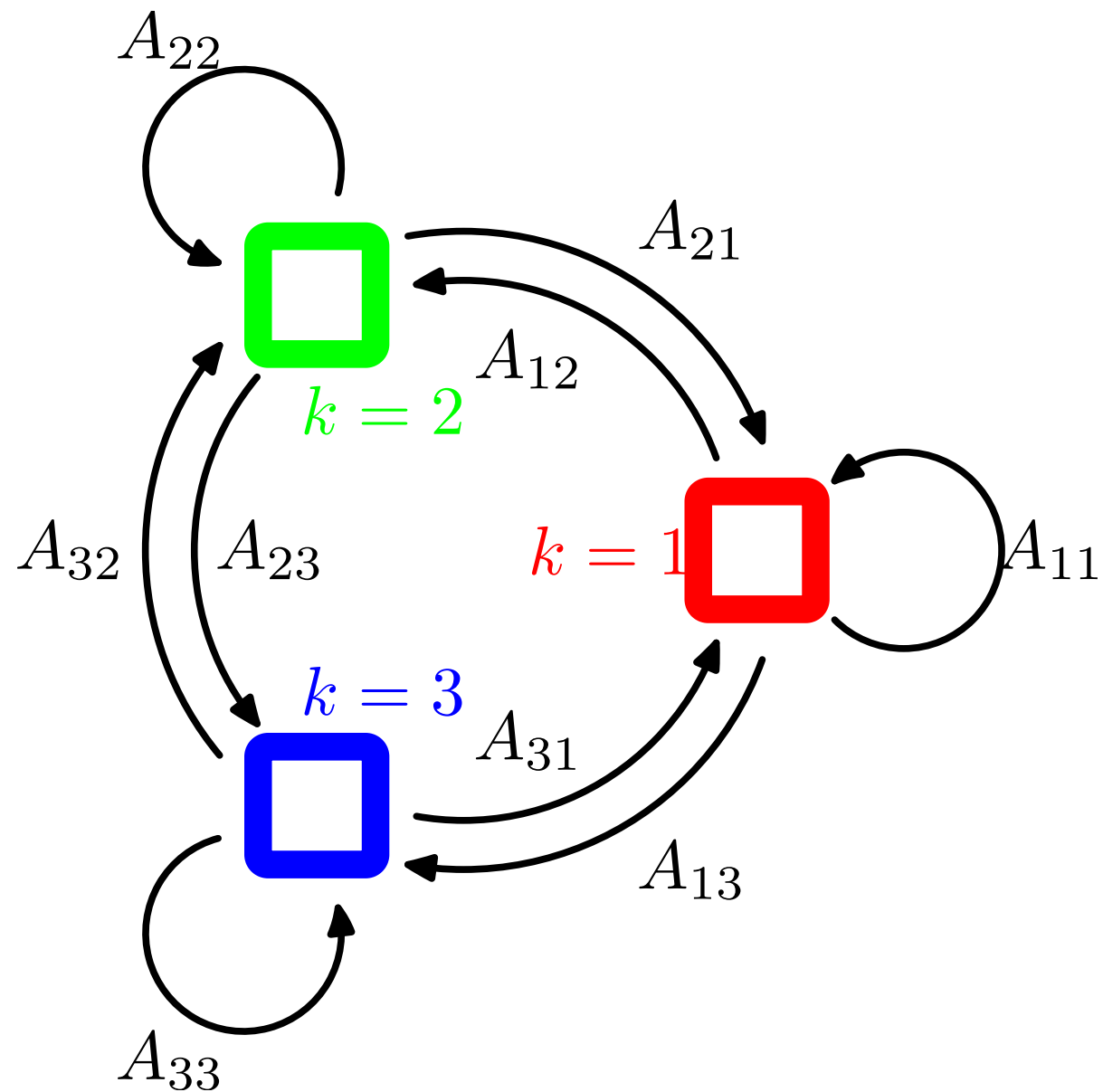
Bigram model:

$$P(w_i | w_1 \cdots w_{i-1}) \approx P(w_i | w_{i-1})$$

Train by counting all word pairs in a large text corpus

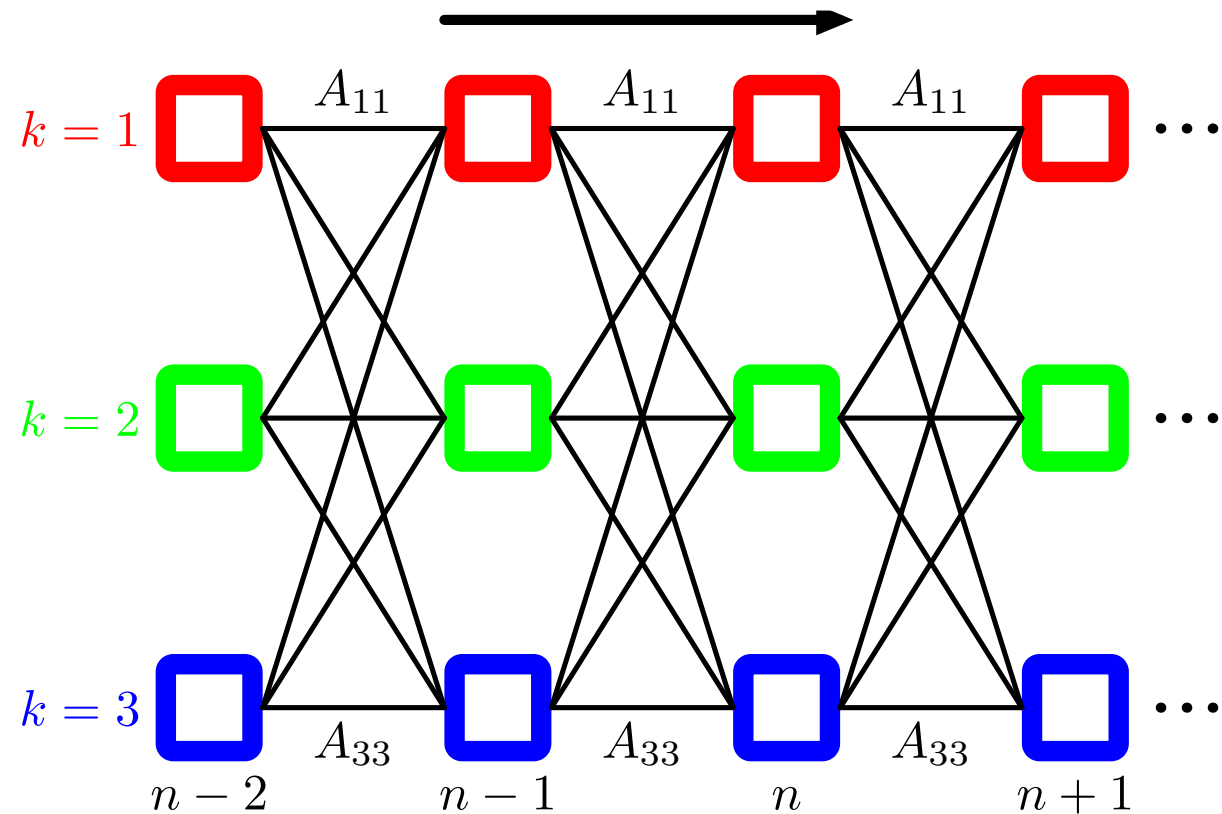
More sophisticated models (trigrams, grammars, etc.) help a little bit

Transition diagram



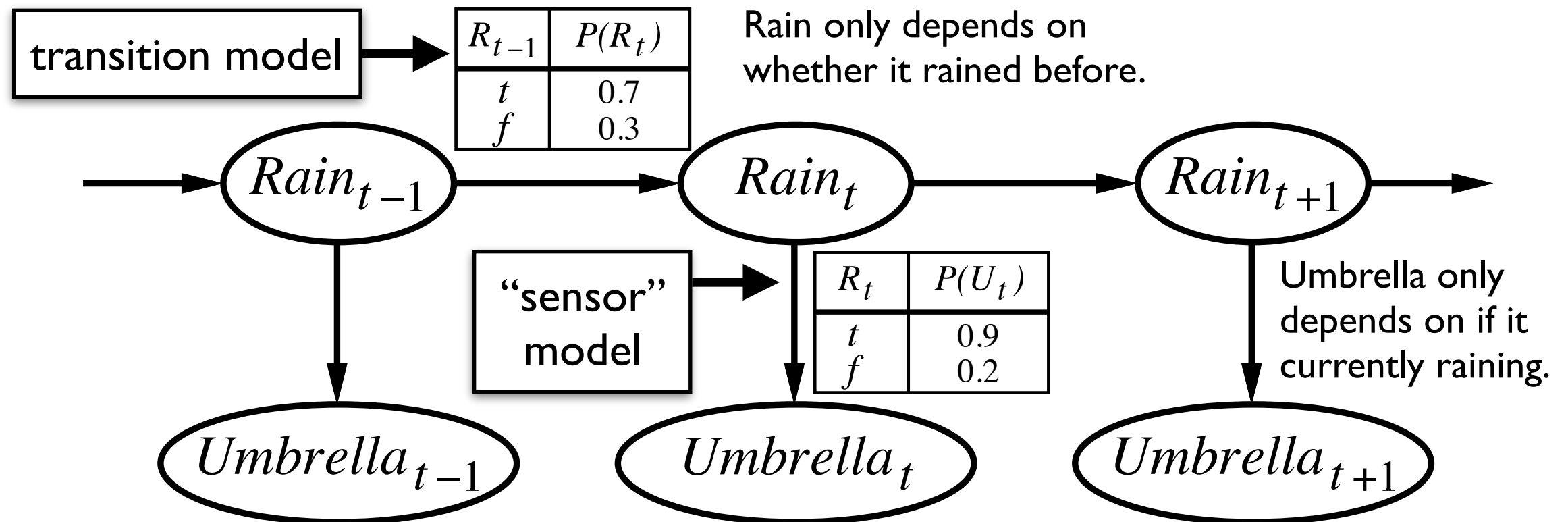
- 3-state model
- A_{ij} are transition probabilities
- Note: this is not a graphical model
 - nodes are not separate variables
 - they're states of a single variable

Alternative transition diagram



- Unfold the 3-state model overtime
- A_{ij} are transition probabilities
- Still not a graphical model.
- Nodes are states of a single variable, z_n .

Example



First-order Markov assumption not exactly true in real world!

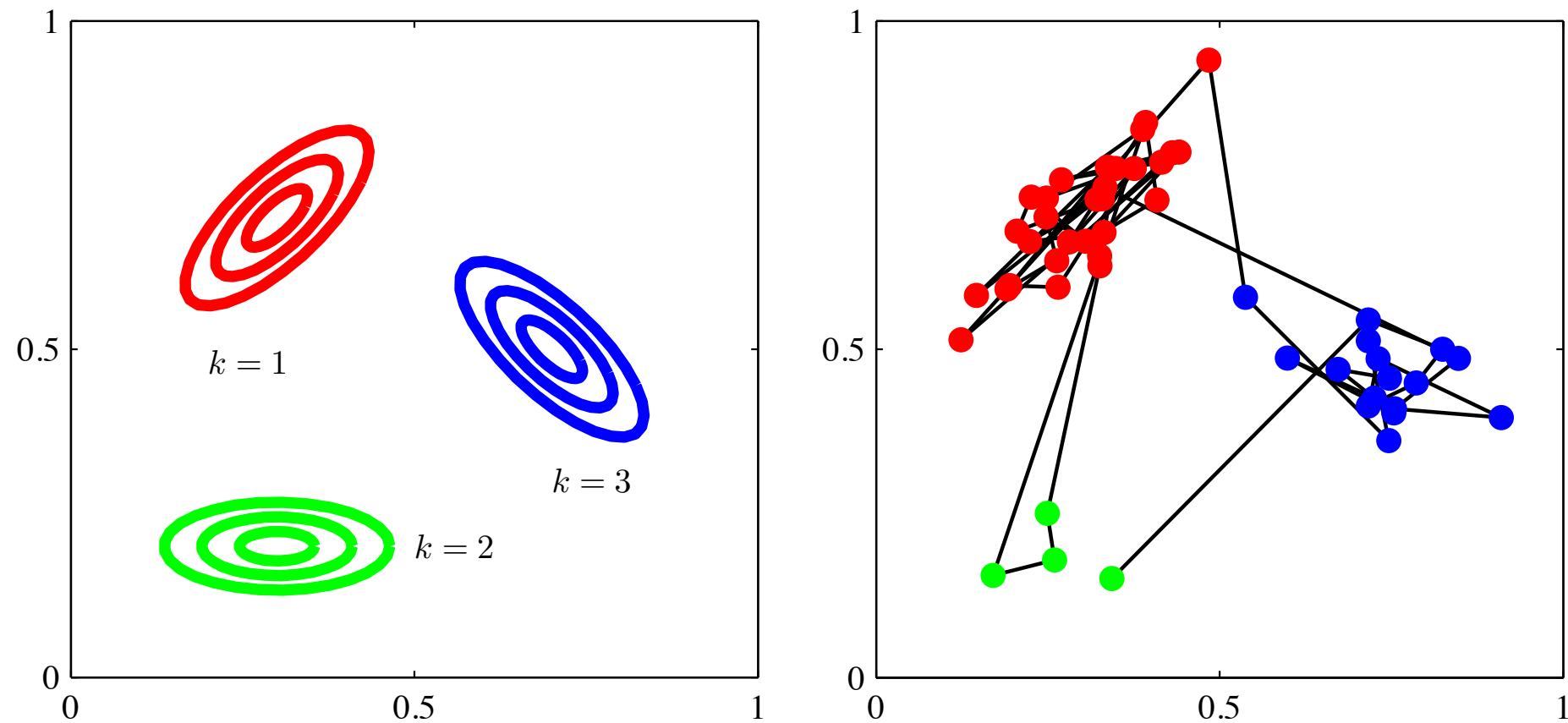
Possible fixes:

1. **Increase order** of Markov process
2. **Augment state**, e.g., add $Temp_t$, $Pressure_t$

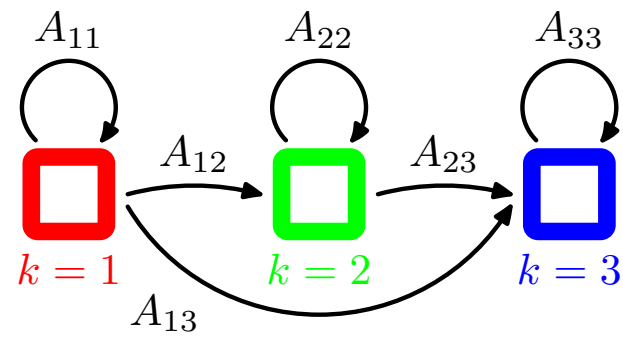
Example: robot motion.

Augment position and velocity with $Battery_t$

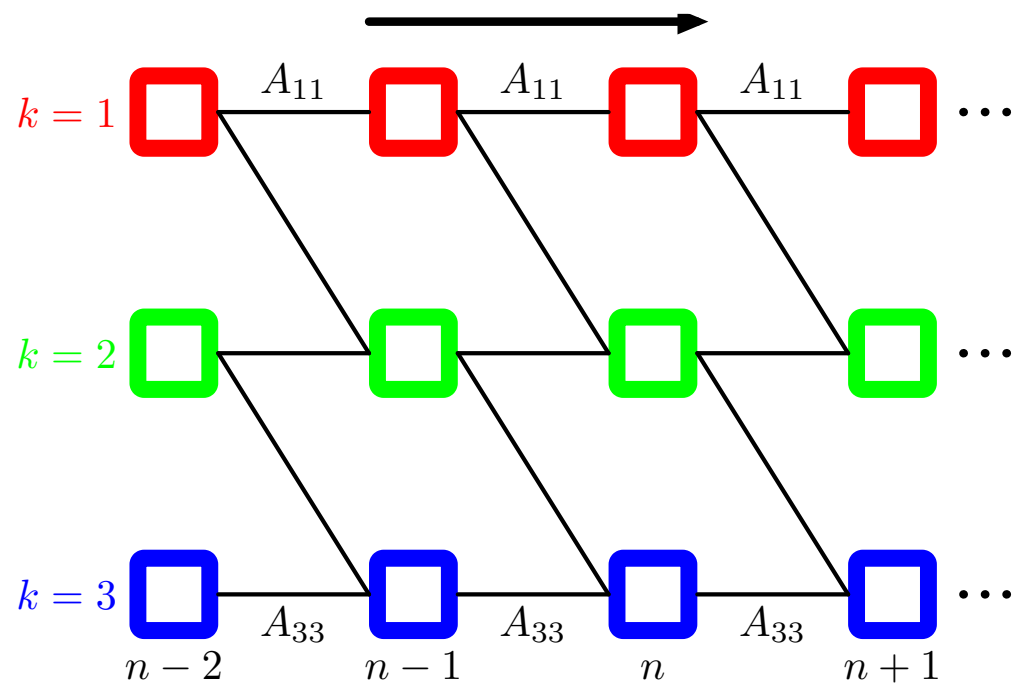
A 3-state Gaussian mixture *emission* model



A left-to-right HMM



- can't go back to previous state
- $A_{jk} = 0$ if $k < j$



A phone HMM model

- Frame features in $p(\text{features}|\text{phone})$, eg:
 - ▀ integer in $[0...255]$ using vector quant.
 - ▀ parameters of a mixture of Gaussians
- Three-state-phones: Onset, Mid, End
 - ▀ eg: [t] silent onset, explosive mid, hissing end: $p(\text{features}|\text{phone}, \text{phase})$
- Triphone context: each phone becomes n^2 distinct phones, depending on phones before and after
 - ▀ eg: [t] in “star” is [t(s,aa)], different from [t] in “tar”
- Triphones handle *coarticulation* effects

Word pronunciation models

Monaural speech recognition challenge

Monaural speech recognition challenge

Monaural speech recognition challenge

Human subjects compared to automated speech recognition

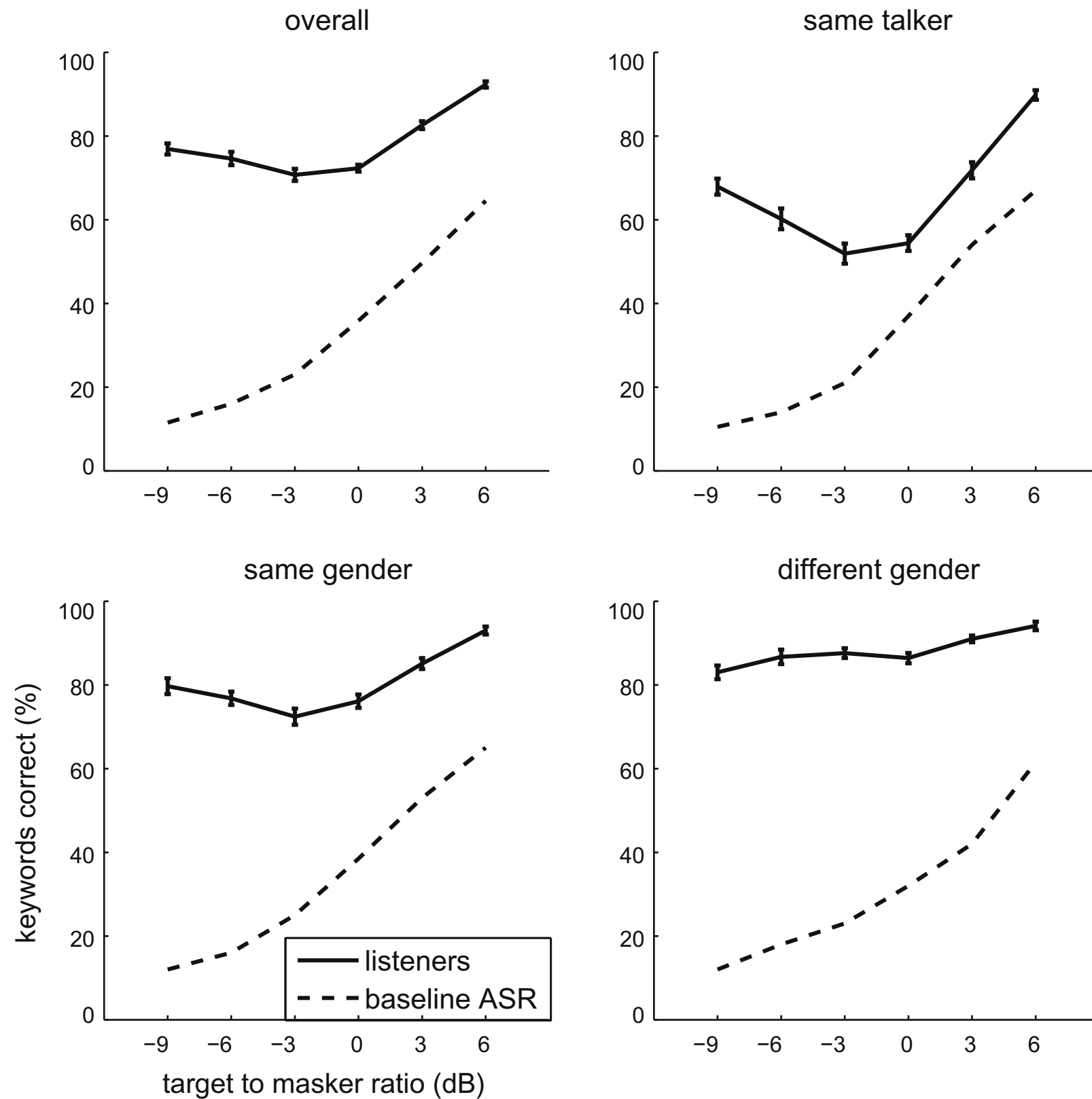


Table 1
Overall word error rate (%) of the ASR systems that were entered into the Pascal 2006 speech separation challenge.

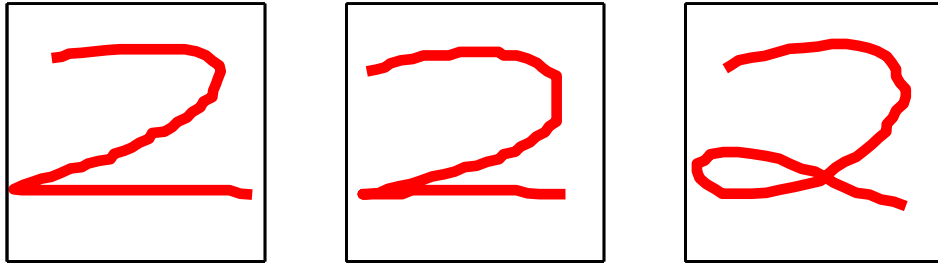
| System | Approach | Accuracy (%) |
|--|-----------------------------------|--------------|
| Hershey et al. (2010) | Model-based, joint decoding | 78.4 |
| Human listeners | Listening | 77.7 |
| Virtanen (2006) ^a | Model-based, alternating decoding | 65.8 |
| Barker et al. (2010) | CASA, missing features | 63.8 |
| Ming et al. (2010) | Model-based, missing features | 58.4 |
| Schmidt and Olsson (2006) ^a | Non-neg. matrix factorization | 50.2 |
| Weiss and Ellis (2010) | Model-based, joint decoding | 48.0 |
| Li et al. (2010) | Model-based, reconstruction | 47.7 |
| Shao et al. (2010) | CASA, missing features | 45.5 |
| Baseline recognizer | HTK recognizer, no enhancement | 33.4 |
| Deshmukh and Espy-Wilson (2006) ^a | Phase opponency enhancement | 31.6 |
| Every and Jackson (2006) ^a | Pitch-based enhancement | 23.3 |
| Chance | Guessing | 7.0 |

Hershey et al (2010) from IBM

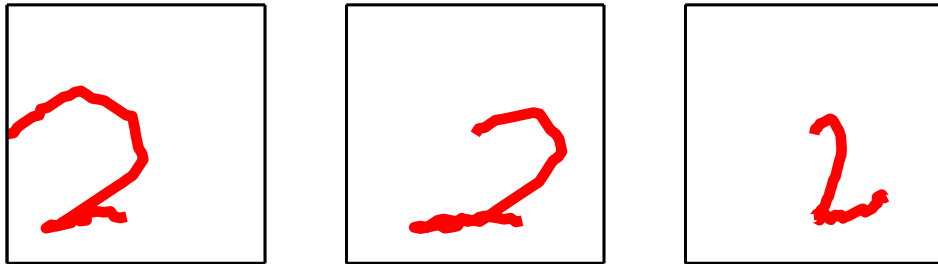
- estimate speaker identities and gains of both talkers
- separation system combines task grammar with speaker-dependent acoustic models, and acoustic interaction model
- gives two sets of sources, speaker A is target or speaker B is target
- recognize each signal using speaker-dependent labeling

Task grammar model and acoustic source models

Hand written digit model



- real examples



- synthetic examples
generated from left-to-right HMM trained on 45 examples

HMM Inference and Learning problems

