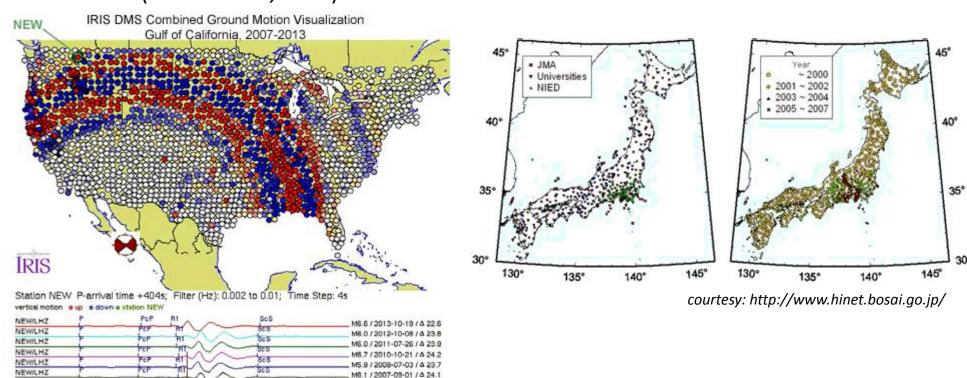
Large Seismic Networks

USArray (http://www.usarray.org/)

00:00:00

Hi-net (http://www.hinet.bosai.go.jp/), one of the densest, distance ~20 km between receivers (Okada et. al., 2004)



courtesy: http://www.iris.edu/

00:20:00

Visualization Elapsed Time (hh:mm:ss)

Seismic Gradiometry - Introduction

- New technique for treating a large array data to reconstruct and to characterize a seismic wavefield observed
- Original concept by Langston (2007a), to measure the spatial gradient of seismic waves observed by dense array. He showed that slowness could be directly estimated.
- Igel (2005) proposed a similar approach with rotational seismometers.
- Langston (2007b) SG applied to 2D problem
- Langston (2007c) improved its stability in time domain
- Langston & Liang (2008) SG applied to polarized waves
- Liang & Langston (2009) estimated Rayleigh waves with grid locations collocated with seismic stations (limited to the station location)
- Spudich (1995) performed a similar series expansion to estimate surface strain and stress tensors recorded by dense array
- Maeda (2016) used SG to reconstruct the seismic wavefield as a continuous 2D field irrespective of the station location

Seismic Gradiometry - Benefits

- SG has the advantage that it estimates slowness as a spatially varying value, whereas
 other array methods ie. semblance method (Neidell & Taner, 1971) which assume a
 homogeneous plane-wave incidence and utilize phase differences to estimate slowness
- SG models both phase and amplitude of the observed wavefield
- Possibility to separate non-plane wave characteristics, ie. the radiation pattern and geometrical spreading
- SG is a tool for reconstructing a spatially continuous seismic wavefield
- Divergence (div) and Rotation (rot) of 3C seismic wavefield can be estimated by SG and used to characterize seismic wave propagation features

SG Method - Theory

Uses Taylor series expansion (1st order) of the seismic wavefield in 2D horizontal space

$$u^{\text{obs}}(x_S, y_S; t) \cong u(x_G, y_G; t) + \frac{\partial u(x_G, y_G; t)}{\partial x} (x_S - x_G) + \frac{\partial u(x_G, y_G; t)}{\partial y} (y_S - y_G)$$
observed location
nearby grid location
1st order Taylor expansion

 Using several observations from stations near target grid to construct an observation equation (N is the number of stations used for estimation)

$$u^{\text{obs}} = \textit{Gm}$$

$$\begin{pmatrix} u^{\text{obs}}\left(x_{S1}, y_{S1}; t\right) \\ u^{\text{obs}}\left(x_{S2}, y_{S2}; t\right) \\ \vdots \\ u^{\text{obs}}\left(x_{SN}, y_{SN}; t\right) \end{pmatrix} = \begin{pmatrix} 1 & x_{S1} - x_G & y_{S1} - y_G \\ 1 & x_{S2} - x_G & y_{S2} - y_G \\ \vdots & \vdots & \vdots \\ 1 & x_{SN} - x_G & y_{SN} - y_G \end{pmatrix} \begin{pmatrix} u(x_G, y_G; t) \\ \partial_x u(x_G, y_G; t) \\ \partial_y u(x_G, y_G; t) \\ \partial_y u(x_G, y_G; t) \end{pmatrix}$$
spatial derivatives

SG Method - Theory (continued)

- If input data 3 or more stations then it is over-determined problem, regularization by smoothing or damping is not necessary, we use least-squares (LSQ) method to estimate the wave amplitude and the spatial gradients
- Computational cost reduced by using a previously computed kernel matrix for LSQ calculation because the inverse problem depends only on the station configuration (K is a weighting factor and W is a diagonal weight matrix eg. Menke, 2012)

$$m = (G^T W G)^{-1} G^T W u^{\text{obs}}$$

$$\equiv K u^{\text{obs}}$$
weighting
factor

Decompossed as follow

$$m{m} = \left(egin{array}{c} m{k}_{\mathrm{u}} \cdot m{u}^{\mathrm{obs}} \ m{k}_{\partial x} \cdot m{u}^{\mathrm{obs}} \ m{k}_{\partial y} \cdot m{u}^{\mathrm{obs}} \end{array}
ight)$$

SG Method - Theory (continued)

Weighting done by empirically adopted the Gaussian function with variance and cutoff distance

$$\sigma^2 = \Delta_0^2 / 10 \qquad \Delta_0 = 50 \text{ km}$$

- The quality of the estimation of m (the displacement and the spatial gradients)
 depends on locations of the stations relative to the grid point.
- The quality of the estimation of *m* improves as the number of stations used increases
- However, the use of more distant stations may under-estimate of the spatial derivatives
 of the waves, therefore Maeda (2016) used only stations within 50 km with smoothly
 decreasing weighting factor

Love & Rayleigh Wave Decomposition

Slowness Estimation

Proposed SG Notebook Project for Skience 2018

- Simple 2D horizontal space
- Rock properties (?)
- SG analytical solution
- FDM + PML (or else like SPECFEM2D, SALVUS, SOFI2D, OpenSWPC, etc.)
- Moment tensor (simulate an earthquake, P-SV or SH, Rayleigh wave), f = 10-15 Hz
- 3C or 6C (?), around 20-50 receivers, random spreading with distance ~20-30 m
- Compare numerical solution (FDM + PML) with seismic gradiometry (SG) solution

References

- Davis, B. (2011). The Basic Theory of Wave Gradiometry. GEOP 523D.
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- Langston, C., & Lang, C. (2009). Wave gradiometry for USArray: Rayleigh waves. Journal of Geophysical Research, vol. 114.
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- Liu, Y., & Holt, W. (2015). Wave gradiometry and its link to Helmholtz equation solutions applied to USArray in the eastern U.S. Journal of Geophysical Research: Solid Earth.
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