

# Estimating optimal PAC-Bayes bounds with Hamiltonian Monte Carlo

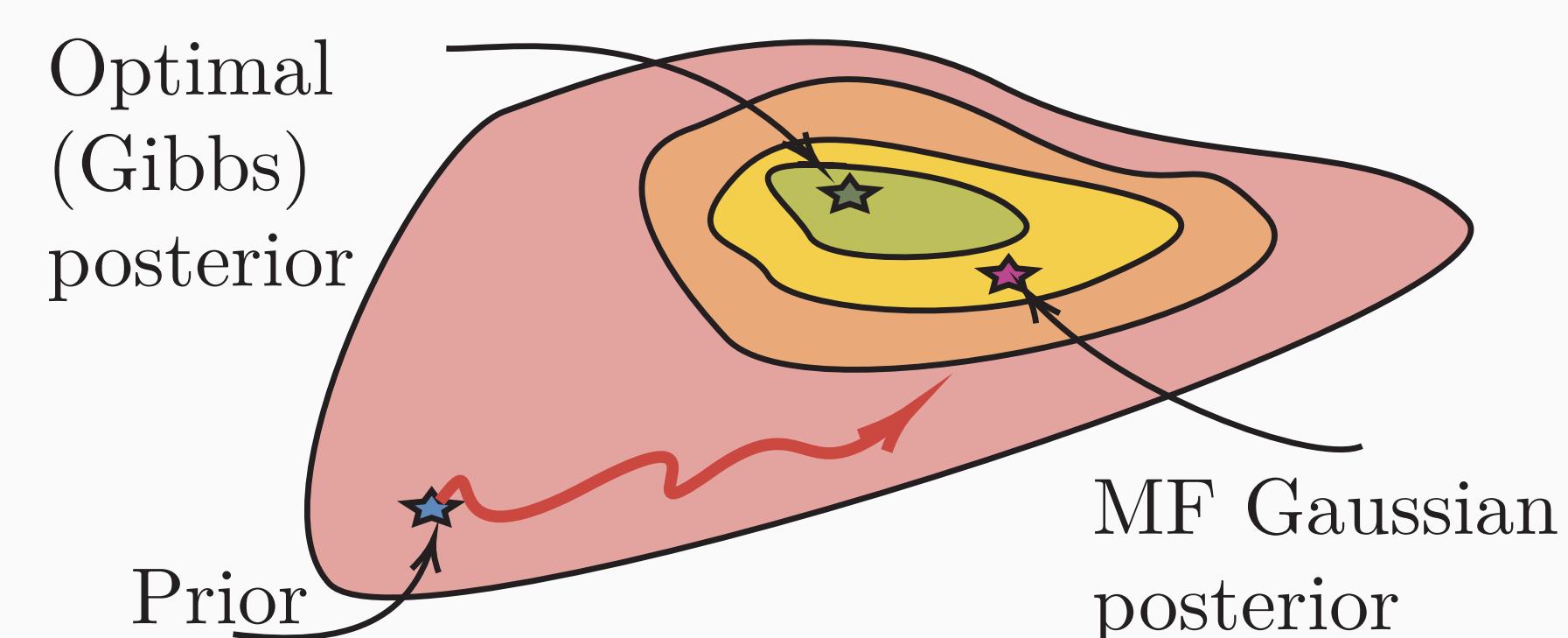
Szilvia Ujváry<sup>1</sup> Gergely Flamich<sup>1</sup> Vincent Fortuin<sup>2</sup> José Miguel Hernández Lobato<sup>1</sup><sup>1</sup>*University of Cambridge* <sup>2</sup>*Hemholtz AI, TU Munich*

Mathematics of Modern Machine Learning Workshop @ NeurIPS 2023



## Introduction

How far from optimality are data-independent PAC-bounds computed using diagonal covariance posteriors?



- We estimate PAC-Bayes bounds at their **optimal posterior** instead of a MF Gaussian approximation
- Leads to **tighter bounds**
- Shows the **need for better posterior approximations**

## Glossary

our task	supervised classification with NNs
MF Gaussian	A Gaussian with diagonal covariance
MFVI	variational inference with MF Gaussians
$P$	prior distribution on model weights
$Q$	a (posterior) distribution on the weights
$L(Q)$	expected risk of randomized predictor $Q$
$\hat{L}_S(Q)$	empirical risk on i.i.d. data sample $S$
risk certificate	a high-confidence upper bound on $L(Q)$

## The bounds

For fixed prior  $P$ , for any  $Q$ , with probability at least  $1 - \delta$

$$\text{kl bound [2]: } \text{kl}(\hat{L}_S(Q) \| L(Q)) \leq \frac{\text{KL}(Q \| P) + \log(\frac{2\sqrt{n}}{\delta})}{n}$$

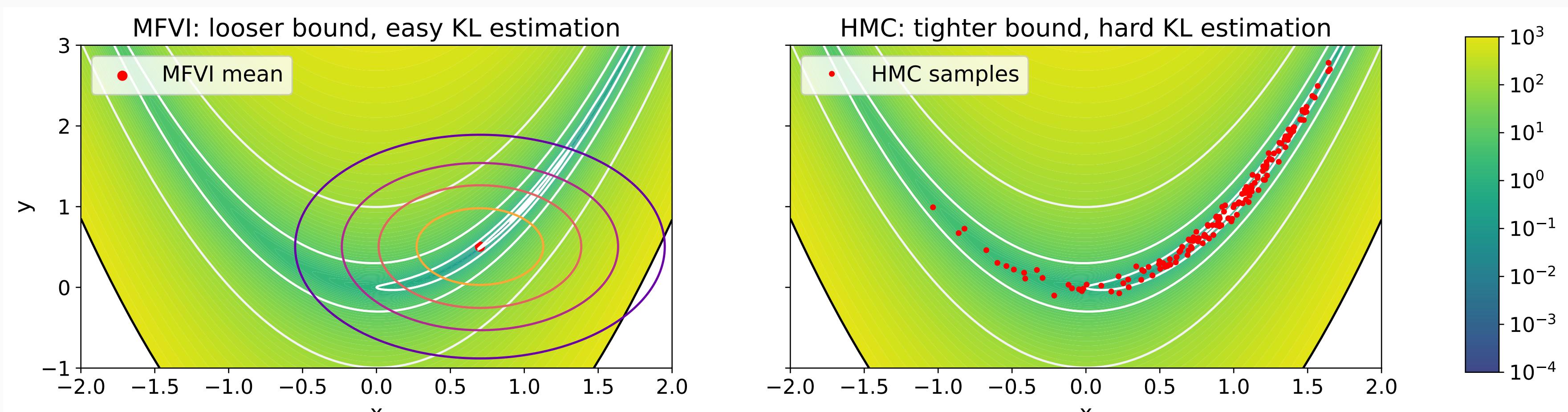
$$\text{linear bound [3]: } L(Q) \leq \frac{\hat{L}_S(Q)}{0.5} + \frac{\text{KL}(Q \| P) + \log(\frac{2\sqrt{n}}{\delta})}{0.5n}$$

We sample from  $Q^*$  (with density  $q^*$ ) minimizing the linear bound and compute a risk certificate with the kl bound.

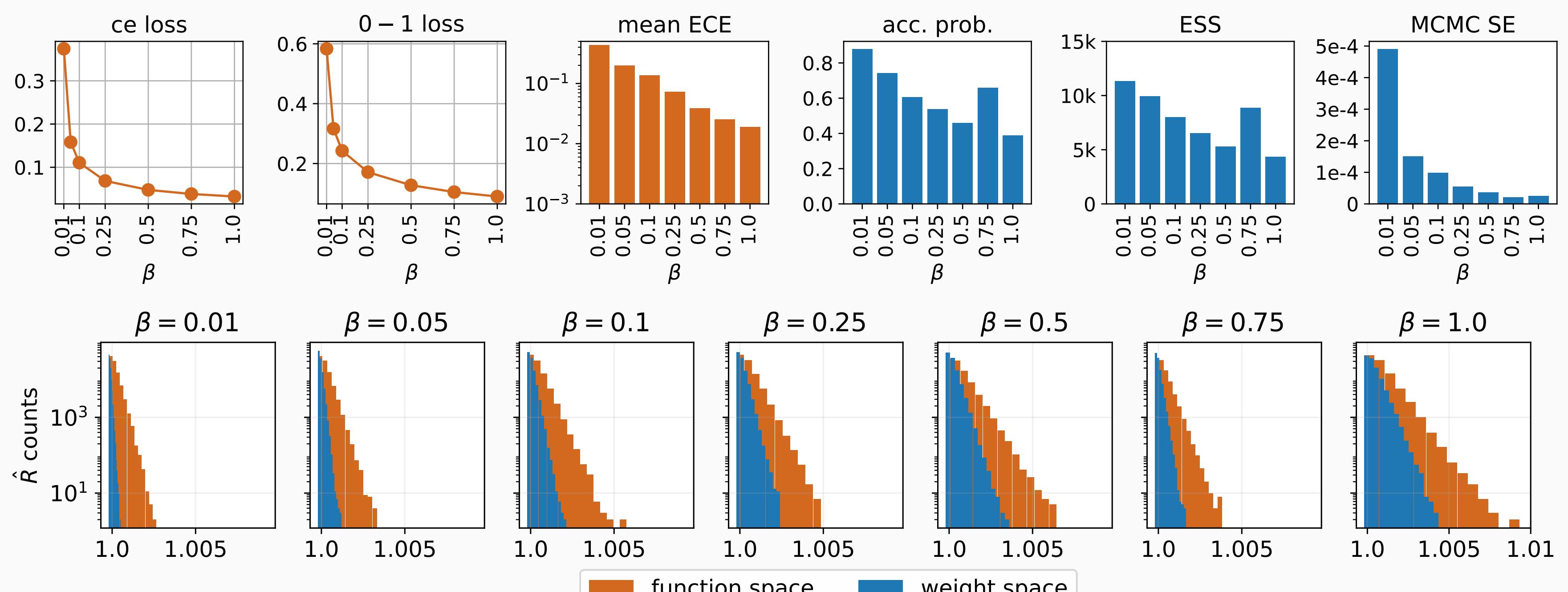
$$q^*(\mathbf{w}) \propto e^{-n\hat{L}_S(\mathbf{w})} p(\mathbf{w})$$

## Method part I - Sampling from $Q^*$ with HMC

- Why HMC? Can approximate complicated posteriors much better than MF Gaussians
- What's the trade-off? It now becomes harder to estimate the bound



- Does it actually work? → our results are backed up by running extensive diagnostics



## Method part III - Ensuring a high-probability bound

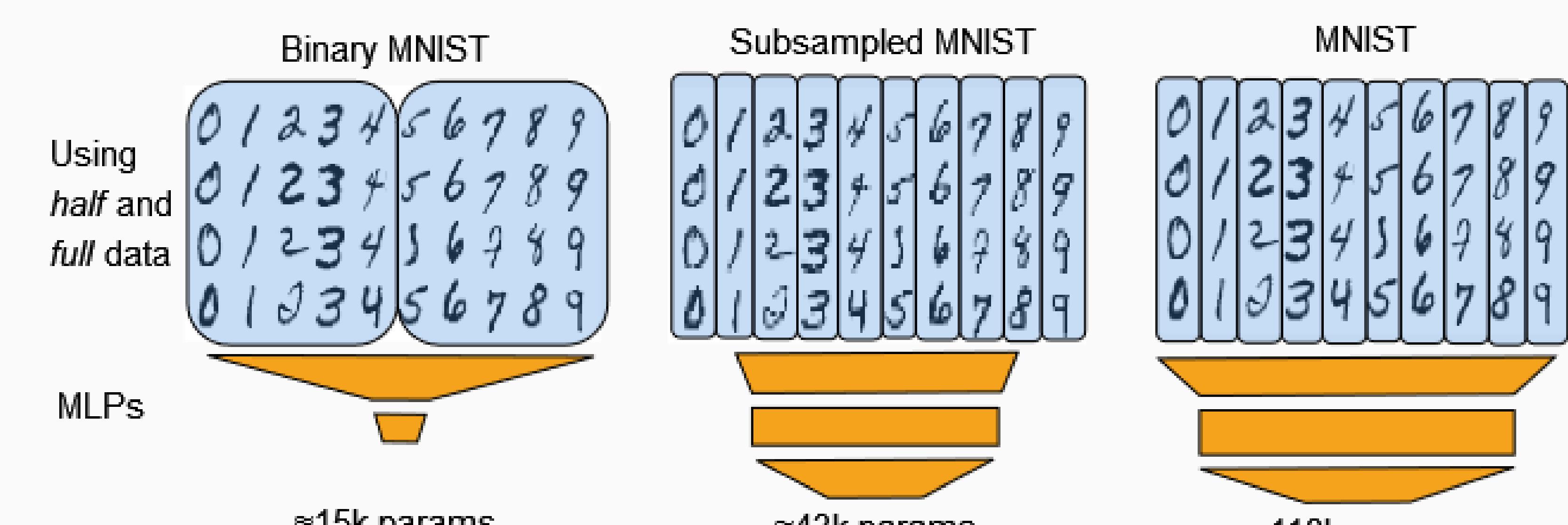
We wish to produce a statement such as

$$L(\widehat{Q}^*) \leq \{\text{our estimate}\} \text{ with prob. at least } 1 - \delta$$

For this we need concentration inequalities on our HMC estimates. It's hard to check convergence assumptions in MCMC, so we give 3 options

1. An i.i.d. concentration inequality on **thinned** samples
2. An asymptotic confidence interval which requires "good estimators"
3. A loose bound that only needs  $\text{KL}(\widehat{Q}^* \| Q^*) < \text{KL}(G \| Q^*)$  for a baseline MF Gaussian

## Experiment details



## Some results & takeaways

Setup	Train/test stats	0-1 RC with kl bound				
		Train 0-1	Test 0-1	KL/n	kl inverse	asympt
MFVI	Binary	0.0960	0.0928	0.0105	0.1640	0.1452
Gibbs p.	Binary	0.0404	0.0415	0.0195	<b>0.1080</b>	<b>0.0702</b>
MFVI	14 × 14	0.1389	0.1313	0.0140	0.2379	0.1991
Gibbs p.	14 × 14	0.0695	0.0723	0.0381	<b>0.1855</b>	<b>0.1335</b>
MFVI	MNIST	0.1236	0.1200	0.0196	0.2070	0.1987
Gibbs p.	MNIST	0.0653	0.0691	0.0334	<b>0.1759</b>	<b>0.1269</b>

- Reasonable estimates, e.g. no bound violations
- Data-independent bounds can be tightened
- Improvement over MFVI is largest for small models

## References

- [1] Vaden Masrani, Tuan Anh Le, and Frank Wood. The thermodynamic variational objective. In *Advances in Neural Information Processing Systems*, 2019.
- [2] Andreas Maurer. A note on the PAC Bayesian theorem, 2004.
- [3] Niklas Thiemann, Christian Igel, Olivier Wintenberger, and Yevgeny Seldin. A strongly quasiconvex PAC-Bayesian bound. In *Proceedings of the 28th International Conference on Algorithmic Learning Theory*, 2017.