MATH3051: Applied Real and Functional Analysis

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Sets and Functions

Metric Spaces

Our first object of study come from sets endowed with a notion of a *distance*. The ordinary distance function over the real numbers is the absolute difference; that is, over the real numbers, we can define the distance of x and y by the magnitude of its difference: d(x,y) = |x-y|. What we would like to do is to extract some of the useful properties from this distance function and generate a more general description of distance. What properties do we want in a distance function?

The first property that we would want is that the distance is non-negative; it doesn't *really* make sense to refer to negative distance. Therefore, one property that we would want is that, for any pair of points x, y in your set, $d(x, y) \ge 0$. What about the distance from x to itself? Define d(x, x) = 0 for each x.

The second property is that distances are symmetric; it takes the same distance if we started at x to y as it would if we started at y instead. Therefore, it would be nice if d(x,y)=d(y,x). Finally, distances should satisfy the triangle inequality; that is, $d(x,y) \leq d(x,z) + d(z,y)$. In fact, this is enough to define a distance function, thereafter referred to as a *metric*.

Definition. Let X be a non-empty set. A *metric* on X is a function $d: X \times X \to \mathbb{R}$ satisfying the following properties for any $x, y, z \in X$.

- [1] **Positive definiteness**: $d(x,y) \ge 0$ with d(x,y) = 0 if and only if x = y.
- [2] **Symmetric**: d(x, y) = d(y, x).
- [3] Triangle inequality: $d(x, y) \le d(x, z) + d(z, y)$.

The pair (X, d) is called a *metric space*. These properties are clear for the metric d(x, y) = |x - y| over the set $X = \mathbb{R}$. It is more interesting to explore more exotic examples of metric spaces.

Consider the set C([a,b]) of continuous functions on the closed interval [a,b], and let $d_1(f,g) = \max_{a \le t \le b} |f(t) - g(t)|$. It is not hard to see that $(C([a,b]),d_1)$ forms a metric space. The first two properties of the metric are obvious. It suffices to check the triangle inequality. We see that

$$\begin{split} d_1(f,g) &= \max_{a \leq t \leq b} |f(t) - g(t)| \\ &= \max_{a \leq t \leq b} |f(t) - h(t) + h(t) - g(t)| \\ &= \max_{a \leq t \leq b} (|f(t) - h(t)| + |h(t) - g(t)|) \\ &\leq \max_{a \leq t \leq b} |f(t) - h(t)| + \max_{a \leq t \leq b} |h(t) - g(t)| \\ &= d_1(f,h) + d_1(h,g), \end{split}$$

as required. Therefore, $(C([a,b]), d_1)$ forms a metric space.

2.1 Convergence in Metric Spaces

2.2 Continuity in Metric Spaces

2.3 Completeness

In the previous sections, we talked about sequences of points converging in a metric space. In particular, every convergence sequence is *Cauchy*. However, not all Cauchy sequences converge. The completeness property of metric spaces rectifies this.

Definition (Completeness). A metric space X is *complete* if every Cauchy sequence converges to some element in X.

For example, the metric space $(\mathbb{Q}, |\cdot|)$ is *not* complete. Consider any irrational number x and consider the sequence given by the truncations of x. The sequence is Cauchy but does not converge to any element in \mathbb{Q} because the sequence converges to x which is clearly not in \mathbb{Q} .

Theorem. A closed subspace of a complete metric space is complete.

Proof. Let X be a complete metric space, and let Y be a closed subspace of X. We now show that Y is complete. To do this, consider any Cauchy sequence $\{x_n\}$ in Y. We need to show that such a sequence converges to a point in Y. Clearly, $\{x_n\}$ is Cauchy in X. Since X is complete, $\{x_n\}$ converges to a point X in X. But Y is closed in X; therefore, Y must contain all of its limit points which implies that $X \in Y$ since $\{x_n\} \subseteq Y$. Therefore, $\{x_n\}$ converges to a point in Y which finishes the proof. \square

2.3.1 Baire's Theorem

One reason why completeness is such a fundamental result is due to Baire's theorem. Loosely speaking, Baire's theorem says that if we begin with a complete metric space, then the intersection of every countable collection of dense open sets of X is dense in X. We can also think about this in the context of closed sets too. Given a collection of

Topological Spaces

In the previous chapter, we explored the concept of *metric spaces*. These were familiar objects to study but they aren't quite versatile. The metric object isn't quite general and so, some notions of convergence aren't well-defined on some set structures. When a set *X* does not have a metric equipped, we need to look for something stronger. It turns out that all we need is a notion of an *open set*.

In fact, metrics induce a very natural open set. Consider the metric defined by d(x, y) = |x - y|. One way to define an open set using d is to consider the collection of points y that is contained inside

3.1 Axioms of Separation

The axioms of separation impose further restrictions on a topological space (X, τ) to provide information about whether there are *enough* open sets to *separate* distinct points (subsets). The first natural restriction is the *existence* of an open set U that contains x but not y. Topological spaces that satisfy this property are often called T_0 -spaces or Kolmogorov spaces. This is the weakest separation axiom but the simplest restriction to ensure that all points in a T_0 -space are topologically distinguishable.

3.1.1 T_1 -space

We can make this restriction stronger. Instead of requiring one open set that contains one point but not another, we might require a pair of open sets $U_x, V_y \in \tau$ such that $x \in U_x, y \notin U_x$ and $x \notin V_y, y \in V_y$ for all pairs of points $x, y \in X$. It is easy to see that all spaces that are T_1 must necessarily be T_0 -spaces. These spaces are called *Fréchet spaces*.

3.1.2 T_2 -space – Hausdorff property

We now come to an even stronger restriction. For T_1 -spaces, the pair of open sets may overlap. The second axiom of separation requires the open sets to be disjoint; that is, for each pair of points $x, y \in X$, we have that

$$x \in U_x, y \in V_y, U_x \cap V_y = \emptyset.$$

These are called *Hausdorff spaces*.

- 3.2 Bases
- 3.3 Compactness
- 3.3.1 Compactness in Metric Spaces
- 3.4 Continuity
- 3.5 Connectedness
- 3.6 Topology: The weak topology

Measure Theory and Lebesgue Integrals

Normed Vector Spaces

Differential Calculus in Normed Spaces