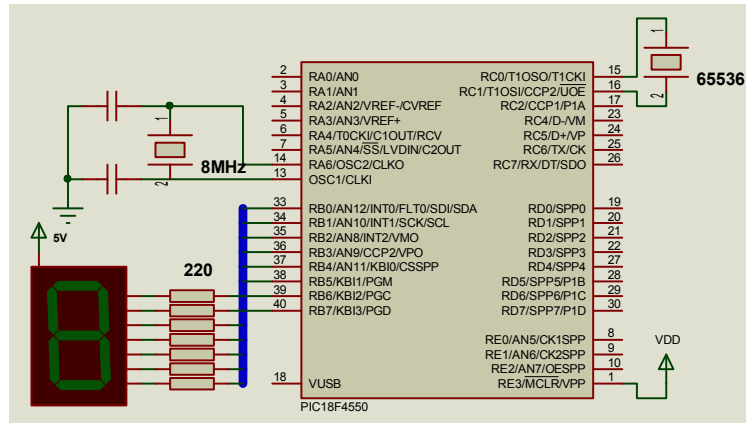


**Nom i Cognoms:** \_\_\_\_\_

- 1) El circuit de la figura, presenta la connexió d'un display de 7 segments al PORTB del PIC18F4550



- a) (1p.) Quin valor hem de carregar als registres TRISB i PORTB per a encendre tots leds del display? Per què?

TRISB = \_\_\_\_\_

PORTB = \_\_\_\_\_

- b) (1p.) Calculeu el corrent  $I_{RB0}$  quan el led corresponent està encès. Considereu  $V_{\gamma}=1'1V$ ,  $V_{dd} = 5V$ ,  $V_{ol} = 0'6V$ ,  $V_{oh} = 4'3V$ . JUSTIFICA el resultat

$I_{RB0} =$  \_\_\_\_\_

- c) (2p.) Volem mostrar pel display el comptatge de segons (cíclic del 0 al 9). Per a tal fi, usarem el timer1 connectat a un oscil.lador de quartz extern de  $2^{16}$  Hz.

```

main ( )
{
    ....//inicialitzacions    vàries    i
    correctes
    for ( ; ; )
    {
        PORTB = PatroLeds[segs];
        Sleep ( ) ;
    }
}

Void interrupt RSI_timer1 (void)
{
    segs ++;
    segs = segs %10 ;
    TMR1IF = 0;
}

```

A partir del codi presentat, indiqueu el valor (en binari) del registre T1CON per a que el comptatge de segons sigui correcte. JUSTIFICA la resposta.

T1CON = \_\_\_\_\_

- d) (1p.) Durant quin percentatge de temps aproximat el micro estarà dormint? (Podeu considerar que el compilador optimitza el codi).

Nom i Cognoms: \_\_\_\_\_

	7	6	5	4	3	2	1	0
value after reset	RD16	T3CCP2	T3CKPS1	T3CKPS0	T3CCP1	T3SYNC	TMR3CS	TMR3ON
	0	0	0	0	0	0	0	0

RD16: 16-bit read/write mode enable bit  
 0 = Enables read/write of Timer3 in two 8-bit operations  
 1 = Enables read/write of Timer3 in 16-bit operation

T3CCP2:T3CCP1: Timer3 and Timer1 to CCPx enable bits  
 00 = Timer1 and Timer2 are the clock sources for CCP1 through CCP5  
 01 = Timer3 and Timer4 are the clock sources for CCP2 through CCP5;  
 Timer1 and Timer2 are the clock sources for CCP1  
 10 = Timer3 and Timer4 are the clock sources for CCP3 through CCP5;  
 Timer1 and Timer2 are the clock sources for CCP1 and CCP2  
 11 = Timer3 and Timer4 are the clock sources for CCP1 through CCP5

T3CKPS1:T3CKPS0: Timer3 input clock prescale select bits  
 00 = 1:1 prescale value  
 01 = 1:2 prescale value  
 10 = 1:4 prescale value  
 11 = 1:8 prescale value

T3SYNC: Timer3 external clock input synchronization select bit  
 When TMR3CS = 1  
 0 = Synchronizes external clock input  
 1 = Do not synchronize external clock input  
 When TMR3CS = 0  
 This bit is ignored.

TMR3CS: Timer3 clock source select bit  
 0 = Instruction cycle clock (FOSC/4)  
 1 = External clock from pin RC0/T1OSO/T13CKI

TMR3ON: Timer3 on bit  
 0 = Stops Timer3  
 1 = Enables Timer3

Figure 8.8. T3CON contents (redraw with permission of Microchip)

	7	6	5	4	3	2	1	0
value after reset	--	--	DCxB1	DCxB0	CCPxM3	CCPxM2	CCPxM1	CCPxM0
	0	0	0	0	0	0	0	0

DCxB1:DCxB0: PWM duty cycle bit 1 and bit 0 for CCP module x

capture mode:

unused

compare mode:

unused

PWM mode:

These two bits are the 1sbs (bit 1 and bit 0) of the 10-bit PWM duty cycle.

CCPxM3:CCPxM0: CCP module x mode select bits

0000 = capture/ compare/ PWM disabled (resets CCPx module)

0001 = reserved

0010 = compare mode, toggle output on match (CCPxIF bit is set)

0100 = capture mode, every falling edge

0101 = capture mode, every rising edge

0110 = capture mode, every 4th rising edge

0111 = capture mode, every 16th rising edge

1000 = compare mode, initialize CCP pin low, on compare match force CCP pin high (CCPxIF bit is set)

1001 = compare mode, initialize CCP pin high, on compare match force CCP pin low (CCPxIF bit is set)

1010 = compare mode, generate software interrupt on compare match (CCP pin unaffected, CCPxIF bit is set).

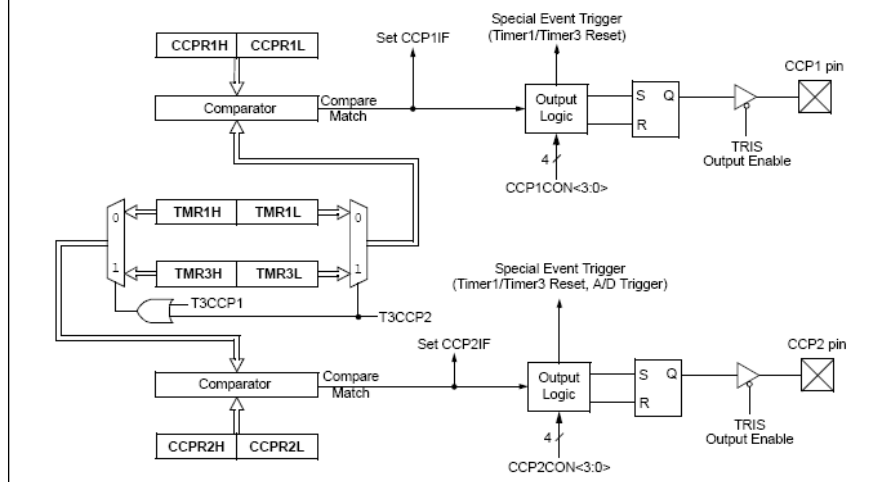
1011 = compare mode, trigger special event (CCPxIF bit is set)

For CCP1 and CCP2: Timer1 or Timer3 is reset on event

For all other modules: CCPx pin is unaffected and is configured as an I/O port.

11xx = PWM mode

Figure 8.10 CCPxCON register (x = 1...5) (redraw with permission of Microchip)



**Nom i Cognoms:** \_\_\_\_\_

- 2) Volem utilitzar la unitat CCP2 per fer una funció Delay\_us(int n) on rebem un paràmetre n que és el nombre de microsegons que volem esperar. Internament, farem servir el Timer3 ja que el Timer1 el tenim ocupat a l'exercici 1. L'oscil·lador connectat al nostre processador (Fosc) és de 8 MHz. Observeu el codi de la funció:

```
void Delay_us(int n)
{
    TIMER3 = 0 ;
    CCPR2 = n;
    while(!CCP2IF);
    CCP2IF=0;
}
```

- a) Per que la funció Delay\_us(int n) sigui efectiva i actuï correctament, amb quins valors haurem hagut d'inicialitzar, els registres CCP2CON i T3CON? Justifica la resposta!! (1p)

CCP2CON =

T3CON =

- b) Quin és el nombre màxim que podem acceptar com a paràmetre? Per què? (0,5p)
- c) Té sentit cridar la funció amb un n petit, com per exemple: Delay\_us(3) Justifica la resposta. (1p)

Nom i Cognoms: \_\_\_\_\_

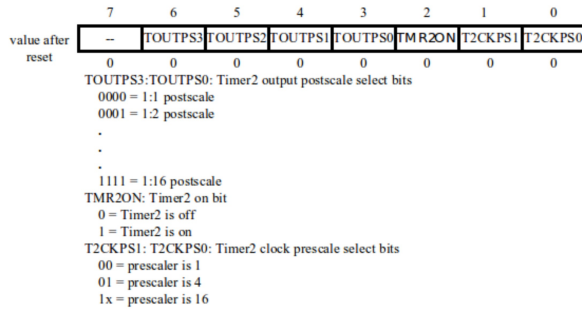


Figure 8.6. T2CON control register (redraw with permission of Microchip)

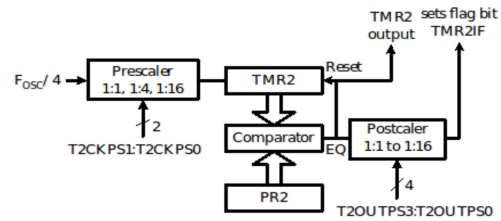


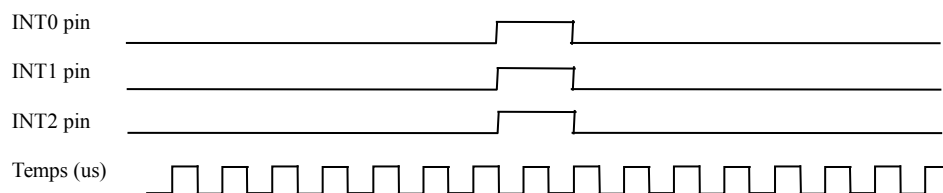
Figure 8.5 Timer2 block diagram (redraw with permission of Microchip)

- 3) Observeu el següent codi. El rellotge del PIC és de **8MHz**. (suposeu que, inicialment, INT0IE=0; INT1IE=1; INT2IE=0; GIEH=1; INT0IP=1; INT1IP=1; INT2IP=1, INT0IF=0; INT1IF=0; INT2IF=0);

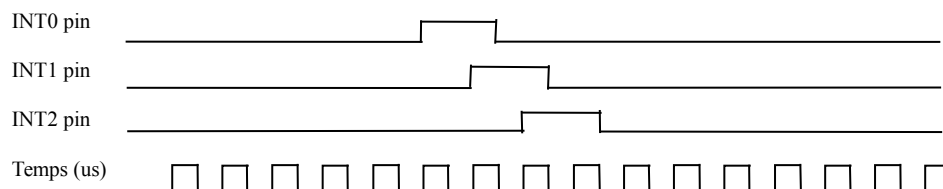
```
void interrupt InterruptHigh()
{
    if ((INT0IF)&&(INT0IE))
    {
        INT0IF=0; INT1IF=0;INT2IF=0;
        INT2IE=1;
    }
    if ((INT1IF)&&(INT1IE))
    {
        INT0IF=0; INT1IF=0;INT2IF=0;
        INT0IE=1;
    }
    if ((INT2IF)&&(INT2IE))
    {
        INT0IF=0; INT1IF=0;INT2IF=0;
        EncénLED();
    }
}
```

Ara observeu les següent seqüències d'events, amb referència temporal, als pins d'interrupció, que estan ben configurats:

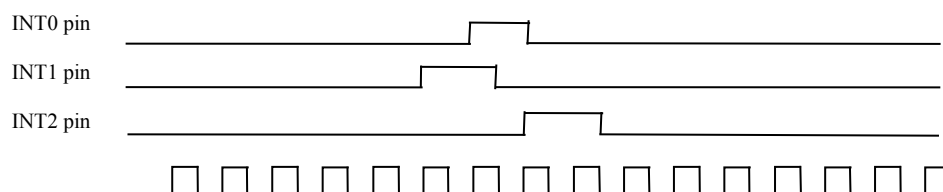
#### Seqüència 1:



#### Seqüència 2:



#### Seqüència 3:



**Nom i Cognoms:** \_\_\_\_\_

Alguna o algunes d'aquestes seqüències provocaran l'encesa del LED? Justifica la resposta (1p) ?

- 4) Programeu tot el necessari per generar al PIN CCP1 un senyal PWM de freqüència 1KHz i DC=18%. Supposeu Fosc=8MHz. (1,5p)

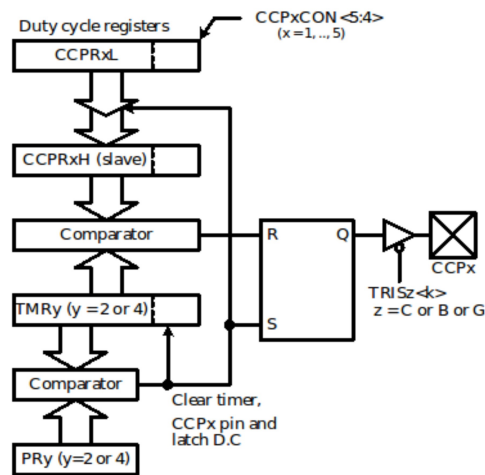


Figure 8.24 Simplified PWM block diagram (redraw with permission of Microchip)

$$\text{PWM period} = [(PRy) + 1] \times 4 \times TOSC \times (TMRy \text{ prescale factor})$$

$$\text{PWM duty cycle} = (CCPRxL:CCPxCON<5:4>) \times TOSC \times (TMRy \text{ prescale factor})$$

Figure 8.3 Timer1 block diagram: 16-bit mode (redraw with permission of Microchip)

R/W-0	R-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
RD16	T1RUN	T1CKPS1	T1CKPS0	T1OSEN	T1SYN	TMR1CS	TMR1ON
bit 7		bit 0					

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared      x = Bit is unknown

- |         |  |
|---------|--|
| bit 7   | <b>RD16:</b> 16-Bit Read/Write Mode Enable bit<br>1 = Enables register read/write of Timer1 in one 16-bit operation<br>0 = Enables register read/write of Timer1 in two 8-bit operations   |
| bit 6   | <b>T1RUN:</b> Timer1 System Clock Status bit<br>1 = Device clock is derived from Timer1 oscillator<br>0 = Device clock is derived from another source  |
| bit 5-4 | <b>T1CKPS1:T1CKPS0:</b> Timer1 Input Clock Prescale Select bits<br>11 = 1:8 Prescale value<br>10 = 1:4 Prescale value<br>01 = 1:2 Prescale value<br>00 = 1:1 Prescale value  |
| bit 3   | <b>T1OSCEN:</b> Timer1 Oscillator Enable bit<br>1 = Timer1 oscillator is enabled<br>0 = Timer1 oscillator is shut off<br>The oscillator inverter and feedback resistor are turned off to eliminate   |
| bit 2   | <b>T1SYNC:</b> Timer1 External Clock Input Synchronization Select bit<br><u>When TMR1CS = 1:</u><br>1 = Do not synchronize external clock input<br>0 = Synchronize external clock input<br><u>When TMR1CS = 0:</u><br>This bit is ignored. Timer1 uses the internal clock when TMR1CS = 0. |
| bit 1   | <b>TMR1CS:</b> Timer1 Clock Source Select bit<br>1 = External clock from RC0/T1OSO/T13CK1 pin (on the rising edge)<br>0 = Internal clock (Fosc/4)  |
| bit 0   | <b>TMR1ON:</b> Timer1 On bit<br>1 = Enables Timer1<br>0 = Stops Timer1   |